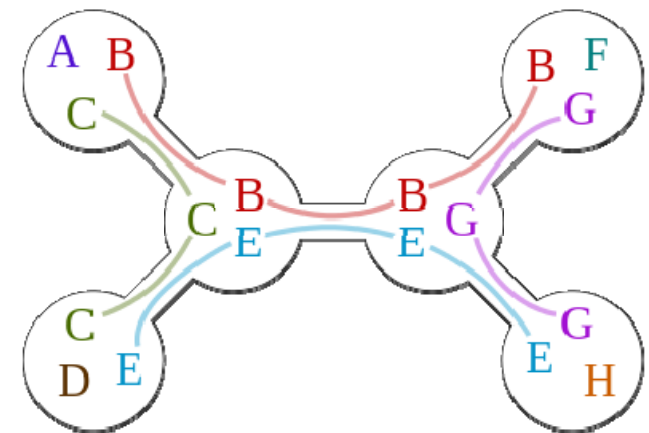
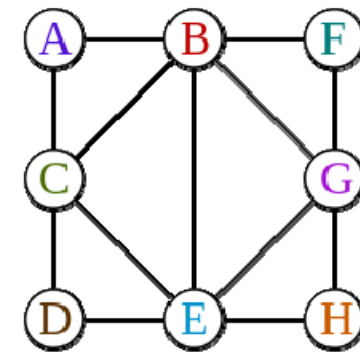
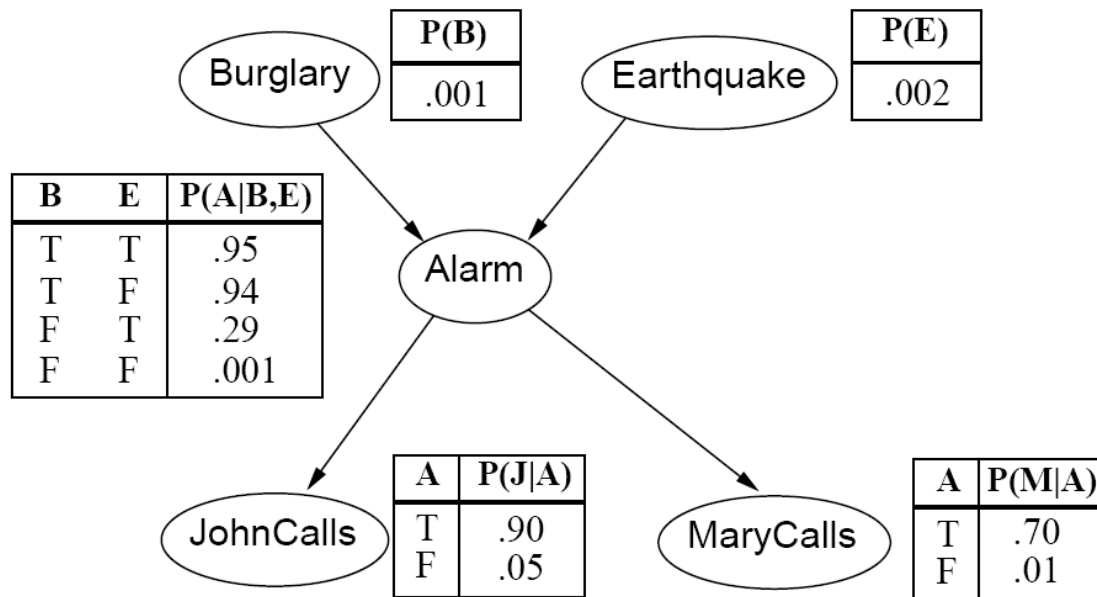


CS 440/ECE448 Lecture 18:

Bayes Net Inference

Mark Hasegawa-Johnson, 3/2018

Including slides by Svetlana Lazebnik, 11/2016



Bayes Network Inference & Learning

Bayes net is a **memory-efficient model** of dependencies among:

- Query *variables*: X
- Evidence (*observed*) variables and their values: $E = e$
- Unobserved variables: Y

Inference problem: answer questions about the query variables given the evidence variables

- This can be done using the posterior distribution $P(X \mid E = e)$
- The posterior can be derived from the full joint $P(X, E, Y)$
- How do we make this **computationally efficient**?

Learning problem: given some training examples, how do we learn the parameters of the model?

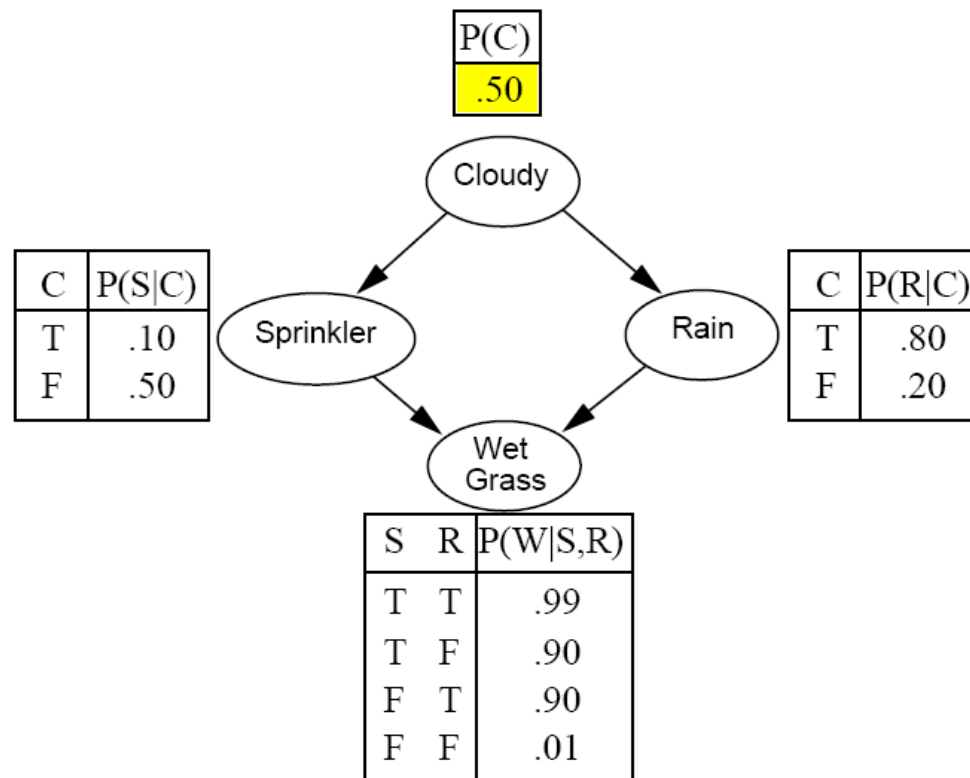
- Parameters = $p(\text{variable} \mid \text{parents})$, for each variable in the net

Outline

- Inference Examples
- Inference Algorithms
 - Trees: Sum-product algorithm
 - Poly-trees: Junction tree algorithm
 - Graphs: No polynomial-time algorithm
- Parameter Learning

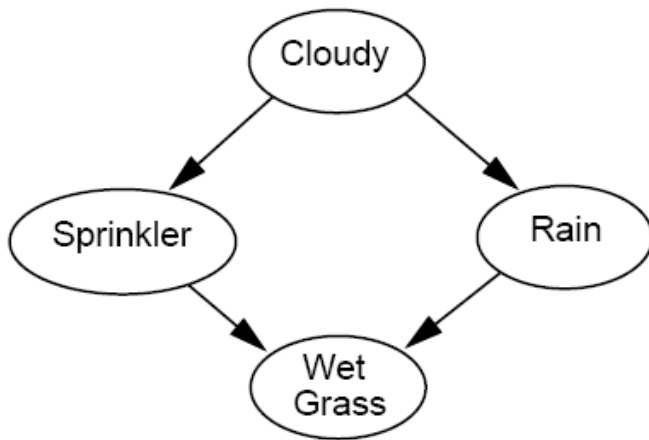
Practice example 1

- Variables: *Cloudy, Sprinkler, Rain, Wet Grass*



Practice example 1

- Given that the grass is wet, what is the probability that it has rained?



