

Lecture 11

• There was an error w/ lecture 9 recording

Recap: let $\vec{k}_\#$ in the Brillouin zone (BZ)
space group G

$$G > G_{k_\#} = \{ \bar{g} | \vec{r} \} \in G \mid \bar{g} k_\# \equiv k_\# \text{ mod } \vec{\Gamma} \}$$

f $g_{k_\#} \in G_{k_\#}$ then $u_{g_{k_\#}} |\Psi_{nk_\#}\rangle = \sum_m |\Psi_{m\bar{g}k_\#}\rangle B_{mn}^{k_\#}(g_{k_\#})$

$$= \sum_m |\Psi_{mk_\#}\rangle B_{mn}^{k_\#}(g_{k_\#})$$

$$B_{mn}^{k_\#}(g_{k_\#}) = \langle \Psi_{mk_\#} | u_{g_{k_\#}} | \Psi_{nk_\#} \rangle$$

$\{ B_{mn}^{k_t}(g_k) \mid g_k \in G_{k_t} \}$ form a representation of the little group

Schur's lemma: Eigenstates of H w/ crystal momentum k_t transforming in reps of G_{k_t} , states transforming in the same irrep are degenerate

Example: Space group $P432 \equiv G$
primitive Bravais lattice octahedral point group
Symmorphic

Primitive Bravais lattice vectors

$$\vec{e}_1 = a \hat{x}$$

$$\vec{e}_2 = a \hat{y}$$

$$\vec{e}_3 = a \hat{z}$$

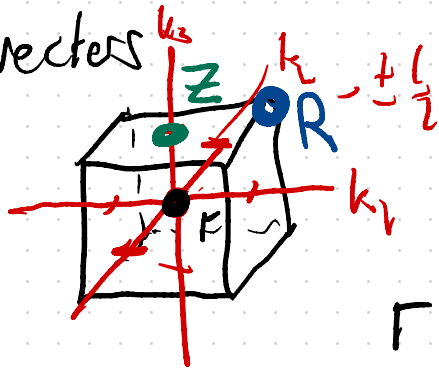
$$G = \langle \vec{e}_1, \vec{e}_2, \vec{e}_3, C_{4z}, C_{3,111} \rangle$$

Primitive reciprocal lattice vectors

$$\vec{b}_1 = \frac{2\pi}{a} \hat{x}$$

$$\vec{b}_2 = \frac{2\pi}{a} \hat{y}$$

$$\vec{b}_3 = \frac{2\pi}{a} \hat{z}$$



$$\vec{K} = k_1 \vec{b}_1 + k_2 \vec{b}_2 + k_3 \vec{b}_3$$

$$\Gamma: (k_1, k_2, k_3) = (0, 0, 0)$$

$$Z: (k_1, k_2, k_3) = (0, 0, \frac{1}{2})$$

$$R: (k_1, k_2, k_3) = (\frac{1}{2}, \frac{1}{2}, \frac{1}{2})$$

$$\textcircled{1} \quad \Gamma \text{ point } \vec{k} = 0$$

$$G_{\Gamma} \cong G \quad \underline{\text{always}}$$

in any space group

$$\{\bar{g} | \vec{d}\} \vec{0} = \bar{g} \vec{0} = \vec{0}$$

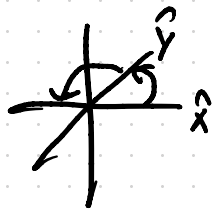
$\Rightarrow \Gamma$ point in any space group is invariant under the whole space group

$$\textcircled{2} \quad R \text{ point } \vec{k} = \frac{1}{2}(\vec{b}_1 + \vec{b}_2 + \vec{b}_3)$$

$$= \frac{\pi}{a}(\hat{x} + \hat{y} + \hat{z})$$

$$\{\bar{E} | \vec{t}\} \in G_R$$

$$C_{4z} : \begin{aligned} \hat{x} &\rightarrow \hat{y} \\ \hat{y} &\rightarrow -\hat{x} \\ \hat{z} &\rightarrow \hat{z} \end{aligned}$$



$$C_{4z} k_R = \frac{\pi}{a}(\hat{y} - \hat{x} + \hat{z}) \stackrel{?}{=} k_R \bmod \frac{\pi}{a}$$

