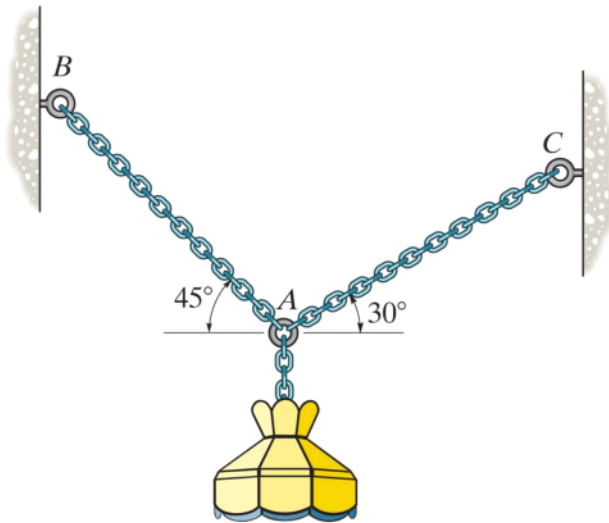


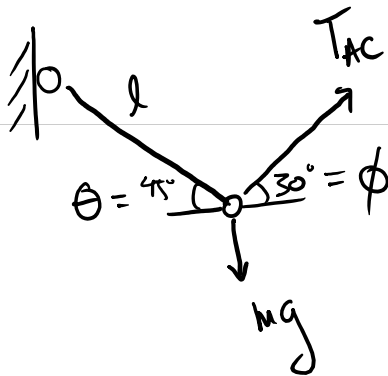
To do ...

- Quiz 7 – good luck!
 - Last day of office hours and piazza help: **Wed, Dec 13**
 - No discussion sections next week
 - TAM 211 final starts Thurs, Dec 14
-
- HW 27 ME due **Sat (Dec 9) – Last one!!**
 - HW 26 PL due **Tues (Dec 12) – Last one!!**

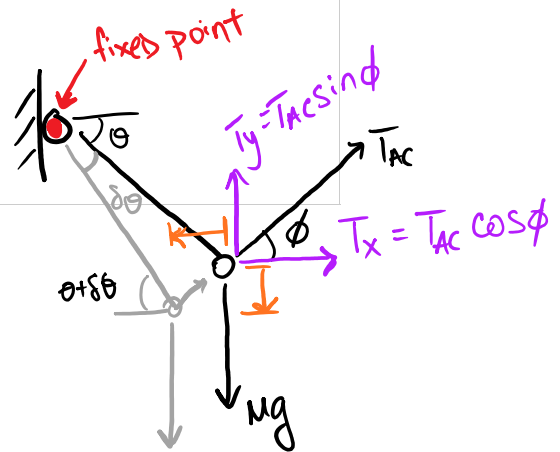


Determine the tension in the cable AC. The lamp weighs 10 lb.

FBD



VDD



Coordinates from fixed point:

$$x = l \cos \theta \quad y = l \sin \theta$$

$$\delta x = -l \sin \theta \delta \theta \quad \delta y = l \cos \theta \delta \theta$$

Virtual work eqn.

$$\delta U = W \delta y - T_y \delta y + T_x \delta x = 0$$

$$W l \cos \theta \delta \theta - T_{Ac} \sin \phi l \cos \theta \delta \theta - T_{Ac} \cos \phi l \sin \theta \delta \theta = 0$$

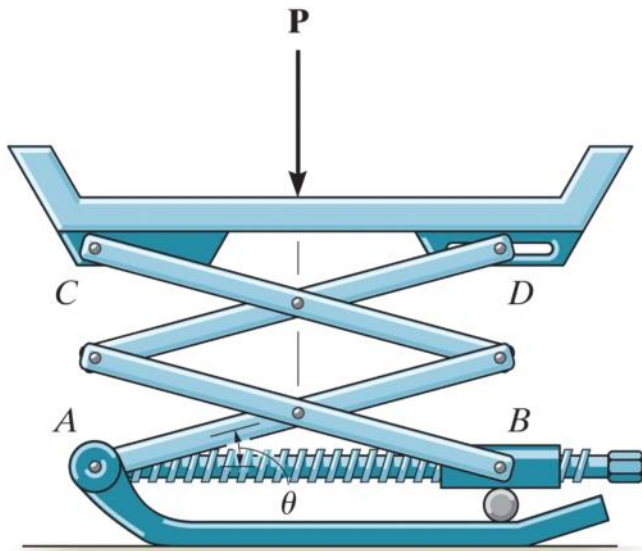
$$(W \cos \theta - T_{Ac} \sin \phi \cos \theta - T_{Ac} \cos \phi \sin \theta) l \delta \theta = 0$$

