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# CS440/ECE448 Lecture 8: Logistic Regression



## Outline

- One-hot vectors: rewriting the perceptron to look like linear regression
- Softmax: Soft category boundaries
- Cross-entropy = negative log probability of the training data
- Stochastic gradient descent for logistic regression

#### Comparison of Multi-Class Perceptron to Multiple Regression

#### Multi-Class Perceptron



#### Multiple Regression



Here's a weird question:

Can we come up with some new notation that can be used to write both the multi-class perceptron AND the linear regression algorithm?

New notation: Don't change the multi-class perceptron algorithm, but make it easier to write

• Instead of defining  $y_i$  as an integer, let's define  $\vec{y}_i$  to be a vector:

$$\vec{y}_i = \begin{bmatrix} y_{i,1} \\ \vdots \\ y_{i,V} \end{bmatrix}$$

• For a multi-class perceptron, this only makes sense if  $\vec{y}_i$  is what's called a <u>one-hot</u> vector:

$$y_{i,c} = \begin{cases} 1 & c = \text{true class label of the } i^{th} \text{ token} \\ 0 & \text{otherwise} \end{cases}$$

New notation: Don't change the multi-class perceptron algorithm, but make it easier to write

• Let's also define the output to be a one-hot vector:

$$f(\vec{x}_i) = \begin{bmatrix} f_1(\vec{x}_i) \\ \vdots \\ f_V(\vec{x}_i) \end{bmatrix}$$

... where ...

$$f_c(\vec{x}_i) = \begin{cases} 1 & c = \operatorname{argmax} \vec{w}_c^T \vec{x} \\ 0 & \text{otherwise} \end{cases}$$

#### Example: Binary classifier

Consider the classifier

$$f(\vec{x}_i) = \begin{bmatrix} f_1(\vec{x}_i) \\ f_2(\vec{x}_i) \end{bmatrix}, \qquad f_c(\vec{x}_i) = \begin{cases} 1 & c = \operatorname{argmax} \vec{w}_c^T \vec{x} \\ 0 & \text{otherwise} \end{cases}$$

... with only two classes. Then the classification regions might look like this:





Consider the classifier  $f(\vec{x}_i) = \begin{bmatrix} f_1(\vec{x}_i) \\ \vdots \\ f_V(\vec{x}_i) \end{bmatrix},$ 

$$f_c(\vec{x}_i) = \begin{cases} 1 & c = \operatorname{argmax} \vec{w}_c^T \vec{x} \\ 0 & \text{otherwise} \end{cases}$$

... with 20 classes. Then some of the classifications might look like this.

By Balu Ertl - Own work, CC BY-SA 4.0, https://commons.wikimedia.org/w/index.php?curid=38534275

# Now the perceptron has a vector error, just like linear regression

Now we can define an error term for every output:  $F_{i+1}$ 

$$\vec{\epsilon}_i = \begin{bmatrix} \epsilon_{i,1} \\ \vdots \\ \epsilon_{i,V} \end{bmatrix}, \qquad \epsilon_{i,c} = f_c(\vec{x}_i) - y_{i,c}$$

• If c was the correct class label ( $y_{i,c} = 1$ ), but the network didn't get it right ( $f_c(\vec{x}_i) = 0$ ), then it **<u>undershot</u>**:

$$\epsilon_{i,c} = -1$$

• If the network thought the correct answer was c ( $f_c(\vec{x}_i) = 1$ ), but it wasn't ( $y_{i,c} = 0$ ), then it <u>overershot</u>

$$\epsilon_{i,c} = +1$$

• Otherwise,

$$\epsilon_{i,c} = 0$$

# Multi-class perceptron, written in terms of one-hot vectors

But with this definition, we can write the perceptron update the same as the linear regression update:

$$\vec{w}_c \leftarrow \vec{w}_c - \eta \epsilon_{i,c} \vec{x}_i = \begin{cases} \vec{w}_c + \eta \vec{x}_i & \epsilon_{i,c} = -1 \\ \vec{w}_c - \eta \vec{x}_i & \epsilon_{i,c} = +1 \\ \vec{w}_c & \epsilon_{i,c} = 0 \end{cases}$$

#### Comparison of Multi-Class Perceptron to Multiple Regression

#### <u>Multi-Class Perceptron:</u> <u>One-hot output</u>





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#### Probabilistic boundaries

Instead of trying to find the exact boundaries, logistic regression models the probability that token  $\vec{x}$  belongs to class  $\vec{y}$ .