↓

$$\vec{b}_1 = \frac{2\pi}{a} \hat{x}$$

$$\vec{b}_2 = \frac{2\pi}{a} \hat{y}$$

$$\vec{b}_3 = \frac{2\pi}{a} \hat{z}$$

$$= \frac{\pi}{a} (\hat{x} + \hat{y} + \hat{z}) - \frac{2\pi}{a} \hat{x}$$

$$C_{4z} k_R = k_R - \vec{b}_1$$

$$\Rightarrow C_{4z} \in G_R$$

$$C_{3,111} : \begin{array}{l} \hat{x} \rightarrow \hat{y} \\ \hat{y} \rightarrow \hat{z} \\ \hat{z} \rightarrow \hat{x} \end{array}$$

$$C_{3,111} k_R = k_R$$

$$\Rightarrow C_{3,111} \in G_R$$

$\Rightarrow G_R \cong G$ the entire space group P432

$$Z \text{ point } k_z = \frac{1}{2} \vec{b}_3 = \frac{\pi}{a} \hat{z}$$

$$\{E|\hat{e}\} \in G_Z$$

$$C_{3,111} k_z = \frac{\pi}{a} \hat{x} \neq k_z \text{ mod } \Gamma$$

$$C_{4z} \in G_Z$$

$$\text{But: } C_{2x} k_z = -\frac{\pi}{a} \hat{z} = k_z - \frac{2\pi}{a} \hat{z} = k_z - \vec{b}_3$$

$$\Rightarrow C_{2x} \in G_Z$$

$$G_Z = \langle T, C_{4z}, C_{2x} \rangle = P422 < P432$$

Lessons: ① for any k , $T < G_k$ - G_k is a space group, and a subgroup of G (space subgroup of G)

② for any space group G , $G_T = G$

③ if G is symmorphic, then G_k is symmorphic for all k

(if G is nonsymmorphic, some G_k are symmorphic and some G_k are nonsymmorphic)

| To look up k -vectors & little groups:
- Bradley & Cradnell
- cryst.ehues "Kvec" tool

↳ G symmorphic \Rightarrow

$$G = T\bar{G} = \bigcup_{i=0}^{n-1} T\bar{g}_i \quad \{\bar{g}_i\} = \bar{G}$$

$$\nexists G_k < G \quad \text{and} \quad T < G_k$$

$$\underline{G_k = T\bar{G}_k}$$

Representations of Little groups

G_k of k

- $T \triangleleft G_k$ (Since G_k is a space group)
- in any representation ρ_k of G_k $\rho_k(\{E|\vec{t}\}) = e^{-ik \cdot \vec{t}} \text{Id}$

Two cases: ① G_k is symmorphic

② G_k is nonsymmorphic

① Easy: G_k symmorphic $G_k = T \bar{G}_k = \{ \{E|\vec{t}\} \{ \bar{g}_k | \vec{0} \} \}$

$\bar{G}_k < \bar{G}$ and is a point group

$\bar{G}_k = G_k / T$ - "little co-group"

point group of the little group

π ρ_k is a representation of G_k

$$\rho_k(\{\bar{g}_k | \vec{t}\}) = \rho_k(\{\bar{E} | \vec{t}\}) \rho_k(\{\bar{g}_k | 0\})$$

$$= e^{-ik \cdot \vec{t}} \underbrace{\rho_k(\{\bar{g}_k | 0\})}_{\text{point group representation matrix for } \bar{G}_k}$$

point group representation
matrix for \bar{G}_k

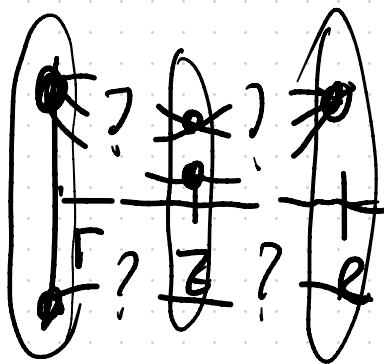
$\{e_k(\{\bar{g}_k|0\}) | \bar{g}_k \in \bar{G}_k\}$ form a representation
of \bar{G}_k

\Rightarrow given any representation η of \bar{G}_k
we can construct a representation

$$e_k(\{\bar{g}_k|\vec{t}\}) = e^{-ik \cdot \vec{t}} \eta(\bar{g}_k)$$

\Rightarrow For symmetric G_k , reps are determined by irreps
of the point group $\bar{G}_k = G_k/\Gamma$

Ex: P432



can label states by
irreps of G_k

$$G_T = G_R = P432$$

↓
irreps of 432

| | | | | | |
|-------|---|----|----|----|----|
| A_1 | 1 | 1 | 1 | 1 | 1 |
| A_2 | 1 | -1 | 1 | 1 | -1 |
| E | 2 | 0 | 2 | -1 | 0 |
| T_2 | 3 | -1 | -1 | 0 | 1 |
| T_1 | 3 | 1 | -1 | 0 | -1 |

