

# **AUTOMATIC HANDSHAKE CONTACT INFO EXCHANGER**

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By

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# 1. Introduction

## 1.1 Title

### Automatic Handshake Contact Info Exchanger

We selected to design this device in order to improve the way people exchange their contact information with each other. Instead of taking time to exchange information and wasting paper with business cards, you could automatically receive contact information with the shake of a hand. We are excited about doing this project because we believe that it would be useful to a lot of people in the business world.

## 1.2 Objectives

### 1.2.1 Goals

- To create a device that would be able to wirelessly transmit and receive contact information with a handshake
- To make the device as small as possible and be able to be worn by the user
- To make the product marketable if design is successful

### 1.2.2 Functions

- Wirelessly transmit data between two devices on the detection of a handshake
- The device will have 4 modes of operations: On/Off, Transmit Only, Receive Only, Receive & Transmit
- Data can be uploaded to a personal computer

### 1.2.3 Features

- A gyroscope and accelerometer to detect handshake
- Information being transmitted includes name, phone numbers, email, company name, position/title, address and URL
- If basic data transfer is successful then add the ability to transfer a picture along with contact information
- Device is completely wireless for the user

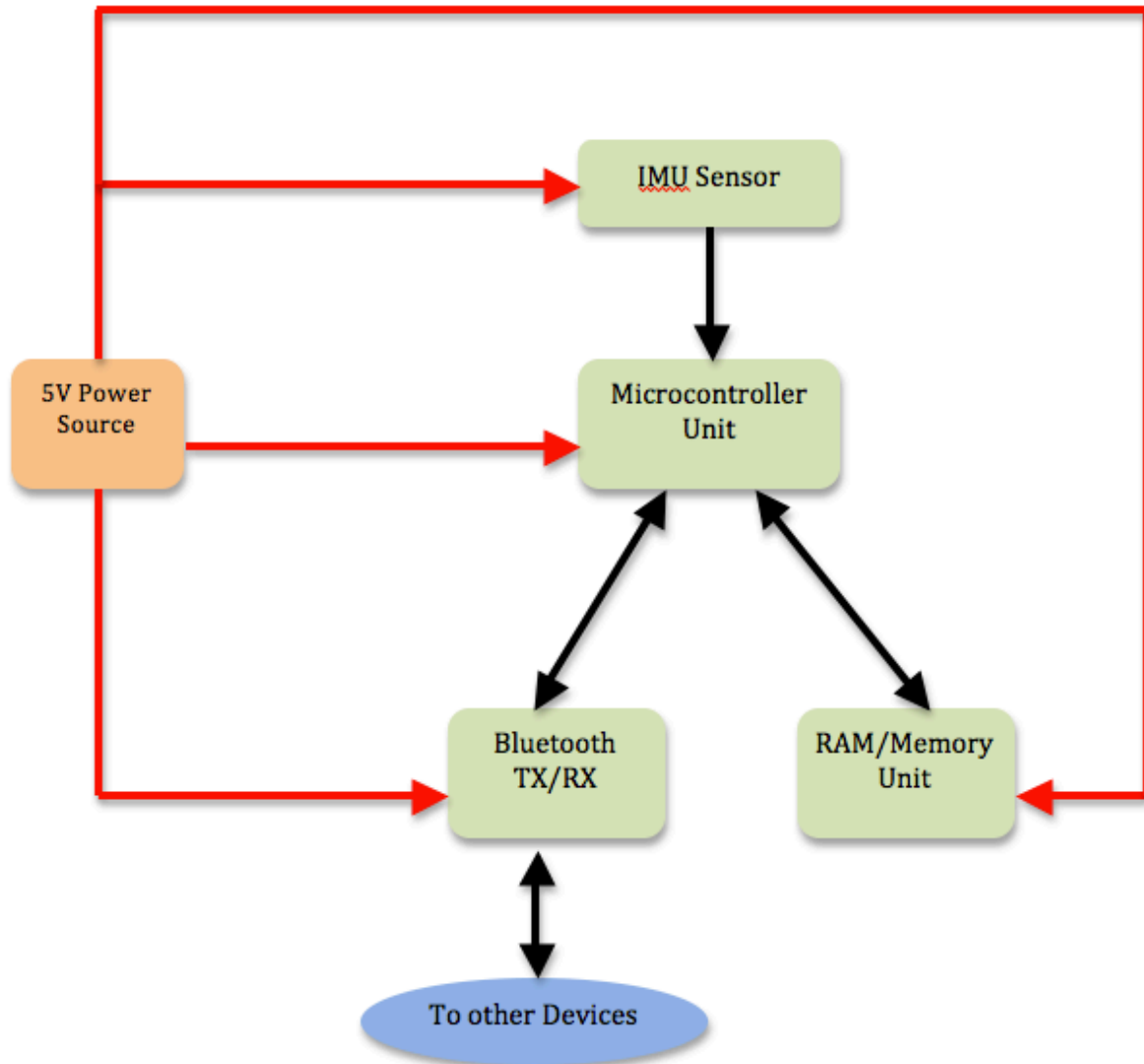
### 1.2.4 Benefits

- Quick exchange of contact information
- Availability of linked photograph allows user to quickly remember the person by face even if the user forgets the name

- Eliminate the need to print new business cards whenever information is updated
- Easy organization and access of contact information (reduces the need to carry around huge numbers of business cards; reduces risk of accidentally losing someone's business card)

## 2. Design

### 2.1 Block Diagram



—	Power Flow
—	Data Flow

## 2.2 Block Descriptions

### 2.1.1 Microcontroller Unit:

The microcontroller will be used to process received and transmitted data and store or fetch the coded data from the RAM/memory. It will also be responsible for controlling the flow of data throughout the device. It will specify the mode of communication between the two devices (Transmit only, receive only, ON/OFF, and swap).

### 2.1.2 IMU Sensor:

The IMU sensor will be the part of the circuit that detects when a handshake between two users is detected. It will be made up of an accelerometer and gyroscope that is able to sense the motion of the user's hand. When a handshake is detected it will send a signal to the microcontroller unit telling it to communicate with the other device.

