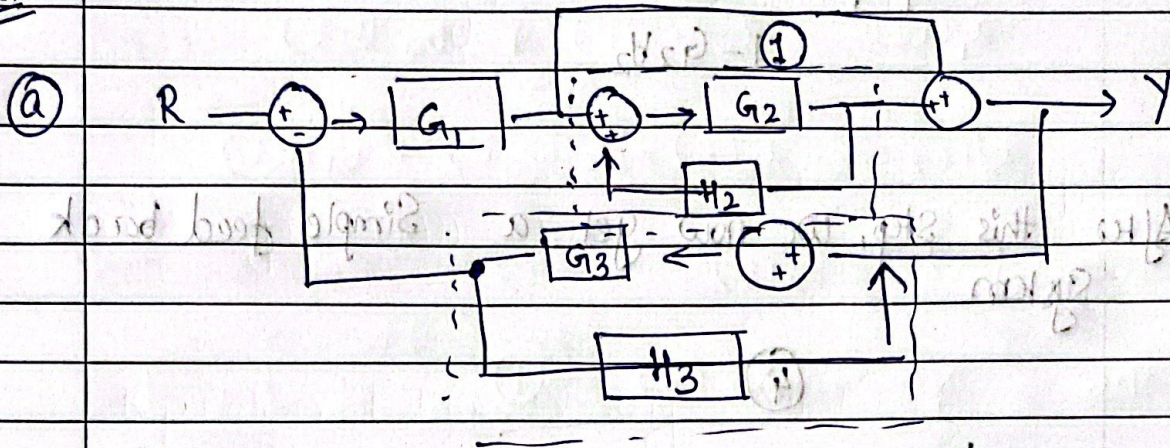


ECE 486 - HW2 Solution

Q1



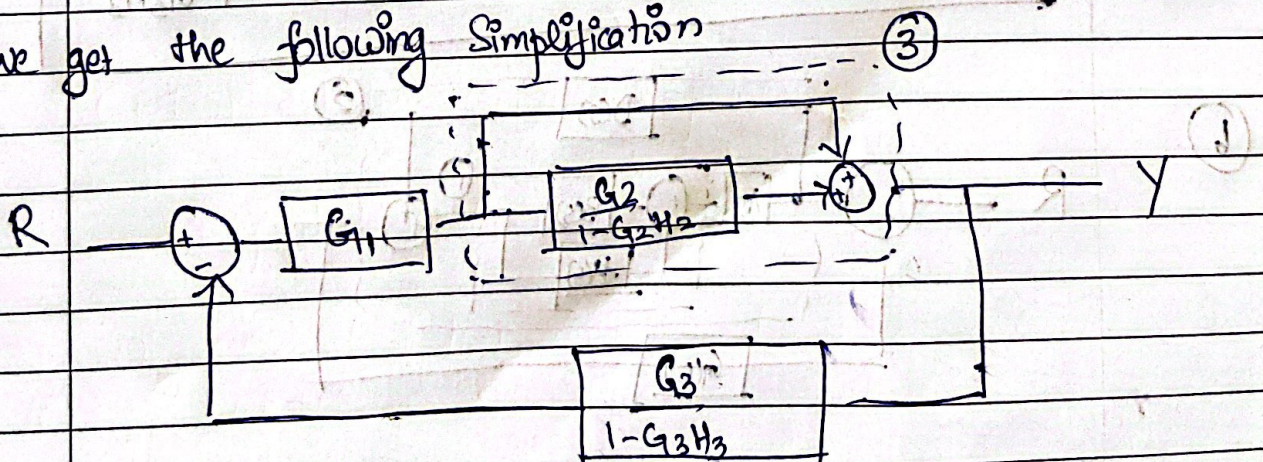
1) We can simplify ① using Block diagram Rules

