

# Universal Battery Charger/Discharger

ECE 445

Fall 2024

Team 14

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Design Document

# I. Introduction

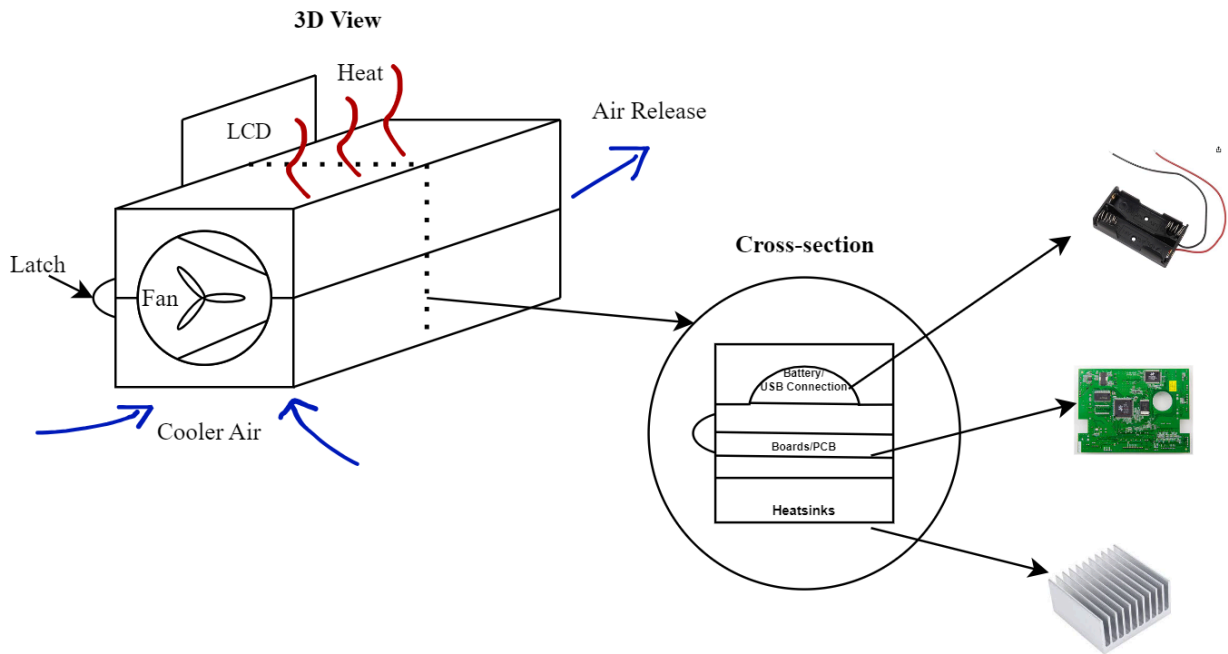
## 1.1 Problem:

Batteries are a common and underestimated fire hazard in many homes, especially where a lack of knowledge meets convenience. There are a rapidly growing number of videos online of trash cans bursting into flames or dogs starting fires by chewing on charge banks. A partially charged battery in a trash compactor could lead to devastating damages, added expenses, and, in severe cases, casualties. As society grows more dependent on portable and sophisticated electronics, proper battery disposal is crucial in preventing potential hazardous situations.

## 1.2 Solution:

A battery discharger that rapidly discharges a battery for safe disposal by using variable paths to maximize current flow within normal battery operating temperatures. Real-time monitoring of circuit and system conditions would allow the system to fine tune the rate of cooling and heat generation to maintain safety as the attached cells expend amp hours. It would also allow quick fault detection and rapid response to battery failure, preventing damaged cells from igniting. The system would also, when directed by the user, charge rechargeable batteries using similar safety margins.

