



ECE 445 Senior Design

Electrical & Computer Engineering

Group 29

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Introduction



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Problem



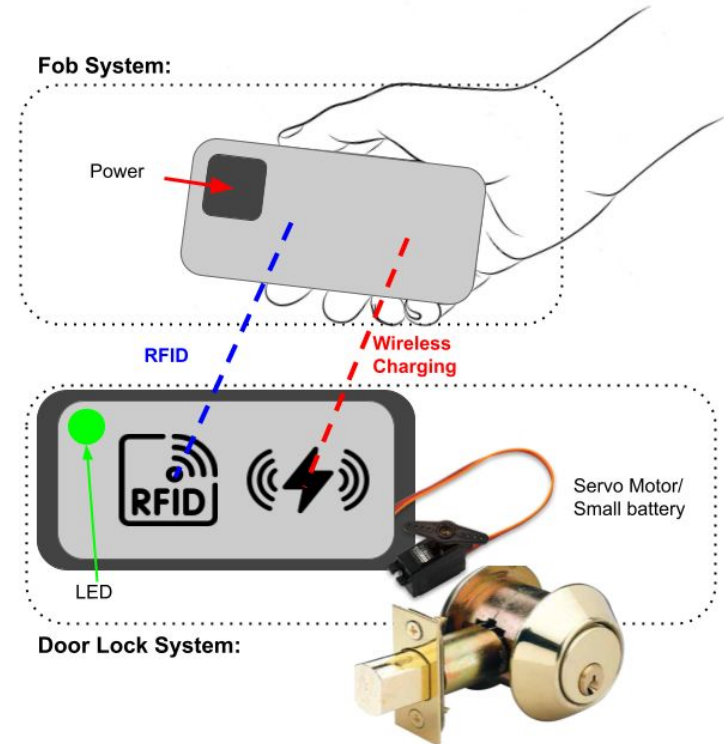
Have you ever struggled with grocery bags at a locked door after climbing stairs, only to place them down to unlock the door? Or needed quick entry to avoid danger outside? Smart locks can help, but traditional ones still need a passcode, which can be slow and error-prone.

Solution



Our solution: an RFID system with Qi Wireless Charging for automatic door unlocking.

- No need for keys or passcodes—just approach with a wireless transmitter fob.
- The door unlocks when the fob is detected, which powers both the motor and the circuitry inside the door.



