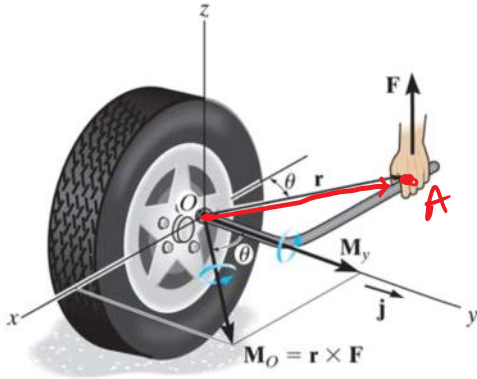


To do ...

- Quiz 2 this week (**Tues-Fri**)
- HW 6 due **Tues**
- HW 7 due **Thurs**
- WA 1 (FBD only) due **Fri**

Ein
Prosit!

Moment of a force about a specified axis



$$\vec{F} = [0, 0, F]$$

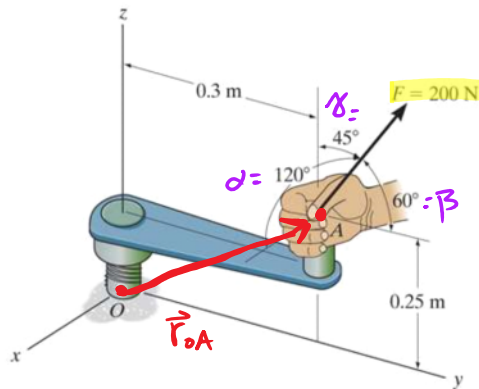
$$\vec{r}_{OA} = [-x, y, 0]$$

$$\vec{M}_O = \vec{r}_{OA} \times \vec{F} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ -x & y & 0 \\ 0 & 0 & F \end{vmatrix} = [yF, xF, 0]$$

$$M_y = \vec{u}_y \cdot \vec{M}_O = \vec{u}_y \cdot (\vec{r}_{OA} \times \vec{F}) = [0, 1, 0] \cdot [yF, xF, 0] = xF$$

triple SCALAR product.

scalar magnitude.



A force is applied to the tool as shown. Find the magnitude of the moment of this force about the x axis of the value.

given: $|\vec{F}|$, α, β, γ , $\vec{u}_x$

$$\vec{r}_{OA} = \vec{r}_A - \vec{r}_O = [0, 0.3, 0.25] \text{ m}$$

$$\vec{F} = 200 [\cos(120), \cos(60), \cos(45)] = [-100, 100, 141.4] \text{ N}$$

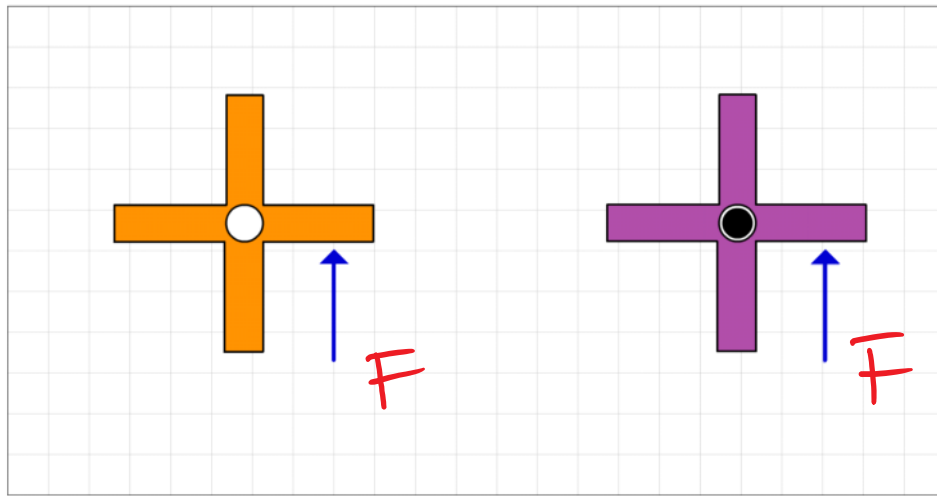
$$M_x = \vec{u}_x \cdot (\vec{r}_{OA} \times \vec{F}) = \begin{vmatrix} 1 & 0 & 0 \\ 0 & 0.3 & 0.25 \\ -100 & 100 & 141.4 \end{vmatrix} = 1(0.3(141.4) - 0.25(100)) \text{ N}\cdot\text{m}$$

$$\underline{M_x = 17.4 \text{ N}\cdot\text{m}} \quad (\text{CCW})$$

BECAUSE positive.

