

UNIVERSITY OF ILLINOIS AT URBANA-CHAMPAIGN
CS440/ECE448 Artificial Intelligence
Conflict Exam 1
Spring 2022

February 24, 2022

Your Name: _____

Your NetID: _____

Instructions

- Please write your name on the top of every page.
- This will be a **CLOSED BOOK, CLOSED NOTES** exam. You are permitted to bring and use only one 8.5x11 page of hand-written notes, front and back.
- No electronic devices (phones, tablets, calculators, computers etc.) are allowed.
- No calculators are permitted. You need not simplify explicit numerical expressions.

Possibly Useful Formulas

Probability: $P(B = 1|A = 1) = \frac{P(A = 1, B = 1)}{P(A = 1)}$

Naïve Bayes: $P(X = x|Y = y) \approx \prod_{i=1}^n P(W = w_i|Y = y)$

Laplace Smoothing: $P(w) = \frac{\text{Count}(w) + k}{\sum_w \text{Count}(w) + k(1 + \sum_w 1)}$

Perceptron: $\vec{w}_y = \vec{w}_y + \eta \vec{x}$, $\vec{w}_{f(\vec{x})} = \vec{w}_{f(\vec{x})} - \eta \vec{x}$

Linear Regression w/SGD: $\vec{w} \leftarrow \vec{w} - \frac{\eta}{2} \nabla_{\vec{w}} \epsilon_i^2 = \vec{w} - \eta \epsilon_i \vec{x}_i$

Logistic Regression: $\nabla_{\vec{w}_c} \mathcal{L}_i = \nabla_{\vec{w}_c} \left(-\ln \frac{e^{\vec{w}_c^T \vec{x}_i}}{\sum_k e^{\vec{w}_k^T \vec{x}_i}} \right) = \left(\frac{e^{\vec{w}_c^T \vec{x}_i}}{\sum_k e^{\vec{w}_k^T \vec{x}_i}} - y_{i,c} \right) \vec{x}_i$

Neural Net: $\xi_j^{(l)} = b_j^{(l)} + \sum_k w_{j,k}^{(l)} h_k^{(l-1)}$, $h_j^{(l)} = g^{(l)} \left(\xi_j^{(l)} \right)$

Back-Propagation: $\frac{\partial \mathcal{L}}{\partial h_k^{(l-1)}} = \sum_j \frac{\partial \mathcal{L}}{\partial h_j^{(l)}} \frac{\partial h_j^{(l)}}{\partial h_k^{(l-1)}}$

Pinhole Camera: $\frac{x'}{f} = -\frac{x}{z}$, $\frac{y'}{f} = -\frac{y}{z}$

Question 1 (7 points)

Consider two binary random variables, X and Y . Suppose that

$$P(Y = 0) = b$$

$$P(X = 1, Y = 0) = c$$

In terms of b and/or c , what is the largest possible value of $P(X = 1)$?

Question 2 (7 points)

Suppose you are training a naïve Bayes model. There are two classes, $Y = 0$ and $Y = 1$, with the following observations:

- Training text for class $Y = 0$: “apple apple apple apple apple”.
- Training text for class $Y = 1$: “banana banana banana banana banana apple”.

Use this example to discuss, in a few sentences, the importance of Laplace smoothing.

Question 3 (7 points)

Describe, in one sentence each, (1) what does it mean for a classifier to overfit a training corpus?, (2) what does it mean for a model to underfit a training corpus?, (3) how can overfitting and underfitting be avoided?

Question 4 (7 points)

Imagine training a perceptron with a training dataset that contains only two training tokens: $\vec{x}_1 = [1, 1]^T, y_1 = 1$ and $\vec{x}_2 = [-1, -1]^T, y_2 = -1$. Suppose you begin with the weight vector $\vec{w} = [0, 0]^T$ and bias $b = -1$, then present the data in alternating order $\{(\vec{x}_1, y_1), (\vec{x}_2, y_2), (\vec{x}_1, y_1), (\vec{x}_2, y_2), \dots\}$, with a learning rate of $\eta = 1$, until \vec{w} and b converge. What are the final converged values of \vec{w} and b ?

Question 5 (7 points)

In stochastic gradient descent, we train using one training token at a time. Suppose x is a scalar input, and suppose we have

$$\mathcal{L} = -\ln f_2(x)$$

where

$$f_k(\vec{x}) = \frac{e^{w_k x + b_k}}{e^{w_1 x + b_1} + e^{w_2 x + b_2}} \text{ for } k \in \{1, 2\}$$

In terms of x , w_1 , w_2 , b_1 , b_2 , $f_1(x)$ and/or $f_2(x)$, what is $\frac{d\mathcal{L}}{db_1}$?

Question 6 (7 points)

Consider a two-layer neural network with a scalar input, x . Assume that all of the weights and biases are nonzero, and that the output $f(x)$ is computed as:

$$f(x) = w_{1,1}^{(2)}h_1 + w_{1,2}^{(2)}h_2 + b^{(2)}$$

$$h_1 = \text{ReLU}(w_{1,1}^{(1)}x + b_1^{(1)})$$

$$h_2 = \text{ReLU}(w_{2,1}^{(1)}x + b_2^{(1)})$$

For what values of x is $\frac{\partial f}{\partial w_{1,1}^{(1)}} \neq 0$? Express your answer in terms of h_j , $w_{j,k}^{(l)}$, and/or $b_k^{(l)}$ for any values of j , k , and/or l that may be useful to you.

Question 7 (7 points)

You are standing on a downward-sloping hillside, with your camera pointed straight ahead of you. Parallel to your line of sight, on your left-hand side (at position $x = -2$ meters), there is a low fence (height 1 meter). The fence descends the hill in front of you, vanishing into a point far in the distance. Let (x', y') denote the position of the fence's vanishing point on your photograph, where x' is horizontal position, y' is vertical position, and $(0, 0)$ is the point directly corresponding to your line of sight.

- Is $x' < 0$, $x' = 0$, or $x' > 0$? Explain.
- Is $y' < 0$, $y' = 0$, or $y' > 0$? Explain.