## Perceptron versus logistic regression

Remember that for the perceptron, we have  

$$f(\vec{x}_i) = \begin{bmatrix} f_1(\vec{x}_i) \\ \vdots \\ f_V(\vec{x}_i) \end{bmatrix}, \quad f_c(\vec{x}_i) = \begin{cases} 1 & c = \operatorname{argmax} \vec{w}_c^T \vec{x} \\ 0 & \text{otherwise} \end{cases}$$

For logistic regression, we have

$$f(\vec{x}_i) = \begin{bmatrix} f_1(\vec{x}_i) \\ \vdots \\ f_V(\vec{x}_i) \end{bmatrix}, \qquad f_c(\vec{x}_i) = \frac{e^{\vec{w}_c^T \vec{x}}}{\sum_{k=1}^V e^{\vec{w}_k^T \vec{x}}}$$

The softmax function

• This is called the softmax function:

softmax
$$(\vec{x}_i) = \begin{bmatrix} \operatorname{softmax}(W^T \vec{x}) \\ 1 \\ \vdots \\ \operatorname{softmax}(W^T \vec{x}) \end{bmatrix}, \quad \operatorname{softmax}(W^T \vec{x}) = \frac{e^{\vec{w}_c^T \vec{x}}}{\sum_{k=1}^V e^{\vec{w}_k^T \vec{x}}}$$

• ...where the matrix W is defined to be  $W = [\vec{w}_1, ..., \vec{w}_V]$  Argmax and Softmax

$$f_c(\vec{x}_i) = \begin{cases} 1 & c = \operatorname{argmax} \vec{w}_c^T \vec{x} \\ 0 & \text{otherwise} \end{cases}, \qquad f_c(\vec{x}_i) = \frac{e^{\vec{w}_c^T \vec{x}}}{\sum_{k=1}^V e^{\vec{w}_k^T \vec{x}}} \end{cases}$$

In both cases, we have:

- $f_c(\vec{x}_i) \ge 0$
- $f_c(\vec{x}_i) \leq 1$
- $\sum_{c=1}^{V} f_c(\vec{x}_i) = 1$

Argmax and Softmax

$$f_c(\vec{x}_i) = \begin{cases} 1 & c = \operatorname{argmax} \vec{w}_c^T \vec{x} \\ 0 & \text{otherwise} \end{cases}, \qquad f_c(\vec{x}_i) = \frac{e^{\vec{w}_c^T \vec{x}}}{\sum_{k=1}^V e^{\vec{w}_k^T \vec{x}}} \end{cases}$$

In both cases, we can interpret these as probabilities:

$$f_c(\vec{x}) = P(\text{Class} = c | X = \vec{x})$$

#### Some details: Logistic function

The probability P(Class = 1 | X = x) in the two-class case has an interesting form. It's called the "logistic sigmoid" function:

P(Class = 1|X = x) = softmax(
$$\vec{w}_1^T x$$
) =  $\frac{e^{\vec{w}_1^T x}}{e^{\vec{w}_1^T x} + e^{\vec{w}_2^T x}} = \frac{1}{1 + e^{-\vec{w}^T x}}$ 

where  $\vec{w} = \vec{w}_1 - \vec{w}_2$ .



This function,

P(Class = 1|X = x) = 
$$\frac{1}{1 + e^{-\vec{w}^T x}}$$

is called the "logistic sigmoid function."

- It's called "sigmoid" because it is S-shaped.
- It was first discovered by Verhulst in the 1830s, as a model of population growth. The idea was that the population grows exponentially until it runs up against resource limitations, and then starts to stagnate.