$$\frac{G_2}{1 - G_2 H_2}$$

2) We can further simplify ② as follows,

$$\frac{G_3}{1 - G_3 H_3}$$

We get the following simplification

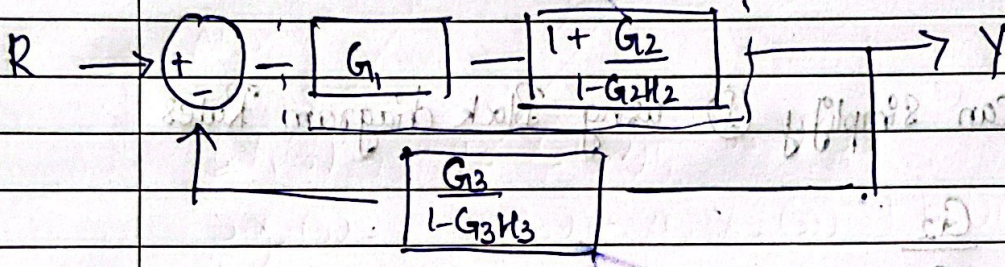


we can now simplify (3) as

$$1 + \frac{G_2}{1 - G_2 H_2}$$

After this step, we now get a simple feed back system

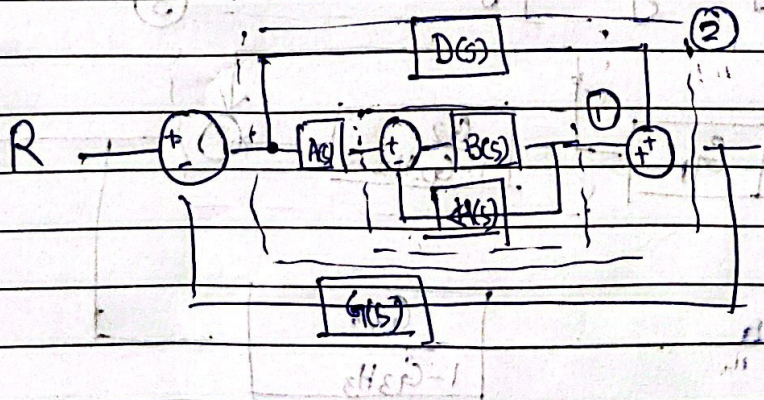
(4)



(4) is a simple feed back system such that

$$\frac{Y(s)}{R(s)} = \frac{G_1 \left(1 + \frac{G_2}{1 - G_2 H_2} \right)}{1 + G_1 \left(1 + \frac{G_2}{1 - G_2 H_2} \right) \left(\frac{G_3}{1 - G_3 H_3} \right)}$$

(6)

