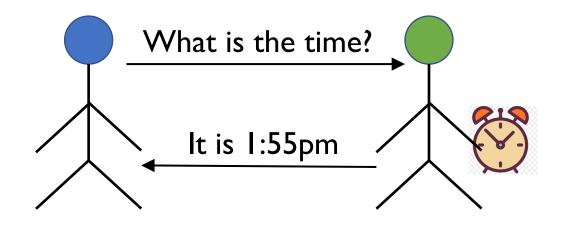
Distributed Systems

CS425/ECE428

Instructor: Radhika Mittal

While we wait...



Bluey does not own a clock, and wants to know the time. He sends a message to Greeny asking the time, and Greeny sends a response as soon as he receives the request. Bluey records that it took 6 minutes for him to receive Greeny's response after sending his request.

Given this information, what time should Bluey assume it actually is when he receives Greeny's message? Can he be totally accurate?

Logistics Related

- We have shared the VM mappings with Eng-IT.
 - We'll update you once the clusters have been assigned.

• We will add all registered students to Gradescope early next week.

- <u>https://courses.grainger.illinois.edu/ece428/sp2025/mps/mp0.html</u>
- Lead TA: Emerson Sie
- Task:
 - Collect events from distributed nodes.
 - Aggregate them into a single log at a centralized logger.
- Objective:
 - Familiarize yourself with the cluster development environment.
 - Practice distributed experiments and performance analysis.
 - Build infrastructure that might be useful in future MPs.

• We provide you with a script that generates logs

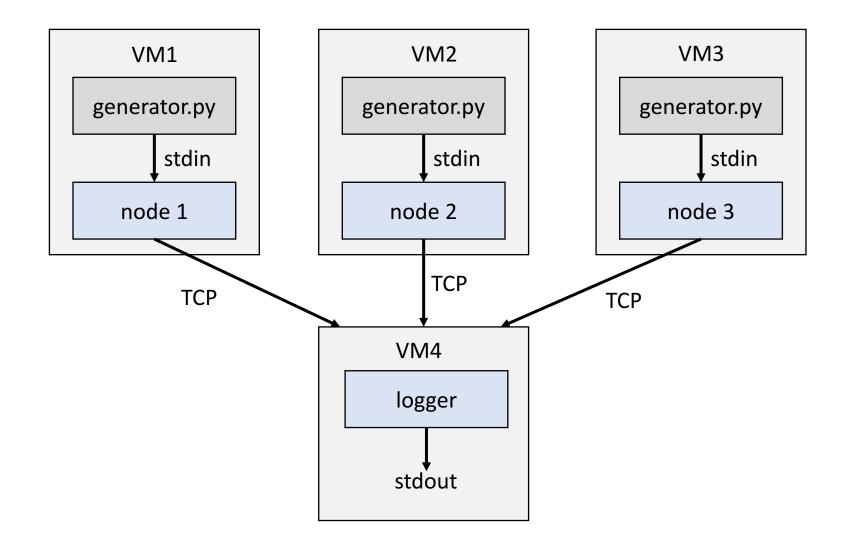
generator.py

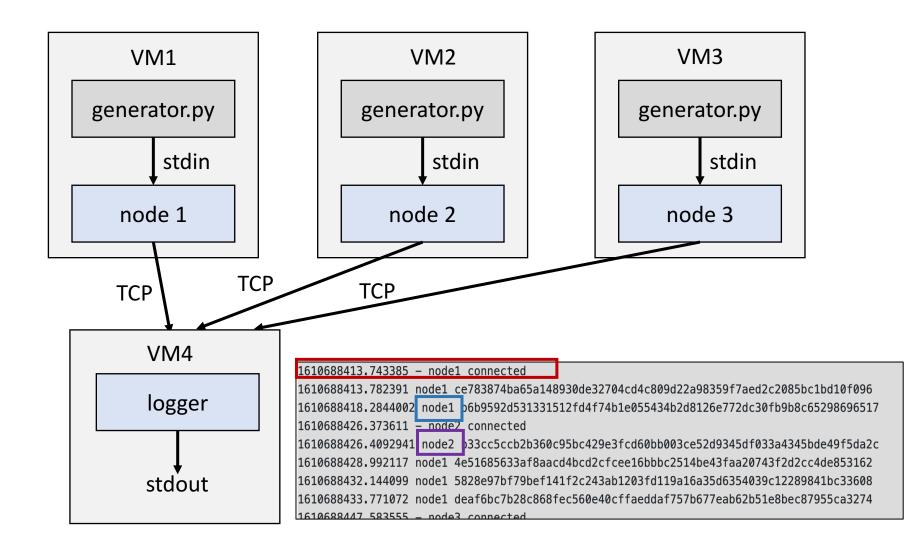
Event name (random)