Moment of a couple

Q: What happens?



* translation AND
Rotation

$$\Sigma F \neq 0$$

$$\Sigma M \neq 0$$

* Rotation only

$$\Sigma F = 0$$

$$\Sigma M \neq 0$$

Moment of a couple

A **couple** is defined as two parallel forces that have the same magnitude, but opposite directions, and are separated by a perpendicular distance d.

Since the resultant force is zero, the only effect of a couple is to produce an actual rotation, or if no movement is possible, there is a tendency of rotation in a specified direction.

The moment produced by a couple is called couple moment.

Requirements:

- * At least two forces
- * Lines of action are parallel
- * Same magnitude: $|\vec{F}_1| = |\vec{F}_2|$
- * Opposite direction: $\vec{F}_1 = -\vec{F}_2$
- * Forces separated by perpendicular distance d

SINCE $\vec{F}_1 = -\vec{F}_2$

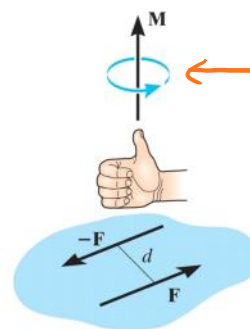
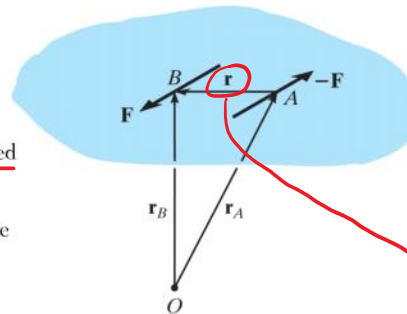
the $\sum \vec{F} = \vec{F}_1 - \vec{F}_2 = 0 \Rightarrow$

PRODUCES NO NET FORCE,
NO TRANSLATION!

BUT DUE TO THE SEPARATION THERE IS PURE ROTATION!

Moment of a couple is a free vector!

↳ only direction and



← representation on a diagram.

$$N = \sum (\vec{r} \times \vec{F})$$

$$M_o = \vec{r}_B \times \vec{F} + \vec{r}_A \times -\vec{F}$$

$$M_o = (\vec{r}_B - \vec{r}_A) \times \vec{F}$$

$$M_o = \vec{r} \times \vec{F}$$

* Independent of point of rotation!!

↳ only direction and magnitude ARE important, not confined to unique line of action!

MAGNITUDE of a couple moment:

$$M = dF \quad (\text{Scalar})$$

$$M = \vec{r} \times \vec{F} \quad (\text{Vector Analysis})$$

↑ ANY position vector from line of action of $\vec{F}_1$ to the line of action of $\vec{F}_2$!

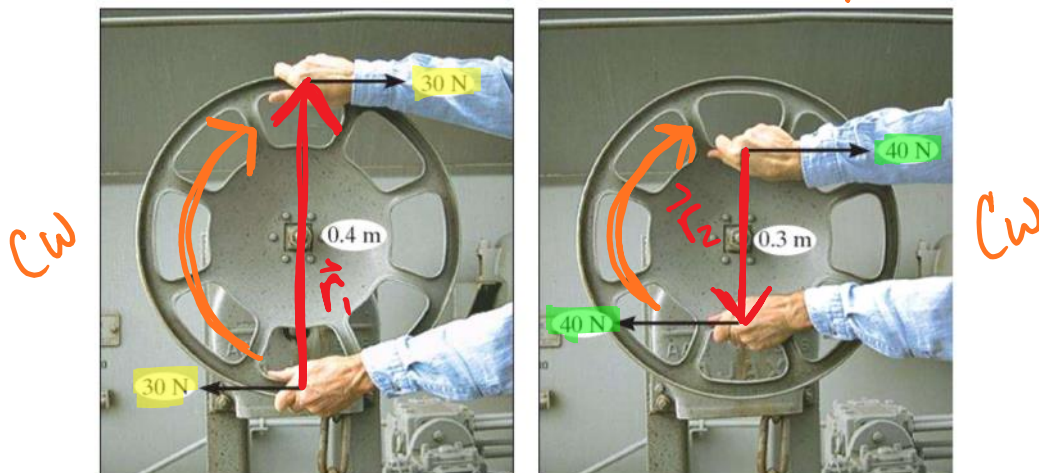
Direction:

use right hand rule convention,

CCW $\rightarrow$ positive

CW $\rightarrow$ negative

Consider the equivalent couples



A torque or moment of $12 \text{ N}\cdot\text{m}$ is required to rotate the wheel. Why does one of the two grips of the wheel above require less force to rotate the wheel?