## Logistic Regression

We can frame the basic idea of logistic regression in this way: replace the non-differentiable decision  $\frac{2}{5}$  function

$$\hat{y} = \mathbf{u}(\vec{w}^T x)$$

with a differentiable decision function:

$$\hat{y} = \sigma(\vec{w}^T x) = \frac{1}{1 + e^{-\vec{w}^T x}}$$

...so that the classifier can be trained using gradient descent.



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- One-hot vectors: rewriting the perceptron to look like linear regression
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#### Learning logistic regression

- Suppose we have some data.
- We want to learn vectors  $\vec{w}_c = [w_{c,1}, \dots, w_{c,D}, b_c]^T$  so that  $P(Class = c | X = \vec{x}) = softmax(W^T \vec{x}).$



Learning logistic regression: Training data Data:

$$\mathfrak{D} = \{ (\vec{x}_1, c_1), (\vec{x}_2, c_2), \dots, (\vec{x}_n, c_n) \}$$

where each  $\vec{x}_i = [x_{i,1}, ..., x_{i,D}, 1]^T$  is a vector, and each  $c_i \in \{1, ..., V\}$  is a integer encoding the true class label.



#### Learning logistic regression: Model parameters

We want to learn the model parameters

$$W = [\vec{w}_1, \dots, \vec{w}_V]$$

so that

$$P(C = c_i | X = \vec{x}_i) = \operatorname{softmax}(W^T \vec{x}_i)$$



#### Learning logistic regression: Training criterion

We want to learn the model parameters,  $W = [\vec{w}_1, ..., \vec{w}_V]$ , in order to maximize the probability of the observed data:

$$P(\mathfrak{D}|W) = \prod_{i=1}^{n} P(C = c_i | X = \vec{x}_i)$$



#### Learning logistic regression

We want to learn the model parameters,  $W = [\vec{w}_1, ..., \vec{w}_V]$ , in order to maximize the probability of the observed data:

$$P(\mathfrak{D}|W) = \prod_{i=1}^{n} \operatorname{softmax}_{c_{i}}(W^{T}\vec{x}_{i})$$



#### Learning logistic regression

We want to learn the model parameters,  $W = [\vec{w}_1, ..., \vec{w}_V]$ , in order to maximize the probability of the observed data:

$$P(\mathfrak{D}|W) = \prod_{i=1}^{n} \frac{e^{\overrightarrow{w}_{c_i}^T \overrightarrow{x}_i}}{\sum_{k=1}^{V} e^{\overrightarrow{w}_k^T \overrightarrow{x}_i}}$$



## How do you maximize a function?

Our goal is to find  $W = [\vec{w}_1, ..., \vec{w}_V]$  in order to maximize

$$P(\mathfrak{D}|W) = \prod_{i=1}^{n} \frac{e^{\overrightarrow{w}_{c_i}^T \overrightarrow{x}_i}}{\sum_{k=1}^{V} e^{\overrightarrow{w}_k^T \overrightarrow{x}_i}}$$

Here are some useful things to know:

- 1. Logarithm turns products into sums
- 2. Maximizing f(W) is the same thing as minimizing -f(W)

### 1. Logarithms turn products into sums

 $\ln x$  (the natural logarithm of x, shown as  $\log_e x$  in the plot at right) is a monotonically increasing function of x.

Since it's monotonically increasing,

 $\underset{W}{\operatorname{argmax}} P(\mathfrak{D}|W) = \underset{W}{\operatorname{argmax}} \ln P(\mathfrak{D}|W)$ 

Almost always, maximizing the log probability is easier than maximizing the probability, because logarithms turn products into sums.



