

# **ECE 445 Final Presentation**

Electrical & Computer Engineering

Group 67 TA: Zicheng Ma Professor: Jonathon Schuh

04/29/2024



#### **Team Members**

Eric Lin

**Computer Engineering** 

Focus on software programming and testing

Carl Xu

Computer Engineering

Focus on software programming and testing

Laurenz Nava

**Electrical Engineering** 

Focus on power circuit design and some general circuit design

#### Main challenge:

Every morning, waking and getting up by the time the alarm rings.

#### **Current Solution:**

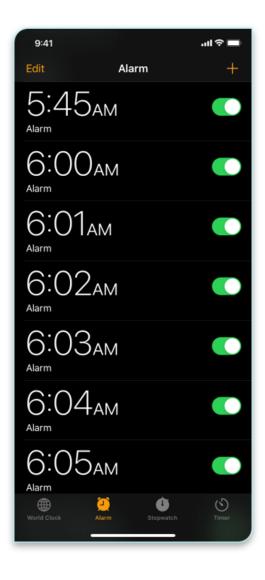
Have a snooze button!!!

Traditional alarms provide less time for sleep and are inefficient wake-ups.

Setting multiple alarms may still result in oversleeping.

#### **Negative effects:**

Disrupted daily schedule, reduced productivity, increased stress, and more!





### **Idea/Objective**



- The alarm will ring at the designated time
- The user must get up and go to the bathroom to brush their teeth
- The alarm will only turn off after the user brushes their teeth for 2 minutes

- Goal/Objective: efficiently wake up, more sleep, and get out of bed



# Conditions for correct brushing

- $\circ~$  2.2 mN min force
- $\circ$  10 Hz max frequency

## **Conditions for user detection**

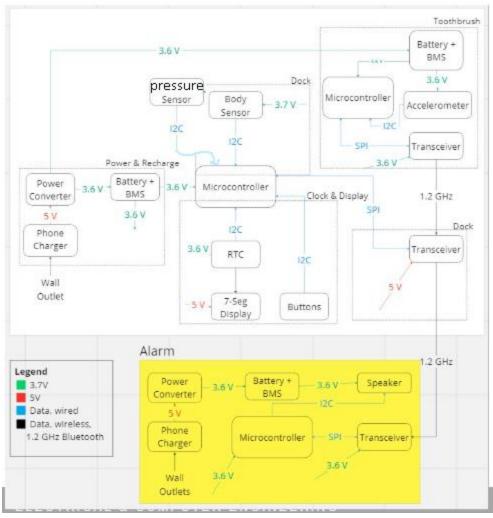
- Within 3 m
- **180°**

## **Conditions for the alarm to stop**

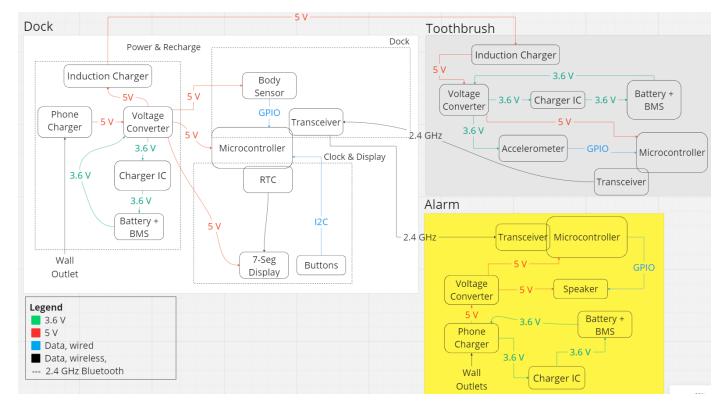
- Brush teeth for 2 mins
- Override Buttons 10 secs
- $\circ$  Unattended 30 mins.

#### Block Diagram

#### Initial



#### **Final**





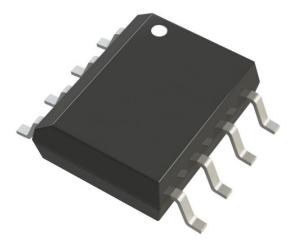
BQ24115RHLR (Recharging IC)



BQ7791501PWR (BMS)

