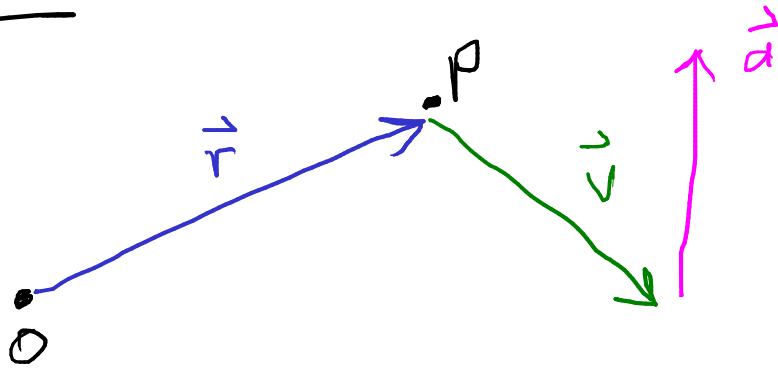


Recap



Any vector:

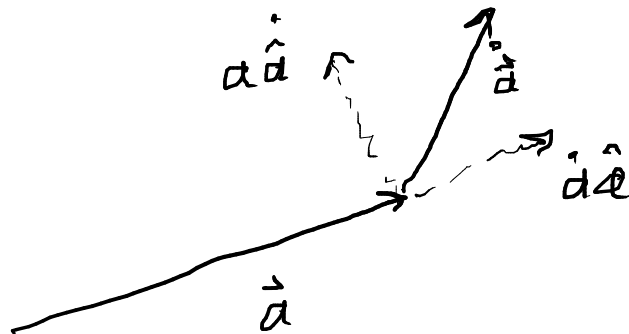
$$\vec{a} = a \hat{a}$$

$$\dot{\vec{a}} = \dot{a} \hat{a} + a \dot{\hat{a}}$$

$$\uparrow$$

 $\dot{\vec{a}} \cdot \hat{a}$

$\uparrow$ orth to $\hat{a}$



Always: $\dot{\hat{a}} \cdot \hat{a} = 0$

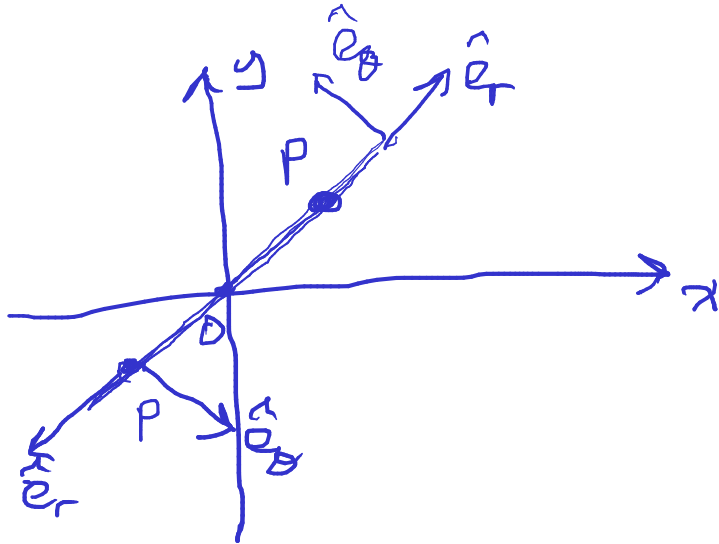
polar : $\dot{\hat{e}}_r = \dot{\theta} \hat{e}_\theta$ $\dot{\theta} = \omega$
 $\dot{\hat{e}}_\theta = -\dot{\theta} \hat{e}_r$

$$\vec{r} = r \hat{e}_r \rightarrow \dot{\vec{r}} = \dot{r} \hat{e}_r + r \dot{\hat{e}}_r$$

$$\dot{\vec{v}} = \dot{r} \hat{e}_r + r \dot{\theta} \hat{e}_\theta$$

Today: acceleration in Cartesian and polar

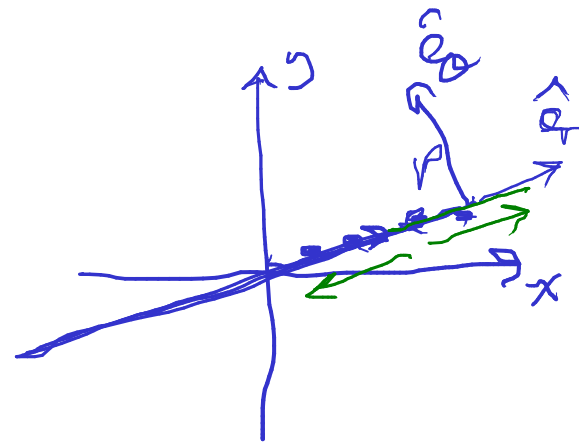
✓ $\vec{r}(t) = (\sin t)(\hat{i} + \hat{j})$