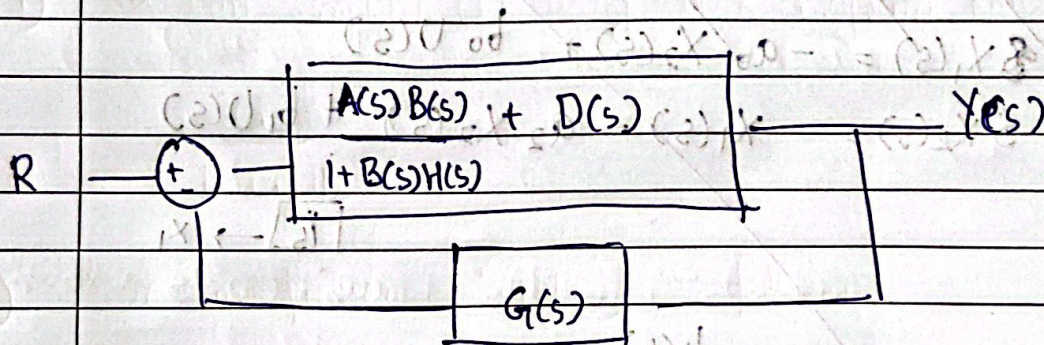


Simplifying ① and ② gives us,

$$\textcircled{1} \quad \frac{B(s)}{1 + B(s)H(s)} \cdot (f) = (f)$$

$$\textcircled{2} \quad \frac{A(s) \cdot B(s) + D(s)}{1 + B(s)H(s)} = (f)$$

We now get,



Simplifying this using Feed back Loop formula gives us

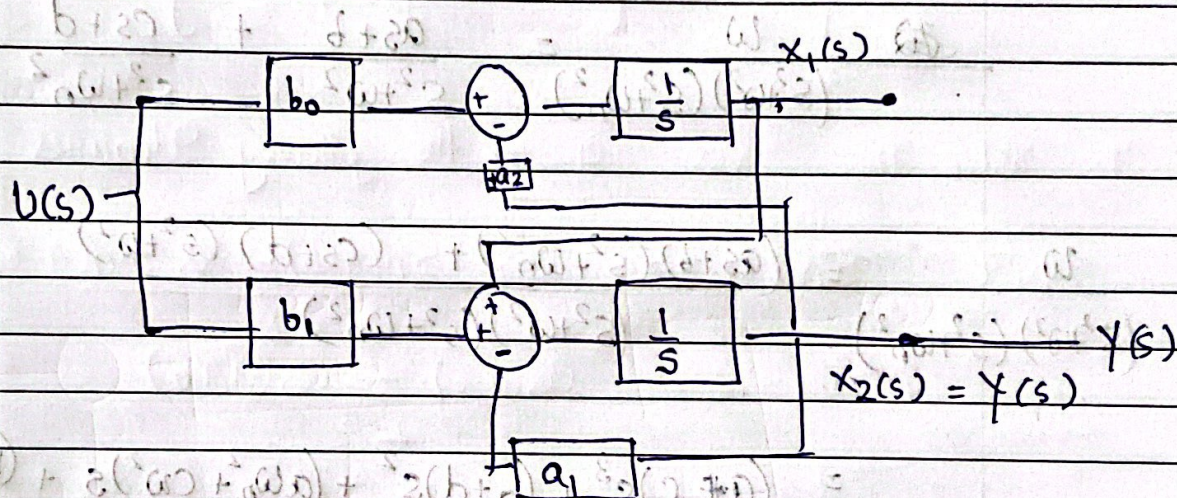
$$\frac{Y(s)}{R(s)} = \frac{\left(\frac{A(s)B(s)}{1 + B(s)H(s)} + D(s) \right)}{1 + G(s) \left(\frac{A(s)B(s)}{1 + B(s)H(s)} + D(s) \right)}$$

Q2

$$\dot{x}_1(t) = -a_2 x_2(t) + b_0 u(t)$$

$$\dot{x}_2(t) = x_1(t) - a_1 x_2(t) + b_1 u(t)$$

$$y(t) = x_2(t)$$



Note that this is one of the solutions. Different Solution might exist

Q3

$$H(s) = \frac{\omega}{s^2 + \omega_n^2}$$

$$U = V(s) = \frac{\omega}{s^2 + \omega^2}$$

$$\text{Thus, } Y(s) = H(s) \cdot U(s) = \frac{\omega}{(s^2 + \omega_n^2)(s^2 + \omega^2)}$$

This can be ~~made~~ solved for Laplace Inverse as follows

$$\mathcal{L}^{-1}(Y(s)) = \mathcal{L}^{-1}\left(\frac{\omega}{(s^2 + \omega^2)(s^2 + \omega_n^2)}\right)$$

Using partial fractions

$$\frac{\omega}{(s^2 + \omega^2)(s^2 + \omega_n^2)} = \frac{as + b}{s^2 + \omega^2} + \frac{cs + d}{s^2 + \omega_n^2}$$

$$\frac{\omega}{(s^2 + \omega^2)(s^2 + \omega_n^2)} = \frac{(as + b)(s^2 + \omega_n^2) + (cs + d)(s^2 + \omega^2)}{(s^2 + \omega^2)(s^2 + \omega_n^2)}$$

$$= \frac{(a + c)s^3 + (b + d)s^2 + (a\omega_n^2 + c\omega^2)s + (b\omega_n^2 + d\omega^2)}{(s^2 + \omega^2)(s^2 + \omega_n^2)}$$