Timestamp

% python3 generator.py 0.1

1610688413.782391ce783874ba65a148930de32704cd4c809d22a98359f7aed2c2085bc1bd10f0961610688418.2844002b6b9592d531331512fd4f74b1e055434b2d8126e772dc30fb9b8c652986965171610688428.9921174e51685633af8aacd4bcd2cfcee16bbbc2514be43faa20743f2d2cc4de8531621610688432.1440995828e97bf79bef141f2c243ab1203fd119a16a35d6354039c12289841bc336081610688433.771072deaf6bc7b28c868fec560e40cffaeddaf757b677eab62b51e8bec87955ca32741610688449.1301062ca6e5225e2ea02c1174701dd0320954fbfffb51dbcd9d15717e11d7e40556efb1610688455.484428ed4b1eb8a7bd980a1f0da41f5d6513e919e2bf201ba9ec9f9c05201bd777af941610688463.5431338110f0cc37404a10989bfe14ae83224a73e642bb676ded625b08ed7d3e439706





- Run two experiments
 - 3 nodes, 2 events/s each
 - 8 nodes, 5 events/s each
- Collect graphs of two metrics:
 - Delay between event generation at the node and it appearing in the centralized log.
 - Amount of bandwidth used by the central logger.
 - Need to add instrumentation to your code to track these metrics.

- Due on Feb 12, 11:59pm
 - Late policy: Can use part of your 168hours of grace period accounted per student over the entire semester.
- Carried out in groups of I-2
 - Same expectations regardless of group size.
 - Fill out form on CampusWire to get access to cluster.
 - Getting cluster access may take some time.
 - But you can start coding now!
- Can use any language.
 - Supported languages are C/C++, Go, Java, Python.
 - Remember that MP2 must be in Go.

Today's agenda

- Time and Clocks
 - Chapter 14.1-14.3
- Logical Clocks and Timestamps
 - Chapter 14.4

Clock Skew and Drift Rates

- Each process has an internal clock.
- Clocks between processes on different computers differ:
 - Clock skew: relative difference between two clock values.
 - Clock drift rate: change in skew from a perfect reference clock per unit time (measured by the reference clock).
 - Depends on change in the frequency of oscillation of a crystal in the hardware clock.

• Synchronous systems have bound on maximum drift rate.

Two forms of synchronization

- External synchronization
 - Synchronize time with an authoritative clock.
 - When accurate timestamps are required.
- Internal synchronization
 - Synchronize time internally between all processes in a distributed system.
 - When internally comparable timestamps are required.
- If all clocks in a system are externally synchronized, they are also internally synchronized.

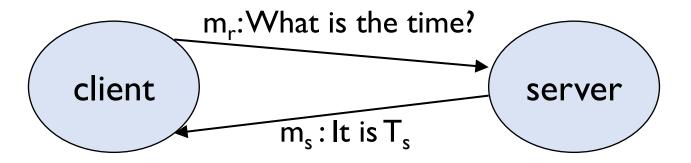
Synchronization Bound

- Synchronization bound (D) between two clocks A and B over a real time interval I.
 - |A(t) B(t)| < D, for all t in the real time interval I.
 - Skew(A, B) < D during the time interval I.
 - A and B agree within a bound D.
 - If A is authoritative, D can also be called *accuracy bound*.
 - B is *accurate* within a bound of D.
- Synchronization/accuracy bound (D) at time 't'
 - worst-case skew between two clocks at time 't'
 - Skew(A, B) < D at time t

Q: If all clocks in a system are externally synchronized within a bound of D, what is the bound on their skew relative to one another?