↑
can have 1, 2, or
3 fold degenerate
states at T and R

$$G_Z = P422$$

↓
irreps of 422

| | |
|-------|-----|
| | dim |
| A_1 | 1 |
| A_2 | 1 |



can have 1 or 2 fold
degenerate states @ Z

$$\begin{array}{c|c} \beta_1 & 1 \\ \beta_2 & 1 \\ \hline E & 2 \end{array}$$

② G_k nonsymmorphic - more interesting

$$G_k = \bigcup_{i=0}^{n-1} T\{\bar{g}_i | \vec{d}_i\} \quad \{\bar{g}_i | i=0, \dots, n\} = \overline{G_k}$$

but at least one \vec{d}_i is a fraction of an
Bravais lattice translation

\Rightarrow there exists some $\{\bar{g}_1 | \vec{d}_1\}, \{\bar{g}_2 | \vec{d}_2\}$
 $\quad \quad \quad \downarrow \quad \quad \quad \downarrow$
 $\quad \quad \quad g_1 \quad \quad \quad g_2$

$$g_1 g_2 = \{ \bar{g}_1 | \vec{d}_1 \} \{ \bar{g}_2 | \vec{d}_2 \} = \{ \bar{g}_1 \bar{g}_2 | \bar{g}_1 \vec{d}_2 + \vec{d}_1 \}$$

$$= \{ E | \vec{t}_{12} \} \{ \bar{g}_1 \bar{g}_2 | \vec{d}_3 \}$$

$$\Rightarrow \vec{t}_{12} = \bar{g}_1 \vec{d}_2 + \vec{d}_1 - \vec{d}_3$$

$$\left(\begin{array}{l} \text{Ex } \{ C_{2z} | \frac{1}{2} \hat{z} \} = g_1 = g_2 \\ \{ C_{2z} | \frac{1}{2} \hat{z} \} \{ C_{2z} | \frac{1}{2} \hat{z} \} = \{ E | \hat{z} \} \{ E | 0 \} \end{array} \right)$$

this means that for any representation ρ_k

$$\underbrace{\rho_k(\{\bar{g}_1 | \vec{d}_1\}) \rho_k(\{\bar{g}_2 | \vec{d}_2\})}_{\downarrow} = \rho_k(\{E | t_{12}\}) \rho_k(\{g_1 g_2 | \vec{d}_3\})$$

but in \bar{G}_k ,

$$\eta(\bar{g}_1) \eta(\bar{g}_2) = \eta(g_1 g_2)$$

$$e^{-ik \cdot \vec{t}_{12}} \uparrow \text{twist}^0$$

To accomodate this - generalize our idea of representations
instead of representations η of \bar{G}_k , consider

$$\rho_k: \bar{G}_k \rightarrow U(V)$$

$$\rho_k(\bar{g}_1) \rho_k(\bar{g}_2) = e^{ic(\bar{g}_1, \bar{g}_2)} \rho_k(g_1 g_2)$$

associativity:

$$\begin{aligned}
 & \left(\rho_k(\bar{g}_1) \left(\rho_k(\bar{g}_2) \rho_k(\bar{g}_3) \right) \right) = e^{ic(\bar{g}_2, \bar{g}_3)} \rho_k(\bar{g}_1) \rho_k(\bar{g}_2 \bar{g}_3) \\
 & \stackrel{''}{=} e^{ic(\bar{g}_1, \bar{g}_2)} e^{ic(\bar{g}_1, \bar{g}_2 \bar{g}_3)} \rho_k(\bar{g}_1 \bar{g}_2 \bar{g}_3) \\
 & \stackrel{''}{=} e^{ic(\bar{g}_1, \bar{g}_2)} e^{ic(\bar{g}_1 \bar{g}_2, \bar{g}_3)} \rho_k(\bar{g}_1 \bar{g}_2 \bar{g}_3)
 \end{aligned}$$

$$c(\bar{g}_1, \bar{g}_2) + c(\bar{g}_1 \bar{g}_2, \bar{g}_3) - c(\bar{g}_1, \bar{g}_2 \bar{g}_3) - c(\bar{g}_1 \bar{g}_2, \bar{g}_3) = 0$$

"cocycle condition"

a map $\rho_k: \bar{G}_k \rightarrow (U, V)$ s.t.

$$\rho_k(\bar{g}_1) \rho_k(\bar{g}_2) = e^{ic(\bar{g}_1, \bar{g}_2)} \rho(g_1 g_2)$$

with c satisfying the cocycle condition
is a projective representation

For nonsymplectic G_k this is what we have

where $\bar{g}_1, \bar{g}_2 \in \overline{G_k}$

$$c(\bar{g}_1, \bar{g}_2) = -k \cdot t_{12} \quad \text{where} \quad t_{12} = \bar{g}_1 \vec{d}_2 + \vec{d}_1 - \vec{d}_2$$