$$P(r | w) = \frac{P(r, w)}{P(w)} = \frac{\sum_{C=c, S=s} P(c, s, r, w)}{\sum_{C=c, S=s, R=r} P(c, s, r, w)}$$
$$= \frac{\sum_{C=c, S=s} P(c)P(s | c)P(r | c)P(w | r, s)}{\sum_{C=c, S=s, R=r} P(c)P(s | c)P(r | c)P(w | r, s)}$$

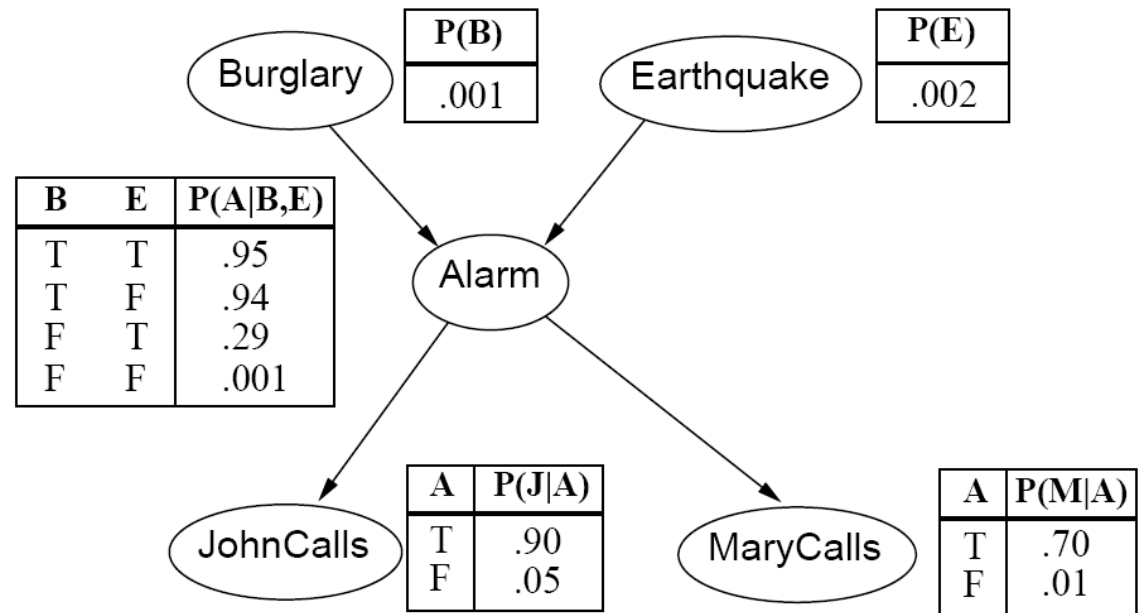
Practice Example #2

- Suppose you have an observation, for example, “Jack called” ($J=1$)
- You want to know: was there a burglary?
- You need

$$P(B|J = 1) = \frac{P(B, J = 1)}{\sum_j P(B, J = j)}$$

- So you need to compute the table $P(B, J)$ for all possible settings of (B, J)

Bayes Net Inference: The Hard Way



$$1. P(B,E,A,J,M)=P(B)P(E)P(A|B,E)P(J|A)P(M|A)$$

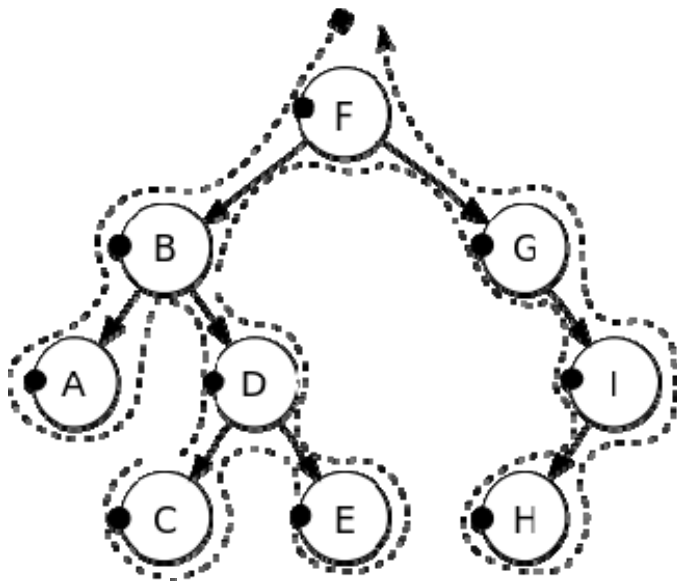
$$2. P(B,J) = \sum_E \sum_A \sum_M P(B,E,A,J,M)$$

Exponential complexity (#P-hard, actually): N variables, each of which has K possible values $\Rightarrow O\{K^N\}$ time complexity

Is there an easier way?

- Tree-structured Bayes nets: the sum-product algorithm
 - Quadratic complexity, $O\{NK^3\}$
- Polytrees: the junction tree algorithm
 - Pseudo-polynomial complexity, $O\{NK^M\}$, for $M < N$
- Arbitrary Bayes nets: #P complete, $O\{K^N\}$
 - The SAT problem is a Bayes net!
- Parameter Learning

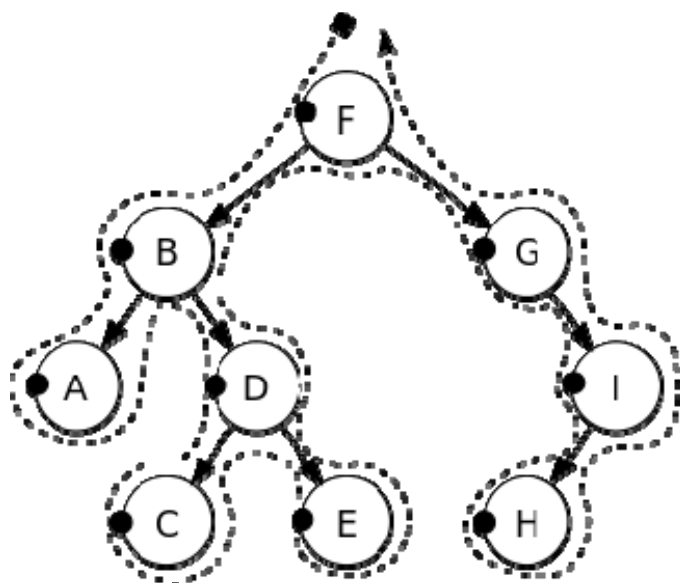
1. Tree-Structured Bayes Nets



- Suppose these are all binary variables.
- We observe $E=1$
- We want to find $P(H=1|E=1)$
- Means that we need to find both $P(H=0, E=1)$ and $P(H=1, E=1)$ because

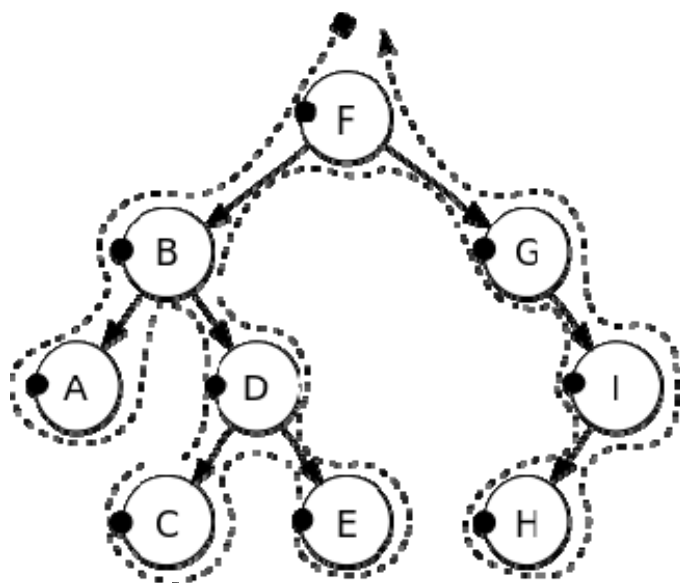
$$P(H = 1|E = 1) = \frac{P(H = 1, E = 1)}{\sum_h P(H = h, E = 1)}$$