Agenda



1. Design
2. Results
3. Challenges
4. Changes
5. Conclusions
6. Future Work



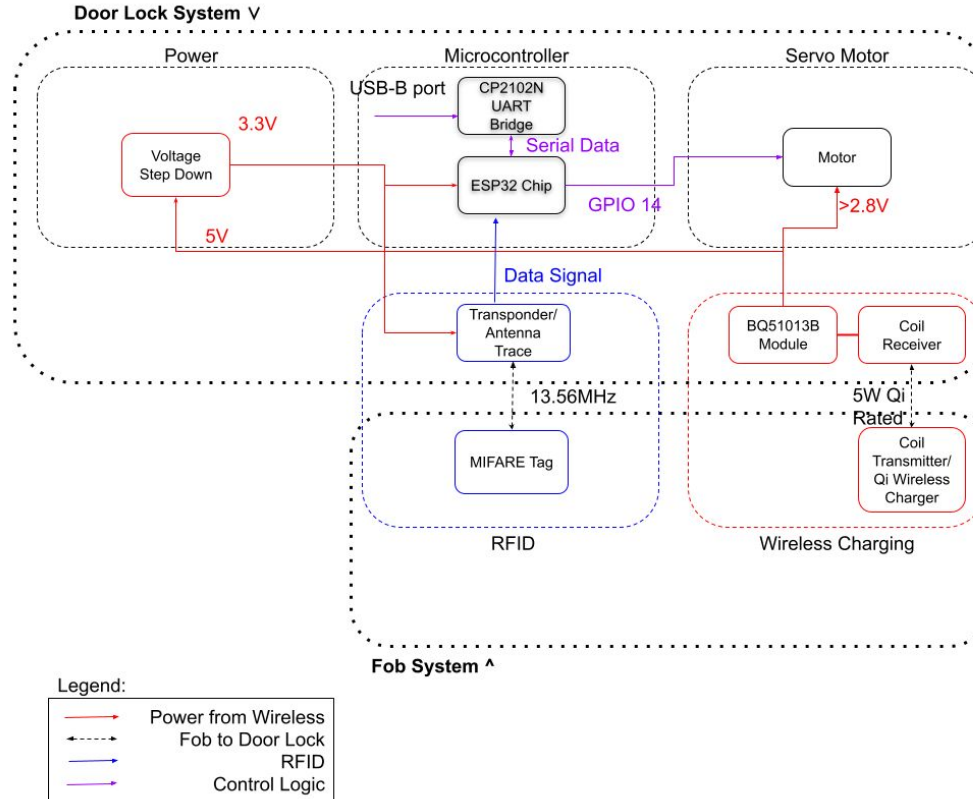
High Level Requirements

1. The RFID must uniquely identify the correct fob using RFID technology. Success will be indicated by a green LED visible to the user 1 second after detection.
2. The fob must transfer power to turn the deadbolt within 15 seconds.
3. The deadbolt must continue through its full range of motion even when the fob is removed prematurely by engaging the backup battery in the door.

Subsystems

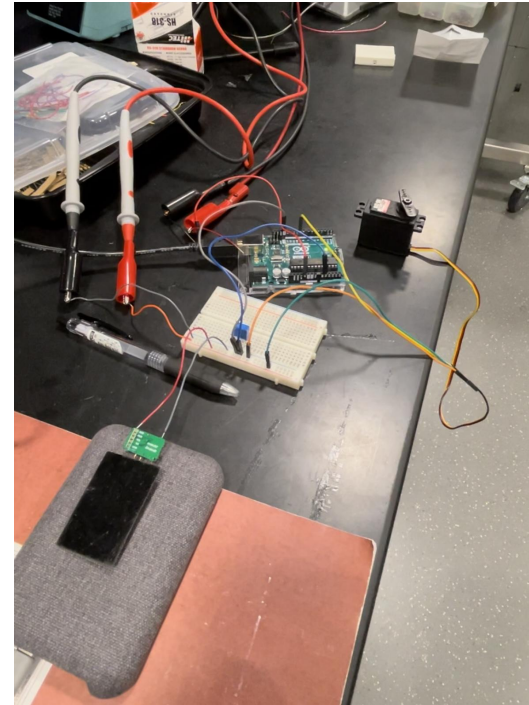
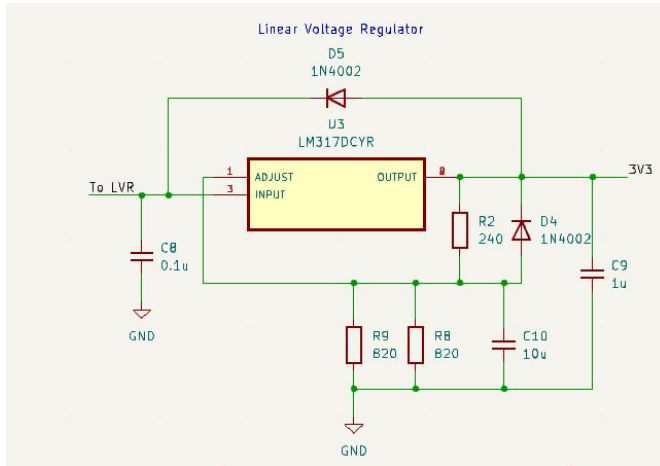
- RFID/Indicator LED
- Wireless Charging
- Micro Controller
- Servo Motor
- Power

Design (Block Diagram)



Wireless Power Subsystem

- Using a wireless power receiver coil to turn a servo motor
- Power Subsystem utilizes Voltage Regulator