## 1.3 Visual Aid:

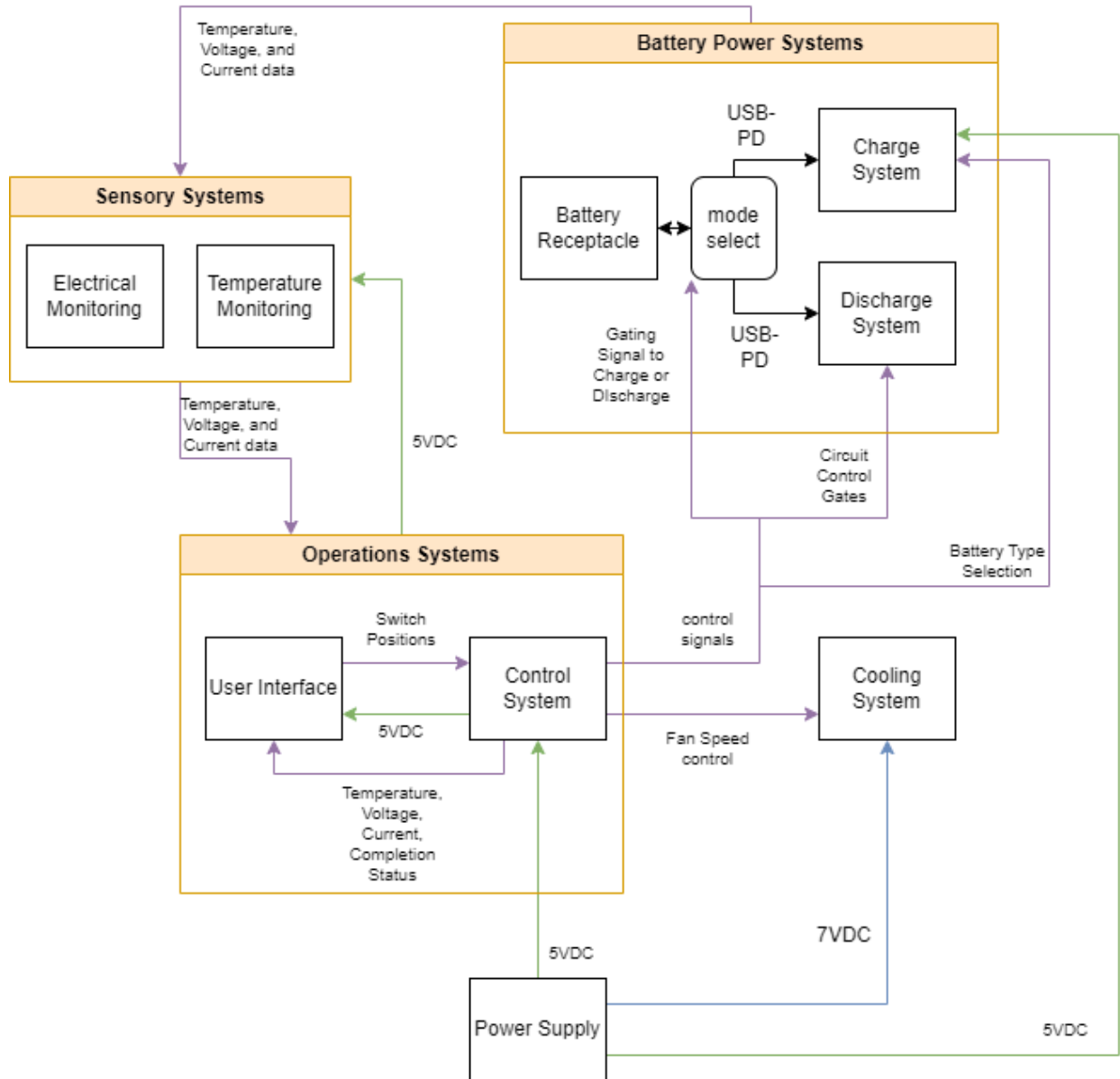


## 1.4 High Level Requirements:

- Be able to discharge continuously at 1-3A a condition the battery can be considered safe to common trash-borne hazards.
- Maintain temperature within safe battery limits to enable maximum sustained charge/discharge rate without exceeding hazard thresholds (120F steady state, 140F transient for discharge, 110F steady state to 120F transient for charge (105F for lithium) (Energizer), (Energizer), +/- 2F margin of error).
- Be able to cycle active circuits based on system conditions to maximize charge/discharge, minimize system temperature(as much as feasible to at least be safe), and maximize system's operating lifetime. This should include rapid response (within 1s with 10% margin of error) to emergent conditions, such as battery failure, exceeding transient temperature limits, and thermal runaway.

## II. Design

### 2.1 Block Diagram:



## 2.2 Subsystems Overview and Requirements:

### Battery Receptacle Subsystem:

This subsystem can hold two battery receptacles, one for AA batteries and another for AAA batteries. This is where the soon to be charged/discharged batteries will be placed in the system. Each receptacle will hold two batteries. This system will also include a USB connection port for USB battery inputs. Based on the user's input preferences, the control system picks which receptacle or port is in use and dictates whether it is connected to the charge or discharge subsystem. Furthermore, this subsystem is connected directly to the electrical monitoring subsystem in order to record the electrical charge and current flow from the battery. It is also connected to the temperature monitoring subsystem in order to pass on temperature readings from the system and batteries.

### Battery Receptacle Requirements:

The Battery Receptacle Subsystem must be able hold batteries, transfer their energy to the necessary circuits, and leave the batteries exposed to airflow to aid in cooling. This subsystem must be able to handle 5Vdc and 3A.

Requirements	Verification
- Hold and securely connect batteries to the circuit for charging/discharging.	1. Insert batteries and verify the receptacle securely holds them and connects to circuitry.
- Allow airflow around the batteries for cooling.	1. Verify that airflow around batteries is not blocked and is effective during operation.
- Handle up to 5Vdc and 3A for efficiency.	1. Test by charging and discharging batteries, ensuring no interruptions.

### Cooling Subsystem:

Since we will be rapidly charging/discharging a battery, the internal temperature may become too hot for the system to remain safely operational. This subsystem focuses on keeping the overall circuit in a stable and controlled environment. The cooling subsystem will consist of a fan (PN:ROB-09238) that receives input from the control system and a heatsink that is located near

heat generating components. The fan will turn on or off based on the signal sent by the control system. Furthermore, the cooling subsystem will be directly connected to the power supply, powered independently from the rest of the circuit.

**Cooling Subsystem Requirements:**

The Cooling Subsystem must be able to collect and disperse heat to the air to cool the system down, at a rate potentially exceeding 50W of heat generation by the system. The heat sink must be in close enough proximity to vulnerable components to aid this, but not so close that airflow or other operations are unnecessarily restricted. The fan must be able to accept 12 Vdc as a power source.