The Sum-Product Algorithm (Belief Propagation)



- Find the only undirected path from the evidence variable to the query variable (EDBFG)
- Find the directed root of this path $P(F)$
- Find the joint probability of root and evidence: $P(F, E=1)$
- Find the joint probability of query and evidence: $P(H, E=1)$

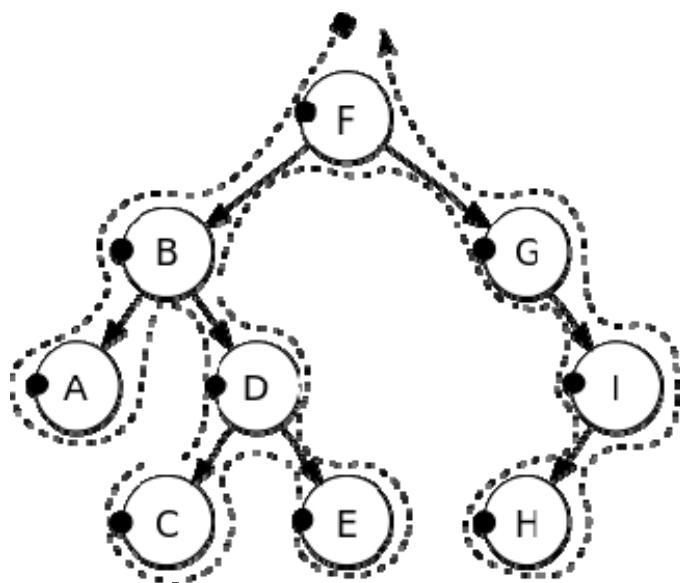
The Sum-Product Algorithm (Belief Propagation)



Starting with the root $P(F)$, we find $P(F,E)$ by alternating product steps and sum steps:

1. Product: $P(B,D,F) = P(F)P(B|F)P(D|B)$
2. Sum: $P(D,F) = \sum_B P(B,D,F)$
3. Product: $P(D,E,F) = P(D,F)P(E|D)$
4. Sum: $P(E,F) = \sum_D P(D,E,F)$

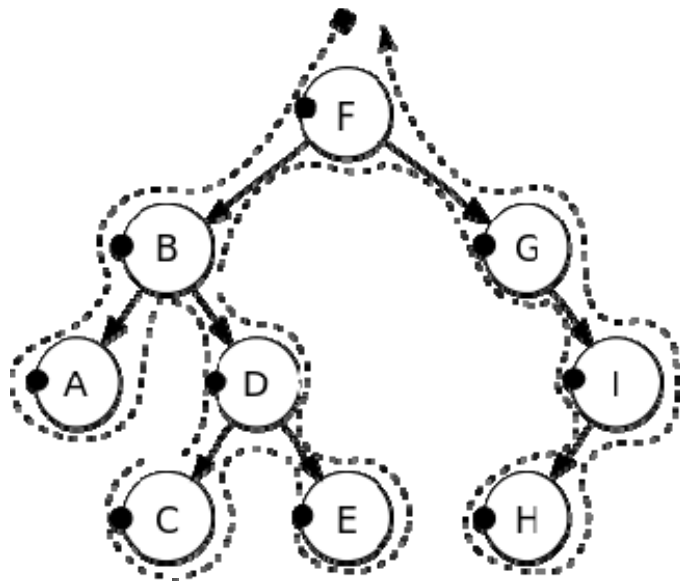
The Sum-Product Algorithm (Belief Propagation)



Starting with the root $P(E, F)$, we find $P(E, H)$ by alternating product steps and sum steps:

1. Product: $P(E, F, G) = P(E, F)P(G|F)$
2. Sum: $P(E, G) = \sum_F P(E, F, G)$
3. Product: $P(E, G, I) = P(E, G)P(I|G)$
4. Sum: $P(E, I) = \sum_G P(E, G, I)$
5. Product: $P(E, H, I) = P(E, I)P(I|G)$
6. Sum: $P(E, H) = \sum_I P(E, H, I)$

Time Complexity of Belief Propagation



- Each product step generates a table with 3 variables
- Each sum step reduces that to a table with 2 variables
- If each variable has K values, and if there are $O\{N\}$ variables on the path from evidence to query, then time complexity is $O\{NK^3\}$

Time Complexity of Bayes Net Inference

- Tree-structured Bayes nets: the sum-product algorithm
 - Quadratic complexity, $O\{NK^3\}$
- Polytrees: the junction tree algorithm
 - Pseudo-polynomial complexity, $O\{NK^M\}$, for $M < N$
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 - The SAT problem is a Bayes net!
- Parameter Learning

2. The Junction Tree Algorithm

- a. Moralize the graph (identify each variable's Markov blanket)
- b. Triangulate the graph (eliminate undirected cycles)
- c. Create the junction tree (form cliques)
- d. Run the sum-product algorithm on the junction tree

2.a. Markov Blanket

- Suppose there is a Bayes net with variables A,B,C,D,E,F,G,H
- The “Markov blanket” of variable F is D,E,G if

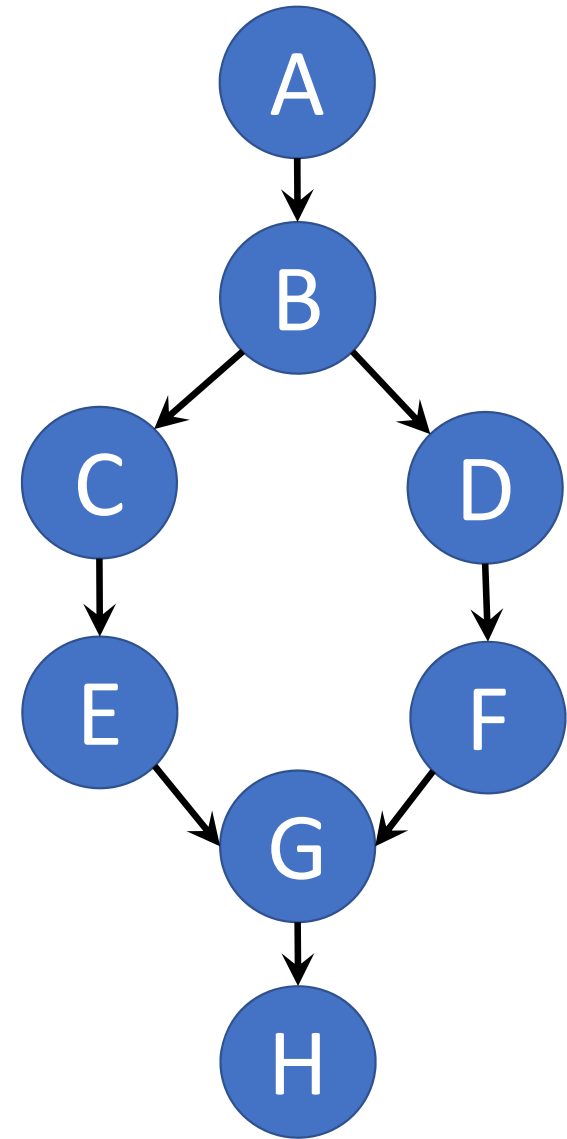
$$\begin{aligned} P(F | A,B,C,D,E,G,H) \\ = P(F | D,E,G) \end{aligned}$$