Comparing Numerator on both sides, we get

$$a + c = 0 \quad b + d = 0 \quad a\omega_n^2 + c\omega^2 = 0$$

$$b\omega_n^2 + d\omega^2 = \omega$$

$$a = c = 0$$

$$b(\omega_n^2 - \omega^2) = \omega$$

$$b = \frac{\omega}{\omega_n^2 - \omega^2}$$

$$d = \frac{-\omega}{\omega_n^2 - \omega^2}$$

$$\mathcal{L}^{-1}(Y(s)) = \mathcal{L}^{-1}\left(\frac{b}{s^2 + \omega^2} + \frac{d}{s^2 + \omega_n^2}\right)$$

$$= \frac{b}{\omega} \sin(\omega t) + \frac{d}{\omega} \sin(\omega_n t)$$

$$Y(t) = \frac{1}{\omega_n^2 - \omega^2} (\sin(\omega t) - \sin(\omega_n t))$$

$\lim_{\omega \rightarrow \omega_n} Y(t) \rightarrow \infty$ (since there is denominator term that blows up)

(We can see the same thing by observing magnitude for a Bode plot.)

$$|G(j\omega)| = \left| \frac{1}{\omega^2 - \omega_n^2} \right|$$

$$\lim_{\omega \rightarrow \omega_n} |G(j\omega)| \rightarrow \infty$$

(b)

Using Convolution, we see that

$$y(t) = \int_0^t \frac{\sin(\omega_n(t-\tau))}{\omega_n} \cdot \sin \omega \tau \, d\tau$$

$$y(t) = \frac{1}{\omega_n} \int_0^t \sin(\omega_n(t-\tau)) \cdot \sin(\omega \tau) d\tau$$

$$= \frac{1}{\omega_n} \int_0^t (\sin(\omega_n t) \cos(\omega_n \tau) - \cos(\omega_n t) \sin(\omega_n \tau)) \sin(\omega \tau) d\tau$$

$$= \frac{1}{\omega_n} \left(\int_0^t \sin(\omega_n t) \sin(\omega \tau) \cos(\omega_n \tau) d\tau - \int_0^t \cos(\omega_n t) \sin(\omega_n \tau) \sin(\omega \tau) d\tau \right)$$

To solve this, Consider the following identities

$$\sin a \cos b = \frac{\sin(a+b) + \sin(a-b)}{2}$$

$$\sin a \sin b = \frac{\cos(a-b) - \cos(a+b)}{2}$$

$$\frac{1}{\omega_n} \int_0^t \sin(\omega_n t) \left(\frac{\sin((\omega+\omega_n)\tau) + \sin((\omega-\omega_n)\tau)}{2} \right) d\tau$$

$$- \cos(\omega_n t) \left(\frac{\cos((\omega-\omega_n)\tau) - \cos((\omega+\omega_n)\tau)}{2} \right) d\tau$$

$$\frac{1}{\omega_n} \left(\sin(\omega_n t) \left(\frac{-\cos((\omega+\omega_n)\tau)}{\omega+\omega_n} \right) \Big|_0^t - \cos(\omega_n t) \left(\frac{\sin((\omega-\omega_n)\tau)}{\omega-\omega_n} \right) \Big|_0^t \right)$$

$$- \frac{1}{\omega_n} \left(\cos(\omega_n t) \left(\frac{\sin((\omega-\omega_n)\tau)}{\omega-\omega_n} \right) \Big|_0^t - \sin(\omega_n t) \left(\frac{-\cos((\omega+\omega_n)\tau)}{\omega+\omega_n} \right) \Big|_0^t \right)$$

as $\omega \rightarrow \omega_n$ the above term blows up

Q4

(a)

We use Routh-Horwitz Criteria

$$s^4 + 8s^3 + 32s^2 + 80s + 10$$

Cond 1 : All Coefficients are positive

Cond 2: s^4 | 1 32 10 \rightarrow Since, sign changes = 0
 s^3 | 8 80 0 \rightarrow No Root on RHS plane

$$s^2 \quad \swarrow$$

170	10
8	

$$s^1 \quad \frac{1620 \times 8}{17} \quad 0$$

$$s^0 \quad \frac{1620 \times 8 \times 10}{17}$$
$$\frac{162 \times 8}{17}$$

(b)

$$s^5 + 5s^4 + 2s^3 - s^2 + 4s + 10$$

Since, one coefficient is negative, there are Roots in RHS