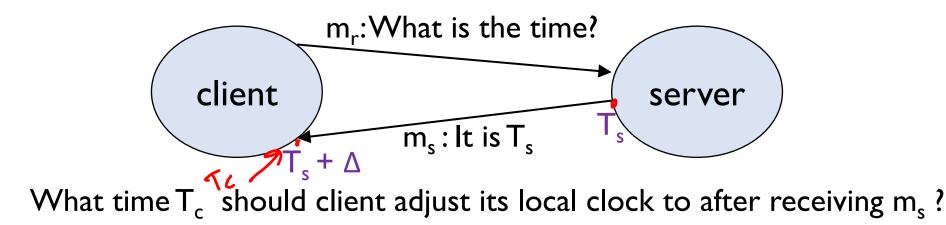
A: 2D. So the clocks are internally synchronized within a bound of 2D.

Synchronization in synchronous systems

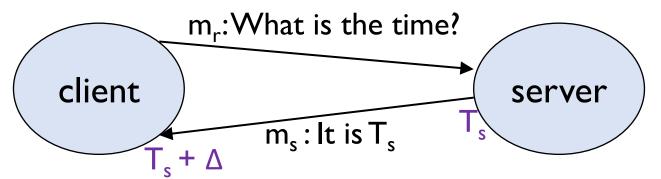


What time T_c should client adjust its local clock to after receiving m_s ?

Synchronization in synchronous systems



Synchronization in synchronous systems

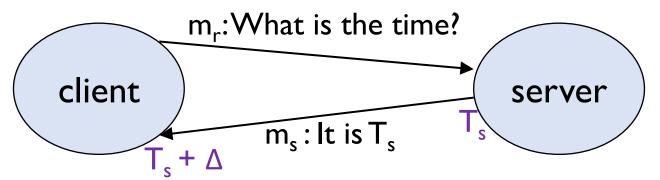


What time T_c should client adjust its local clock to after receiving m_s ?

Let max and min be maximum and minimum network delay. If $T_c = T_s$, skew(client, server) $\leq max$. If $T_c = (T_s + max)$, skew(client, server) $\leq (max - min)$ If $T_c = (T_s + min)$, skew(client, server) $\leq (max - min)$ If $T_c = (T_s + (min + max)/2)$, skew(client, server) $\leq (max - min)/2$

Synchronization in asynchronous systems

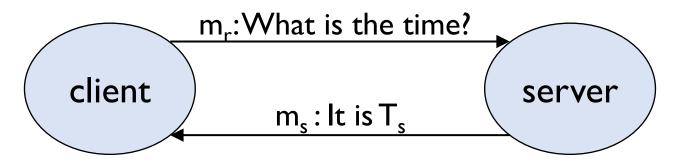
- Cristian Algorithm
- Berkeley Algorithm
- Network Time Protocol



What time T_c should client adjust its local clock to after receiving m_s ?

Client measures the round trip time (T_{round})

= time difference between when client sends m_r and receives m_s .



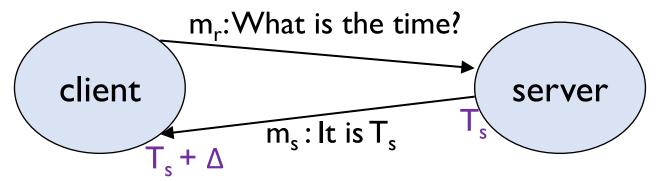
What time $\mathsf{T}_c\;$ should client adjust its local clock to after receiving $\mathsf{m}_s\;\!?$

Client measures the round trip time (T_{round})