Requirements	Verification
<ul style="list-style-type: none"> <li>- Dissipate up to 50W of heat generated during system operation</li> </ul>	<ol style="list-style-type: none"> <li>1. Measure heat output during operation. Ensure the system dissipates up to 50W without exceeding limits. Using our temperature sensors to ensure heat stays within our limits.</li> </ol>
<ul style="list-style-type: none"> <li>- Ensure the fan is powered by 12Vdc and responds to system temperature</li> </ul>	<ol style="list-style-type: none"> <li>1. Connect fan to a 12V supply, ensure it activates/deactivates based on conditions. Observe the fan to see if it is working properly.</li> </ol>
<ul style="list-style-type: none"> <li>- Position heatsink close to components without restricting airflow</li> </ul>	<ol style="list-style-type: none"> <li>1. Verify heatsink placement and confirm effectiveness of airflow. Visually inspect placement and see if airflow is possible.</li> </ol>

**Temperature Monitoring Subsystem:**

This subsystem is made up of temperature sensors (PN:LM235Z) placed around the battery output, charge system, and discharge system. By monitoring and sending this information to the control subsystem, the temperature monitoring subsystem protects the overall circuit from overheating. The temperature sensors output data in the form of analog voltage. Luckily, the microcontroller we chose comes with 8 general purpose ADC (Analog to Digital Converter) pins. Three of these ADC pins will be connected to each temperature sensor’s output. The microcontroller will communicate with the sensors using a standard GPIO (General Purpose

Input/Output) protocol. The data this subsystem outputs helps tell the control subsystem whether to toggle on/off the fan, force shutdown the circuit, alter the charge/discharge rate, or do nothing.

**Temperature Monitoring Requirements:**

This subsystem must be able to monitor temperatures at vital points within a +/- 2C accuracy and relay it to the Control system for use in system operations.

Requirements	Verification
<ul style="list-style-type: none"> <li>- Accurately record the temperatures around the battery output, charge system and discharge system to within +/- 2C</li> </ul>	<ol style="list-style-type: none"> <li>1. Connect the output of the sensor to an ADC pin on the microcontroller.</li> <li>2. The first check will verify whether the sensor is able to accurately update the change in temperature within 260us (+/- 50us). Place the sensor in a cooler environment and record the temperature calculated by the microcontroller. Then place the sensor in a warmer environment and record the temperature calculated by the microcontroller. The microcontroller should show an increase in temperature from start to finish.</li> <li>3. The second check involves precision. Place the sensor near a predetermined temperature and see that the microcontroller matches that temperature within +/- 2C.</li> </ol>

**Electrical Monitoring Subsystem:**

This subsystem is made up of voltage and current sensors(LAH 25-NP) placed near the batteries. Its purpose is to ensure that the circuit doesn't exceed a certain current or voltage level. It monitors and sends this information to the control system. Both the current and voltage sensor outputs will be connected to its own ADC pin on the microcontroller. The microcontroller will communicate with the electrical sensor using standard GPIO protocol. This system's output helps the control subsystem figure out appropriate voltage and current levels that need to be supplied to the system.

**Electrical Monitoring Requirements:**

The Electrical Monitoring system should be able to accurately (+/- 1%) determine the current and voltage at the battery output, and send it to the Control system for use in system operation and failure detection.

Requirements	Verification
<ul style="list-style-type: none"> <li>- Accurately record the current and voltage at the battery output within +/- 1%</li> </ul>	<ol style="list-style-type: none"> <li>1. Connect the output of the sensor to an ADC pin on the microcontroller</li> <li>2. Introduce a simulated voltage at the input gate of the sensor and see if the microcontroller records the same voltage within +/-1%</li> <li>3. Introduce a simulated current at the input gate of the sensor and see if the microcontroller records the same current within +/-1%</li> <li>4. Additional verification includes using a multimeter to read the output voltage/current and comparing it with the known input current.</li> </ol>

**Charge Subsystem:**

This subsystem’s purpose is to recharge the desired battery introduced to the system. It is made up of two battery charging IC’s, one for lithium types(PN:BQ25820) and the other for nickel types (PN:BQ25172). These IC’s will be programmed to accept AA or AAA batteries. There is also an MOSFET that controls current flow to the IC during the charge phase. Furthermore, we will include a USB-C port that acts as a 5Vdc supply to any battery that accepts it. This subsystem will be connected to the battery receptacle subsystem via a mode selector to determine whether it’s working on a AA or AAA battery. The control system will send signals to the MOSFET to aid in current flow to the IC. If an overtemperature condition occurs, current flow will be removed until resolved.

**Charge Subsystem Requirements:**

The Charge subsystem must be able to provide stable 5Vdc (+/- 0.3Vdc) to an attached USB charged battery system. It will also need to be able to safely provide the correct charging voltage



(1.2Vdc +0.1/- 0.2Vdc) at safe current values to attached AA/AAA batteries. It must also be able to be gated away from the other systems and isolated when not in use.