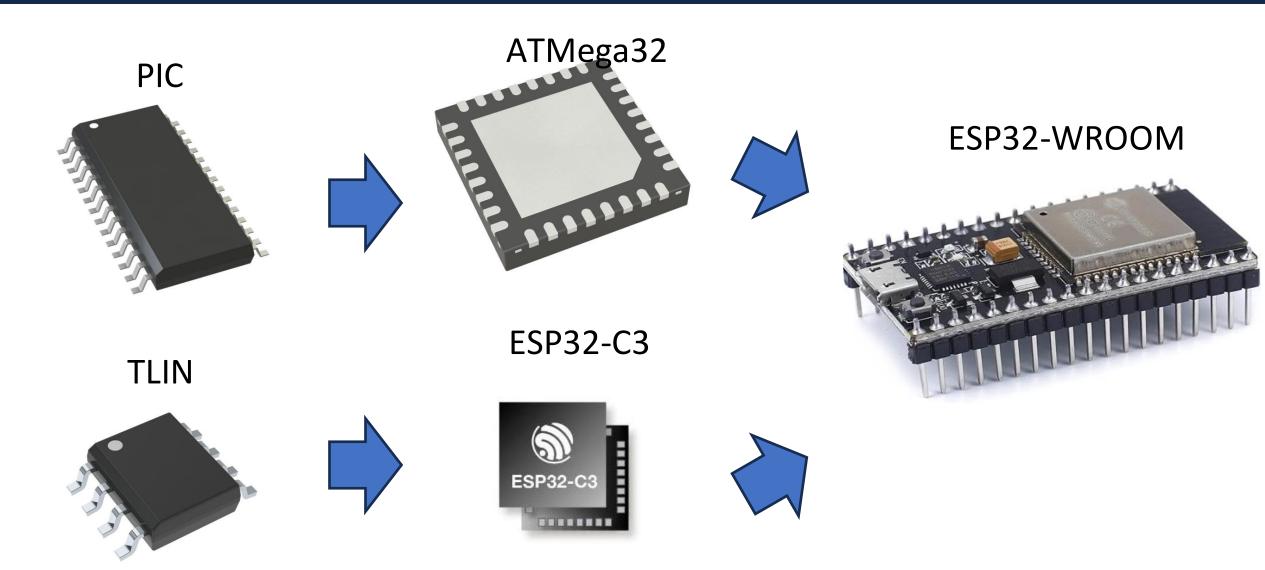


AP64350SP-13 (Regulator)



#### Hardware Components



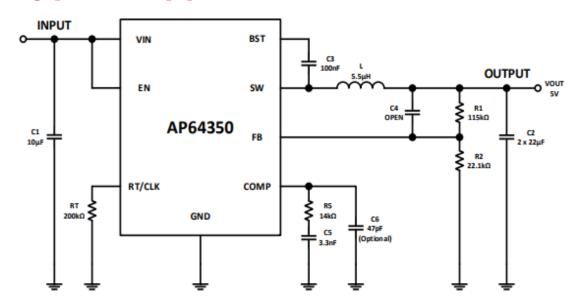


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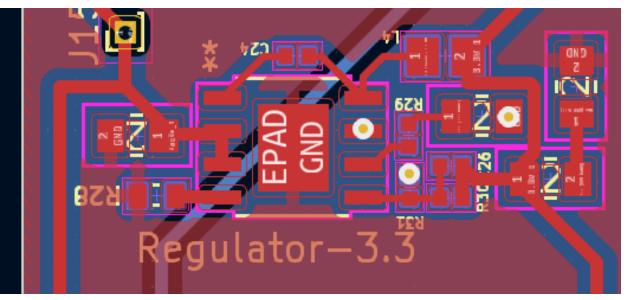
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## **Typical Application**