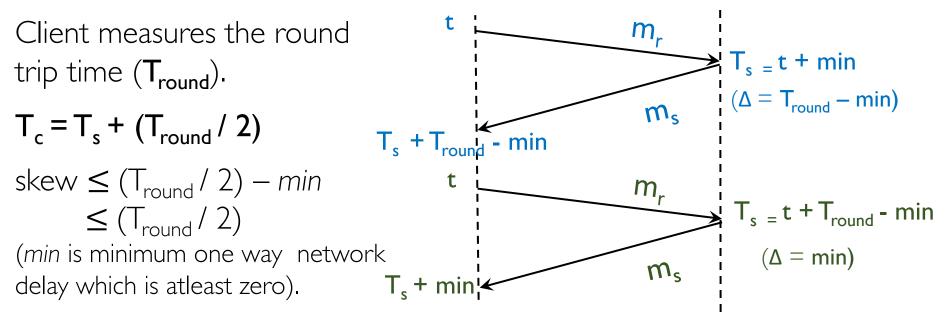
$$\begin{split} \mathbf{T_c} &= \mathbf{T_s} + (\mathbf{T_{round}} / 2) \\ \text{skew} &\leq (\mathbf{T_{round}} / 2) - \min \\ &\leq (\mathbf{T_{round}} / 2) \\ (\min \text{ is minimum one way network} \\ \text{delay which is atleast zero).} \end{split}$$

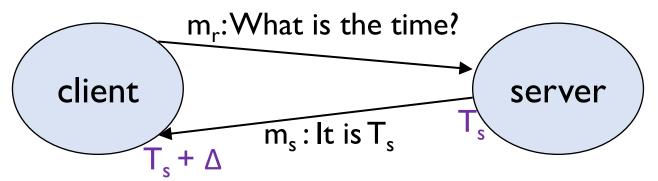
Try deriving the worst case skew!

Hint: client is assuming its one-way delay from server is $\Delta = (T_{round}/2)$. How off can it be?



What time T_c should client adjust its local clock to after receiving m_s ?





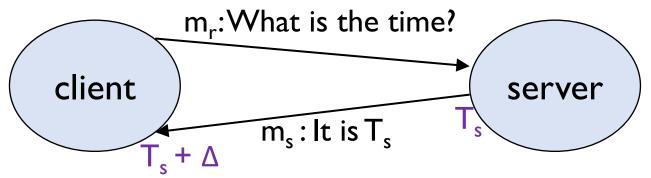
What time T_c should client adjust its local clock to after receiving m_s ?

Client measures the round trip time (T_{round}) .

 $T_{c} = T_{s} + (T_{round} / 2)$

skew $\leq (T_{round} / 2) - min$ $\leq (T_{round} / 2)$ (*min* is minimum one way network delay which is atleast zero). Improve accuracy by sending multiple spaced requests and using response with smallest T_{round} .

Server failure: Use multiple synchronized time servers.



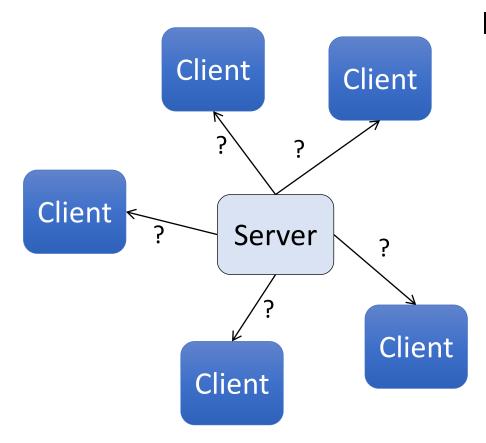
What time T_c should client adjust its local clock to after receiving m_s ?

Client measures the round trip time (T_{round}) .