Testing the Wireless Power Receiver Module

Design

R&V Table Examples

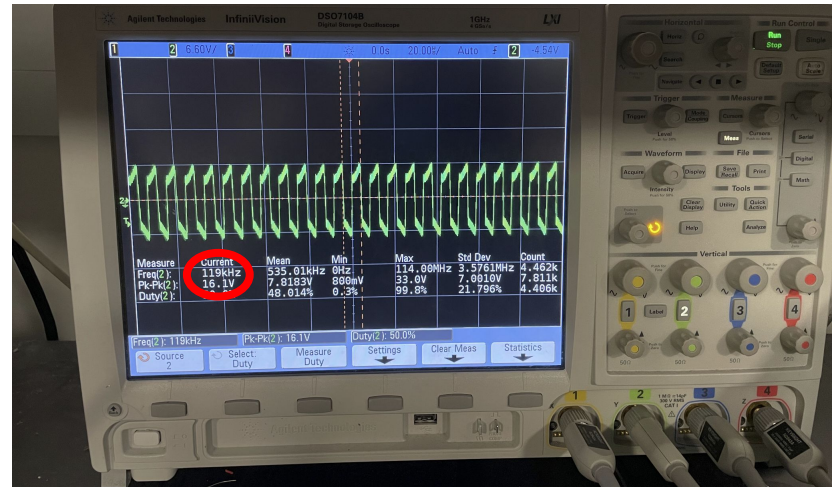
Requirement: 5W Charging

Verification: Used multimeter to confirm 4.992V DC and calculate power using 1A expected current.



Requirement: Wireless Power Consortium transfers power through mutual inductance. Using our coil arrangement we are expecting frequencies from 105kHz to 205kHz

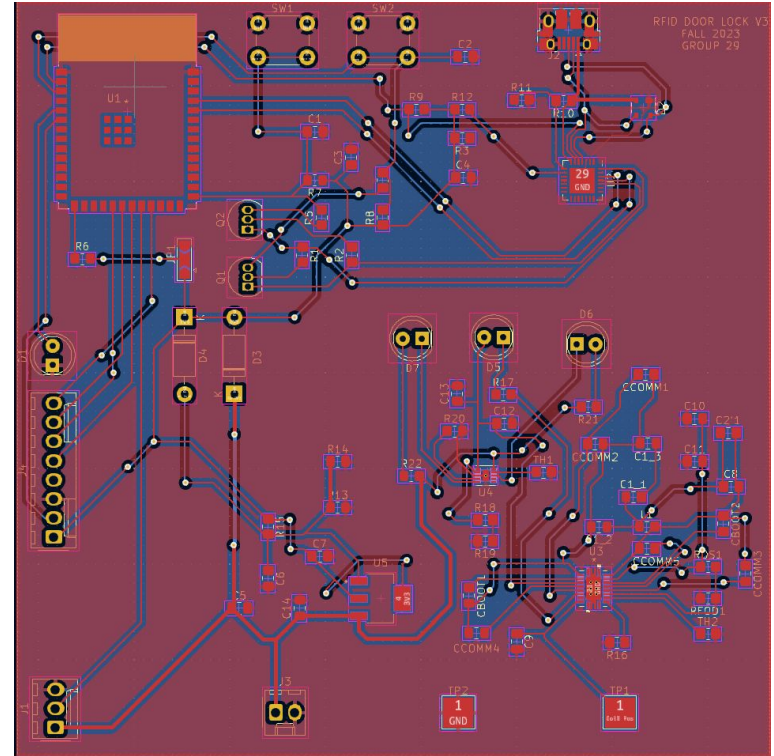
Verification: 119kHz shown on oscilloscope in red



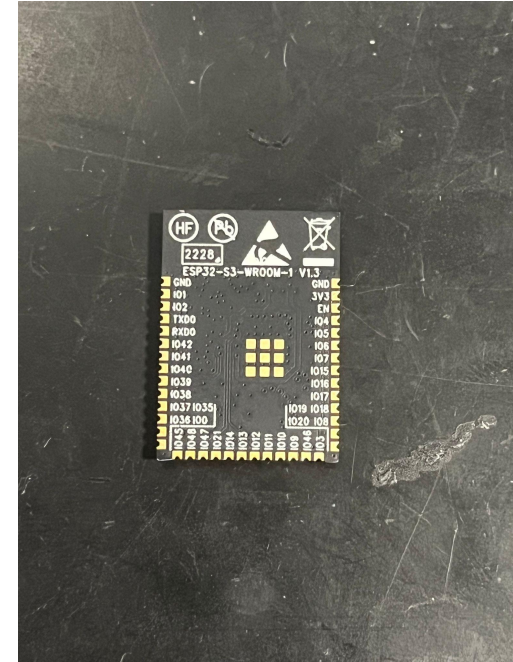
Design



- Board contains:
 - ESP32 and required circuitry
 - Wireless charger receiver circuit
 - Battery charging circuit
 - Linear voltage regulator
 - USB to UART bridge



- RFID subsystem has of three parts:
 - The RFID receiver
 - The RFID tag
 - The ESP32 microcontroller
- ESP32 is the brains of the project.