Requirements	Verification
<ul style="list-style-type: none"> <li>- Provide stable 5Vdc (+/-0.3Vdc) for charging USB compatible batteries</li> </ul>	<ol style="list-style-type: none"> <li>1. Connect USB-C charging port to a 5V load and verify with a multimeter that output remains within the threshold.</li> </ol>
<ul style="list-style-type: none"> <li>- Safely charge AA/AAA batteries at 1.2Vdc (+0.1/-0.2Vdc) with safe current levels</li> </ul>	<ol style="list-style-type: none"> <li>1. Connect AA/AAA battery and verify charging voltage is between 1 and 1.3 Vdc.</li> </ol>
<ul style="list-style-type: none"> <li>- Enable isolation of the charging subsystem when not in use.</li> </ul>	<ol style="list-style-type: none"> <li>1. Simulate control signals to isolate the charging system. Confirm with the multimeter no current flow.</li> </ol>

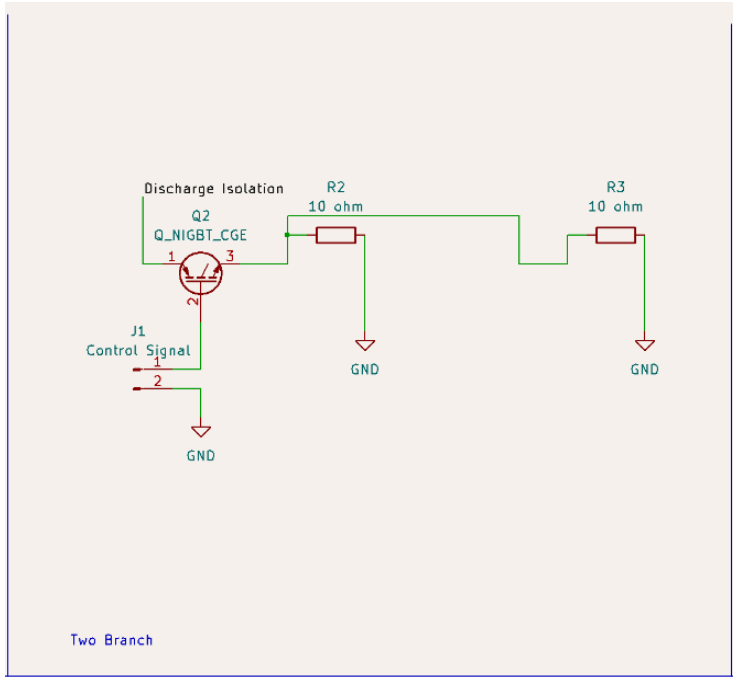
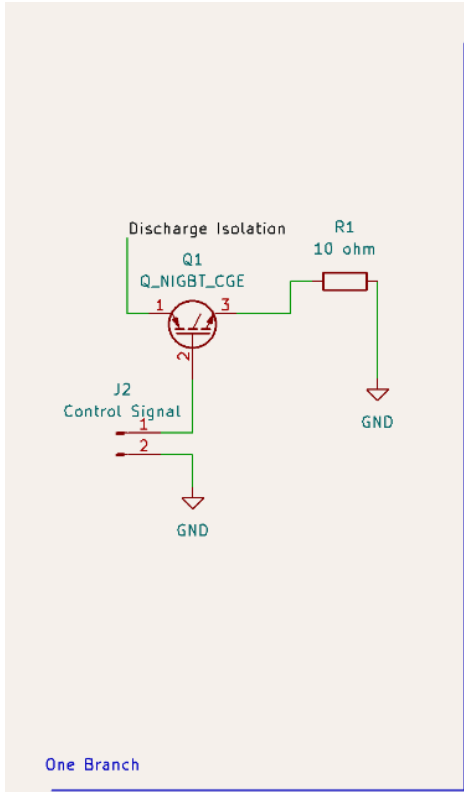
**Discharge System:**

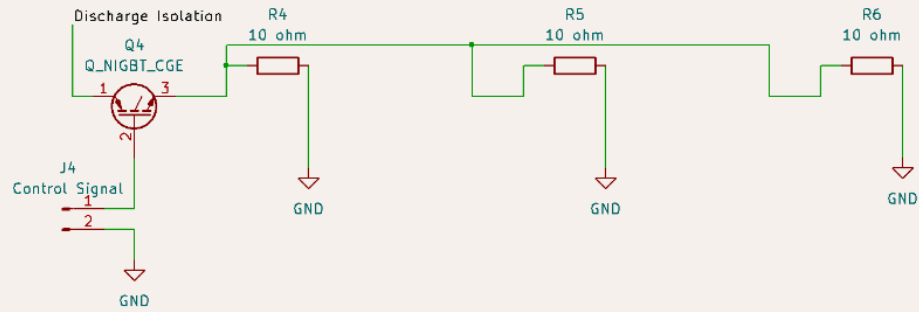
This subsystem controls the safe discharge of batteries by using a custom-made PCB that will function as a current divider. MOSFETs controlled by the control system will regulate discharge paths and manage energy dissipation. The control system will adjust based on discharging rates and will minimize heat buildup. The Discharge system will be connected to the battery receptacle subsystem and will work in conjunction with the electrical and temperature subsystems to keep discharge rates at a safe level. When not in use this system will be isolated for overall safety.

The discharge system accomplishes this by using ten branches of resistors in parallel. Each resistor branch has a 10 ohm resistor (PN: LTR18EZPF10R0). When the MOSFETs are gated on with a potential of 5V applied, you will get a discharge rate of 500 mA across a resistor branch. These can be stepped up to a discharge rate of 3A in six increments. With 3V instead, the discharge rate per branch will be 300 mA, which can be stepped up in ten increments, using all of the branches. When isolated, all MOSFETs will be deenergized, isolating the discharge system.