$$F_1 = 30 \text{ N}$$

$$d_1 = 0.4 \text{ m}$$

$$\vec{M}_1 = (.4)(30) = \underline{-12 \text{ N}\cdot\text{m}}$$

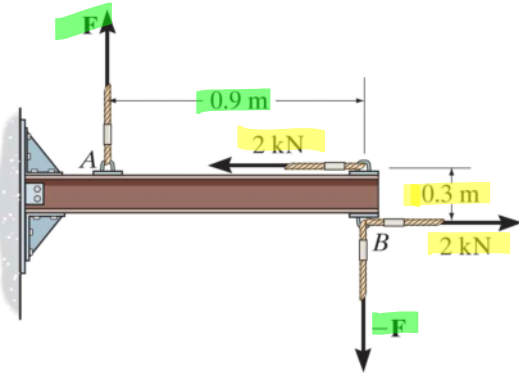
$$F_2 = 40 \text{ N}$$

$$d_2 = 0.3 \text{ m}$$

$$\vec{M}_2 = (.3)(40) = \underline{-12 \text{ N}\cdot\text{m}}$$

Both CW

*note that $F_2 > F_1$ because $d_1 > d_2$



Two couples act on the beam with the geometry shown. Find the magnitude of F so that the resultant couple moment is 1.5 kN·m clockwise.

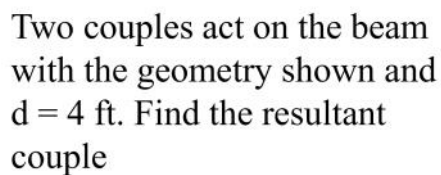
- identify couples, $F \cdot d$

$$\begin{array}{c}
 \begin{array}{c}
 2 \text{ kN} \\
 \leftarrow \\
 \text{0.3 m} \\
 \rightarrow \\
 2 \text{ kN} \\
 \text{CCW (+)}
 \end{array}
 +
 \begin{array}{c}
 F \uparrow \\
 \text{0.9 m} \\
 \downarrow \\
 \text{CW (-)}
 \end{array}
 = -1.5 \text{ kN}\cdot\text{m} \quad \curvearrowright
 \end{array}$$

$$\sum M_F = (0.3 \text{ m})(2 \text{ kN}) - (0.9)F = -1.5 \text{ kN}\cdot\text{m}$$

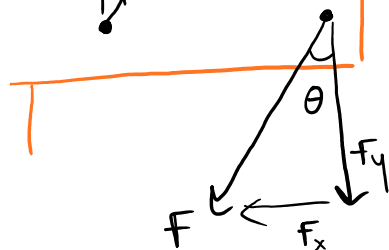
$$0.6 \text{ kN}\cdot\text{m} + 1.5 \text{ kN}\cdot\text{m} = 0.9 F \text{ m}$$

$$\underline{F = 2.33 \text{ kN}}$$



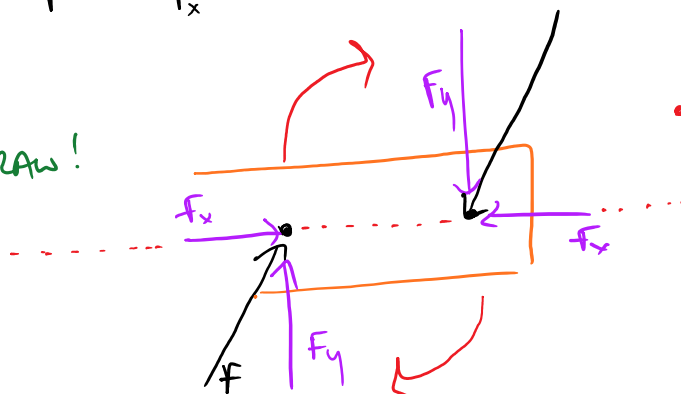
- identify couples.
- find perpendicular distance OR resolve forces into x & y components.

first consider forces on the top beam.



Q: Which components would lead to rotation of the body?

REDRAW!

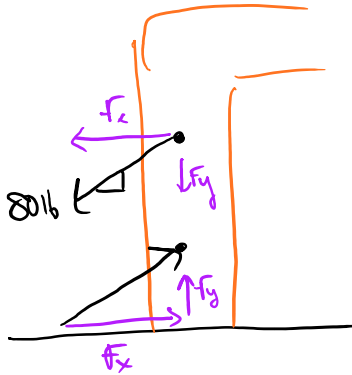


- F_x would not CAUSE rotation,
- F_y components would rotate in CW direction!

$$\vec{M}_1 = -d F_y = -(3)(50 \cos(30)) \text{ ft}\cdot\text{lb}$$

now the second beam.