ESP32 Microchip

```
1 // Libraries
2 #include <SPI.h>
3 #include <MFRC522.h>
4 #include <ESP32Servo.h>
5
6 // Constants
7 #define SS_PIN 21
8 #define RST_PIN 6
9 #define LED_PIN 38 // Define the pin where the LED is connected
10
11 // Fixed RFID UID to compare with
12 const byte fixedUID[4] = {227, 252, 203, 13};
```

Pin assignments, Headers, RFID UID

```
22 void setup() {
23     Serial.begin(115200);
24     SPI.begin();
25     rfid.PCD_Init();
26     myServo.attach(servoPin);
27     pinMode(LED_PIN, OUTPUT); // Initialize the LED pin as an output
28     Serial.println(F("Initialize System"));
29 }
```

Initializing RFID, Servo, LED

```
35 void readRFID(void) {
36     if (rfid.PICC_IsNewCardPresent() && rfid.PICC_ReadCardSerial()) {
37         // Compare the current UID with the fixed UID
38         bool isSameUID = true;
39         for (byte i = 0; i < 4; i++) {
40             if (fixedUID[i] != rfid.uid.uidByte[i]) {
41                 isSameUID = false;
42                 break;
43             }
44         }
45         if (!isSameUID) {
46             Serial.println(F("Error: RFID does not match the fixed RFID!"));
47         } else if (!servoMoved) {
48             Serial.println(F("Valid RFID read. Moving servo."));
49             myServo.write(180);
50             digitalWrite(LED_PIN, HIGH); // Turn on the LED
51             delay(1000);
52             myServo.write(90);
53             digitalWrite(LED_PIN, LOW); // Turn off the LED
54             servoMoved = true;
55         }
56         cardPresent = true;
57     } else if (cardPresent) {
58         servoMoved = false;
59         cardPresent = false;
60         myServo.write(90);
61     }
62 }
```