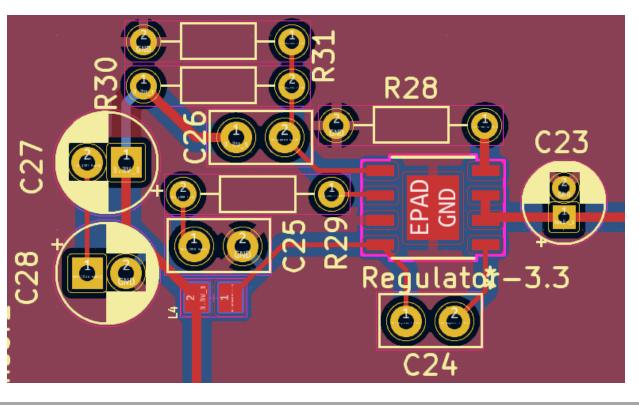
## **Latest Design**





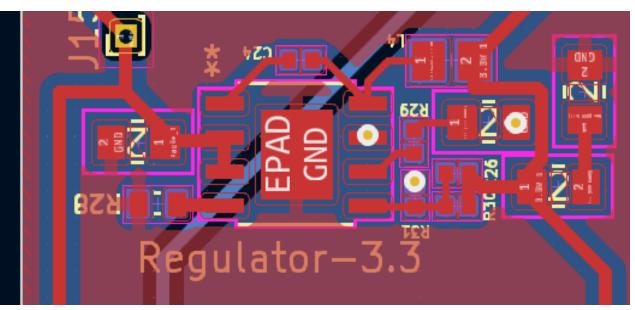
# First Design

- Through-holes
- Bulky



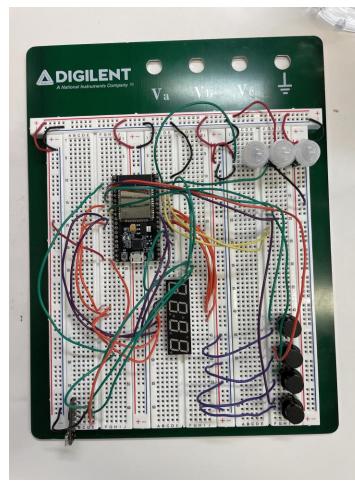
# **Latest Design**

- Surface-mounted
- Better organized

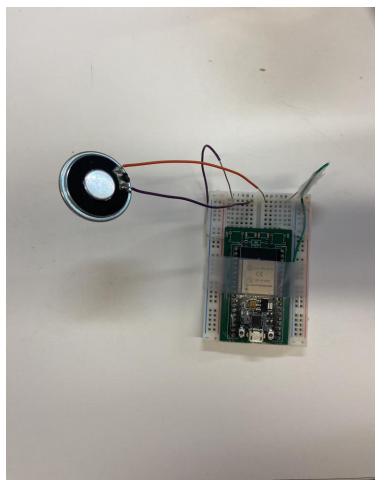


#### Breadboard

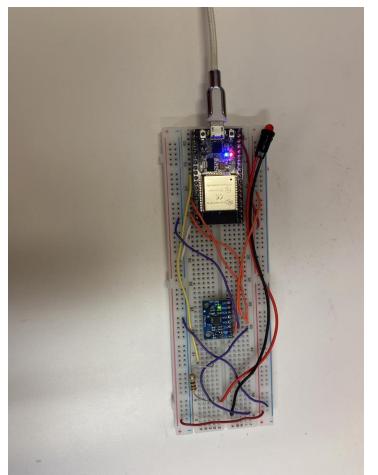
#### Dock



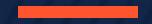
#### Alarm



## **Toothbrush**







# Subsystems

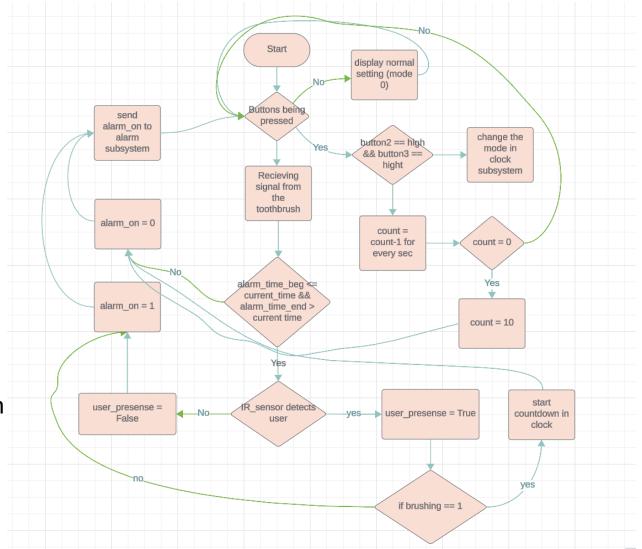
(Main section divider slide option two, or transition slide.)

