Final Review

Grading Update

- HW5 and MP2 graded
- This leaves:
 - HW6 (6%) + final (33%) for 3-credit
 - HW6 (0-~4%) + MP3 (7% + 3% bonus) + final (25%) for 4-credit
- Participation grade (1%)
 - Will be used to bump people to next grade
 - Based on your activity in CampusWire
- Reminder:
 - CR/NC means course does not affect GPA, but grade < C- means no credit
 - If you keep a letter grade, anything >= D- is a pass

Final Logistics

Timed Exam: Wed, May 13, 8–11 a.m.

- Format similar to midterm 2
 - Exam released to you at 8 a.m.
 - Upload answer sheet to Gradescope by 11 a.m.
 - Open book, but individual work
 - Zoom room + Google doc for clarifications
- Topic coverage: 50% from MT1+MT2, 50% new material
- Exam structure similar to MT1/MT2
 - Some multiple choice
 - Some short answer / synthesis
 - ~50% longer

Topic coverage (Part III, 50% of final)

- DHTs
- RPCs
- Distributed transactions
 - Concurrency, isolation, and deadlocks
 - Atomicity and 2PC
- Combining 2PC and Paxos; Spanner and linearizability
- Cloud computing and MapReduce
- Distributed data stores and Cassandra

Topic coverage (Parts I and II, 50% of final)

- System model and Failures
- Failure Detection
- Clock Synchronization
- Event ordering and Logical Timestamps
- Global Snapshot
- Multicast
- Mutual Exclusion

- Leader election
- Consensus
 - Formulation
 - Synchronous consensus
- Paxos
- FLP Theorem
- Bitcoin
- Raft

Distributed Hash Tables / Chord

Goal: horizontal scaling to millions of peers and data items

- Consistent hashing of keys, node IDs into a large (2¹²⁸–2²⁵⁶) key space
- Neighbor table: successors and fingers
- Finger-based routing:
 - O(log N) neighbors and O(log N) lookup steps
- Resilient structure to departing nodes / incorrect fingers
 - Track multiple successors and replicated keys at succ's/pred's
- Stabilization to restore DHT structure

RPC / RMI

Goal: Execute functions / procedures / methods on remote system, and implement *remote objects*

- Interface definition languages (
- External data representation (JSON, protobuf, etc.)
 - Marshaling / unmarshaling arguments
- Dealing with failures (at least once, at most once, idempotence)
- Remote objects
 - Proxy objects (client)
 - Dispatcher and skeleton (server)
 - Remote reference module

Transactions & Isolation/Concurrency

Goal: support high-level updates to data while maintaining useful properties

- ACID properties (Atomicity, Consistency, Isolation, Durability)
- Isolation
 - Lost update problem
 - Inconsistent retrieval problem
 - Serial equivalence
 - Conflicts (R/W, W/W)
 - Conflicts follow tx ordering === serial equivalence

Concurrency Techniques

Goal: achieve isolation / serial equivalence of transactions

- Two-phase locking: acquire locks during tx, release during commit/abort
 - Exclusive or shared locks
 - Lock promotion
- Timestamp ordering: ensure operations consistent with tx timestamp
 - Don't read data from newer tx's
 - Don't overwrite data from newer tx's
 - Abort (or skip writes) if order not satisfied
- Optimistics vs. pessimistic concurrency

Deadlocks

Goal: Avoid or detect deadlocks

- Deadlock requirements:
 - no preemption
 - hold and wait
 - circular wait
- Deadlock detection
 - timeout
 - centralized
 - edge chasing

- Deadlock avoidance: lock ordering
 - E.g., wait-die / wound-wait
 - E.g., dependency lists in timestamped concurrency
- Deadlock resolution
 - Abort newer tx

Two-phase Commit

Goal: ensure atomic commit across distributed participants

- Problem: need unanimous agreement to commit
 - not majority like Paxos / Raft
- First phase: precommit
 - any participant who agrees to commit must be able to proceed
- Second phase: commit/abort
- Crash-recover semantics
 - Use participant or coordinator log after recovery
 - Sacrifice availability

Distributed, replicated txs

Goal: combine distributed tx's (for horizontal scaling) with replication (for availability / durability)

- Run distributed transactions w/ 2PL, 2PC
- Replace each participant / coordinator with replica group
 - Use Paxos / Raft for replica consistency
- Expensive!