Reading RFID, Moving Motor, Lighting LED

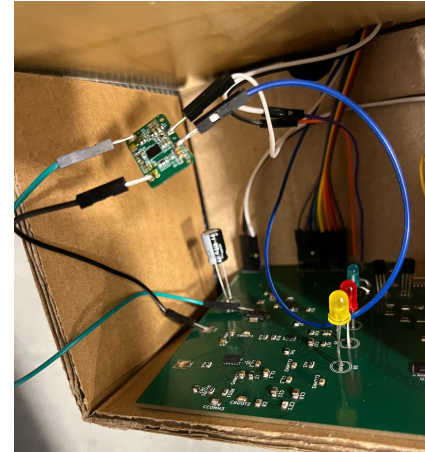
Results



Door without
Motor and PCB



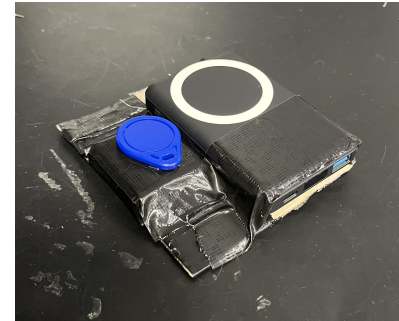
The Servo Motor/PCB



PCB



Fob Utilization

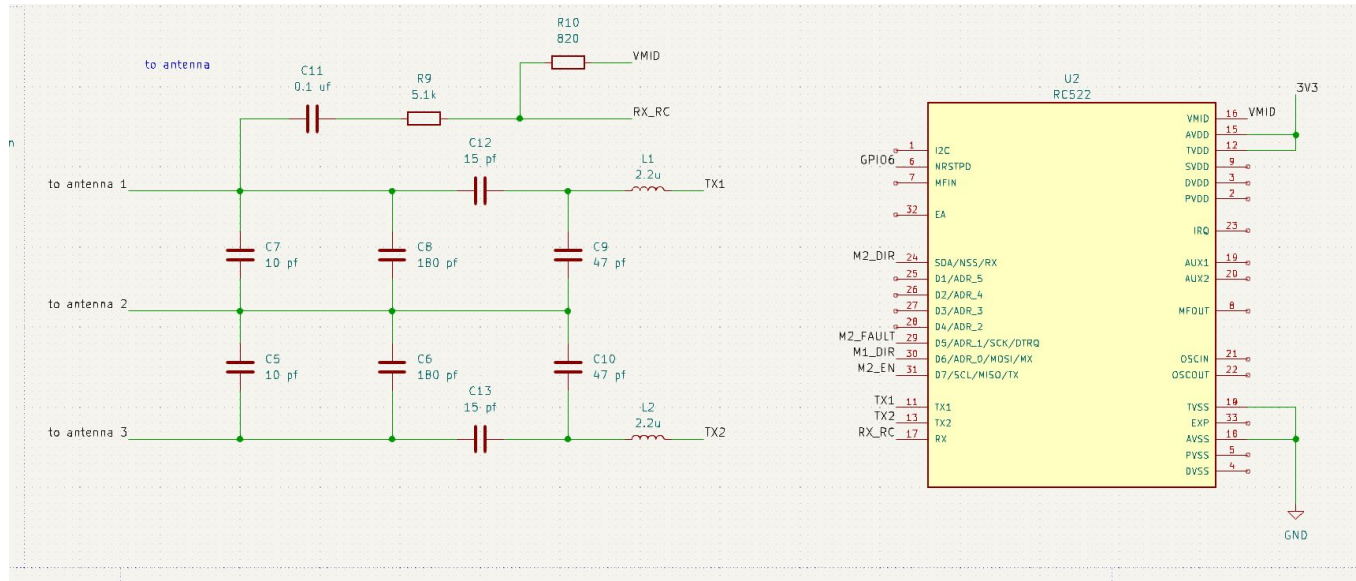


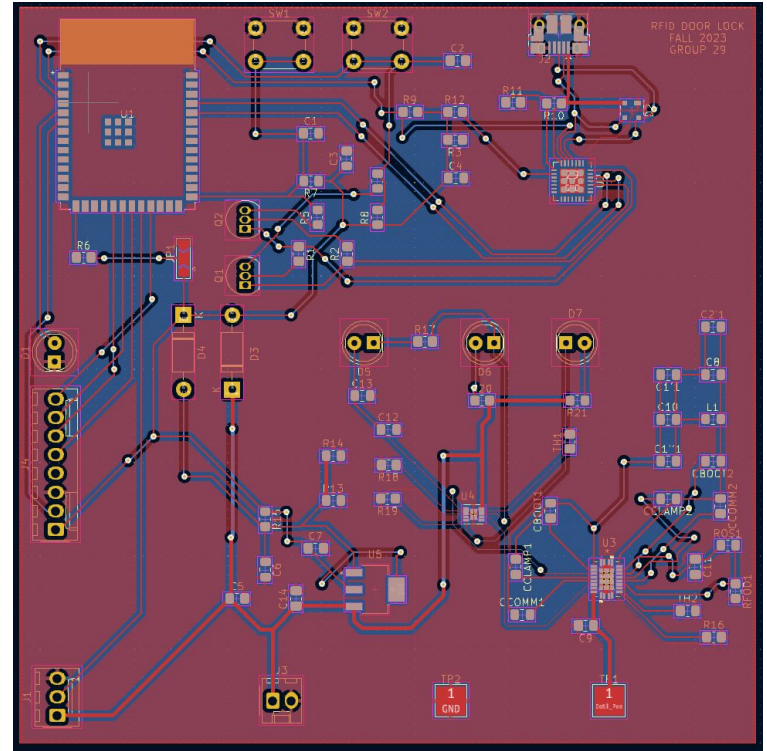
Fob

Changes



Removed RFID circuitry

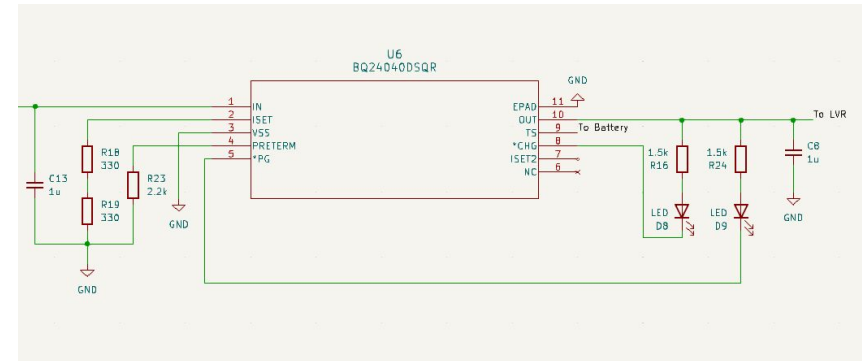
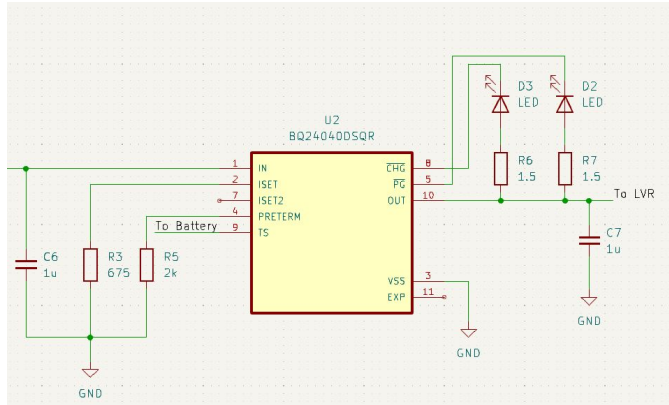




