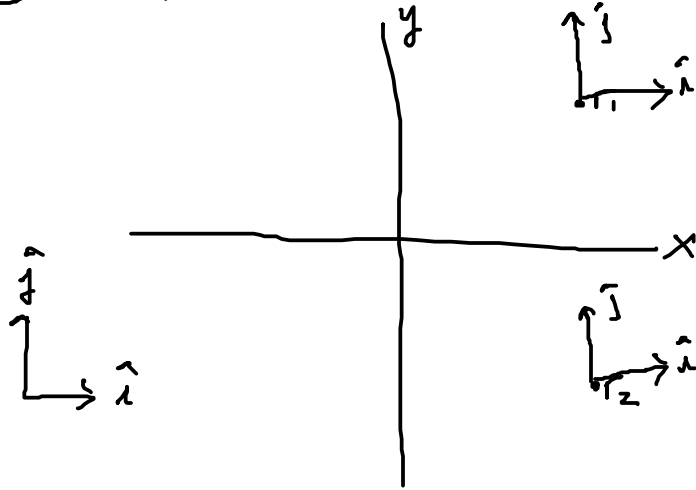


TAM 212 Class # 2: Basis Vectors, Cartesian and Polar Coords.

① CARTESIAN COORDINATE SYSTEM



at r_1 : $x = 3$, $y = 4$

at r_2 : $x = -3$, $y = -4$

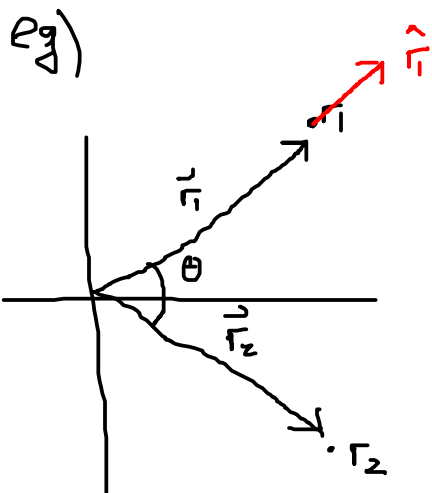
NOTATION:

vectors $\vec{a}$

* unit vector $\hat{a}$

* magnitude of $\vec{a}$: $\|\vec{a}\|$ or a

- CAN WRITE: $\vec{a} = a \hat{a}$



a vector from origin to point r_1 is

$$\vec{r}_1 = 3\hat{i} + 4\hat{j}$$

$$\|\vec{r}_1\| = \sqrt{3^2 + 4^2} = 5$$

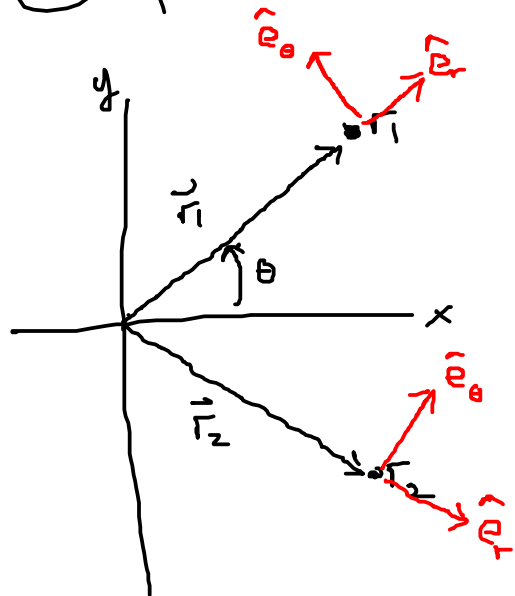
$$\hat{r}_1 = \frac{\vec{r}_1}{\|\vec{r}_1\|} = \frac{1}{5} (3\hat{i} + 4\hat{j})$$

$$\vec{r}_1 = \|\vec{r}_1\| \hat{r}_1 = 5 \cdot \frac{1}{5} (3\hat{i} + 4\hat{j})$$

To find the angle between: use dot product

$$\vec{r}_1 \cdot \vec{r}_2 = \|\vec{r}_1\| \|\vec{r}_2\| \cos \theta$$

② POLAR COORDINATES : (r, θ)



$$r = \sqrt{x^2 + y^2}$$

$$\theta = \tan^{-1}(y/x)$$

$$x = r \cos \theta$$

$$y = r \sin \theta$$

Basis Vectors $\hat{e}_r$ and $\hat{e}_\theta$

example : fill out table

	Cartesian basis	polar basis
$\vec{r}_1$	$\vec{r}_1 = 3\hat{i} + 4\hat{j}$	$\vec{r}_1 = r\hat{e}_r$
$\vec{r}_2$	$\vec{r}_2 = 3\hat{i} - 4\hat{j}$	$\vec{r}_2 = r\hat{e}_r$

* position vector is always $\vec{r} = r\hat{e}_r$