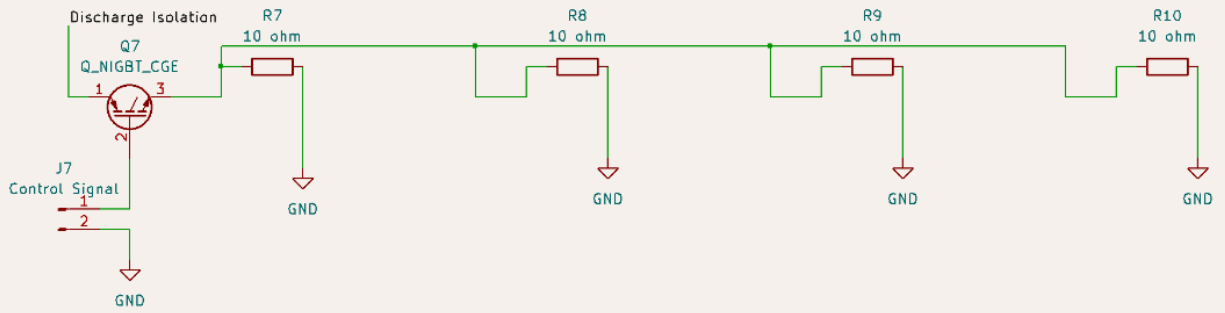
**Discharge System Requirements and Verification:**

Requirements	Verification
<ul style="list-style-type: none"> <li>- The Discharge System must be able to safely discharge 3A from 5V and 3V potentials.</li> </ul>	<ol style="list-style-type: none"> <li>1. Single Branch test: With a 5V potential test each branch of the discharge path. Monitor for temperature changes for 30 minutes or stabilization (+/-1C). The test will be considered satisfactory if temperature remains below 60C or stabilizes for 5 minutes below 60C.</li> <li>2. Whole Subsystem test: With a 5V and 3V potential (separately) verify that you can achieve a 3A discharge rate.</li> <li>3. Stress test: with a 5V potential and the circuit aligned to achieve 3A discharge, monitor temperatures for an hour or until stabilization(+/-1C). The test will be considered satisfactory if the temperature remains below 60C (+/-1) or stabilizes for 5 minutes below 60C.</li> </ol>
<ul style="list-style-type: none"> <li>- The Discharge System must be able to be isolated from the other systems.</li> </ul>	<ol style="list-style-type: none"> <li>1. Simulate control signals from the Control System on the isolating gates. The test will be considered satisfactory if the path to the system reads as OPEN or not shorted as appropriate on the diode setting of a multimeter.</li> </ol>
<ul style="list-style-type: none"> <li>- The Discharge system must be able to alter the discharge current in at least six increments up to 3A.</li> </ul>	<ol style="list-style-type: none"> <li>1. With 3V potential, gate each branch on, one at a time, and measure the current across the resistor branch with a multimeter. Readings should be in increments of .3A +/-30mA. Final reading should be 3A +/- 200mA.</li> <li>2. With 5V potential, gate six branches on, one at a time, and measure the current across the resistor bank with a multimeter. Readings should be in increments of .5A +/-50mA. Final reading should be 3A +/- 200mA.</li> </ol>

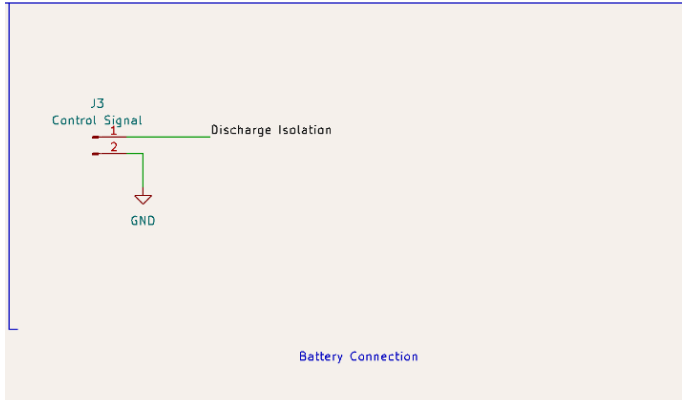




Three Branch



Four Branch



**Control System:**

The Control Subsystem is the central point of the system. It will be responsible for managing the Electrical and Temperature subsystems and adjusting operations where necessary. It processes data to alter current paths through the charge and discharge systems ensuring safe and adequate performance. This subsystem also controls the cooling subsystem, and will remove power to the fan in the event of thermal runaway to limit oxygen addition to a fire hazard. An ATMEGA328 (Atmel) microcontroller will be the core of the control system, which will execute any necessary commands to successfully manage the system. It will interface with all other subsystems ensuring proper operation based on real time data.

**Control System Requirements and Verification:**

Completing the following tests will also satisfy requirements that the system responds properly to User interface inputs.

Requirements	Verification
<ul style="list-style-type: none"> <li>- Must be able to control MOSFETs</li> </ul>	<ol style="list-style-type: none"> <li>1. Starting with the Mode Selector Switch (User Interface Subsystem) in the DISCHARGE position, verify status of the Discharge System MOSFETs with the diode setting of a multimeter. It should read a small resistance but not SHORTed. Verify the status of the Charge system MOSFETs. With a multimeter in the diode setting, it should read OPEN or very high resistance. Move the Mode Selector Switch to the CHARGE position and the TYPE SELECTOR to</li> </ol>