2.a. Markov Blanket

- Suppose there is a Bayes net with variables A,B,C,D,E,F,G,H
- The “Markov blanket” of variable F is D,E,G if

$$P(F | A, B, C, D, E, G, H) \\ = P(F | D, E, G)$$

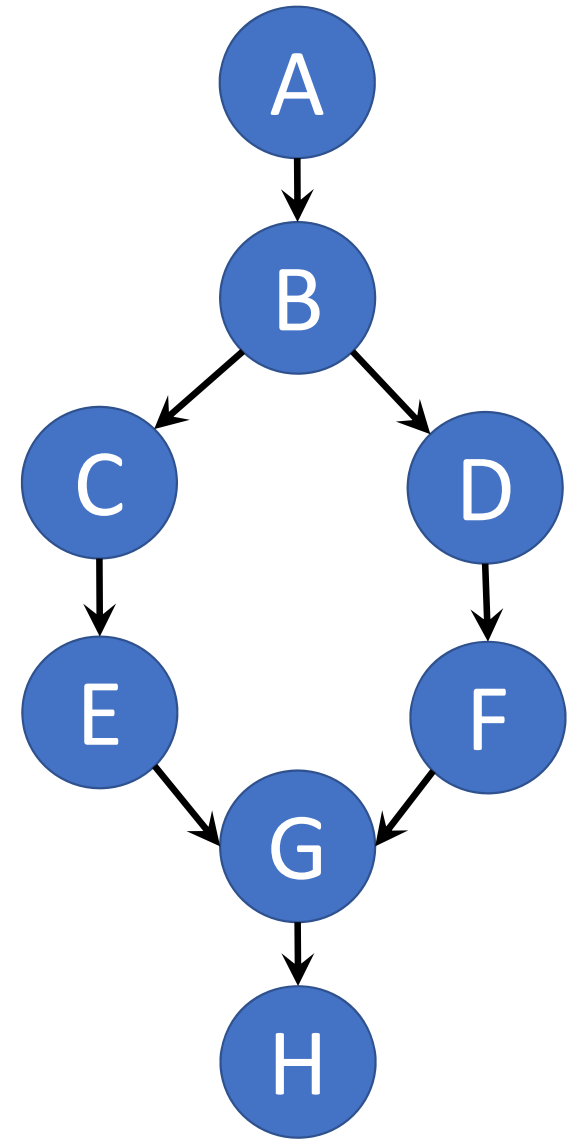


2.a. Markov Blanket

- The “Markov blanket” of variable F is D,E,G if

$$P(F|A,B,C,D,E,G,H) \\ = P(F|D,E,G)$$

- How can we prove that?
- $P(A,...,H) = P(A)P(B|A) \dots$
- Which of those terms include F?



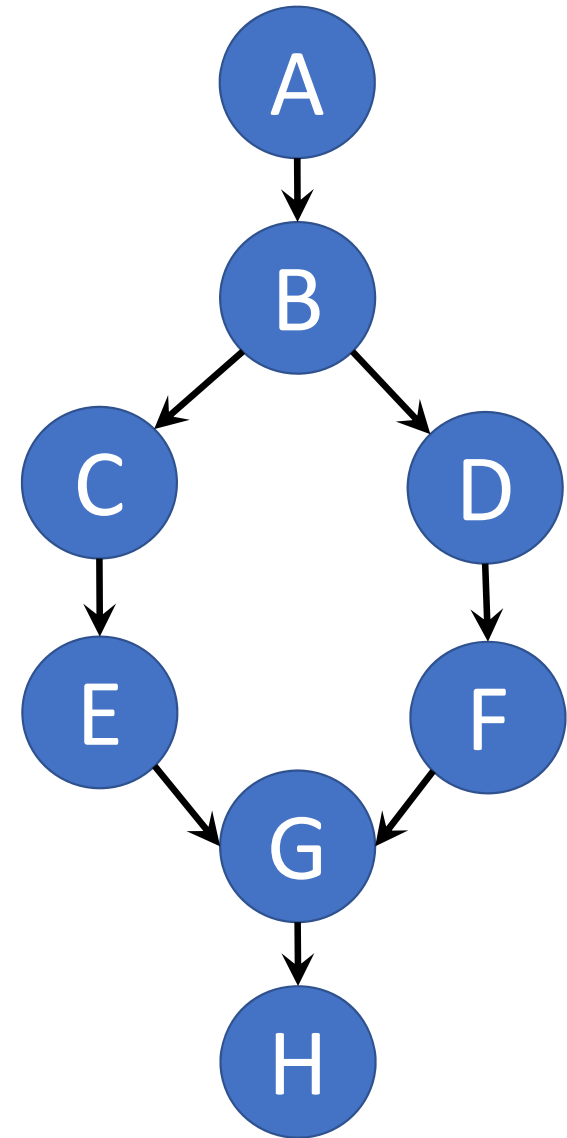
2.a. Markov Blanket

- Which of those terms include F?
- Only these two:

$$P(F | D)$$

and

$$P(G | E, F)$$



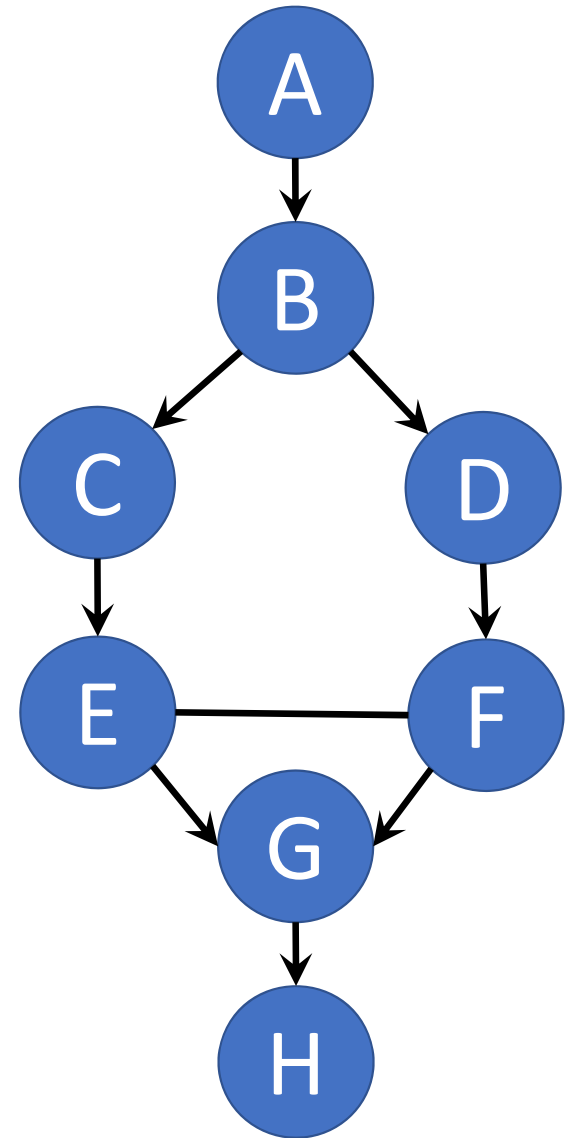
2.a. Markov Blanket

The Markov Blanket of variable F includes only its immediate family members:

- Its parent, D
- Its child, G
- The other parent of its child, E



$$\begin{aligned} \text{Because } P(F | A, B, C, D, E, G, H) \\ = P(F | D, E, G) \end{aligned}$$