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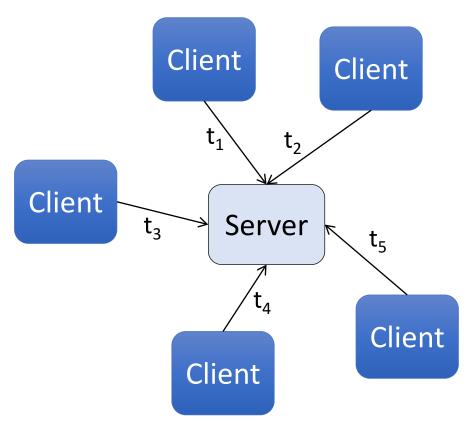
Cannot handle faulty time servers.

Only supports internal synchronization.



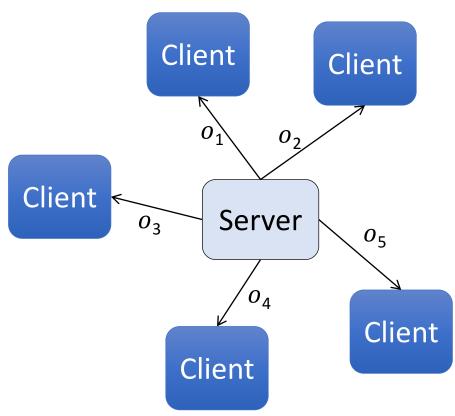
I. Server periodically polls clients: "what time do you think it is?"

Only supports internal synchronization.



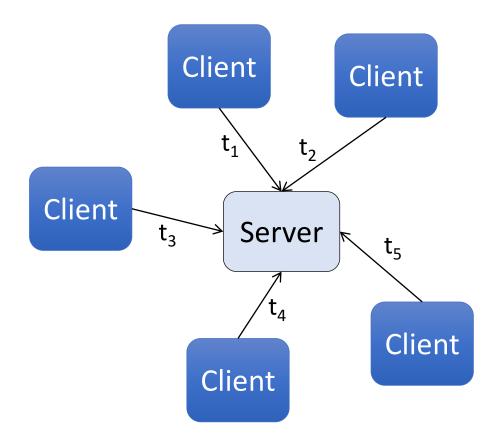
- I. Server periodically polls clients: "what time do you think it is?"
- 2. Each client responds with its local time.
- 3. Server uses Cristian algorithm to estimate local time at each client.
- 4. Average all local times (including its own) use as updated time.

Only supports internal synchronization.



- I. Server periodically polls clients: "what time do you think it is?"
- 2. Each client responds with its local time.
- 3. Server uses Cristian algorithm to estimate local time at each client.
- 4. Average all local times (including its own) use as updated time.
- 5. Send the offset (amount by which each clock needs adjustment).

Only supports internal synchronization.

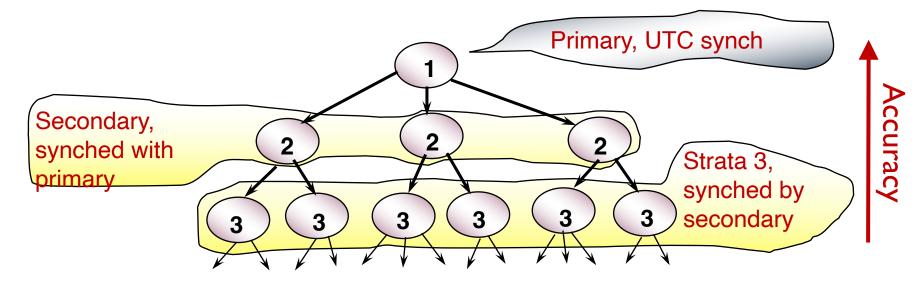


Handling faulty processes: Only use timestamps within some threshold of each other.

Handling server failure: Detect the failure and elect a new leader.

