

TAM 212 – Dynamics

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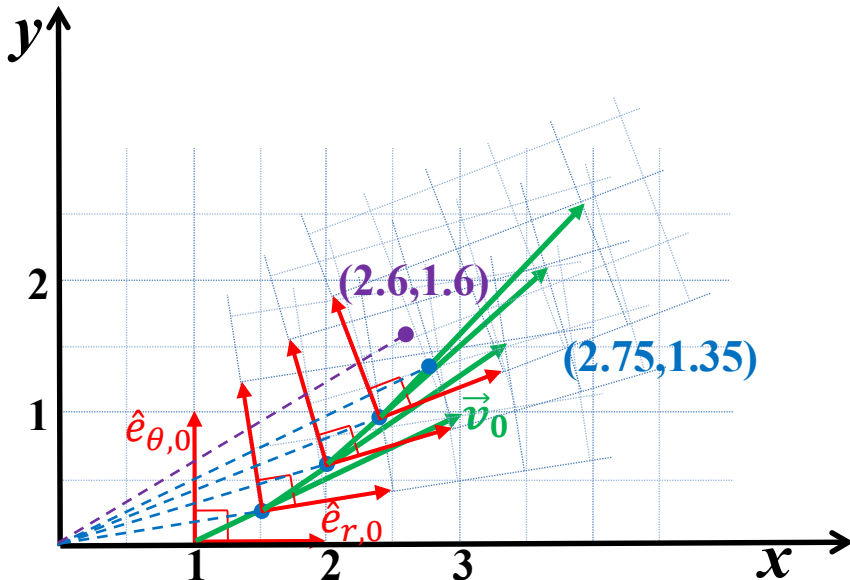
Summer 2019

Recap

- Polar coordination Integrating
- Acceleration terms – centripetal acceleration
- Angular velocity

Today

- Angular velocity and acceleration



Cartesian: $\vec{v} = \dot{x}\hat{i} + \dot{y}\hat{j}$

integrate to find $x(t)$ and $y(t)$

Polar: $\vec{v} = \dot{r}\hat{e}_r + r\dot{\theta}\hat{e}_\theta$

reduce to $\dot{r}(t)$ and $\dot{\theta}(t)$ before integrating

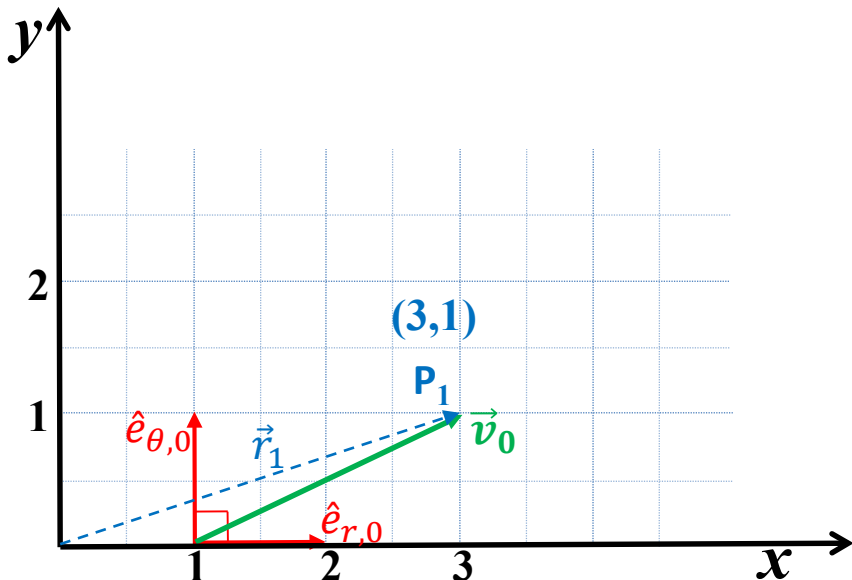
Base idea: turn vector integrals into scalar
integrals in coordinates

Example – Polar coordination integrating

A particle P starts at time $t = 0$ s, it is at $\vec{r} = \hat{i}$ m and always has a velocity $\vec{v} = 2\hat{e}_r + \hat{e}_\theta$ m/s.

Where is P at $t = 1$ s?