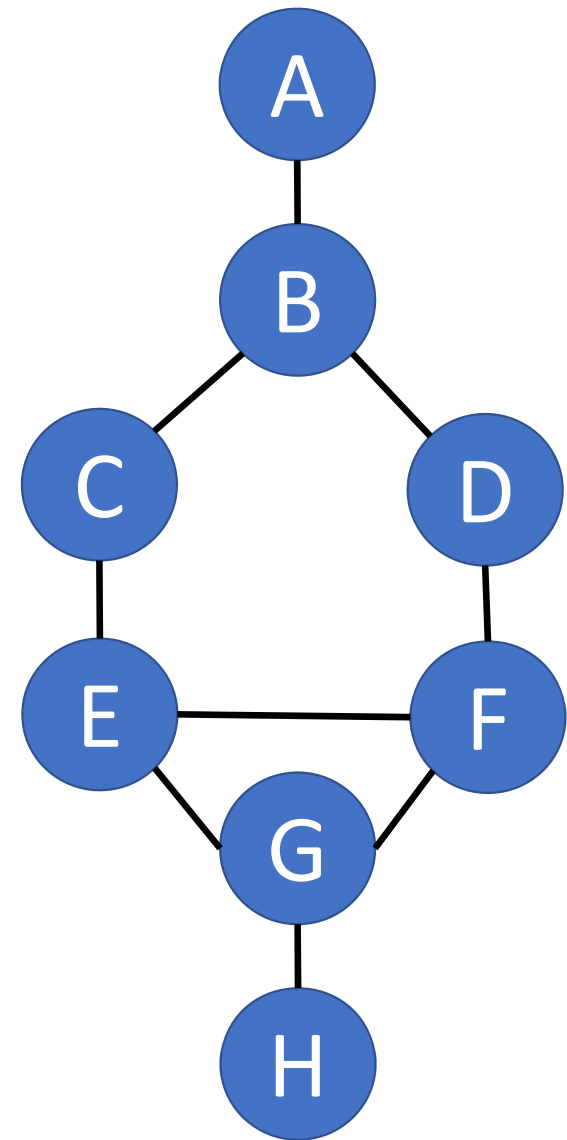


2.a. Moralization

“Moralization” =

1. If two variables have a child together, force them to get married.
2. Get rid of the arrows (not necessary any more).

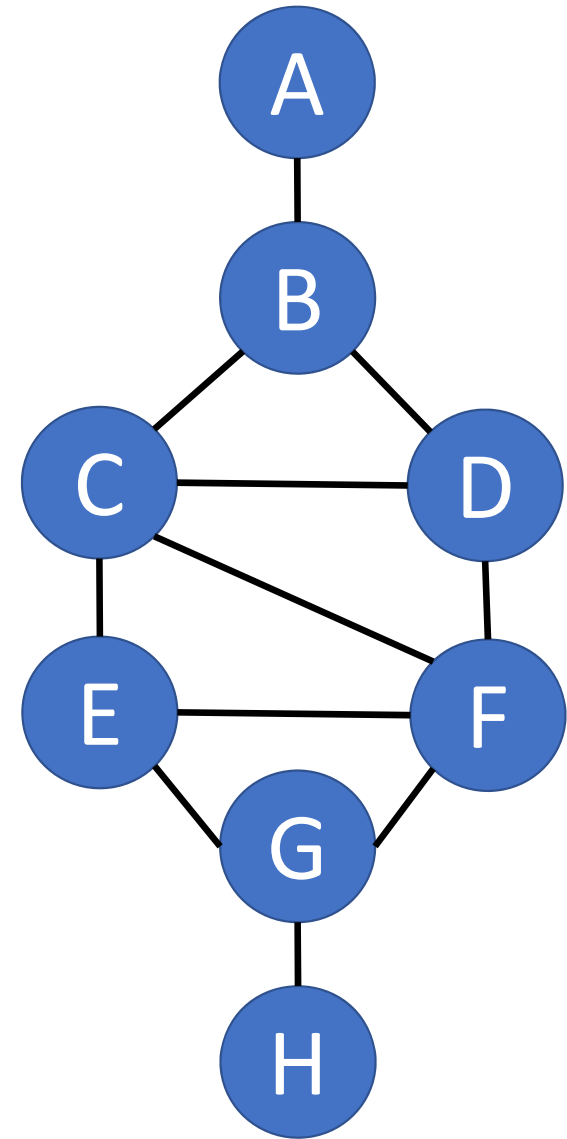
Result: Markov blanket = the set of variables to which a variable is connected.



2.b. Triangulation

Triangulation = draw edges so that there is no unbroken cycle of length > 3 .

There are usually many different ways to do this. For example, here's one:

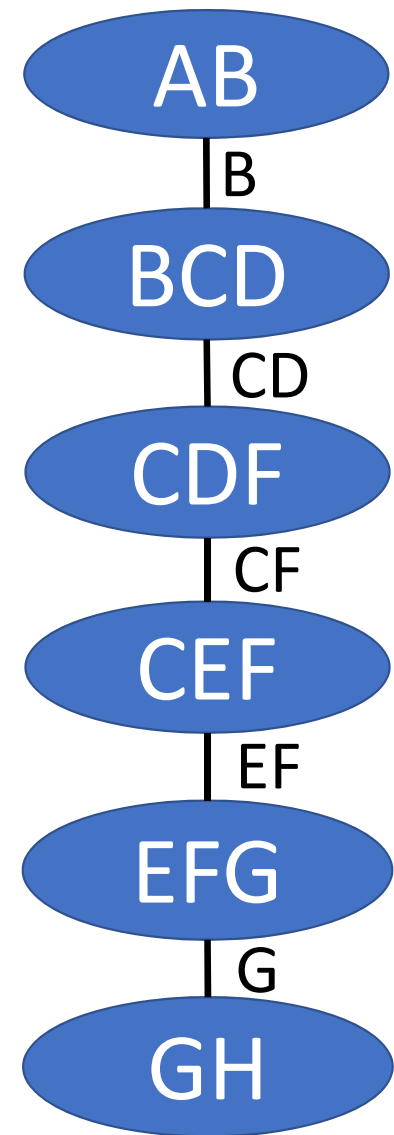
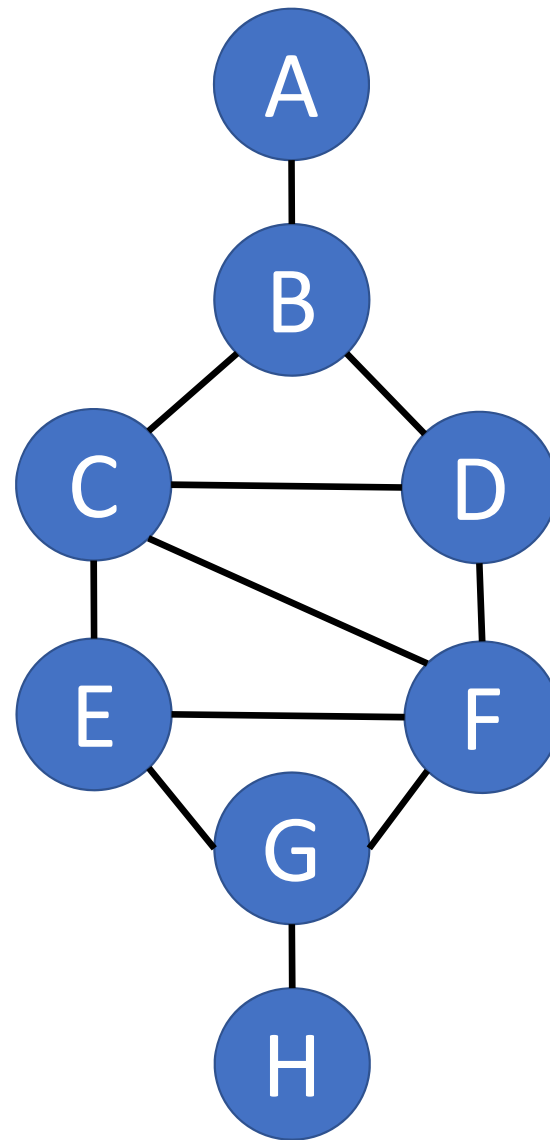


2.c. Form Cliques

Clique = a group of variables, all of whom are members of each other's immediate family.