Solve this = 0

$$T_{Ac} (\sin \phi \cos \theta + \cos \phi \sin \theta) = W \cos \theta$$

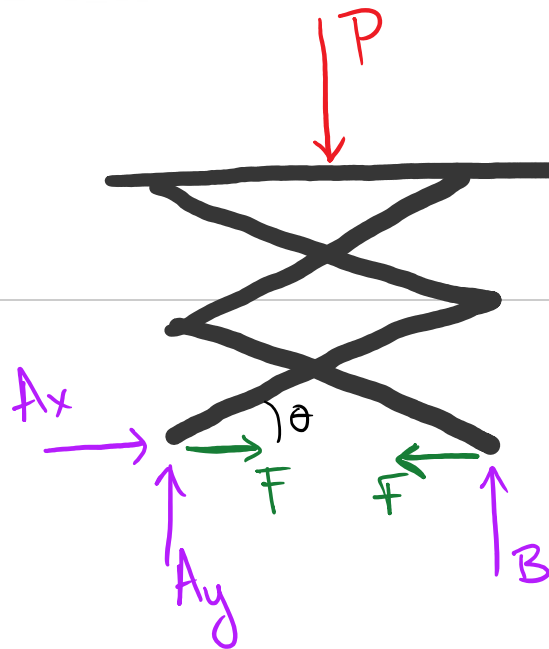
$$T_{Ac} = \frac{W \cos \theta}{\sin \phi \cos \theta + \cos \phi \sin \theta}$$

for $\theta = 45^\circ$ and $\phi = 30^\circ$



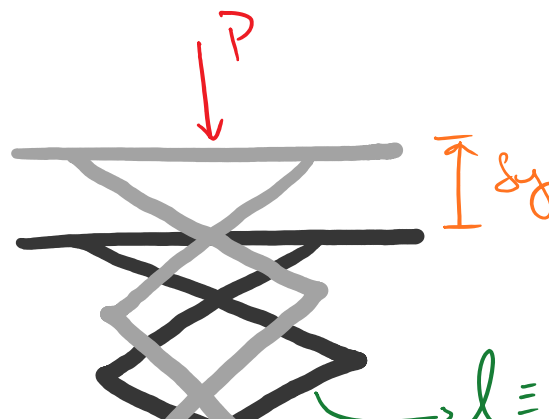
The scissors jack supports a load P . Determine the axial force in the screw necessary for equilibrium when the jack is in the position θ .

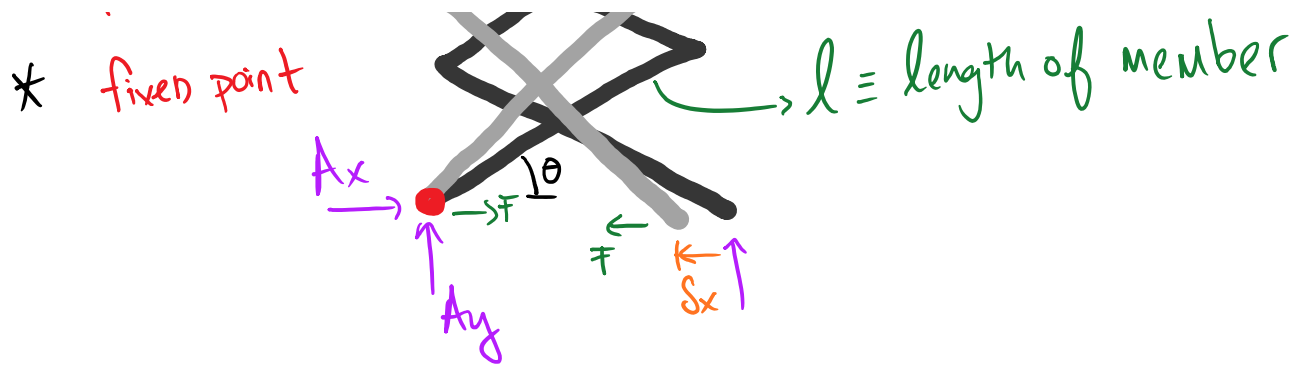
FBD



VDD

- * 2 Active forces
- * fixed point





Coordinates from fixed point:

$$x = l \cos \theta$$

$$y = 2l \sin \theta$$

$$\delta x = -l \sin \theta \delta \theta$$

$$\delta y = 2l \cos \theta \delta \theta$$

Virtual work eqn:

$$\delta U = -F \delta x - P \delta y = 0$$

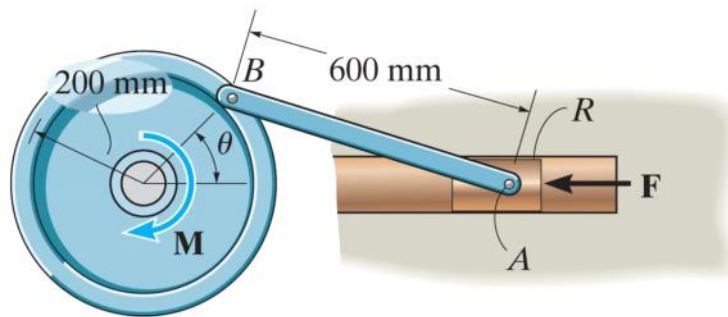
$$-F(-l \sin \theta \delta \theta) - P(2l \cos \theta \delta \theta) = 0$$

$$(F \sin \theta - 2P \cos \theta) l \delta \theta = 0$$

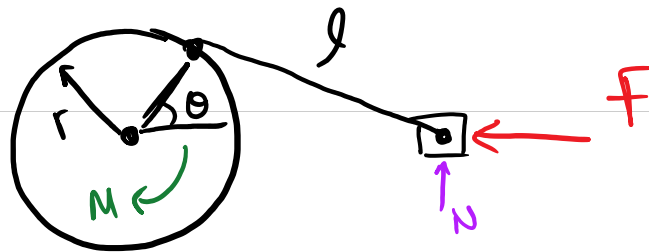
solve for $= 0$

$$F = 2P \frac{\cos\theta}{\sin\theta} = 2P \frac{1}{\tan\theta}$$

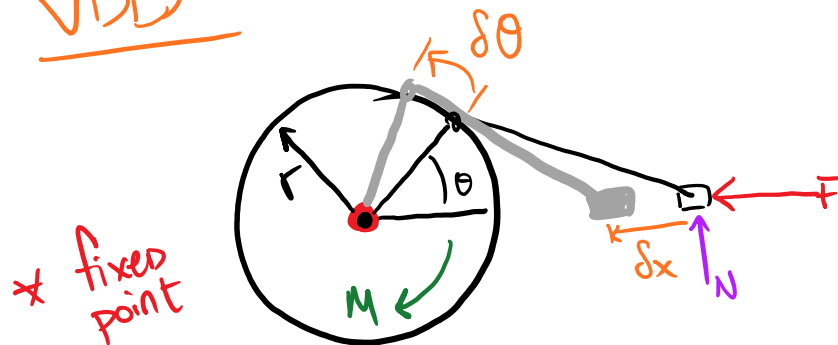
The flywheel is subjected to a torque M of 75 Nm. Determine the horizontal compressive force F and plot the result versus the equilibrium position θ .



FBD

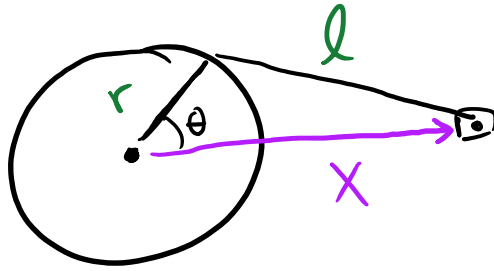


VDD



* 1 active force, 1 active moment.

Coordinates from fixed point:



* use law of cosines!

$$l^2 = r^2 + x^2 - 2rx \cos \theta$$

* use quadratic formula to solve $x(\theta)$

$$\underbrace{1}_a x^2 + x \underbrace{(-2r \cos \theta)}_b + \underbrace{(r^2 - l^2)}_c = 0$$

$$x = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

$$x(\theta) = r \cos \theta \pm \sqrt{r^2 \cos^2 \theta - (r^2 - l^2)}$$

And differentiate:

$$x^2 - 2rx \cos \theta = l^2 - r^2$$

$$2x \delta x - 2r(\cos \theta \delta x - x \sin \theta \delta \theta)$$

$$\delta x = \frac{2rx \sin \theta}{2r \cos \theta - 2x} \delta \theta$$

Virtual work eqn.

$$\delta U = -F \delta x - M \delta \theta = 0$$

$$-F \left(\frac{2rx \sin \theta}{2r \cos \theta - 2x} \right) \delta \theta - M \delta \theta = 0$$

$$F = -M \left(\frac{r \cos \theta - x(\theta)}{rx(\theta) \sin \theta} \right)$$