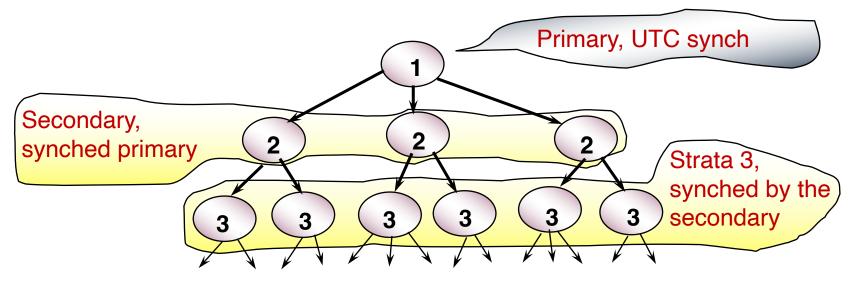
Network Time Protocol

Time service over the Internet for synchronizing to UTC.



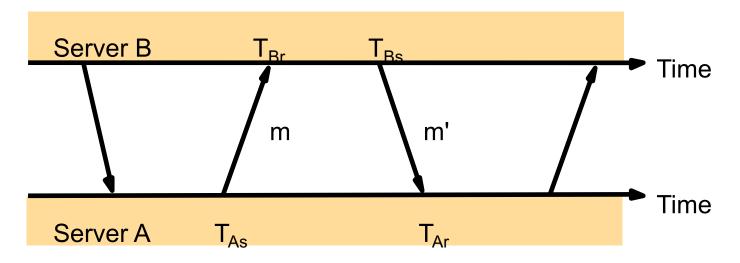
Hierarchical structure for scalability. Multiple lower strata servers for robustness. Authentication mechanisms for security. Statistical techniques for better accuracy.

Network Time Protocol

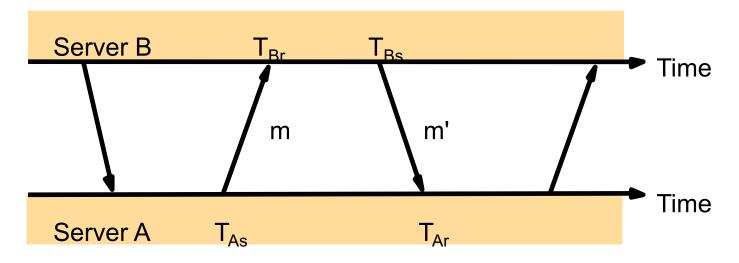


How clocks get synchronized:

- Servers may *multicast* timestamps within a LAN. Clients adjust time assuming a small delay. *Low accuracy*.
- Procedure-call (Cristian algorithm). Higher accuracy.
- Symmetric mode used to synchronize lower strata servers. Highest accuracy.



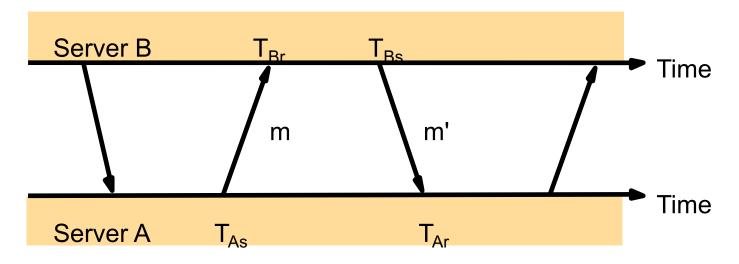
- A and B exchange messages and record the send and receive timestamps.
 - T_{Br} and T_{Bs} are local timestamps at B.
 - T_{Ar} and T_{As} are local timestamps at A.
 - A and B exchange their local timestamp with eachother.
- Use these timestamps to compute offset with respect to one another.