Junction Tree = a tree in which

- Each node is a clique from the original graph,
- Each edge is an “intersection set,” naming the variables that overlap between the two cliques.

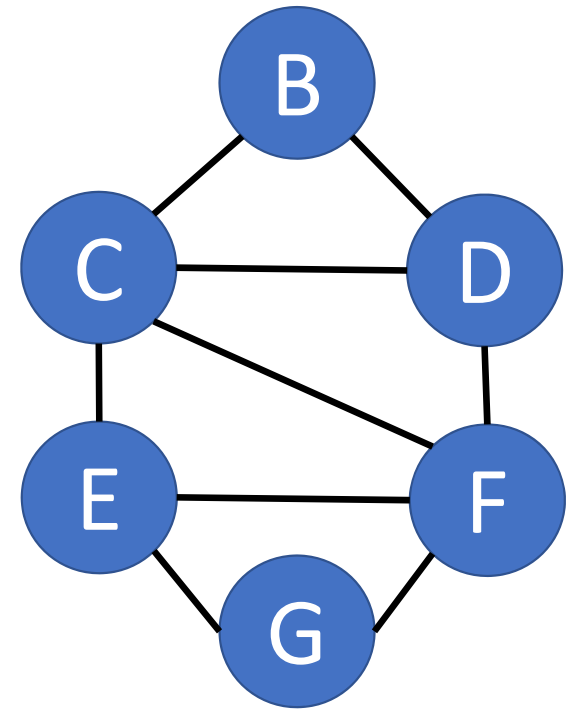


2.d. Sum-Product

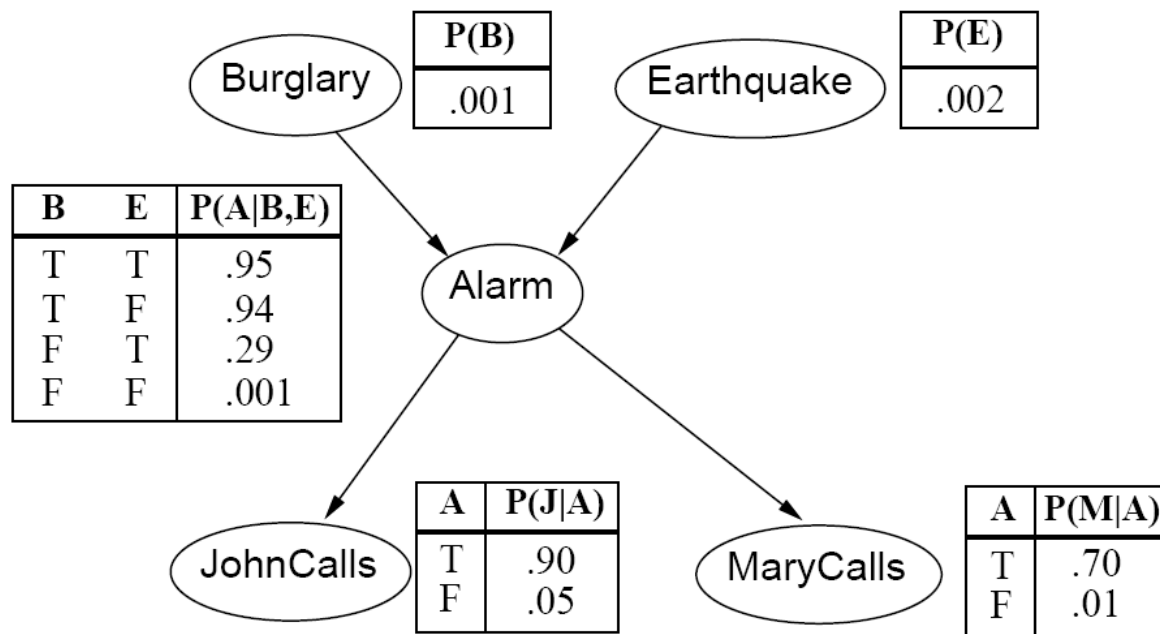
Suppose we need $P(B, G)$:

1. Product: $P(B, C, D, F) = P(B)P(C|B)P(D|B)P(F|D)$
2. Sum: $P(B, C, F) = \sum_D P(B, C, D, F)$
3. Product: $P(B, C, E, F) = P(B, C, F)P(E|C)$
4. Sum: $P(B, E, F) = \sum_C P(B, C, E, F)$
5. Product: $P(B, E, F, G) = P(B, E, F)P(G|E, F)$
6. Sum: $P(B, G) = \sum_E \sum_F P(B, E, F, G)$

Complexity: $O\{NK^M\}$, where $N = \# \text{ cliques}$,
 $K = \# \text{ values for each variable}$,
 $M = 1 + \# \text{ variables in the largest clique}$



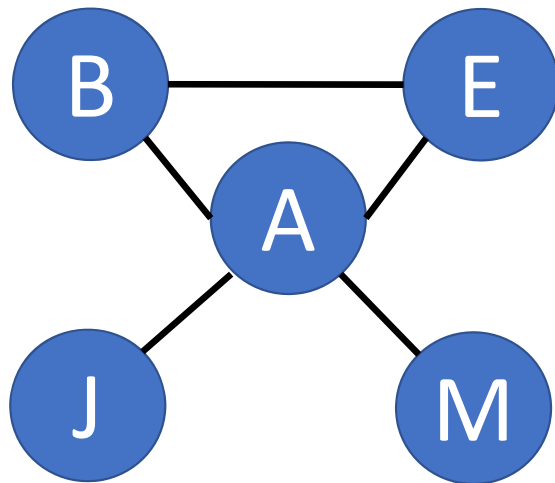
Junction Tree: Sample Test Question



Consider the burglar alarm example.

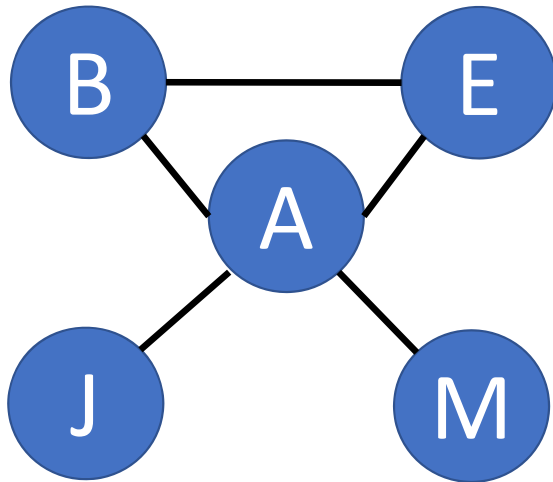
- Moralize this graph
- Is it already triangulated? If not, triangulate it.
- Draw the junction tree

Solution



a. Moralize this graph

Solution

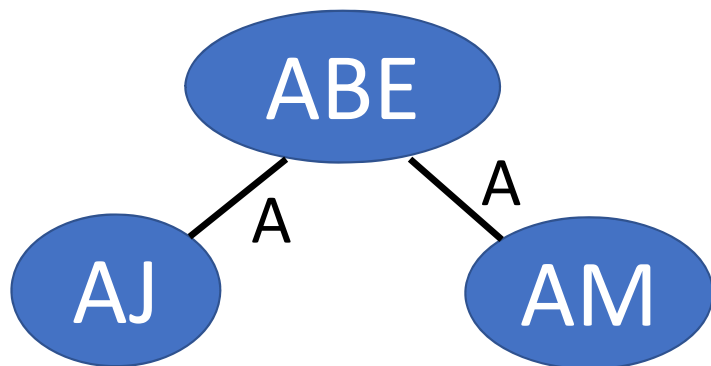


b. Is it already triangulated?