Changes



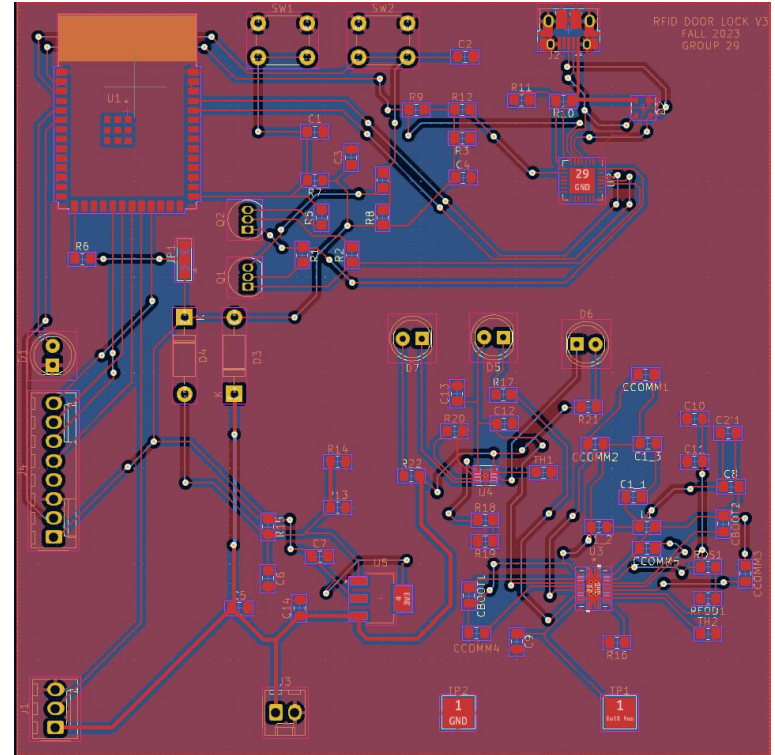
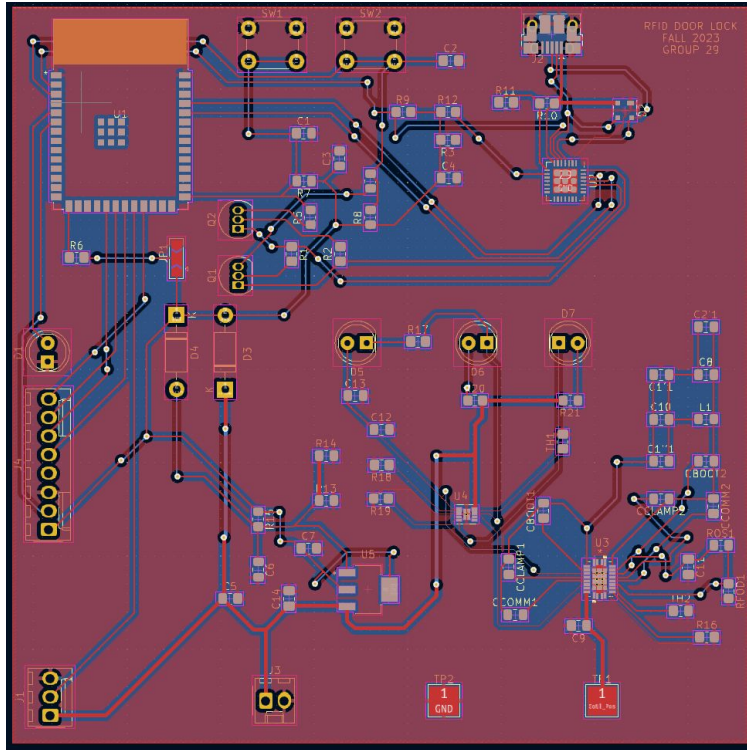
- Changes to wireless charging schematic to revise component values
- However, in the final design we used the Module bought from off the shelf
- This caused us to use a capacitor connected across the terminals where the battery was supposed to go