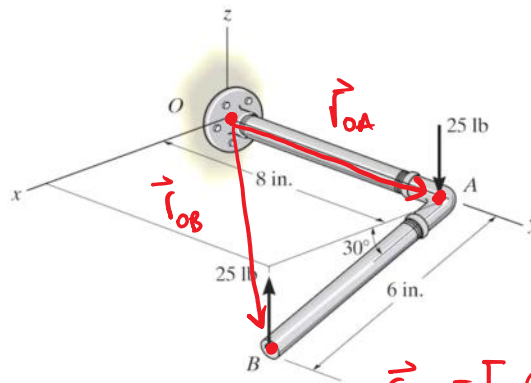
- F_y does not rotate body, only F_x would in CCW direction.



$$\vec{M}_2 = d F_x = (4 \text{ ft}) \left(\frac{4}{5} 80 \right) \text{ ft}\cdot\text{lb}$$

$$\vec{M} = \vec{M}_1 + \vec{M}_2 = \dots = \boxed{126 \text{ ft}\cdot\text{lb} \text{ CCW}}$$

Determine the couple moment acting on the pipe



$$\vec{r}_{OA} = [0, 8, 0] \text{ in}$$

$$\vec{F}_B = [0, 0, -25] \text{ lb}$$

Approach 1:

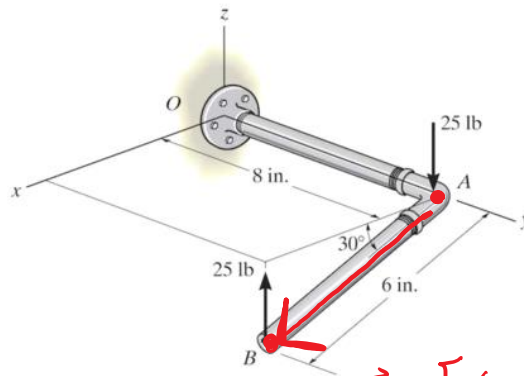
$$\vec{M} = \vec{r}_{OA} \times \vec{F}_A + \vec{r}_{OB} \times \vec{F}_B$$

$$\vec{F}_A = [0, 0, 25] \text{ lb}$$

$$\vec{M} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 0 & 8 & 0 \\ 0 & 0 & -25 \end{vmatrix} + \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 6\cos(30) & 8 & -6\sin(30) \\ 0 & 0 & 25 \end{vmatrix} = \dots =$$

$$\vec{M} = [0, -25(6\cos(30)), 0] \text{ lb}\cdot\text{in}$$

Determine the couple moment acting on the pipe



$$\vec{r}_A = [0, 8, 0] \text{ in}$$

$$\vec{r}_B = [6\cos(30), 8, -6\sin(30)]$$

$$\vec{r}_{AB} = \vec{r}_{OB} - \vec{r}_{OA} = [6\cos(30), 0, -6\sin(30)] \text{ in}$$

Approach 2 :

use couple moment since

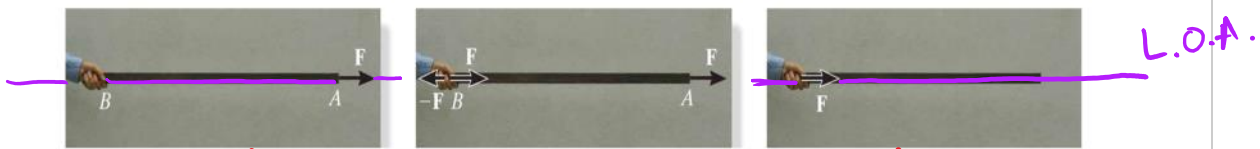
$$|\vec{F}_1| = |\vec{F}_2| \quad \vec{F}_1 = -\vec{F}_2$$

$$\vec{M} = \vec{r}_{AB} \times \vec{F}_B = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 6\cos(30) & 0 & -6\sin(30) \\ 0 & 0 & 25 \end{vmatrix} = \dots =$$

$$\vec{M} = [0, -25(6\cos(30)), 0] \text{ lb} \cdot \text{in}$$

* SAME AS previous!

Moving a force on its line of action (L.O.A.)



↑ Equivalent to ↑

Moving a force from A to B, when both points are on the vector's line of action, does not change the **external effect**.

→ translation/rotation of body.

→ depends on where and how force is applied to body

* F is a Sliding Vector

↳ line of Action is defined,
produces the same external
effect on a body.