- t and t': actual transmission times for m and m'(unknown)
- o: true offset of clock at B
- o_i: <u>estimate</u> of actual offset between the two clocks

$$T_{Br} = T_{As} + t + o$$
$$T_{Ar} = T_{Bs} + t' - o$$

relative to clock at A (unknown) $O = ((T_{Br} - T_{As}) - (T_{Ar} - T_{Bs}) + (t' - t))/2$ $o_i = ((T_{Br} - T_{As}) - (T_{Ar} - T_{Bs}))/2$ $o = o_i + (t' - t)/2$

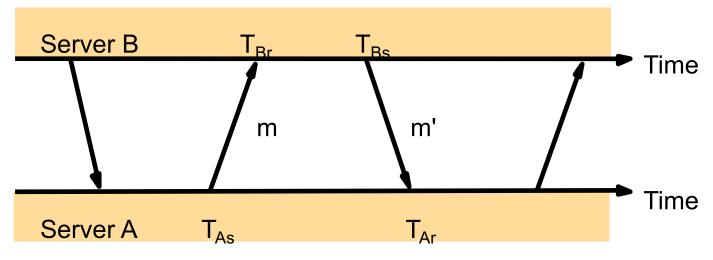


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(n)
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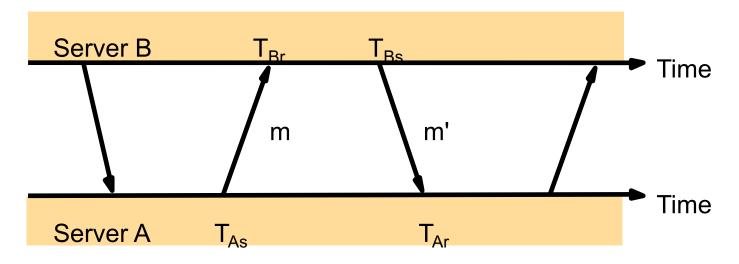
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- o_i: <u>estimate</u> of actual offset between the two clocks
- d_i: estimate of <u>accuracy</u> of o_i; d_i=t+t'
- d_i/2: synchronization bound

 $o = o_i + (t' - t)/2$

How off can o_i be?

- We do not know, t, t' or (t'-t)
- We do not know max or min delays.
- We know (t + t'), t ≥ 0, t' ≥ 0
 d_i = t + t'
- $(t'-t) \sim = (t + t')$, if $t \sim = 0$ (one extreme)
- $(t'-t) \sim = -(t + t')$, if $t' \sim = 0$ (other extreme)

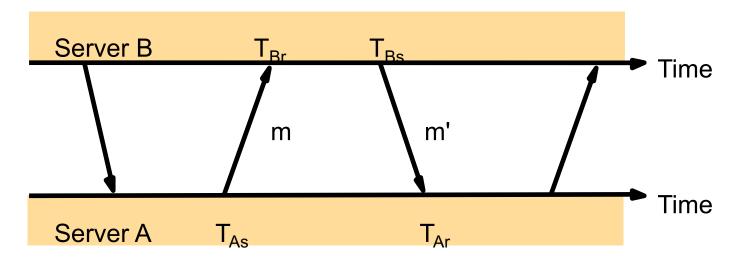
 $(o_i - d_i / 2) \le o \le (o_i + d_i / 2)$



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- o: true offset of clock at B
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$$T_{Br} = T_{As} + t + o$$
$$T_{Ar} = T_{Bs} + t' - o$$

relative to clock at A (unknown) $O = ((T_{Br} - T_{As}) - (T_{Ar} - T_{Bs}) + (t' - t))/2$ $o_i = ((T_{Br} - T_{As}) - (T_{Ar} - T_{Bs}))/2$ $o = o_i + (t' - t)/2$ $d_i = t + t' = (T_{Br} - T_{As}) + (T_{Ar} - T_{Bs})$ $(o_i - d_i / 2) \le o \le (o_i + d_i / 2)$ given t, t' ≥ 0



A and B exchange messages and record the send and receive timestamps.

Use these timestamps to compute offset with respect to one another (\mathbf{o}_i) .

A server computes its offset from multiple different sources and adjust its local time accordingly.

Synchronization in asynchronous systems

- Cristian Algorithm
 - Synchronization between a client and a server.
 - Synchronization bound = $(T_{round} / 2) min \leq T_{round} / 2$
- Berkeley Algorithm
 - Internal synchronization between clocks.
 - A central server picks the average time and disseminates offsets.
- Network Time Protocol
 - Hierarchical time synchronization over the Internet.