Answer: yes. There is no unbroken cycle of length > 3 .

Solution

c. Draw the junction tree



Time Complexity of Bayes Net Inference

- Tree-structured Bayes nets: the sum-product algorithm
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Bayesian network inference

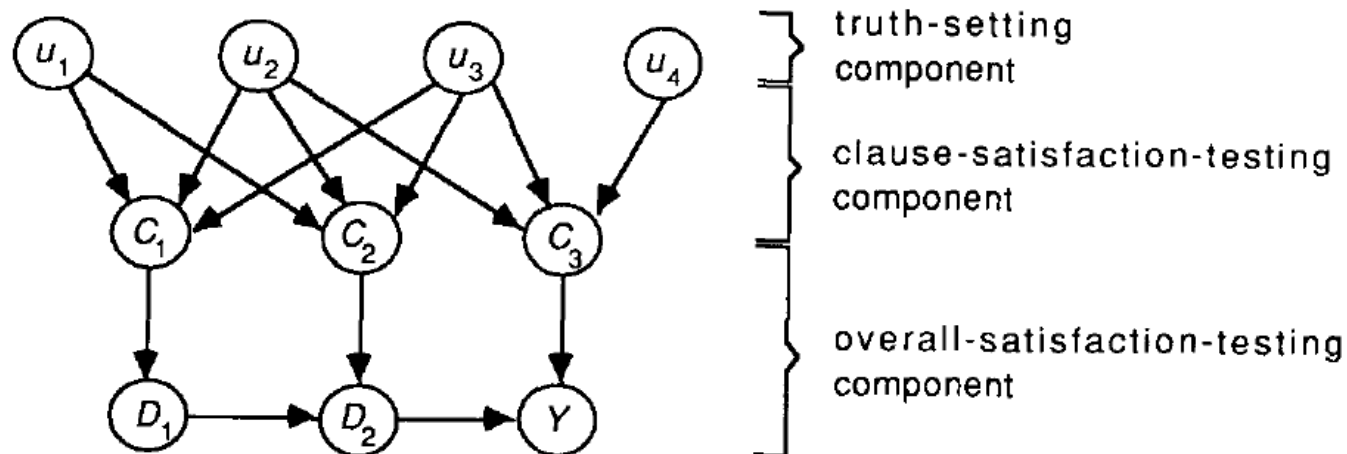
- In full generality, NP-hard
 - More precisely, #P-hard: equivalent to counting satisfying assignments
- We can reduce **satisfiability** to Bayesian network inference
 - Decision problem: is $P(Y) > 0$?

$$Y = (U_1 \vee U_2 \vee U_3) \wedge (\neg U_1 \vee \neg U_2 \vee U_3) \wedge (U_2 \vee \neg U_3 \vee U_4)$$

Bayesian network inference

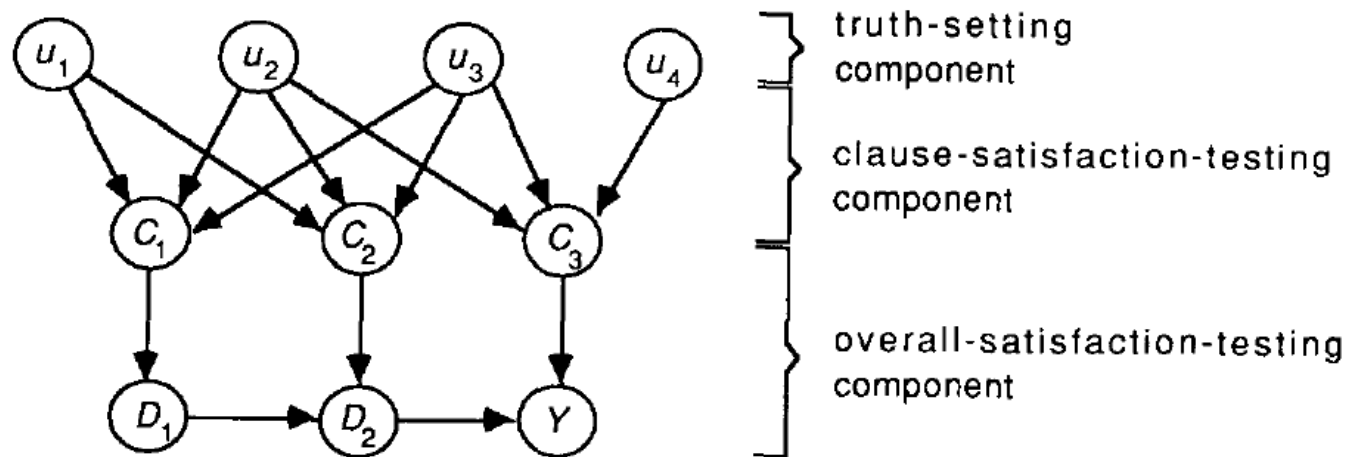
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$$Y = \underbrace{(U_1 \vee U_2 \vee U_3)}_{C_1} \wedge \underbrace{(\neg U_1 \vee \neg U_2 \vee U_3)}_{C_2} \wedge \underbrace{(U_2 \vee \neg U_3 \vee U_4)}_{C_3}$$



