

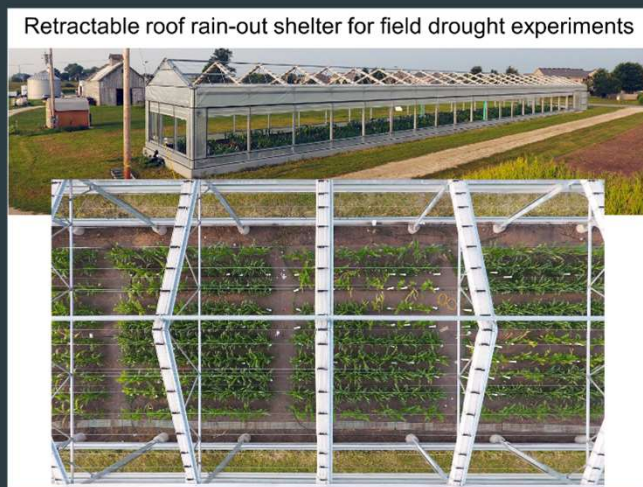
Underground Root Imaging System

Sr Design Project



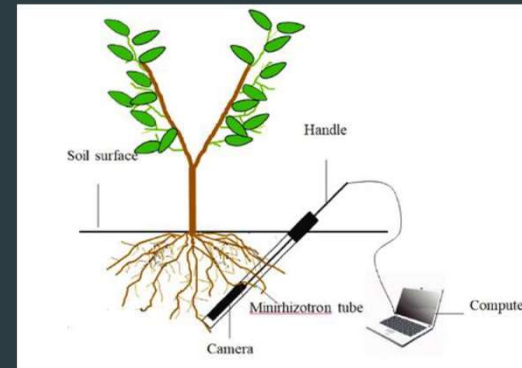
Main Focus of Agriculture Research

- ▶ Create New Breeds of Food Crops Resistant to Climate Change
- ▶ Grow Test Plots and Collect Phenotype Data to Evaluate
- ▶ Continue Process Until Water Efficient Breed is Established



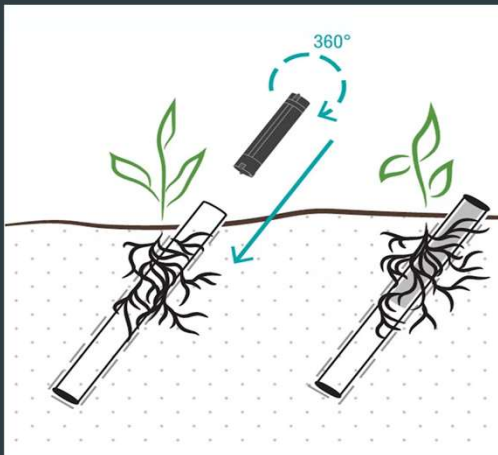
Data Collection in the Field

- ▶ Collect Phenotype Data of Roots
- ▶ Clear Acrylic Tubes Placed in Ground Under Plants
- ▶ Camera Inserted to Capture Root Growth
- ▶ Tedious and Time-Consuming Method



Difficulties of Current Approach

- ▶ Scanner Components are Not Durable Enough for Extended Field Use
- ▶ Solution is Not Portable
- ▶ Multiple Axis of Travel (Rotational and Depth)
- ▶ Image Collection Prone to Errors



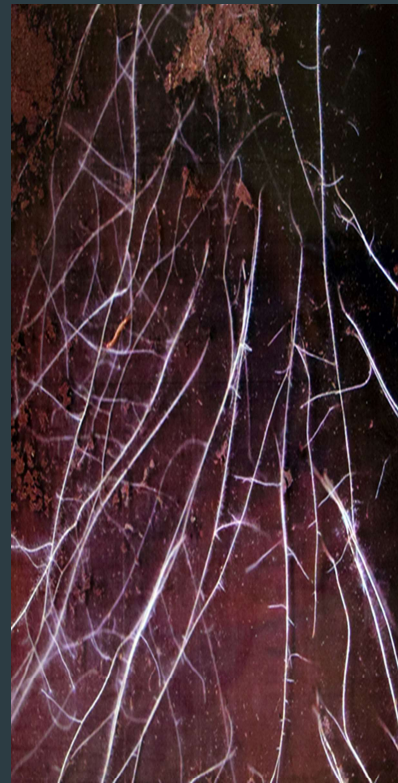
Goals for Capstone Project

- ▶ Devise a System Based on the Following Novel Design for Efficient Image Capture of Roots that Utilizes a Hemispherical Camera
 - ▶ Develop Camera System and Triggering to Capture Underground Images
 - ▶ Obtain Suitable Camera Imaging of Roots at Desired Depths
 - ▶ Record Location of Individual Root Tubes in the Field
 - ▶ Transfer Image Data From Device to Remote Storage
 - ▶ Process Hemispherical Image into Separate Planar Images for Analysis
 - ▶ Test System in the Field and Adjust Design If Necessary



Innovative Approach Desired

- ▶ Meet with Agriculture/Engineering Group
- ▶ See Demo of Existing System
- ▶ Use Automation and State of the Art Equipment
- ▶ Design for Ruggedization
 - ▶ High Moisture
 - ▶ Heavy Usage (100K+ images a season)
 - ▶ Transported All Over Midwest
 - ▶ Drop and Vibration Resistant



Project Support Group

- ▶ Professor Andrew Leakey
 - ▶ *Michael Aiken Chair* Professor of Plant Biology (IGB)
 - ▶ Jeremy Ruhter
 - ▶ Farm Field Technician
 - ▶ John M. Hart
 - ▶ Principal Research Engineer (CSL) and
 - ▶ Manager and Coordinator of the CfA Robotics Labs
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