- $\vec{r}(1) =$
- A. $3\hat{i}$ m
 - B. $-3\hat{i}$ m
 - C. $3\hat{i} + \hat{j}$ m
 - D. $3\hat{i} - \hat{j}$ m
 - E. none of the above



$(1,0) + (2,1) = (3,1)$ incorrect!

$$v = \dot{x} = \frac{x(t + dt) - x(t)}{dt}$$

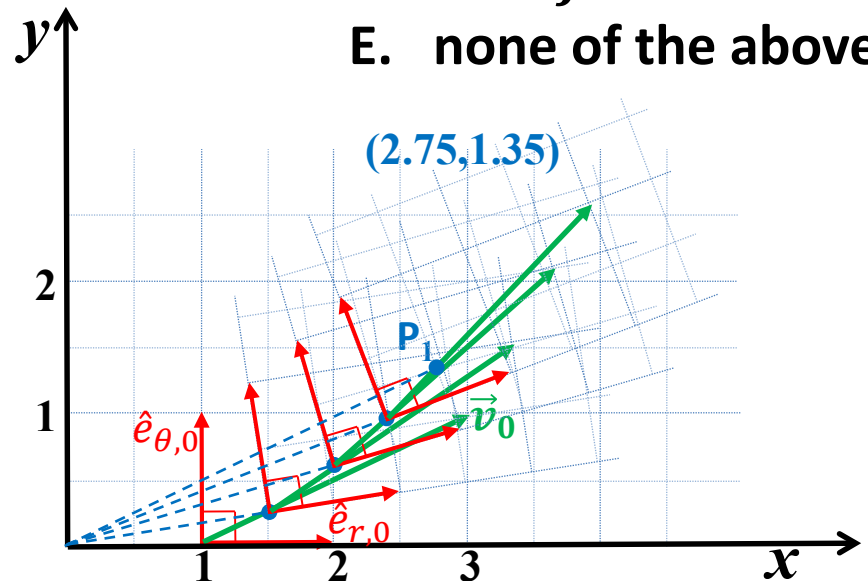
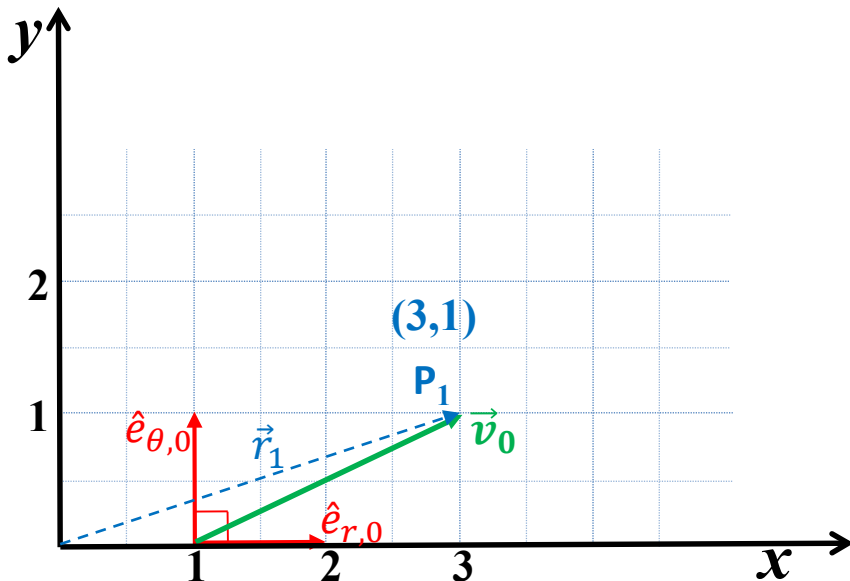
$$x(t + \Delta t) \approx x(t) + v\Delta t$$

