

TAM 212 Class 7 : Acceleration Vectors

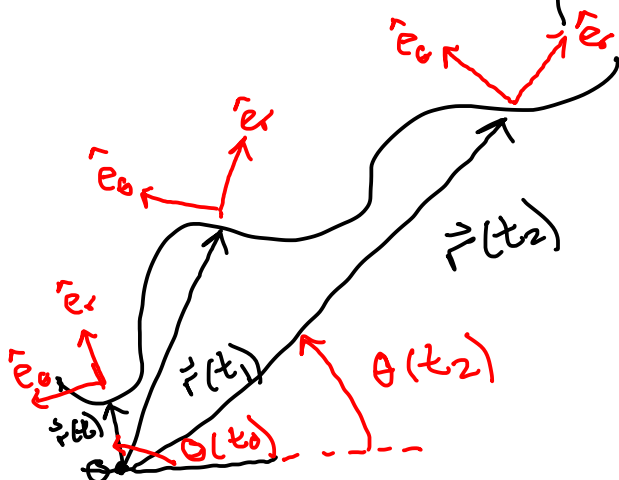
ANNOUNCEMENTS

① PL2 due Friday 11:59pm
Report 2 due Monday 11:59pm, PL 2-13

② James Scholten Honors:
F 4-5pm MEL 2005

Review: in 2D

	cartesian	polar
position	$\vec{r} = x\hat{i} + y\hat{j}$	$\vec{r} = r\hat{e}_r$
velocity	$\vec{v} = \dot{x}\hat{i} + \dot{y}\hat{j}$	$\vec{v} = \dot{r}\hat{e}_r + r\dot{\theta}\hat{e}_\theta$
accel.	$\vec{a} = \ddot{x}\hat{i} + \ddot{y}\hat{j}$	$\boxed{\vec{a}} = (\ddot{r} - r\dot{\theta}^2)\hat{e}_r + (r\ddot{\theta} + 2\dot{r}\dot{\theta})\hat{e}_\theta$ $\downarrow$ radial $\downarrow$ centripetal "center-seeking" $\downarrow$ angular $\rightarrow$ coriolis



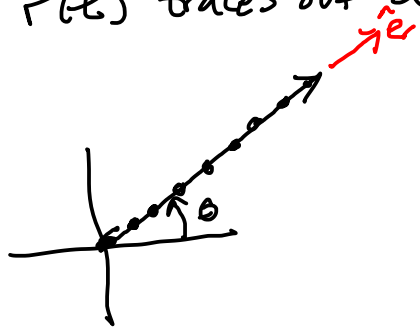
How did we obtain $\vec{a}$? differentiate $\vec{v}$

used: $\hat{e}_r = \cos\theta\hat{i} + \sin\theta\hat{j} \Rightarrow$
 $\hat{e}_\theta = -\sin\theta\hat{i} + \cos\theta\hat{j} \Rightarrow$

$$\begin{aligned} \dot{\hat{e}}_r &= \dot{\theta}\hat{e}_\theta \\ \dot{\hat{e}}_\theta &= -\dot{\theta}\hat{e}_r \end{aligned}$$

What are all the terms in $\vec{a}$? (polar)