	<p>the NiMH position. Verify the MOSFETs are reversed, with the exception of the isolation to the lithium charging IC which should read as OPEN or high resistance. Move the TYPE SELECTOR SWITCH to the LI position. Discharge isolations remain OPEN, NiMH charge isolations become OPEN, and LI charge isolations become low resistance.</p> <ol style="list-style-type: none"> <li>2. Move the Mode Selector Switch to the CHARGE position and the TYPE SELECTOR to the NiMH position. Verify the MOSFETs are reversed, with the exception of the isolation to the lithium charging IC which should read as OPEN or high resistance. Move the TYPE SELECTOR SWITCH to the LI position. Discharge isolations remain OPEN, NiMH charge isolations become OPEN, and LI charge isolations become low resistance.</li> <li>3. Move the TYPE SELECTOR SWITCH to the LI position. Discharge isolations remain OPEN, NiMH charge isolations become OPEN, and LI charge isolations become low resistance.</li> </ol>
<ul style="list-style-type: none"> <li>- Must demonstrate correct responses to temperature</li> </ul>	<ol style="list-style-type: none"> <li>1. With a simulated temperature input, verify for all modes of operation that exceeding the Transient Temperature Limit ( 140F for discharge, 120F for charging NiMH, 105 for charging LI) will cause current flow paths to isolate. Simulate rising temperature after this condition for 10 seconds and verify signal to fan stops.</li> <li>2. With the Mode Selector Switch in the DISCHARGE position, verify that exceeding the Steady State Temperature limits for 3 seconds results in a reduction in current. If not all flowpaths are open, verify that remaining below the Steady State</li> </ol>

	limits for 5 seconds results in raising current up, up to a maximum of 3A.
- Must be able to respond within one second (+/- 10%)	1. Beginning with the Mode Selector Switch in DISCHARGE and the Type Selector Switch in LI, verify HIGH signal on the output isolation pins. Move the Mode Selector Switch to CHARGE and time how long it takes for the signal to go LOW. Test the other switch combinations as applicable.

### User Interface Subsystem:

The User Interface Subsystem allows the user to control and monitor the subsystems operation. The User Interface will accept input to determine whether the system should be in charge/discharge mode and what kind of battery is currently in use (lithium or nickel). This subsystem will contain external switches for selecting charge/discharge, type, and an on/off switch. The subsystem also features an LCD display that will show the charge/discharge status to keep the user informed on the status of the system.

### User Interface Requirements and Verification:

Requirements	Verification
- Signals to the Control System should be well defined and clear.	1. Each switch must be able to interrupt a 5Vdc signal and allow it to pass.
- The display must be clear and legible. The data should be accurate.	1. With the display connected, you should be able to see battery voltage, battery current, charge status, and highest temperature. With a multimeter, verify battery voltage and battery current are accurate to the display by +/-5%. Use this data to calculate charge status and verify it with the displayed. Check the output of the temperature probes to see if the highest is consistent with displayed.

## Power Supply Subsystem:

The Power Supply Subsystem will provide the electrical input to power the system. It will utilize an AC/DC converter (PN: 237-1443-ND) to step voltage down from 120Vac to 12Vdc for the fan. We would then use a Voltage regulator (PN:LM1085IT-5.0/NOPB-ND) to step this down to 5Vdc for use by the rest of the system. This system will ensure a stable power supply which will allow for the systems control, monitoring, and other components to behave as needed.

## Power Supply Requirements:

This subsystem must be able to receive power from a standard 120 Vac electrical outlet, pass it along to the fan in the cooling system, and reduce it to 5Vdc (+/- .3Vdc) for the rest of the system to use and 12Vdc(+/-0.5Vdc) for fan use.

Requirements	Verification
- Must reduce 120 Vac from an electrical outlet to 12Vdc (+/-0.5Vdc) for fan use	4. With the system plugged in and on, use a multimeter to measure the voltage across the fan input. If correct, this voltage should read 12Vdc (+/-0.5Vdc).
- Use a voltage regulator to produce 5Vdc (+/-0.5Vdc) from 12Vdc for the rest of the system to consume	1. With the system plugged in and on, use a multimeter to measure the voltage across the microcontroller, user interface, temperature/electrical sensors, and charging system. If correct, these voltages should all read 5Vdc (+/-0.5Vdc). Additional verification can be tested by seeing if the voltage regulator's output is 5Vdc (+/-0.5Vdc).

## 2.3 Tolerance Analysis:

The batteries (located in the Battery Receptacle) will likely be the most limiting part of the design. Because a battery will be a temporary addition to the system, we must account for damage and conditions that might be outside of our control being introduced to the system. For this reason, the battery will be the most likely source of faults and irregular conditions. However, there is very little we can do about the batteries, so we will instead focus on analyzing the discharge and cooling subsystems, incorporating the limiting nature of the battery.



The batteries will also be the limiting component when it comes to temperature. Most batteries have a maximum operating temperature of 60 C, and should ideally be maintained below 50 C. IC chips often are limited at 70 C, and individual board components can have operating temperatures exceeding 130 C (the resistors we will be using to dissipate energy will likely have 155 C, far exceeding 130 C). Because the battery will also be the power sink/source for the charge and discharge circuits, it will also match their power utilization.

