

## **Final Presentation**

Team 36: LED Surgical Light

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## **Team Introduction**

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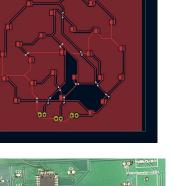
Surgeons and medical professionals use sense of vision and analysis of tissues to find cells that are malignant and work towards appropriately removing those

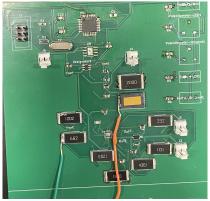
- Limit to the human vision
- It is very difficult to detect cancer cells in areas where there is not as much growth and visibility
- Hard to identify the exact location





- Infrared and white LEDs
- User interface that will allow user to change the brightness of each LED system
- 3 PCBs
  - Microcontroller ATMEGA328PB
  - LED PCB Infrared LED, 24 White LEDs
  - Rechargeable battery







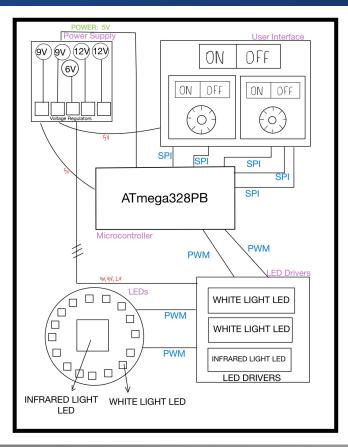


# **High-Level Requirements**

 Turn on a set of white LEDs- aid surgeons' to view cells
 Employ one infrared LED- aid camera to view cells
 Develop a mechanism to allow user to increase or decrease the brightness of each of the LEDs

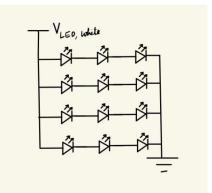
#### **Original Design**





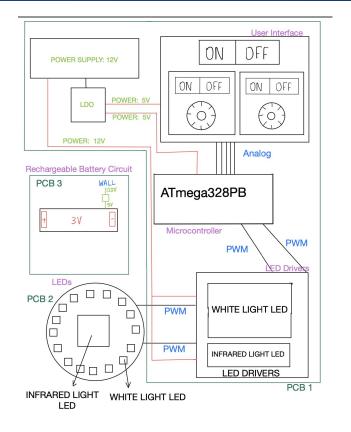
#### Our original design:

- Multiple Power Supplies: Two 9V, two 12V and a 6V battery
- Linear Dropout Regulators- dropped down 4V
- □ Two regular LED Drivers
- □ White light LEDs were placed in a parallel fashion

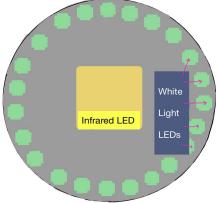


#### Changes to the Original Design





- Replaced the multiple power sources with one battery 18650 Rechargeable Batteries
- Combined the LED drivers and buck and boost voltage regulators
- □ Used a linear dropout as the voltage regulator for the user-interface and the microcontroller
- Produced a rechargeable battery circuit to recharge the battery





# Subsystems



## **Batteries**

- □ 18650 Rechargeable batteries
- □ 3 batteries in series to provide 12.6 V

## **Recharging Batteries**

- □ Mosfet to control the current flow towards the battery
- General Shunt regulator controls determines the state of Mosfet

## **Linear Dropout Regulator**

□ 5V fixed output LDO regulator





| Requirements   | Verifications   | Results  |
|--|---|--|
| LDO is able to step down the voltage to 5V +/- 0.2V                    | Using a voltmeter check the output of the voltage     | Initially only doing a 3V drop, later there was no voltage drop    |
| Rechargeable battery circuit can<br>charge each battery to 3V +/- 0.2v | Check battery voltage after connecting to the circuit | Batteries weren't used, we weren't able to test a battery charging |

#### Microcontroller

## ATMEGA328PB-AU

#### **D** Primary requirement:

- □ Able to produce multiple PWM signals
- □ Have multiple analog and digital input pins
- ATMEGA328PB-AU characteristics:
  - □ 23 general purpose I/O pins
  - □ Has two 8-bit PWM and two 16-bit PWM

## Coding

- Read the switch values from digital pins and analog pins
  - □ Use values to determine strength and on/off state
  - Adding delay to mitigate inconsistencies reading





| Requirements   | Verifications  | Results  |
|--|--|--|
| Can read potentiometer voltages and switches voltage                         | Connect voltages from 0V-5V to the input pins and print out readings | Development Board could read correct digital and analog values       |
| Using the analog and digital inputs, produce accurate duty ratio PWM signals | Output register values should change with analog signals             | Output register values changed according the input values separately |

| 14:21:17.202 -> | Master:1 WhiteSwitch:1 | InfraSwitch0 | WhiteAnalog:623 | InfraAnalog:0  |
|-----------------|------------------------|--------------|-----------------|----------------|
| 14:21:17.267 -> | Master:1 WhiteSwitch:1 | InfraSwitch0 | WhiteAnalog:623 | InfraAnalog:0  |
| 14:21:17.332 -> | Master:1 WhiteSwitch:1 | InfraSwitch0 | WhiteAnalog:623 | InfraAnalog:0  |
| 14:21:17.396 -> | Master:1 WhiteSwitch:1 | InfraSwitch1 | WhiteAnalog:623 | InfraAnalog:80 |
| 14:21:17.461 -> | Master:1 WhiteSwitch:1 | InfraSwitch1 | WhiteAnalog:623 | InfraAnalog:80 |
| 14:21:17.556 -> | Master:1 WhiteSwitch:1 | InfraSwitchl | WhiteAnalog:623 | InfraAnalog:80 |