#### 1. Logarithms turn products into sums

Our goal is to find  $W = [\vec{w}_1, ..., \vec{w}_V]$  in order to maximize

$$\ln P(\mathfrak{D}|W) = \sum_{i=1}^{n} \ln \frac{e^{\vec{w}_{c_i}^T \vec{x}_i}}{\sum_{k=1}^{V} e^{\vec{w}_k^T \vec{x}_i}} = \sum_{i=1}^{n} \left( \vec{w}_{c_i}^T \vec{x}_i - \ln \sum_{k=1}^{V} e^{\vec{w}_k^T \vec{x}_i} \right)$$

2. Maximizing f(W) is the same thing as minimizing -f(W).

Our goal is to find  $W = [\vec{w}_1, ..., \vec{w}_V]$  in order to maximize

$$\ln P(\mathfrak{D}|W) = \sum_{i=1}^{n} \left( \vec{w}_{c_i}^T \vec{x}_i - \ln \sum_{k=1}^{V} e^{\vec{w}_k^T \vec{x}_i} \right)$$

Choosing W to maximizing  $\vec{w}_{c_i}^T \vec{x}_i$  is kind of obvious: just set  $\vec{w}_{c_i} = A \vec{x}_i$ , where A is a scalar that's as big as possible. Maximizing  $-\ln \sum_{k=1}^V e^{\vec{w}_k^T \vec{x}_i}$ , is not obvious.

2. Maximizing f(W) is the same thing as minimizing -f(W).

To emphasize the hard part of the problem, there is a convention that, instead of maximizing  $\ln P(\mathfrak{D}|W)$ , we minimize  $-\ln P(\mathfrak{D}|W)$ : Our goal is to find  $W = [\vec{w}_1, ..., \vec{w}_V]$  in order to minimize

$$\mathfrak{L} = -\ln P(\mathfrak{D}|W) = \sum_{i=1}^{n} \left( \ln \sum_{k=1}^{V} e^{\vec{w}_{k}^{T} \vec{x}_{i}} - \vec{w}_{c_{i}}^{T} \vec{x}_{i} \right)$$

The curly  $\mathfrak{L}$  is a symbol we use to denote a "loss function". A loss function is something you want to minimize.

#### Some details: Cross entropy

- The loss function is called "cross entropy," because it is similar in some ways to the entropy of a thermodynamic system in physics.
- When you implement this in software, it's a good idea to normalize by the number of training tokens, so that the scale is easier to understand:

$$\mathfrak{L} = -\frac{1}{n}\log P(\mathfrak{D}|W) = -\frac{1}{n}\sum_{i=1}^{n}\log P(\mathcal{C} = c_i|X = \vec{x}_i)$$

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## Logistic regression training

- In each iteration, present a batch of training data,  $\mathfrak{D} = \{(x_1, c_1), (x_2, c_2), \dots, (x_n, c_n)\}.$ 
  - If the batch contains all the data, this is called "gradient descent"
  - If the batch contains a randomly chosen subset of the data, this is called "stochastic gradient descent"
- Calculate P(Class =  $c|X = \vec{x}_i$ ) = softmax( $W^T \vec{x}$ ) for each training token  $\vec{x}_i$ , for each class c.
- Update all the weight vectors using stochastic gradient descent.

Start with the given dataset  $\mathfrak{D}.$  Here the true class is indicated by both color and shape.



Randomly initialize the weight vectors, and then calculate the probabilities  $P(Y = c | X = x_i)$  for every class c, for every training token (shown as transparency and color change, left side)



Modify the weight vectors to reduce the loss function, as  $\vec{w}_c \leftarrow \vec{w}_c - \eta \nabla_{\vec{w}_c} \mathfrak{L}$ 



Repeat until the loss stops decreasing:  $\vec{w}_c \leftarrow \vec{w}_c - \eta \nabla_{\vec{w}_c} \mathfrak{L}$ 



Stochastic gradient descent

Our goal is to find  $W = [\vec{w}_1, ..., \vec{w}_V]$  in order to minimize

$$\mathfrak{L} = -\ln P(\mathfrak{D}|W) = \sum_{i=1}^{n} \left( \ln \sum_{k=1}^{V} e^{\vec{w}_{k}^{T} \vec{x}_{i}} - \vec{w}_{c_{i}}^{T} \vec{x}_{i} \right)$$