$\vec{r}(t) = (\cos t)(2\hat{i} + \hat{j})$

- $\vec{v}$ has
- A. only $\hat{e}_r$ component
 - B. only $\hat{e}_\theta$ component
 - C. both
 - D. neither

A → D

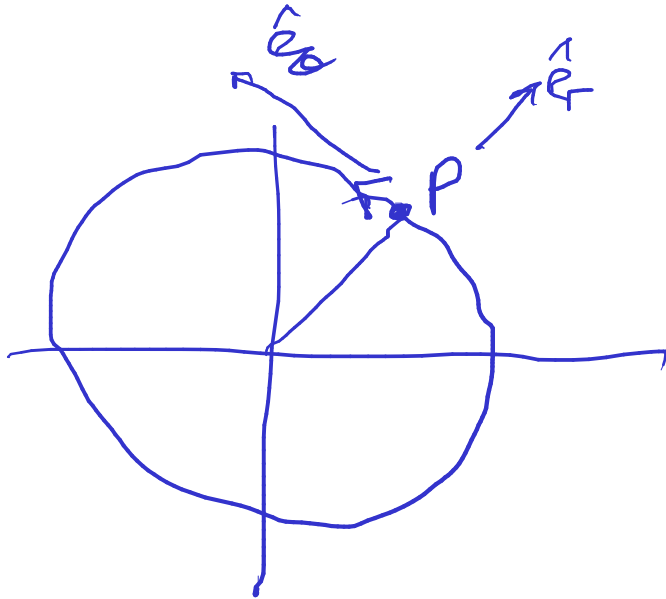


Z/

$$r(t) = \text{const}$$

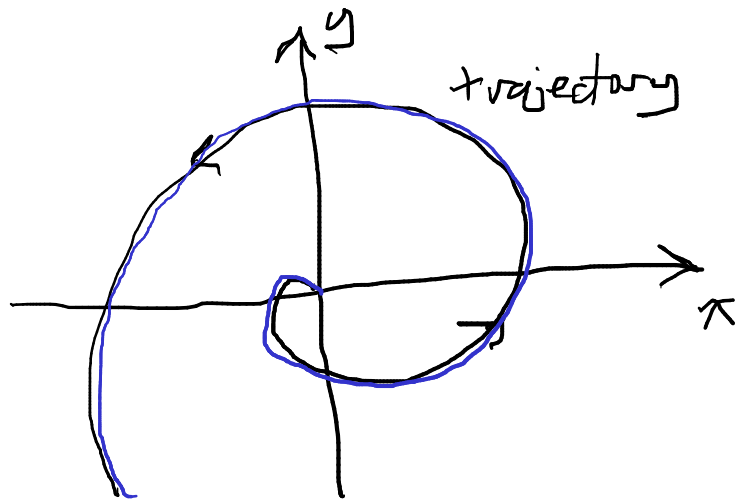
$$\theta(t) = \omega t$$

$\uparrow$
const



- $\vec{v}$ has
- A. only $\hat{e}_r$ component
 - B. only $\hat{e}_\theta$ component
 - C. both
 - D. neither

3/



- $\vec{v}$ has
- A. only $\hat{e}_r$ component
 - B. only $\hat{e}_\theta$ component
 - C. both
 - D. neither

$$\vec{v} = \dot{r} \hat{e}_r + r \dot{\theta} \hat{e}_\theta$$

4/ A particle observed at a particular instant has:

speed $\rightarrow$

$$v = 5 \text{ m/s}$$
$$\dot{\theta} = 1 \text{ rad/s}$$
$$\dot{r} = -3 \text{ m/s}$$

What is r closest to?