### 2.1.3 RAM/Memory Unit:

The RAM unit will be in charge of storing the code words that will be transmitted between the two devices. The microcontroller will have direct access to the contents of the RAM. The memory size needs to be large enough to store up to about 100 users information.

### 2.1.4 Bluetooth Tx/Rx:

The Bluetooth transceiver will be used to send and receive the data being transmitted wirelessly between the two devices. The device can be low power because the communication range between two devices will always be less than 1 meter. Since the files being transmitted are generally small duration of communication time will also be low. The transceiver will use the microcontroller as a host to process the data.

### 2.1.5 Power Source:

The power source for the circuit components will be a small 3V button cell batteries. If needed, the cells will be connected in series to make a 6V source and a voltage regulator will be used to step down the voltage to 5V.

## 3. Block Level Requirements And Verification

### 3.1 Requirements

#### 3.1.1 Microcontroller Unit:

- Able to properly process and store data when a handshake is detected
- Takes input signal from IMU sensor and outputs data to transceiver to be sent to other device
- Data must be read from memory and processed fast enough (~1 kbps) for complete transmission upon a handshake
- Ability to detect if received data has an error

#### 3.1.2 IMU Sensor:

- Able to accurately detect the motion of a handshake
- Outputs a signal to the microcontroller only when a handshake is detected

#### 3.1.3 RAM/Memory Unit:

- Must have enough memory to store about 100 business cards
- Read/write capabilities and be error free

#### 3.1.4 Bluetooth Tx/Rx:

- Transceiver on each device must be able to exchange data at a range of ~30 cm (max handshake distance)
- Able to transmit and receive data at a rate of ~1kbps for complete data transfer during a handshake

#### 3.1.5 Power Source:

- Considerable lifetime (>3 months) with normal usage

### 3.2 Verification

#### 3.2.1 Microcontroller Unit:

1. Probe the output of the microcontroller to verify that data is being sent to tx/rx unit upon detection of a handshake.
2. Verify that the microcontroller is correctly reading/writing data to and from memory using debugging software.

#### 3.2.2 IMU Sensor:

1. We will view the output of the sensor's accelerometer on the oscilloscope.
2. When the motion of a handshake is detected we will make sure the signal that is sent to the microcontroller goes high with a simple LED driver circuit.



### **3.2.3 RAM/Memory Unit:**

1. We will verify that the memory unit is working correctly by writing random data to memory locations and then reading from those locations to ensure proper function.

### **3.2.4 Bluetooth Tx/Rx:**

1. We can build the tx/rx unit on a breadboard initially in order to test its reliability for the requirements needed for this project.
2. These tests can be completed by writing software to input data serially to one unit and make sure the other unit is receiving the same data.