Example – Polar coordination integrating

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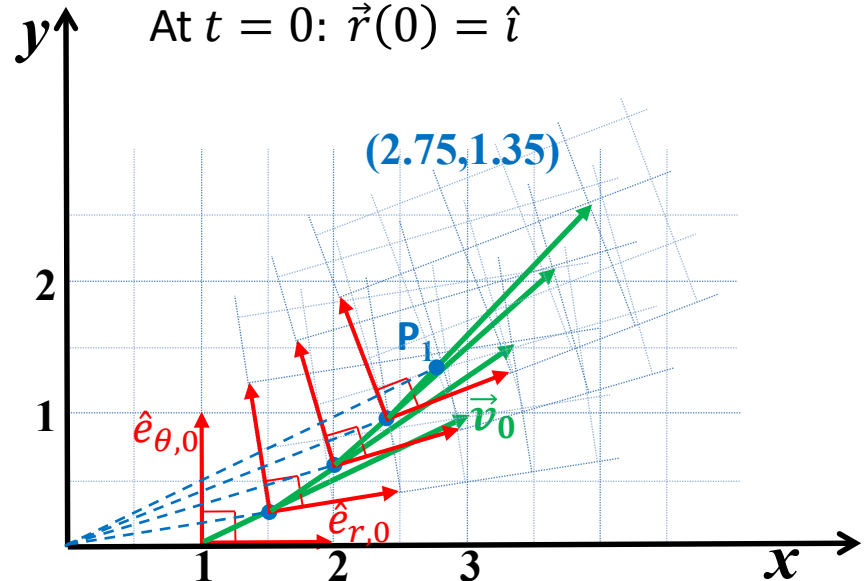
Where is P at $t = 1$ s?

Actual computation:

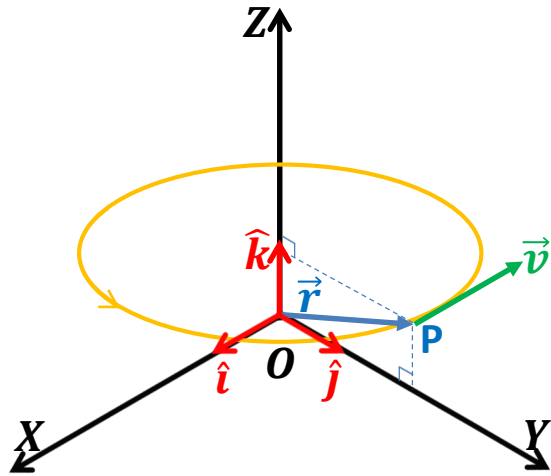
$$\vec{v} = 2\hat{e}_r + \hat{e}_\theta$$

$$\vec{v} = \dot{r}\hat{e}_r + r\dot{\theta}\hat{e}_\theta$$

$$\text{At } t = 0: \vec{r}(0) = \hat{i}$$



Angular velocity for particles (rotating about axis through origin)



ω = speed of rotation

$\hat{\omega}$ = axis of rotation

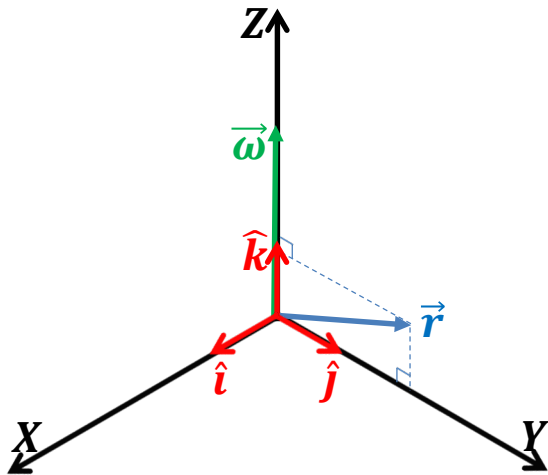
$\vec{\omega} = \omega \hat{\omega}$ = angular velocity

Ex. $\vec{\omega} = \omega \hat{k}$. What is $\vec{v}$ of P?

Example

$$\vec{r} = 4\hat{j} + 3\hat{k} \text{ m}$$

$$\vec{\omega} = 3\hat{k} \text{ rad/s}$$

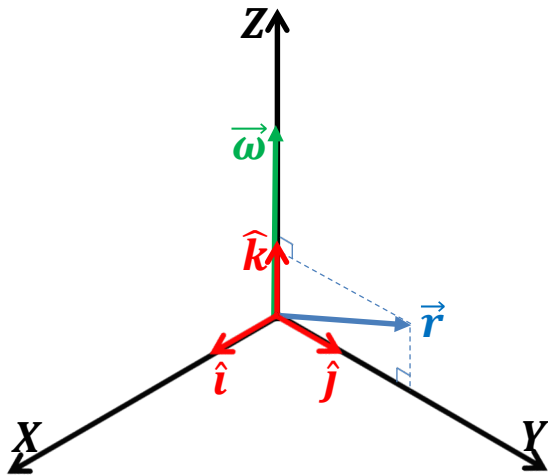


Example

$$\vec{r} = 4\hat{j} + 3\hat{k} \text{ m}$$

$$\vec{\omega} = 3\hat{k} \text{ rad/s}$$

What is $\vec{v}$?

