



CS 579: Computational Complexity. Lecture 3

NL=coNL, Polynomial Hierarchy

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Today

- Randomized log-space
- Alternate characterization of NL
- $NL = coNL$
- Definition of Polynomial Hierarchy
- Alternate characterization
- Some facts, and when does it collapse

Randomized log-space

- Introduce randomized space-bounded TM (for simplicity only for decision problems).
 - Read-only input tape
 - Read/write work tape
 - Read-only random tape with one-way access (the head can only move from left to right)
- For every fixed input and fixed content of random tape, TM is completely deterministic and either accepts or rejects.

Randomized log-space

- For machine M , input x , random tape content r , denote $M(r,x)$ the outcome of the computation.
- Decision problem L belongs to the class RL if there is a probabilistic TM M that uses $O(\log n)$ space on inputs of length n and such that
 - For every $x \in L$, $Pr_r[M(r,x) \text{ accepts}] \geq \frac{1}{2}$
 - For every $x \notin L$, $Pr_r[M(r,x) \text{ accepts}] = 0$

Randomized log-space

- Any constant bigger than zero and smaller than one would work.
- Follows that $L \subseteq RL \subseteq NL$
- Even though we now know that $L = SL$, it is interesting to see the “old” proof of $SL \subseteq RL$.
- **Theorem.** The problem ST-UCONN is in RL.

An alternate characterization of NL

- We saw alternate definition of NP that used certificates instead of non-determinism.
- Can we do the same for NL?
- Certificates might be poly length.
- Need to assume that they are provided to a log-space machine on a read only tape.

An alternate characterization of NL

- **Definition.** A language L is in NL if there exists a deterministic TM M (verifier) with an additional read-once tape, and a polynomial $p: \mathbb{N} \rightarrow \mathbb{N}$ such that for every $x \in \{0,1\}^*$
$$x \in L \iff \exists u \in \{0,1\}^{p(|x|)} \text{ s.t. } M(x,u)=1$$
- By $M(x,u)$ we denote the output of M where x is placed on the input tape and u on the special read-once tape, and M uses only $O(\log(|x|))$ space on its work tapes for every input x .

An alternate characterization of NL

- What if we remove the read-once restriction and allow the TM's to move back and forth on the certificate?
- This changes the class from NL to NP (ex).

NL=coNL

- Analogously to coNP, we define coNL to be the class of languages that are complements of NL languages.
- Complement of STCONN is in coNL, denote it by \overline{STCONN} : Given directed graph G and special vertices s,t decide whether t is NOT reachable from s.
- In fact, it is coNL-complete.

NL=coNL

- Will show that there is an NL TM which solves \overline{STCONN} .
- Generally, for every “well behaved” $s(n)$, $NSPACE(s(n))=coNSPACE(s(n))$. (ex)

The polynomial hierarchy

- Difference between NP and coNP is questions of the form “does there exist” (simple, efficient proofs) and “for all” (don’t seem to have simple and efficient proofs).
- Formally, decision problem A is in NP iff there is poly-time procedure $V(.,.)$ and polynomial bound $p(.)$ such that

$$x \in A \Leftrightarrow \exists y: |y| \leq p(|x|) \wedge V(x, y) = 1$$

- Decision problem A is inco NP iff there is poly-time procedure $V(.,.)$ and polynomial bound $p(.)$ such that

$$x \in A \Leftrightarrow \forall y: |y| \leq p(|x|) \wedge V(x, y) = 1$$

Stacking quantifiers

- Suppose you had a decision problem A which asked

$$x \in A \Leftrightarrow \exists z \text{ s.t. } |z| \leq p(|x|) \forall y \text{ s.t. } |y| \leq p(|x|), V(x, z, y)$$

Example: given Boolean formula f , over variables x_1, x_2, \dots, x_n is there formula f' which is equivalent to f and is of size at most k ?

- Member of the second level of the polynomial hierarchy Σ_2

The polynomial hierarchy

- Starts with familiar classes at level 1:
 $\Sigma_1 = NP$ and $\Pi_1 = \text{coNP}$.
- For all i , it includes two classes Σ_i and Π_i
 $A \in \Sigma_i \Leftrightarrow \exists y_1 \forall y_2 \dots Q y_i V_A(x, y_1, \dots, y_i)$
 $B \in \Pi_i \Leftrightarrow \forall y_1 \exists y_2 \dots Q' y_i V_B(x, y_1, \dots, y_i)$

For clarity, I omitted the $p(\cdot)$ conditions but they are still there.

The polynomial hierarchy

- Easy to see that : $\Pi_k = co\Sigma_k$.
- For all $i < k$, $\Pi_i \subseteq \Sigma_k$, $\Sigma_i \subseteq \Sigma_k$, $\Sigma_i \subseteq \Pi_k$,
 $\Pi_i \subseteq \Pi_k$ (ex)

An alternate characterization

- PH characterized in terms of “oracle machines”
- Oracle has certain power and can be consulted as many times as desired. Every consultation costs only one computational step at a time.
- Syntactically, let A be some decision problem and \mathcal{M} a class of TM. Then \mathcal{M}^A is the class of machines obtained from \mathcal{M} by allowing instances of A to be solved in one step.

An alternate characterization

- If C is a complexity class, then $\mathcal{M}^C = \bigcup_{A \in C} \mathcal{M}^A$.
- If L is complete for C and the machines in \mathcal{M} are powerful enough to compute poly-time computations, then $\mathcal{M}^C = \mathcal{M}^L$.

An alternate characterization

- **Theorem.** $\Sigma_2 = NP^{3SAT}$

An alternate characterization

- **Theorem.** For every $i > 1$, $\Sigma_i = NP^{\Sigma_{i-1}}$
(ex)

Additional properties

Here are some facts about PH that we will not prove:

- Σ_i and Π_i have complete problems for all i .
- A Σ_i -complete problem is not in Π_j , $j < i$, unless $\Sigma_i = \Pi_j$.
- A Σ_i -complete problem is not in Σ_j , $j < i$, unless $\Sigma_i = \Sigma_j$.
- Suppose $\Sigma_i = \Pi_i$ for some i . Then $\Sigma_j = \Pi_j = \Sigma_i = \Pi_i$ for all $j \geq i$.
- Suppose that $\Pi_i = \Pi_{i+1}$ for some i . Then $\Sigma_j = \Pi_j = \Pi_i$ for all $j \geq i$.

Additional properties

Theorem. (Special case of (3) above)

Suppose $NP = coNP$. Then for every $i \geq 2$,
 $\Sigma_i = NP$.