Just like in linear regression, let's do that one token at a time. Choose a training token  $(\vec{x}_i, c_i)$ , and try to minimize

$$\mathfrak{L}_{i} = -\ln P(C = c_{i} | X = \vec{x}_{i}) = \ln \sum_{k=1}^{V} e^{\vec{w}_{k}^{T} \vec{x}_{i}} - \vec{w}_{c_{i}}^{T} \vec{x}_{i}$$

Stochastic gradient descent

Our goal is to find  $W = [\vec{w}_1, ..., \vec{w}_V]$  in order to minimize

$$\mathfrak{L}_i = \ln \sum_{k=1}^{V} e^{\overrightarrow{w}_k^T \overrightarrow{x}_i} - \overrightarrow{w}_{c_i}^T \overrightarrow{x}_i$$

We do that by adjusting  $\vec{w}_c \leftarrow \vec{w}_c - \eta \nabla_{\vec{w}_c} \mathfrak{L}_i$ , where

- $\eta$  is called the learning rate. Typically  $\eta \approx 0.001$ , but it's very hard to know in advance what learning rate will work for a particular problem; you need to experiment to see what works.
- $\nabla_{\vec{w}_c} \mathfrak{L}_i$  is the gradient of the loss with respect to  $\vec{w}_c$ .

#### The gradient of the cross-entropy of a softmax

Now, let's calculate that gradient.

$$\nabla_{\vec{w}_{c}} \mathfrak{L}_{i} = \nabla_{\vec{w}_{c}} \left( \ln \sum_{k=1}^{V} e^{\vec{w}_{k}^{T} \vec{x}_{i}} \right) - \nabla_{\vec{w}_{c}} \left( \vec{w}_{c_{i}}^{T} \vec{x}_{i} \right)$$
$$= \nabla_{\vec{w}_{c}} \left( \ln \sum_{k=1}^{V} e^{\vec{w}_{k}^{T} \vec{x}_{i}} \right) - y_{i,c} \vec{x}_{i}$$

...where  $y_{i,c}$  is our old friend the one-hot vector:

$$y_{i,c} = \begin{cases} 1 & c_i = c \\ 0 & \text{otherwise} \end{cases}$$

The gradient of the cross-entropy of a softmax

$$\nabla_{\vec{w}_c} \mathfrak{L}_i = \nabla_{\vec{w}_c} \left( \ln \sum_{k=1}^{V} e^{\vec{w}_k^T \vec{x}_i} \right) - y_{i,c} \vec{x}_i$$
$$= \frac{e^{\vec{w}_c^T \vec{x}_i}}{\sum_{k=1}^{V} e^{\vec{w}_k^T \vec{x}_i}} \vec{x}_i - y_{i,c} \vec{x}_i$$
$$= \left( f_c(\vec{x}_i) - y_{i,c} \right) \vec{x}_i$$
$$= \epsilon_{i,c} \vec{x}_i$$

#### Conclusion

• Perceptron:

$$\epsilon_{i,c} = f_c(\vec{x}_i) - y_{i,c}, \qquad \vec{w}_c \leftarrow \vec{w}_c - \eta \epsilon_{i,c} \vec{x}_i$$

• Linear Regression:

$$\epsilon_{i,c} = f_c(\vec{x}_i) - y_{i,c}, \qquad \vec{w}_c \leftarrow \vec{w}_c - \eta \epsilon_{i,c} \vec{x}_i$$

• Logistic Regression:

$$\epsilon_{i,c} = f_c(\vec{x}_i) - y_{i,c}, \qquad \vec{w}_c \leftarrow \vec{w}_c - \eta \epsilon_{i,c} \vec{x}_i$$

The only difference is how you define the network output (argmax, linear, or softmax).

#### Comparison of Multi-Class Perceptron to Multiple Regression

#### <u>Multi-Class Perceptron:</u> <u>One-hot output</u>





Logistic Regression

