

Lecture 7

Reminder: HW 1 due Thursday 2/13
on gradescope

Recap: Space group $G < E(3)$ rigid symmetries
of a crystal

$$V(\vec{x}) = V(g^{-1}\vec{x}) \text{ for all } g \in G$$

Every space group contains a Bravais lattice $T \trianglelefteq G$

$$T = \{ \{E | \sum_i n_i \vec{e}_i\}, n_i \in \mathbb{Z} \} \quad \vec{e}_1, \vec{e}_2, \vec{e}_3 - \text{primitive lattice vectors}$$

Irreps of T : 1D irreps $\rho_{\vec{k}}(\{e|\vec{t}\}) = e^{-i\vec{k} \cdot \vec{t}}$

$\vec{b}_i$ - primitive reciprocal lattice vectors $\vec{b}_i \cdot \vec{e}_j = 2\pi \delta_{ij}$

$\vec{k} = \sum_i \alpha_i \vec{b}_i$ $\alpha_i \in (-\frac{1}{2}, \frac{1}{2}]$ - 1st Brillouin zone

Schur's Lemma $\rightarrow$ Bloch's theorem

$$[H, e^{-i\vec{p} \cdot \frac{\vec{t}}{\hbar}}] = 0 \quad \Rightarrow$$

$$H|\psi_{nk}\rangle = E_{nk}|\psi_{nk}\rangle$$

$$e^{-i\vec{p} \cdot \frac{\vec{t}}{\hbar}}|\psi_{nk}\rangle = e^{-i\vec{k} \cdot \vec{t}}|\psi_{n\vec{k}_v}\rangle$$

n - "band index"

$\hbar\vec{k}$ - "crystal momentum"

What other transformations $g = \{R | \vec{d}\} \in \hat{E}(3)$ can appear in a space group

Recall: $T \trianglelefteq G$, every (pure) translation $\{E | \vec{t}\} \in G$ should be in the Bravais lattice

Suppose $g = \{R | \vec{d}\} \in G$ $G \ni g^{-1} = \{R^{-1} | -R^{-1}\vec{d}\}$

$\{E | \vec{t}\} \in T$ a Bravais lattice translation

$$T \trianglelefteq G \Rightarrow g \{E | \vec{t}\} g^{-1} \in T$$

$$\begin{aligned}
 (\{R|\vec{\partial}\}\{E|\vec{t}\})\{R^{-1}|-\vec{R}^{-1}\vec{\partial}\} &= \{R|\vec{\partial}+R\vec{t}\}\{R^{-1}|-\vec{R}^{-1}\vec{\partial}\} \\
 &= \{E|\vec{\partial}+R\vec{t}-\vec{\partial}\} \\
 &= \{E|R\vec{t}\} \in T
 \end{aligned}$$

If $g = \{R|\vec{\partial}\} \in G$ then $R\vec{t} \in T$ for every $\vec{t} \in T$

Consider the following homomorphism

$$\varphi(\{R|\vec{\partial}\}) = R \in O(3) \quad \varphi: G \rightarrow O(3)$$

$$\ker \varphi = \{\{E|\vec{t}\} \in G\} \in T$$

$$O(3) \supset \text{Im } \varphi = \{ R \mid \{ R \mid \vec{0} \} \in G \} \cong G/T \stackrel{\text{1st isomorphism theorem}}{=} \overline{G} \leftarrow \text{point group of } G$$

$\overline{G} \subset O(3)$ all the rotations and reflection parts of space group elements

$$R \in \overline{G} \Rightarrow R \vec{t} \in T \quad \text{for all } \vec{t} \in T$$

Important result: Crystallographic Restriction Theorem

let T be a Bravais lattice, $R \in SO(3)$ a rotation
if $R \vec{t} \in T$ for all $\vec{t} \in T$ then:

R is a rotation by either 0° 180° $\pm 120^\circ$ $\pm 90^\circ$ $\pm 60^\circ$
 0 π $\pm \frac{2\pi}{3}$ $\pm \frac{\pi}{2}$ $\pm \frac{\pi}{3}$
 (1-fold) (twofold) (threefold) (fourfold) (sixfold)

pf: Pick a basis $\underbrace{\vec{e}_1, \vec{e}_2, \vec{e}_3}_{\in T}$ of primitive lattice vectors

$$R\vec{e}_i = \sum_j \vec{e}_j n_{ji} \in T \quad n_{ji} \in \mathbb{Z}$$

$\vec{b}_1, \vec{b}_2, \vec{b}_3$
 be primitive
 reciprocal lattice
 vectors

$$R_{ji} = \frac{1}{2\pi} \vec{b}_j \cdot (R\vec{e}_i) = n_{ji}$$

R_{ji} is a 3×3 matrix of integers

matrix elements of R in the basis of primitive lattice vectors

$$(\hat{x}, \hat{y}, \hat{z}) \xrightarrow{V} (\vec{e}_1, \vec{e}_2, \vec{e}_3)$$

$$(\vec{x}, \vec{y}, \vec{z}) \xrightarrow{V^{-1}} (\vec{b}_1, \vec{b}_2, \vec{b}_3) \stackrel{1}{2\pi}$$

$$R_{ij} = V R V^{-1}$$

$$\textcircled{1} \text{tr } R = \sum_i R_{ii} = \sum_j \lambda_{jj} \in \mathbb{Z}$$

$\textcircled{2}$ in a basis aligned with the axis of rotation

$$[R] = \begin{pmatrix} \cos\theta & -\sin\theta & 0 \\ \sin\theta & \cos\theta & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

θ is the angle of rotation of R

$$tr R = 1 + 2 \cos \theta$$

$\Rightarrow 1 + 2 \cos \theta \in \mathbb{Z}$ must be an integer

$$\Rightarrow 2 \cos \theta \in \mathbb{Z}$$

$$\cos \theta = 0, \pm \frac{1}{2}, \pm 1$$

$$\theta = \pm \frac{\pi}{2}, \pm \frac{\pi}{3} \text{ or } \pm \frac{2\pi}{3}, 0, \pi$$

crystallographic
point groups

There are only 32 subgroups of $O(3)$ consistent with this theorem [10 are also pt groups of

2D lattices]

Group	Hermann-Mauguin notation	Schönflies notation
trivial group $\{E\}$	1	C_1
$\langle C_{2z} \rangle$	2	C_2
$\langle C_{3z} \rangle$	3	C_3
$\langle C_{4z} \rangle$	4	C_4
$\langle C_{6z} \rangle$	6	C_6

$C_n \hat{r}$ - rotation by angle $\frac{2\pi}{n}$ about axis $\hat{r}$

$$(C_n)^n = E$$

$\langle \dots \rangle$ - group generated by $\dots$

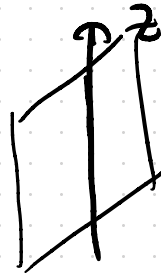
we can also look @ point groups w/
reflection symmetries (mirror symmetries)

$M_{\hat{n}}$ - reflection about a plane normal to $\hat{n}$



Ex: $M_x: (x, y, z) \rightarrow (-x, y, z)$
 $M_y: (x, y, z) \rightarrow (x, -y, z)$
 $M_z: (x, y, z) \rightarrow (x, y, -z)$

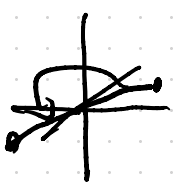
$\langle M_x \rangle$	M	Cs
$\langle C_{2z}, M_x \rangle$	2mm	C_{2v} ← 'vertical'
$\langle C_{3z}, M_x \rangle$	3m	C_{3v}
$\langle C_{4z}, M_x \rangle$	4mm	C_{4v}
$\langle C_{6z}, M_x \rangle$	6mm	C_{6v}