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- Acts as the central control hub of our Toothbrush Alarm system
- O Ensures accurate monitoring of brushing activity
- Have an IR sensor embedded to detect user presence in the area
- Orchestrates seamless communication between components:

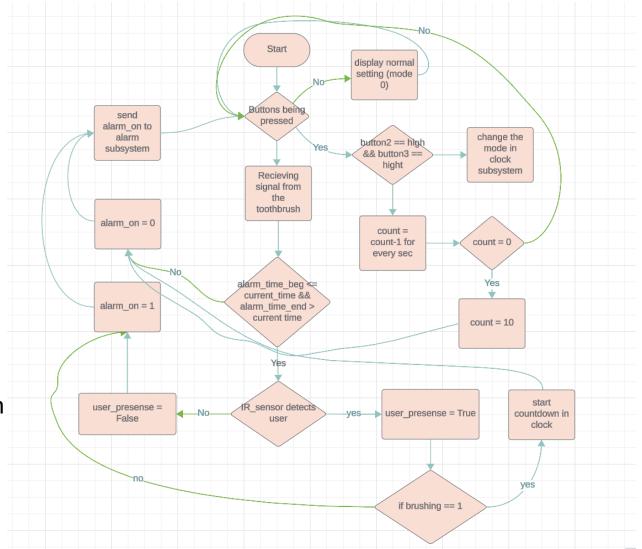
Wireless signal to the alarm speaker Receive wireless signals from toothbrush Wired connected to the clock display





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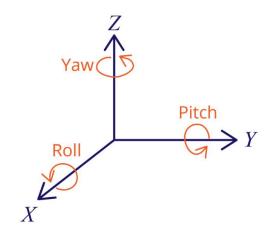
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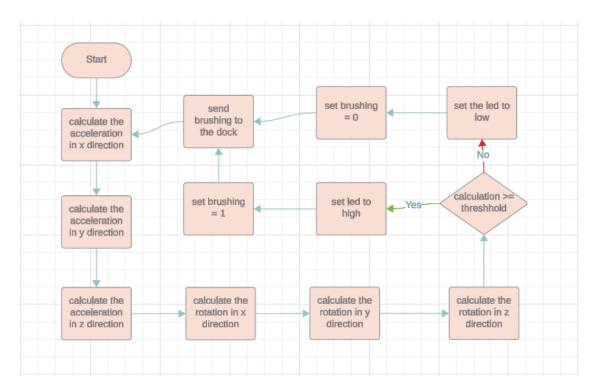


#### Toothbrush Subsystem

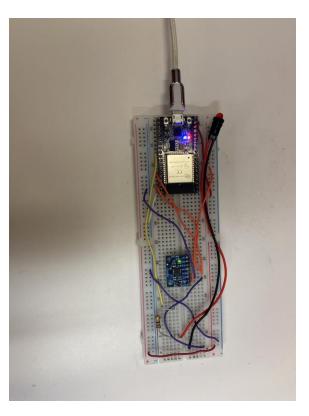


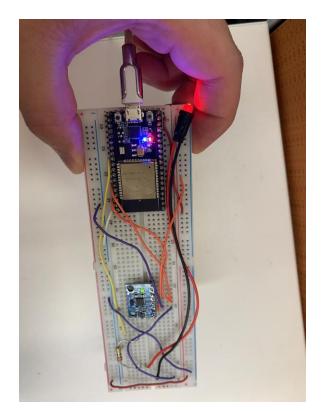
- The gyroscope measures rotational velocity (rad/s), the change of the angular position over time along the X, Y, and Z axis (roll, pitch and yaw)
- The accelerometer measures acceleration (rate of change of the object's velocity) in the X, Y, and Z axis
- Sends the wireless signal to the dock when the user is using the toothbrush





Sends the wireless signal to the dock when the user is using the toothbrush,
If it detects motion, led is on, otherwise is off.