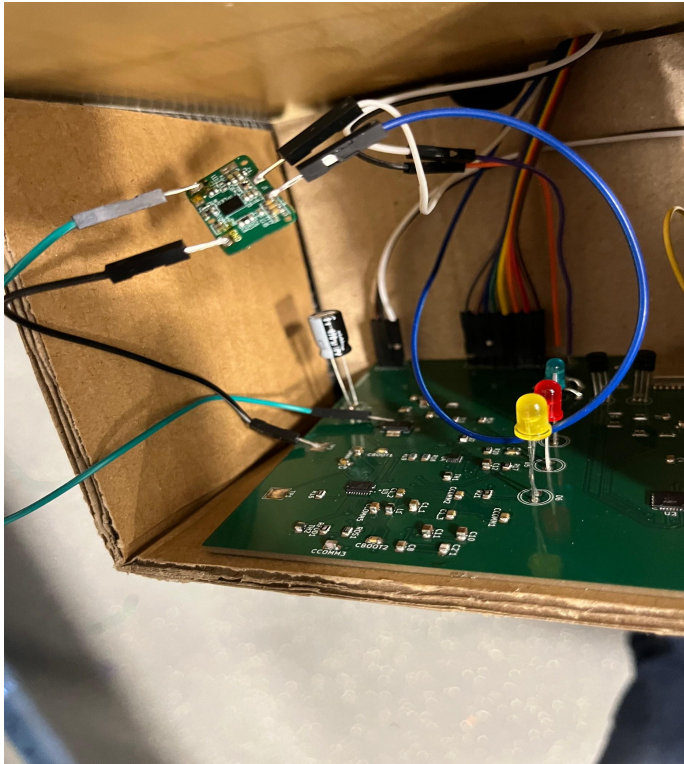
Changes



Revised Wireless Charging circuit



Changes (Physical Design)



PCB inside the cardboard box

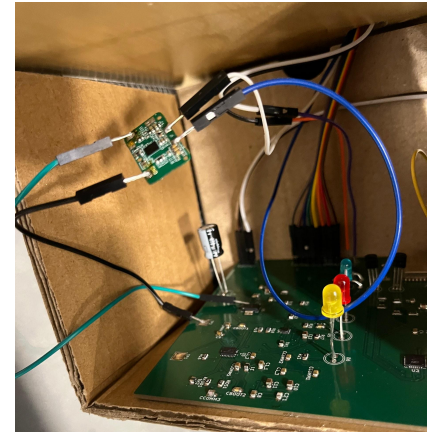
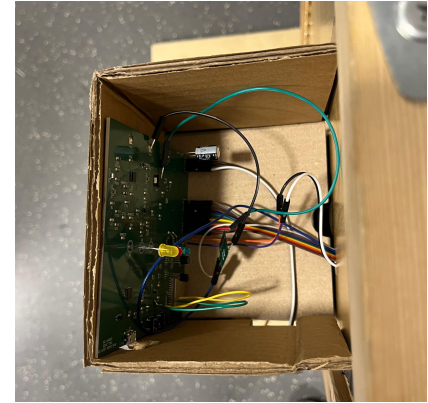


LED, RFID Receiver, Wireless
Charger Receiver

Challenges



- Wireless charging/battery charger circuit
 - Bypassed with dev board and capacitor
- Programming ESP32
 - Jumper wires properly connect UART bridge and ESP32
- Physically lining up charger and tag
 - Fob carefully designed with guidelines on door



Conclusions



Successes

- The ESP32 Microcontroller was programmable using UART bridge on PCB
- The RFID Tag was uniquely recognized
- LED lights up on detection
- Deadbolt turned in under 15 seconds

What We Learned

- Be attentive and proactive when ordering parts
 - Look for back orders
- Create realistic expectations for design
 - Moved RFID sensor to external module

- Re-lock door
- More powerful inductor coil/charger
- Compact the entire module

Thank You

Group Members:

Max, Adam, Antonio

Questions?