The most limiting thermal conductivity identified (Zeng et al. #) is 0.15W/(m\*K) which corresponds to a thermal resistance of 6.67 C/W. For the maximum expect power supplied by the battery:

$$T_f = T_i + Q * R$$

Where  $T_f$ ,  $T_i$ ,  $Q$ , and  $R$  are the final temperature, initial temperature, power and thermal resistance, we have:

$$T_f = 30C + ((5V * 3A) * 6.67C/W) = 130 C$$

using a high room temperature, the maximum specifications of USB-C and assuming only the most limiting part of the battery is able to disperse heat in the most limiting direction. Despite this being a next-to-impossible worst case, it clearly illustrates the need for good thermal design and current control methods. If we limit current flow in high temperature conditions, and good airflow improves thermal performance, we might instead see

$$T_f = 30C + ((5V * 1.5A) * 3.33C/W) = 55 C$$

Using the same limiting component, adjusted by a coefficient of 1/2, the temperature is more manageable. Despite the massive difference, we can conclude that these numbers can be fairly reasonable based on the differences people saw when researching the change in thermal conductivity in heat sinks when airflow is provided (“How Air Velocity Affects - The Thermal Performance of Heat Sinks: A Comparison of Straight Fin, Pin Fin and maxiFLOW™ Architectures”). In the prior cited document, a reduction of half was witnessed unilaterally in an airflow environment of 1 m/s. Given that we were assuming zero consideration for thermodynamics in the original scenario, our new numbers are conservative.

These considerations are so limiting, that our entire system is designed around their mitigation while still maintaining practical use. Each of our High Level Requirements has this mindset at its center. Our current limits take into account the variance necessary to limit heat generation while still discharging effectively. Given thermal momentum and accuracy of components, we are limiting temperatures to the operational maximum only in transients with the ideal operational temperature being a steady state limit, and to do that we are designing flexible discharge paths to adjust current dynamically while fan speed can be changed on the fly.

With accurate temperature monitoring, effective cooling, and timely limitation of heat generation, the system is maintained safe, even in transient conditions.

### III. Cost and Schedule

#### 3.1 Cost Analysis:

##### Control System:

Part	Purpose	Part Number	Quantity	Cost
ATMEGA328	System Control	ATMEGA328	1	\$2.50
SUBTOTAL				\$2.50

##### Power System:

Part	Purpose	Part Number	Quantity	Cost
12V Adaptor	12V Power Supply	237-1443-ND	1	\$18.73
Voltage Regulator	Drop down to 5V power supply	LM1085IT-5.0/ NOPB-ND	1	\$2.08
SUBTOTAL				\$20.81

##### Charge System:

Part	Purpose	Part Number	Quantity	Cost
Lithium Battery Charge IC	Battery charger	BQ25820	1	\$2.99
NiMH Battery Charge IC	Battery charger	BQ25172	1	\$0.28
MOSFET	Charge path isolation	SI2102A-TP	3	\$0.30
SUBTOTAL				\$4.17

##### Discharge System:

Part	Purpose	Part Number	Quantity	Cost
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10 ohm resistor	Discharge path resistor banks	LTR18EZPF10R0	10	\$0.22
MOSFET	Discharge path isolations	SI2102A-TP	4	\$0.30
SUBTOTAL				\$3.40

**Cooling System:**

Part	Purpose	Part Number	Quantity	Cost
12V Motor	Fan motor	ROB-09238	1	\$18.79
SUBTOTAL				\$18.79

**Temperature Monitoring:**

Part	Purpose	Part Number	Quantity	Cost
Sensor	Temperature monitoring sensor	497-7324-ND	3	\$0.66
SUBTOTAL				\$1.98

**Electrical Monitoring:**

Part	Purpose	Part Number	Quantity	Cost
Sensor	Current/Voltage sensor	398-1007-ND	2	\$21.23
SUBTOTAL				\$42.46

**Battery Receptacle:**

Part	Purpose	Part Number	Quantity	Cost
Dual AA Battery Holder	Battery Holder	12BH322B-GR	1	\$2.58
Dual AAA Battery Holder	Battery Holder	HM5214-ND	1	\$2.10
SUBTOTAL				\$4.68

**User Interface:**

Part	Purpose	Part Number	Quantity	Cost
Switch	3-position switch (on-off-on)	COM-14978	3	\$1.05
LCD Display	LCD Display	LINX PCB-EVA-LS-R X Rev E	1	Similar models cost \$9-15
SUBTOTAL				\$16.05

**Case:**

Part	Purpose	Part Number	Quantity	Cost
Case	Case		1	
SUBTOTAL				TBD

The subtotal for the current parts list is \$114.84.

Average salary for UIUC Computer Engineering graduates : \$109,176 (according to UIUC websites).

Project length starting from week of 9/30 is two months and nine days, rounded to two months.

Cost of personnel:  $3 * (109,000/6) = \$54,500$

The total cost comes to **\$54,614.84**.

**3.2 Schedule:**

Week:	Course Calendar:	Project Schedule:
9/30	Wednesday: - DR sign-up closes Thursday: - 11:59p Design Doc Due Friday: - 11:59p Proposal Regrade Due	<ul style="list-style-type: none"> <li>- Finish Design Doc [Everyone]</li> <li>- Finish Proposal Update [Everyone]</li> <li>- Meet with Jack Blevins (Wed 1p) [Everyone]</li> </ul>