#### **Switches - SPST Toggle Switches**

- Main switch
- □ White LED switch
- Infrared LED switch

#### Potentiometers - 100k Ohm

- □ White LED, Infrared LED
- Output is a voltage sent to the microcontroller
- Necessary for PWM output from microcontroller so LED systems can be set to the correct brightness



#### User Interface: Requirements, Verifications and Results



| Requirements   | Verifications   | Result  |
|--|---|---|
| -Switches should control LEDs  | The voltage that is being supplied<br>to the switches was tested to see<br>if the on/off functionality of the<br>switch was correctly changing the<br>voltage | <ul> <li>-Main switch turns on entire LED system.</li> <li>-The infrared and white LED turn on when the switches are turned on</li> </ul> |
| The potentiometers should<br>change the voltage read by<br>the microcontroller | The change in potentiometer<br>should appropriately change the<br>voltage sent to the<br>microcontroller  | The potentiometers change the brightness as expected  |

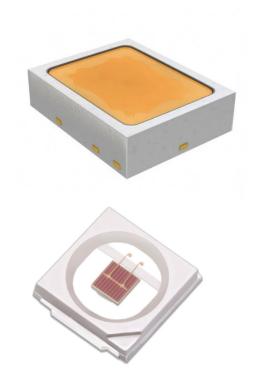


### White Light LEDs

- □ 24 white light LEDs
- □ Nominal Rating: 3V and 60mA
- □ 400-700nm wavelength
- Used to aid the surgeon in viewing the affected area better

## **Infrared Light LEDs**

- 780nm wavelength
- □ Nominal Rating: 2.8V and 350mA
- □ Able to illuminate skin cancer cells specifically





#### LED Drivers



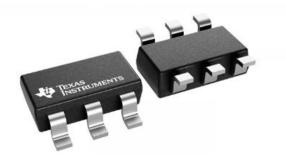
## White Light LED Drivers

- Dual Output LED Driver: ISL97682IRTZ-TK
- Output at 30kHz
- Controls through 8-bit PWM signal
- □ Boost LED Driver- steps-up from 12.6V to 36V

## Infrared Light LED Drivers

- □ Synchronous Buck LED Driver: TPS54200
- □ Steps-down from 12.6V to 2.8V
- □ Fixed 600 kHz PWM frequency
- Controls through 8-bit PWM signal





#### LED Driver: Requirements, Verifications and Results

| Requirements  | Verifications  | Results  |
|---|--|--|
| The voltage and current<br>supplied produced should<br>not exceed:<br>White LED Maximum: 3V<br>and 120mA<br>Infrared LED Maximum: 3V<br>and 500mA | Connect voltage and current<br>probes to the output signals to<br>the LEDs at different PWM duty | -Infrared LED driver meets<br>requirement<br>-White LED driver able to<br>produce total of 2V                                |
| Produce the duty ratio and<br>frequency of the current<br>waveform as requested by<br>the microcontroller.  | Connect current probe to LED driver outputs and vary brightness                                  | -Infrared LED driver able to vary<br>PWM duty ratio without flickering<br>-White LED driver unable to vary<br>PWM duty ratio |



# Functional Test Results

ELECTRICAL & COMPUTER ENGINEERING

## Successes

- Able to control the user-interface and successfully read the inputs from the user
- □ Infrared light LED can be turned on and controlled
- Bucking action of infrared LED driver works
- □ All 24 white LEDs can be turned on

## **Setbacks**

- □ Voltage regulator (LDO) short-circuited
- □ Failure of LDO lead to failure of microcontroller
- □ White light LED driver was not able to produce PWM
- □ Were not able to source/contact the infrared LED





#### Engineering Explanations

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## **Linear Dropout Regulator**

- Short circuited due to the overheating during the soldering or heat oven process
- Overvoltage spikes
- Dropping 7 volts may have caused overheating

## Microcontroller

- LDO short-circuit also short-circuited the microcontroller
- Bootloader compatibility
- Difference in clock speed and bootloader clock speed

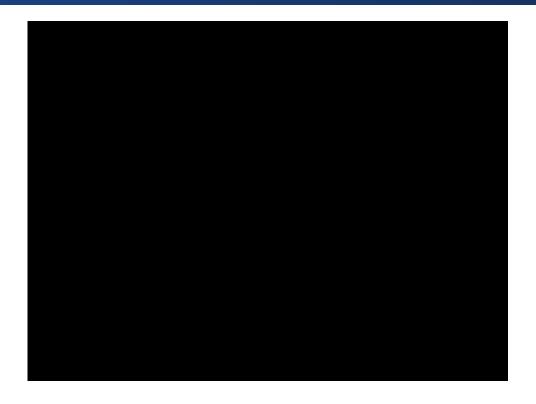


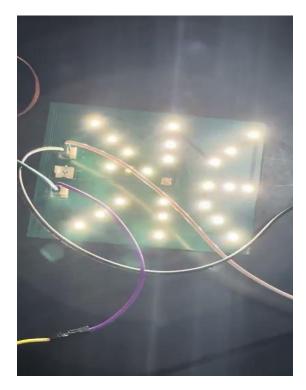
## White LED Driver

- Unable to boost, this could be because there could have been overvoltage and current spikes due to the short-circuit on the board
- Component failure due to overheating when we soldering with a heat gun

#### Video Evidence









# Conclusion

#### What We Would Have Done Differently

- Look into using a different microcontroller
- Replace the LDO regulator with a buck converter
- Choose an LED driver with more support and resources

#### **Future Work**

- Make the user-interface digital
  - ESP microcontroller can connect through bluetooth
- Sensor Integration
  - Based on the user's hand movements, the brightness of the LEDs can be modified
- □ Integration with the microscopic camera