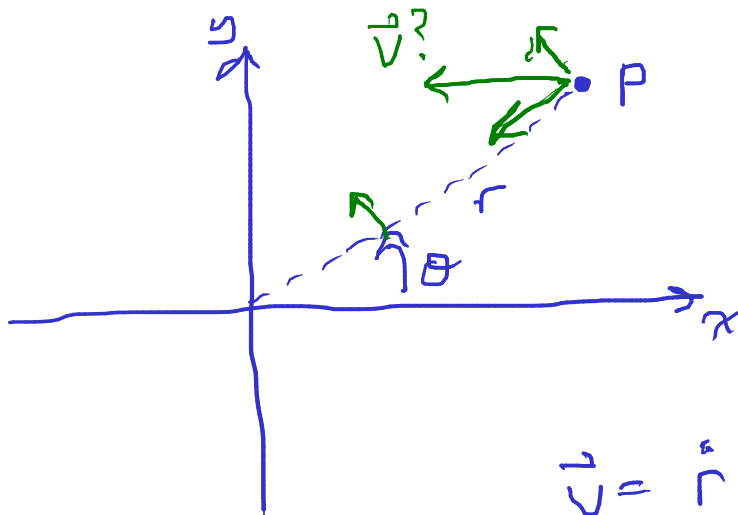
A: 1 m

B: 2 m

C: 3 m

D: 4 m

E: 5 m



$$\vec{v} = \dot{r} \hat{e}_r + r \dot{\theta} \hat{e}_\theta$$

$$v = \sqrt{\dot{r}^2 + (r \dot{\theta})^2}$$

Acceleration

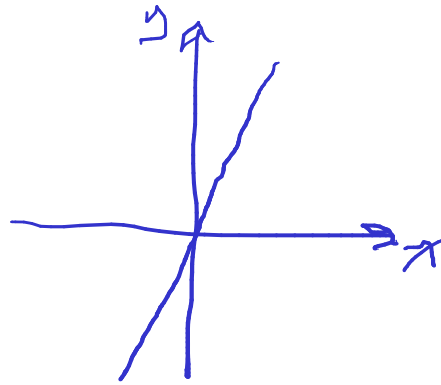
	Cartesian	Polar
position	$\vec{r} = x\hat{i} + y\hat{j}$	$\vec{r} = r\hat{e}_r$
velocity	$\vec{v} = \dot{x}\hat{i} + \dot{y}\hat{j}$	$\vec{v} = \dot{r}\hat{e}_r + r\dot{\theta}\hat{e}_\theta$
acceleration	$\vec{a} = \ddot{x}\hat{i} + \ddot{y}\hat{j}$	$(\ddot{r} - r\dot{\theta}^2)\hat{e}_r + (r\ddot{\theta} + 2\dot{r}\dot{\theta})\hat{e}_\theta$

$$\vec{a} = \frac{d}{dt}(\vec{v}) = \dot{r}\hat{e}_r + \cancel{\dot{r}\hat{e}_r} + \dot{r}\dot{\theta}\hat{e}_\theta + r\ddot{\theta}\hat{e}_\theta + \cancel{r\dot{\theta}\hat{e}_\theta} - \dot{\theta}\hat{e}_r$$

$\downarrow$
 $\dot{\theta}\hat{e}_\theta$
 $\downarrow$
 $-\dot{\theta}\hat{e}_r$

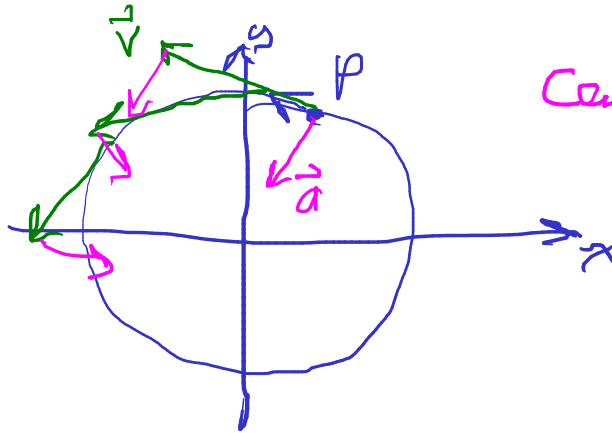
$$= (\ddot{r} - r\dot{\theta}^2)\hat{e}_r + (r\ddot{\theta} + 2\dot{r}\dot{\theta})\hat{e}_\theta$$

$$\vec{a} = \ddot{r} \hat{e}_r$$



$$\vec{a} = -r \dot{\theta}^2 \hat{e}_r$$

$$\begin{aligned} \text{const } r \\ \text{const } \dot{\theta} = \omega \end{aligned}$$



Centripetal acceleration
center seeking

$$\vec{a} = -r \dot{\theta}^2 \hat{e}_r + r \ddot{\theta} \hat{e}_\theta$$

accelerating around
a circle.

$$\vec{a} = -r \dot{\theta}^2 \hat{e}_r + 2 \dot{r} \dot{\theta} \hat{e}_\theta$$

$$\begin{aligned} \dot{r} &= \text{const} \\ \dot{\theta} &= \text{const} \end{aligned}$$

Coriolis
acceleration