		<ul style="list-style-type: none"> <li>- Begin board designs [Everyone]</li> </ul>
10/7	<p>Monday:</p> <ul style="list-style-type: none"> <li>- 4:00p Design Review (ECEB2070)</li> </ul> <p>Friday:</p> <ul style="list-style-type: none"> <li>- 3:00p-5:00p PCB Review (ECEB3081)</li> </ul>	<ul style="list-style-type: none"> <li>- Complete at least one board for review [Everyone]</li> <li>- Identify which case we'll need [Stan]</li> <li>- Final case design/instructions by end of week [Stan]</li> </ul>
10/14	<p>Tuesday:</p> <ul style="list-style-type: none"> <li>- 4:45p PCBWay Audit due</li> </ul> <p>Wednesday:</p> <ul style="list-style-type: none"> <li>- 11:59p Teamwork Eval 1</li> </ul> <p>Friday:</p> <ul style="list-style-type: none"> <li>- Last day for machine shop revisions</li> </ul>	<ul style="list-style-type: none"> <li>- Have passed audit [Everyone]</li> <li>- Begin work on ucontroller code. Will prioritize code for managing systems on order. [Aditya]</li> <li>- Continue PCB design [Everyone]</li> </ul>
10/21	<p>Tuesday:</p> <ul style="list-style-type: none"> <li>- 4:45p PCBWay Audit due</li> </ul>	<ul style="list-style-type: none"> <li>- Build PCBs that we have [Stan and Jonathan]</li> <li>- Work on code [Aditya]</li> <li>- Test completed PCBs [Everyone]</li> <li>- Have made audit on at least one iteration of each system needing a PCB [Everyone]</li> </ul>
10/28	<p>Tuesday:</p> <ul style="list-style-type: none"> <li>- 4:45p PCBWay Audit due</li> </ul>	<ul style="list-style-type: none"> <li>- Redo work as required for errors or troubleshooting [Everyone]</li> <li>- Assemble system for comprehensive testing [Everyone]</li> </ul>
11/4	<p>Tuesday:</p> <ul style="list-style-type: none"> <li>- 4:45p PCBWay Audit due</li> </ul> <p>Wednesday:</p> <ul style="list-style-type: none"> <li>- 11:59p Ind Progress Report due</li> </ul> <p>Friday:</p> <ul style="list-style-type: none"> <li>- 11:59p Design Doc Regrade Due</li> </ul>	<ul style="list-style-type: none"> <li>- Perform comprehensive testing [Everyone]</li> <li>- Individual Progress Report [Everyone]</li> <li>- Design Doc Regrade [Everyone]</li> </ul>
11/11	<p>Tuesday:</p> <ul style="list-style-type: none"> <li>- 4:45p PCBWay Audit due</li> </ul>	<ul style="list-style-type: none"> <li>- Should be complete everything by end of week. Touch-ups. [Everyone]</li> </ul>

11/18	<p>Monday:  - Mock Demo through Friday</p> <p>Tuesday:</p> <p>Wednesday:</p> <p>Thursday:</p> <p>Friday:  - 11:59 Team Contract Fulfillment Due</p>	<ul style="list-style-type: none"> <li>- Mock Demo [Everyone]</li> <li>- Team Contract Fulfillment [Everyone]</li> </ul>
11/25	<p>Monday: Fall Break through Sunday</p>	
12/2	<p>Monday:  - Final Demo through Wednesday</p> <p>Tuesday:</p> <p>Wednesday:</p> <p>Thursday:  - Mock Presentation through Friday</p> <p>Friday:</p>	<ul style="list-style-type: none"> <li>- Final Demo [Everyone]</li> <li>- Mock Presentation [Everyone]</li> </ul>
12/9	<p>Monday:  - Final Presentation through Tuesday</p> <p>Tuesday:</p> <p>Wednesday:  - 11:59p Final Papers due</p> <p>Thursday:  - 3:00-4:30p Lab checkout  - 4:30-5:30p Award Ceremony @ Grainger Auditorium  - 11:59p Lab Notebook Due 11:59p</p>	<ul style="list-style-type: none"> <li>- Final Presentation [Everyone]</li> <li>- Final Papers [Everyone]</li> <li>- Lab Checkout [Everyone]</li> <li>- Lab Notebook [Everyone]</li> <li>- Awards Ceremony [Everyone]</li> </ul>

## **IV. Ethics and Safety**

### **3.1 Safety:**

The purpose of this project is to design a device that enables people's homes and businesses to be more safe. In this vein, it would be remiss not to examine the possible safety issues with the product.

The largest safety issue has to do with fire prevention. To this end, we intend to design a system that will, when working properly, not only limit fire hazards but also work to actively prevent them. The system will have expectations of system response, and will refuse to perform potentially dangerous tasks if a mismatch between response and expectation is detected. Specifically, for example, if the battery exceeds the transient temperature threshold, the system will isolate charging and discharging systems. If temperature continues to increase, all power to the system will shut off, including the fan, to prevent oxygen from reaching a potential developing fire.

That being said, the system will only be as safe as our own efforts allow. Our team will spare no effort to ensure that the system will prevent fires rather than enable them. To use a standard for battery safety, we will use the ECE 445 Battery Safety Guidelines (Spring 2016 Course Staff), as well as applicable portions of the UN's Global Technical Regulation on the Electric Vehicle Safety (United Nations), particularly on battery handling and inspection.

### **3.2 Ethics:**

Our team will maintain intellectual and ethical honesty in our endeavors. In accordance with IEEE code (IEEE), section 1, parts 1-6, we will cut no corners and use the most accurate data we can acquire. If certain efforts or behaviors would benefit the individual, team, or project to the detriment of society or the community, they will be discarded in favor of earnest work towards the betterment of each. Particularly, we will "seek, accept, and offer honest criticism of technical work, [acknowledge] and correct errors, [be] honest and realistic in stating claims or estimates based on available data, and [credit] properly the contributions of others", to quote the IEEE code of ethics.



## **V. Special Thanks**

Jack Blevins, for his expert advice and contributions, including guidance on business decisions and circuit simplification.

## VI. References

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