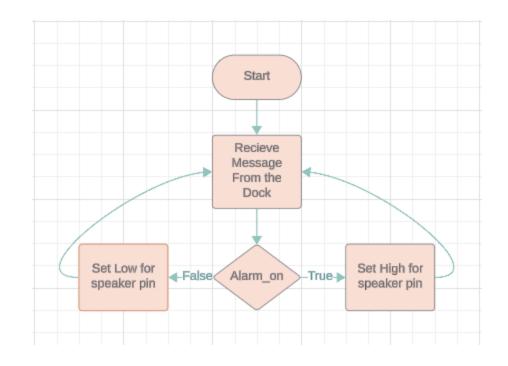


#### Alarm Subsystem



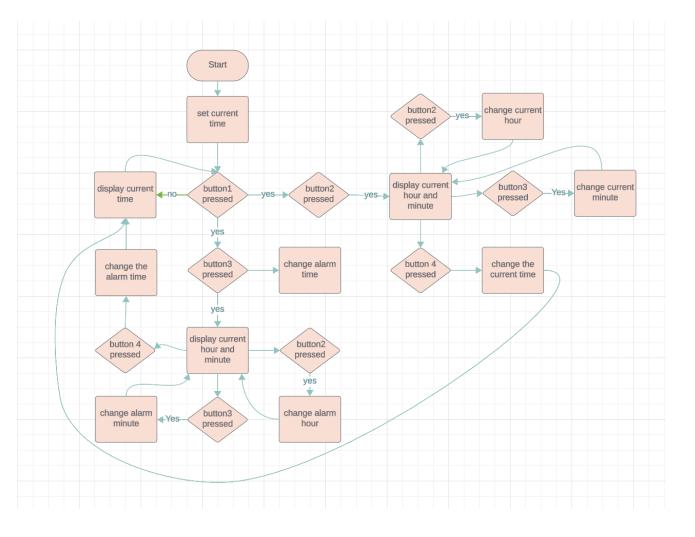
- Receive alarm\_on/alarm\_off Signal from the Dock
- O Have roughly about 60 dB for volume

- $\bigcirc$  Sound Alarm at the Set Alarm Time
- Stop Alarm when the User Starts Brushing Teeth
- Resume Alarm for Incomplete Brushing
- Stop Alarm after 30 minutes once started





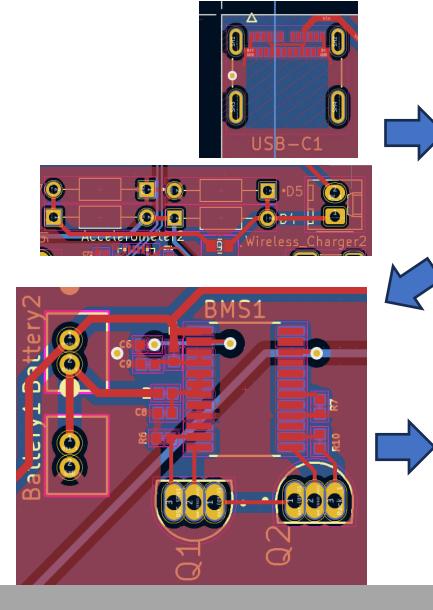
- Serves as the central hub for time management
- Main purpose: real-time clock information and alarm settings
- Equipped with a 7-segment display and a real-time clock module
- Has intuitive button controls enabled users to set and modify alarm times

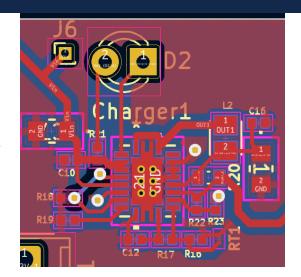


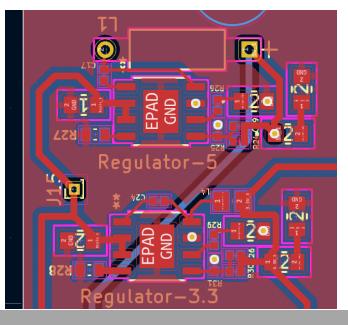
#### Battery & Power Subsystem

Powers and recharges all other subsystems

- Energy enters via USB-C or wireless charger
- $\circ$  Recharging IC
- Battery and battery management system
  - Travel friendly
- 3.3 V and 5 V regulators to all other components







#### **Requirement & Verification**

#### Dock

- Motion sensor range: 3.78m
- Wifi range: 20+m



ToothbrushAcceleration resolution: 0.2 mN

#### 0.01 rad/s \* 120 cm \* 20 g = 0.2 mN

14:40:39.647 -> Last Packet Send Status: Delivery Success 14:40:40.648 -> LOOP START 14:40:40.648 -> Rotation X: -0.05, Y: 0.05, Z: 0.01 rad/s 14:40:40.648 -> 14:40:40.648 -> Sent with success 14:40:40.648 -> LOOP END

# AlarmAverage volume of speaker: 60 dB





(Short video for working Toothbrush Alarm)

#### Conclusion

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#### What did we learn:

- PCB design
- Hardware software integration
- Product design
- Parts selection

#### What would you do differently if you redesigned your project:

- Start earlier
- Test more on breadboard before PCB design
- Check datasheet more carefully before designing

#### **Recommendations for further work:**

- Louder speaker
- Fix PCB implementation
- Wireless batter charging
- More methods to turn of the alarm other than brushing teeth



# Thank You

Eric Lin Carl Xu Laurenz Nava

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