Spanner

Goal: make previous approach more efficient

- Maintain versioned / timestamped database
 - A log of each previous value of each object with tx timestamp
 - Enables read at a past time
- Transaction timestamp is *global time* that occurred during tx commit phase
 - Needs time with known bound on error
 - Commit wait to ensure property (can overlap with consensus protocols)
 - External consistency
- Reads can be lock free

What is a cloud?

• Cloud = Lots of storage + compute cycles nearby



- Cloud services provide:
 - managed *clusters* for distributed computing.
 - managed *distributed datastores*.

Must deal with immense complexity!

- Fault-tolerance and failure-handling
- Replication and consensus
- Cluster scheduling
- How would a cloud user deal with such complexity?
 - Powerful abstractions and frameworks
 - Provide **easy-to-use** API to users.
 - Deal with the complexity of distributed computing under the hood.

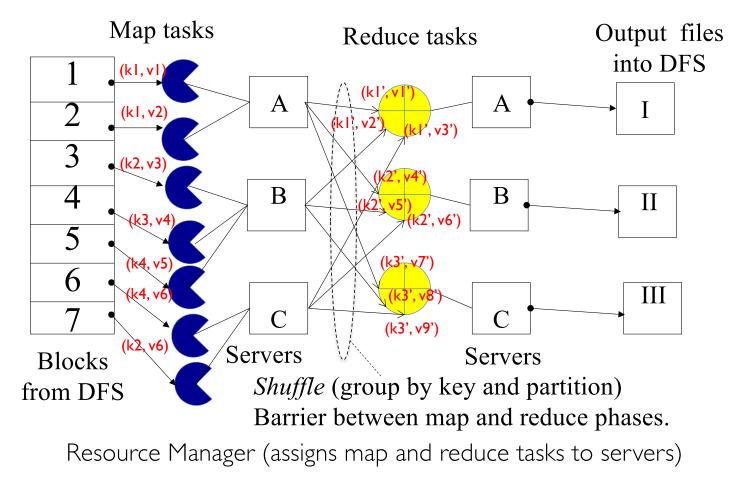
MapReduce Architecture

- MapReduce programming abstraction:
 - Easy to program distributed computing tasks.
- MapReduce programming abstraction offered by multiple open-source *application frameworks*:
 - Handle creation of "map" and "reduce" tasks.
 - e.g. Hadoop: one of the earliest map-reduce frameworks.
 - e.g. Spark: easier API and performance optimizations.
- Application frameworks use *resource managers*.
 - Deal with the hassle of distributed cluster management.

MapReduce Overview

- Input: a set of key/value pairs
- User supplies two functions:
 - map(k,v) \rightarrow list(k1,v1)
 - reduce(k1, list(v1)) \rightarrow v2
- (k1,v1) is an intermediate key/value pair.
- Output is the set of (k1,v2) pairs.

MapReduce Execution



Distributed Datastores

- NoSQL datastores:
 - Similar to databased (RDBMS), but,
 - lack schema and structure.
 - simplified API; might not support 'joins'.
 - typically do support ACID semantics.

Distributed Datastores

- NoSQL datastores:
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 - lack schema and structure.
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Design Requirements

- High performance, low cost, and scalability.
- Avoid single-point of failure
 - Replication across multiple nodes.
- Consistency: reads return latest written value by any client (all nodes see same data at any time).
 - Different from the C of ACID properties for transaction semantics!
- Availability: every request received by a non-failing node in the system must result in a response (quickly).
 - Follows from requirement for high performance.
- Partition-tolerance: the system continues to work in spite of network partitions.

CAP Theorem

- Consistency: reads return latest written value by any client (all nodes see same data at any time).
- Availability: every request received by a non-failing node in the system must result in a response (quickly).
- Partition-tolerance: the system continues to work in spite of network partitions.
- In a distributed system you can only guarantee at most
 2 out of the above 3 properties.
 - Proposed by Eric Brewer (UC Berkeley)
 - Subsequently proved by Gilbert and Lynch (NUS and MIT)

CAP Tradeoff

- Starting point for NoSQL Revolution
- A distributed storage system can achieve at most two of C, A, and P.
- Partition-tolerance important for distributed datastores:
 - choose between consistency and availability