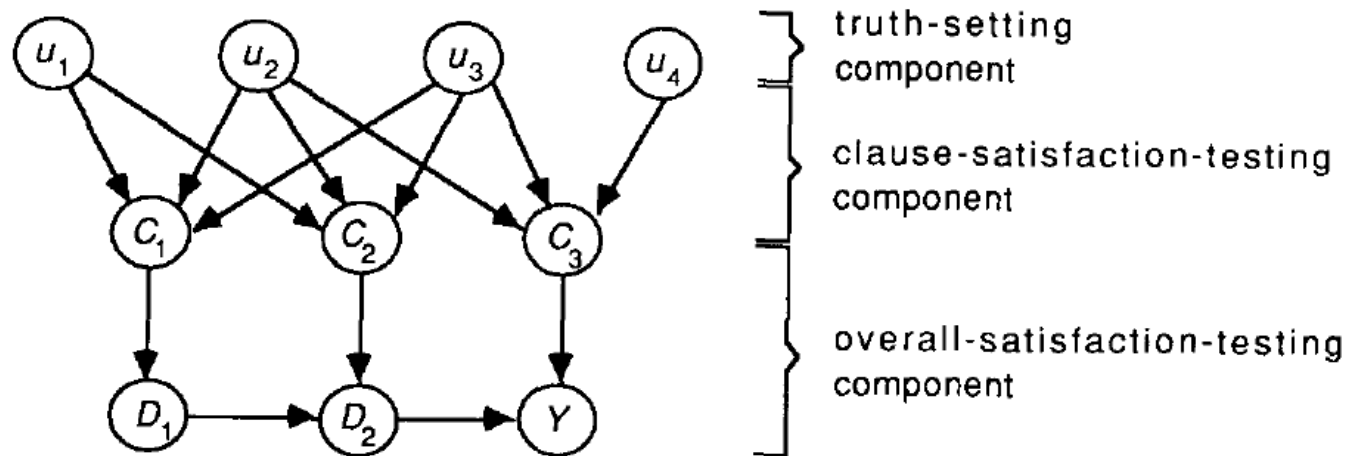
G. Cooper, 1990

Bayesian network inference



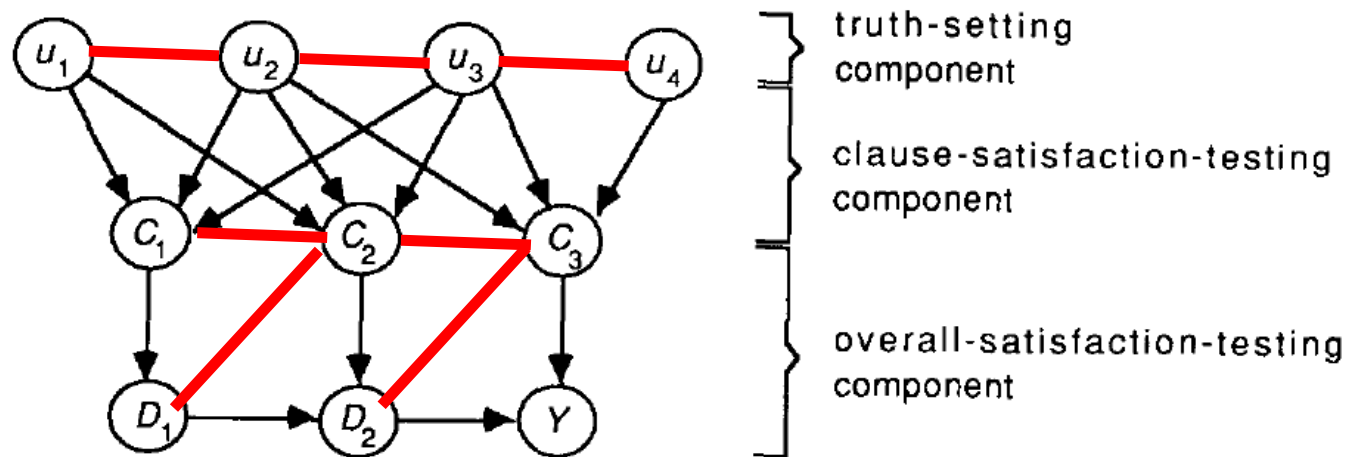
$$\begin{aligned} P(U_1, U_2, U_3, U_4, C_1, C_2, C_3, D_1, D_2, Y) = & \\ P(U_1)P(U_2)P(U_3)P(U_4) & \\ P(C_1 | U_1, U_2, U_3)P(C_2 | U_1, U_2, U_3)P(C_3 | U_2, U_3, U_4) & \\ P(D_1 | C_1)P(D_2 | D_1, C_2)P(Y | D_2, C_3) & \end{aligned}$$

Bayesian network inference



Why can't we use the junction tree algorithm to efficiently compute $\Pr(Y)$?

Bayesian network inference



Why can't we use the junction tree algorithm to efficiently compute $\Pr(Y)$?

Answer: after we moralize and triangulate, the size of the largest clique ($u_2 u_3 c_1 c_2 c_3$) is $M \approx N$, same order of magnitude as the original problem

Time Complexity of Bayes Net Inference

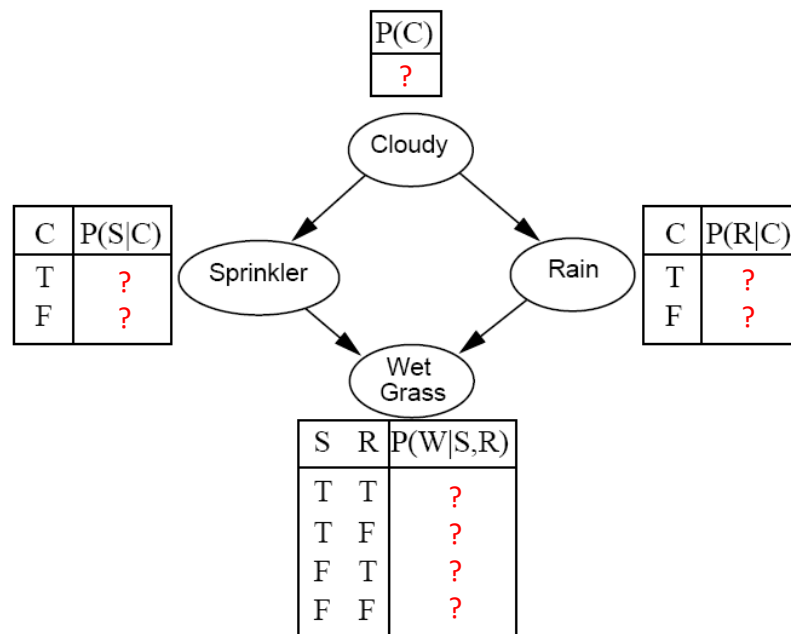
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 - The SAT problem is a Bayes net!
- **Parameter Learning**

Parameter learning

- **Inference problem:** given values of evidence variables $\mathbf{E} = \mathbf{e}$, answer questions about query *variables* \mathbf{X} using the posterior $P(\mathbf{X} \mid \mathbf{E} = \mathbf{e})$
- **Learning problem:** estimate the parameters of the probabilistic model $P(\mathbf{X} \mid \mathbf{E})$ given a *training sample* $\{(\mathbf{x}_1, \mathbf{e}_1), \dots, (\mathbf{x}_n, \mathbf{e}_n)\}$

Parameter learning

- Suppose we know the network structure (but not the parameters), and have a training set of *complete* observations



Training set

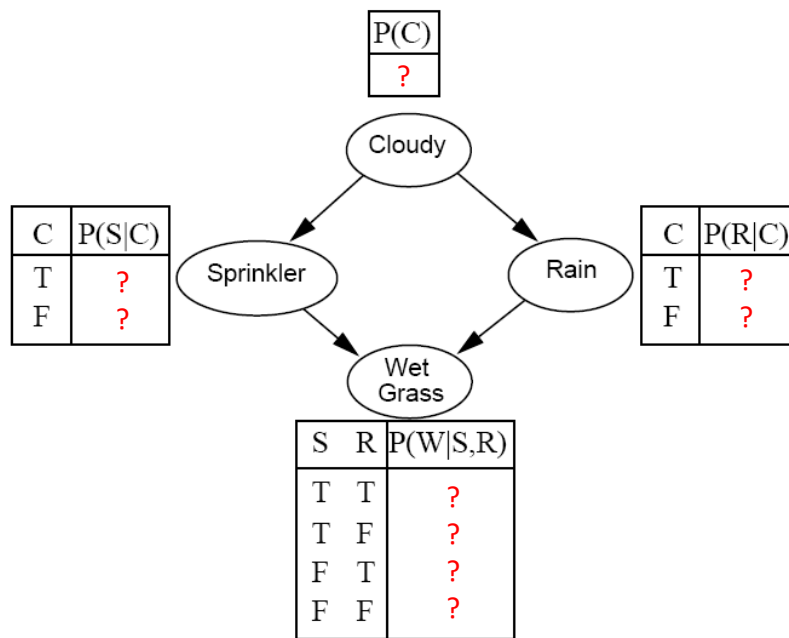
Sample	C	S	R	W
1	T	F	T	T
2	F	T	F	T
3	T	F	F	F
4	T	T	T	T
5	F	T	F	T
6	T	F	T	F
...

Parameter learning

- Suppose we know the network structure (but not the parameters), and have a training set of *complete* observations
 - $P(X \mid \text{Parents}(X))$ is given by the observed frequencies of the different values of X for each combination of parent values

Parameter learning

- Incomplete observations



with missing data

Training set

Sample	C	S	R	W
1	?	F	T	T
2	?	T	F	T
3	?	F	F	F
4	?	T	T	T
5	?	T	F	T
6	?	F	T	F
...

Parameter learning: EM

Sample	C	S	R	W
1	?	F	T	T
2	?	T	F	T
3	?	F	F	F
4	?	T	T	T
5	?	T	F	T
6	?	F	T	F
...

- E-STEP:
 - Find $P(C_n|S_n, R_n, W_n)$ for $1 \leq n \leq 6$
 - Find $E[\# \text{ times } C_n = T, S_n = T]$ by adding up the values of $P(C_n|S_n, R_n, W_n)$
- M-STEP:
 - Re-estimate the parameters as $P(C_n = T|S_n = T) \leftarrow E[\# \text{ times } C_n = T, S_n = T] / E[\# \text{ times } S_n = T]$

Summary: Bayesian networks

- Structure
- Parameters
- Inference
- Learning