## **3.3 Tolerance Analysis**

The most important component of our design will be the microcontroller unit. It is used to process the information that is being transmitted between the two devices. Our group will spend a lot of time testing this part of the device.

In order for this project to function the microcontroller must be able to process and transmit data at a fast rate without any errors. Upon detection of a handshake, data needs to be read from the RAM, processed, and sent to the tx/rx unit almost instantly ( $< 0.5s$ ). We will test a variety of different data rates to see how fast data can be processed by the microcontroller without error and with minimum power consumption. The goal is to find a data rate that is fast enough for the required information to be transferred during a typical handshake without error.

## 4. Cost Analysis & Schedule

### 4.1 Cost Estimate

#### 4.1.1 Parts

Table 1: Parts Costs			
Part	Estimated Cost/Unit (\$)	Quantity	Total Cost (\$)
IMU Sensor (Accelerometer)	10.00	2	20.00
Microcontroller (TI MSP 430)	10.00	2	20.00
Bluetooth	20.00	2	40.00
RAM (1MB)	10.00	2	20.00
Power Supply (Lithium 3V button cells)	3.00	1	3.00
Resistors	0.05	60	1.20
Capacitors	0.10	60	6.00
Inductors	0.10	60	6.00
External Manufacturer for PCB	30.00	2	60.00
<b>Total</b>			<b>\$ 176.20</b>

#### 4.1.2 Labor

Table 2: Labor Costs				
Name	Rate/hour	Overhead (x 2.5)	Hours *	Total (\$)
W. Hanley	50	125	180	22,500
K. Samigollayev	50	125	180	22,500
A. Saha	50	125	180	22,500
<b>Total</b>				<b>\$ 67,500</b>

\* Assuming a 15 hour work week for 12 weeks

### 4.1.3 Grand Total

Table 3: Total Costs	
Section	Total (\$)
Parts	176.20
Labor	67,500.00
<b>Total</b>	<b>\$ 67,676.20</b>

## 4.2 Schedule

Week	Task	Person in-charge
<b>February 04</b>	Looking for components	Kuanysh
	Finalizing proposal	Ambieca
	Research circuit components	William
	NOTE: proposal due, mock DR sign-up	Ambieca
<b>February 11</b>	Design microcontroller unit	William
	IMU testing & verification	Kuanysh
	Ordering required parts	Ambieca
<b>February 18</b>	Learn to program microcontroller unit	Ambieca
	Testing & verification of microcontroller unit	William
	Testing & verification of Bluetooth	Kuanysh
	NOTE: DR sign-up	
<b>February 25</b>	Program microcontroller unit	Ambieca
	Testing & verification of memory unit	William
	Interface memory with microcontroller; Learn about PCB layout & footprints	Kuanysh
	NOTE: Design Reviews	
<b>March 04</b>	Debug microcontroller & wireless components	William
	Interface all components of the circuit	Kuanysh
	Create PCB footprints for each hand device	Ambieca
<b>March 11</b>	Debug parts when circuit is put together	Ambieca
	Test communication between two devices	William
	Submit PCB for manufacture	Kuanysh
	*NOTE: Individual progress reports due	

<b>March 18</b>	SPRING BREAK	
<b>March 25</b>	Learn to solder components onto PCB	Kuanysh
	Prepare for mock-up demo / presentation	Ambieca
	Interface data to computer	William
	*NOTE: Mock-up demo, mock-up presentation sign-up	
<b>April 1</b>	Revise PCB	Ambieca
	Continue interfacing data to computer	William
	Incorporate picture transfer if text is working	Kuanysh
	NOTE: Mock-up presentation, last day for first revision of PCB	
<b>April 8</b>	Revise PCB	Ambieca
	Complete assembly of device	William
	Help with PCB board revisions and device assembly	Kuanysh
	NOTE: last day for final revision of PCB	
<b>April 15</b>	Document final paper / Make device wearable	Ambieca
	Overall Project Debugging	Kuanysh
	Start preparation for final demo and presentation	William
	NOTE: demo sign-up & presentation sign-up	
<b>April 22</b>	Prepare presentation	William
	Final Paper work	Ambieca
	Prepare and assemble final demo	Kuanysh
	NOTE: demos and presentations	
<b>April 29</b>	Presentation preparation	William
	Final paper editing & finishing touches	Ambieca
	Finishing touches on overall project	Kuanysh
	NOTE: final paper due, lab notebook due, checkout	