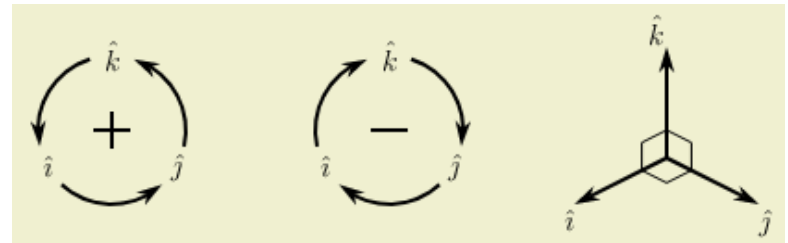


Angular acceleration

$\vec{\alpha} = \dot{\vec{\omega}}$ = angular acceleration – time derivative of angular velocity

$$\vec{v} = \vec{\omega} \times \vec{r} = \dot{\vec{r}}$$

$$\vec{a} = \dot{\vec{v}}$$



Angular acceleration

$\vec{\alpha} = \dot{\vec{\omega}}$ = angular acceleration – time derivative of angular velocity

$$\vec{v} = \vec{\omega} \times \vec{r} = \dot{\vec{r}}$$

$$\begin{aligned} \vec{a} = \dot{\vec{v}} &= \frac{d}{dt} \vec{v} = \frac{d}{dt} (\vec{\omega} \times \vec{r}) \\ &= \dot{\vec{\omega}} \times \vec{r} + \vec{\omega} \times \dot{\vec{r}} \end{aligned}$$

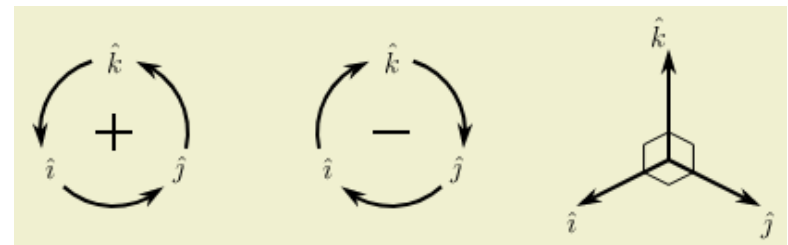
Important !

$$\vec{a} = \vec{\alpha} \times \vec{r} + \vec{\omega} \times (\vec{\omega} \times \vec{r}) \leftarrow \text{Order matters in cross product}$$

Exmaple $\vec{\alpha} = 0, \vec{\omega} = \vec{k}, \vec{r} = \vec{i}$

$$\vec{a} = 0 + \vec{k} \times \vec{k} \times \vec{i} = 0 + 0$$

$$\begin{aligned} \vec{a} &= 0 + \vec{k} \times (\vec{k} \times \vec{i}) \\ &= \vec{k} \times (\vec{j}) \\ &= -\vec{i} \end{aligned}$$



Example

For 2D x-y plane: $\vec{v} = \vec{\omega} \times \vec{r} = \omega_z \vec{r}^\perp$

$$\vec{a} = \vec{\alpha} \times \vec{r} + \vec{\omega} \times (\vec{\omega} \times \vec{r}) = \alpha_z \vec{r}^\perp - \omega_z^2 \vec{r}$$

A particle at position $\vec{r}$ is rotating about the z-axis with $\dot{\theta} = 3$ rad/s and $\ddot{\theta} = 2$ rad/s². What are $\vec{\omega}$ and $\vec{\alpha}$?

Example - Solving vector equations

A particle in the x-y plane is rotating about the origin with an angular velocity $\vec{\omega} = -2\hat{k}$ rad/s. The particle has a velocity $\vec{v} = 12\hat{i} - 2\hat{j}$ m/s. What is the position vector $\vec{r}$ of the particle?

- $r_x =$
- A. -2 m
 - B. -1 m
 - C. 0 m
 - D. 1 m
 - E. 2 m