ex) $\vec{r}(t)$ traces out a straight line at constant θ



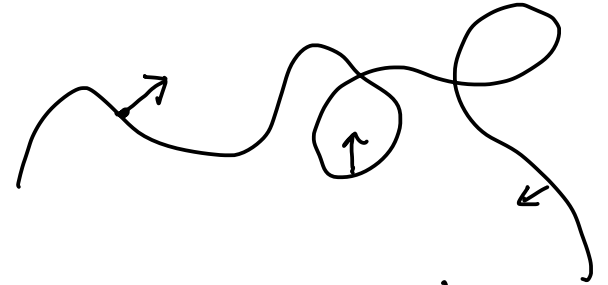
$$\vec{r} = r \hat{e}_r$$

$$\vec{v} = \dot{r} \hat{e}_r + r \dot{\theta} \hat{e}_\theta$$

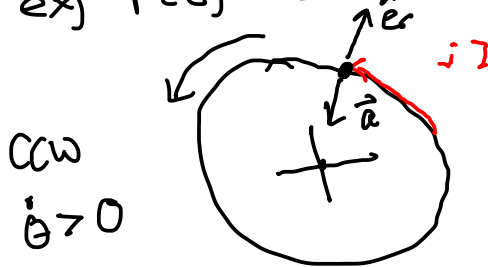
$$\vec{a} = \ddot{r} \hat{e}_r + \dot{r} \dot{\theta} \hat{e}_\theta + r \ddot{\theta} \hat{e}_\theta - r \dot{\theta}^2 \hat{e}_r$$

$$\vec{a} = \ddot{r} \hat{e}_r$$

radial



ex) $\vec{r}(t)$ traces out circular path at constant speed



$$\vec{r} = r \hat{e}_r$$

$$\vec{v} = \dot{r} \hat{e}_r + r \dot{\theta} \hat{e}_\theta$$

$$\vec{a} = \frac{d}{dt} (r \dot{\theta}) \hat{e}_\theta + (r \dot{\theta}) \dot{\hat{e}}_\theta$$

$$= (\dot{r} \dot{\theta} + r \ddot{\theta}) \hat{e}_\theta + (r \dot{\theta}) (-\dot{\theta} \hat{e}_r)$$

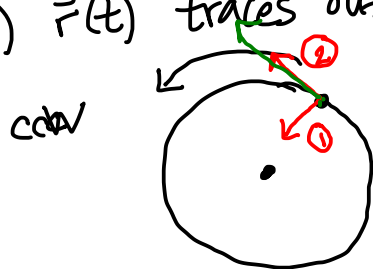
$$= -r \dot{\theta}^2 \hat{e}_r \quad \text{centripetal}$$

$$r = \text{constant}$$

$$\dot{\theta} = \text{constant}$$

$$r \omega^2$$

ex) $\vec{r}(t)$ traces out a circular path at increasing speed



$$\vec{r} = r \hat{e}_r$$

$$\vec{v} = \dot{r} \hat{e}_r + r \dot{\theta} \hat{e}_\theta$$

$$\vec{a} = \frac{d}{dt} (r \dot{\theta}) \hat{e}_\theta + (r \dot{\theta}) \dot{\hat{e}}_\theta$$

$$= (\dot{r} \dot{\theta} + r \ddot{\theta}) \hat{e}_\theta - r \dot{\theta}^2 \hat{e}_r$$

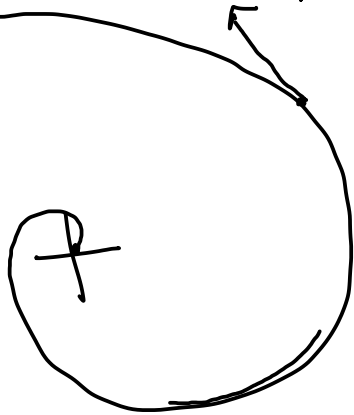
angular

$$\Rightarrow r \ddot{\theta} \hat{e}_\theta - r \dot{\theta}^2 \hat{e}_r \quad \text{centripetal}$$

$$r = \text{constant}$$

$$\dot{\theta} > 0$$

$\vec{r}(t)$ traces out a spiral so that $\dot{r} = \text{constant}$, $\dot{\theta} = \text{constant}$



$$\vec{r} = r \hat{e}_r$$

$$\vec{v} = \dot{r} \hat{e}_r + r \dot{\theta} \hat{e}_\theta$$

$$\vec{a} = (\cancel{\ddot{r}} - r \dot{\theta}^2) \hat{e}_r + (\cancel{r \ddot{\theta}} + 2 \dot{r} \dot{\theta}) \hat{e}_\theta$$

$$= \underbrace{-r \dot{\theta}^2}_{\text{centripetal}} \hat{e}_r + \underbrace{2 \dot{r} \dot{\theta}}_{\text{Coriolis acceleration}} \hat{e}_\theta$$

comes from increase of speed
needed to keep $\dot{r}$ constant