of m 's = # of conjugacy classes of mirror reflections

Ex: 2mm and 3m

$$Z_{mm}: \langle C_{2z}, M_x \rangle = \{E, C_{2z}, M_x, C_{2z} M_x = M_y\}$$



$$C_{2z}: (x, y) \rightarrow (-x, -y)$$

$$M_x: (x, y) \rightarrow (-x, y)$$

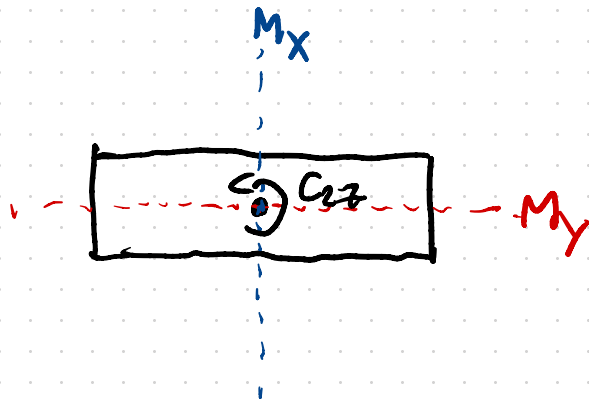
$$C_{2z} M_x: (x, y) \rightarrow (x, -y)$$

$$M_x M_y = C_{2z}$$

$$C_{2z} M_x C_{2z}^{-1} = M_x$$

$$C_{2z} M_y C_{2z}^{-1} = M_y$$

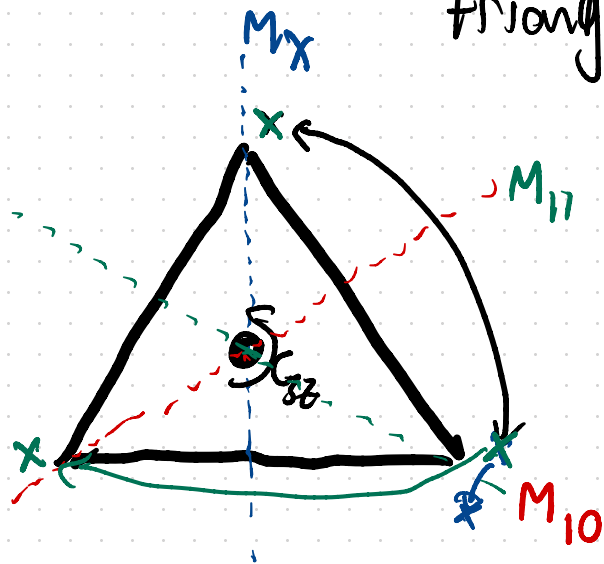
Symmetries of a rectangle



$$M_x M_y = -M_y M_x$$

So M_x and M_y are not
conjugate in Z_{mm}

$3m\bar{2}$ $\langle C_{3z}, M_x \rangle$ - Symmetry group of an equilateral triangle



$$C_{3z} M_{10} = M_{11}$$

$$C_{3z} M_{11} = M_x$$

$$C_{3z} M_x = M_{10}$$

$$C_{3z} M_{10} C_{3z}^{-1} = M_{11} \quad C_{3z}^{-1} = M_x$$

$$C_{3z} M_x C_{3z}^{-1} = M_{11} \quad \rightarrow \text{all 3 mirror}$$

reflections are conjugate in $3m$

Heuristic: multiplying a vertical mirror by C_n rotates the mirror plane by $\frac{\pi}{n}$

conjugating rotates mirror plane by $\frac{2\pi}{n}$

Other 22 pt groups in $3D$:

- horizontal mirror planes
- multiple noncollinear rotation axes (C_2)

• Inversion symmetry

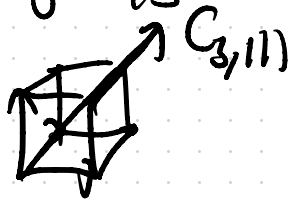
$$I: (x, y, z) \rightarrow (-x, -y, -z)$$

$I \in O(3)$ but not $SO(3)$

C_{nh} : groups w/ horizontal mirrors

D_n : dihedral - grps w/ orthogonal rotation axes

Cubic symmetry groups



$$\bar{1} - \langle I \rangle$$

$$\bar{4} - \langle IC_4 \rangle$$

$$\bar{3} - \langle IC_3 \rangle$$

$$\bar{6} - \langle IC_6 \rangle$$

<https://cryst.ehu.es> for full detail on
all 22 groups

$$\{E, C_5, C_5^2, C_5^3, C_5^4\}$$

