UNIVERSITY OF ILLINOIS AT URBANA-CHAMPAIGN Department of Electrical and Computer Engineering

ECE 417 MULTIMEDIA SIGNAL PROCESSING Fall 2023

EXAM 2

Tuesday, October 31, 2023

- This is a CLOSED BOOK exam.
- You are permitted one sheet of handwritten notes, 8.5x11.
- Calculators and computers are not permitted.
- Don't simplify explicit numerical expressions.
- If you're taking the exam online, you will need to have your webcam turned on. Your exam will appear on Gradescope at exactly 9:30am; you will need to photograph and upload your answers by exactly 11:00am.
- There are a total of 100 points in the exam. Each problem specifies its point total. Plan your work accordingly.
- You must SHOW YOUR WORK to get full credit.

Name:			
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Neural Nets

$$\begin{split} a_{i,k}^{(\ell)} &= g(\xi_{i,k}^{(\ell)}), \qquad \xi_{i,k}^{(\ell)} = b_k^{(\ell)} + \sum_{j=1}^p w_{k,j}^{(\ell)} a_{i,j}^{(\ell-1)} \\ \frac{d\mathcal{L}}{d\xi_{i,k}^{(\ell)}} &= \frac{d\mathcal{L}}{da_{i,k}^{(\ell)}} \dot{g}(\xi_{i,k}^{(\ell)}), \qquad \dot{\sigma}(x) = \sigma(x)(1 - \sigma(x)) \\ \frac{d\mathcal{L}}{da_{i,j}^{(\ell-1)}} &= \sum_k \frac{d\mathcal{L}}{d\xi_{i,k}^{(\ell)}} w_{k,j}^{(\ell)}, \qquad \frac{d\mathcal{L}}{dw_{k,j}^{(\ell)}} = \sum_i \frac{d\mathcal{L}}{d\xi_{i,k}^{(\ell)}} a_{i,j}^{(\ell-1)} \\ w_{k,j}^{(\ell)} \leftarrow w_{k,j}^{(\ell)} - \eta \frac{d\mathcal{L}}{dw_{k,j}^{(\ell)}} \end{split}$$

Viola-Jones

$$II[m,n] = \sum_{m'=1}^{m} \sum_{n'=1^{n}} I[m',n'], \quad 1 \le m \le M, 1 \le n \le N$$

$$\epsilon_{t} = \sum_{i} w_{t}(x_{i})|y_{i} - h_{t}(x_{i})|, \quad w_{t+1}(x_{i}) = \beta_{t}w_{t}(x_{i}), \quad \beta_{t} = \frac{\epsilon_{t}}{1 - \epsilon_{t}}$$

$$h(x) = \begin{cases} 1 & \sum_{t} \alpha_{t}h_{t}(x) > \frac{1}{2}\sum_{t} \alpha_{t} \\ 0 & \text{otherwise} \end{cases}, \quad \alpha_{t} = -\ln \beta_{t}$$

Hidden Markov Model

$$\alpha_{t}(j) = \sum_{i=1}^{N} \alpha_{t-1}(i)a_{i,j}b_{j}(\boldsymbol{x}_{t}), \quad 1 \leq j \leq N, \quad 2 \leq t \leq T, \quad \hat{\alpha}_{t}(j) = \frac{\sum_{i=1}^{N} \hat{\alpha}_{t-1}(i)a_{i,j}b_{j}(\boldsymbol{x}_{t})}{\sum_{j'=1}^{N} \sum_{i=1}^{N} \hat{\alpha}_{t-1}(i)a_{i,j'}b_{j'}(\boldsymbol{x}_{t})}$$

$$\beta_{t}(i) = \sum_{j=1}^{N} a_{i,j}b_{j}(\boldsymbol{x}_{t+1})\beta_{t+1}(j), \quad 1 \leq i \leq N, \quad 1 \leq t \leq T-1$$

$$\gamma_{t}(i) = \frac{\alpha_{t}(i)\beta_{t}(i)}{\sum_{k=1}^{N} \alpha_{t}(k)\beta_{t}(k)}, \quad \xi_{t}(i,j) = \frac{\alpha_{t}(i)a_{i,j}b_{j}(\boldsymbol{x}_{t+1})\beta_{t+1}(j)}{\sum_{k=1}^{N} \sum_{\ell=1}^{N} \alpha_{t}(k)a_{k,\ell}b_{\ell}(\boldsymbol{x}_{t+1})\beta_{t+1}(\ell)}$$

$$a'_{i,j} = \frac{\sum_{t=1}^{T-1} \xi_{t}(i,j)}{\sum_{j=1}^{N} \sum_{t=1}^{T-1} \xi_{t}(i,j)}, \quad b'_{j}(k) = \frac{\sum_{t:x_{t}=k} \gamma_{t}(j)}{\sum_{t=1}^{T} \gamma_{t}(j)}$$

Gaussians

$$p_{X}(x) = \frac{1}{(2\pi)^{D/2} |\Sigma|^{1/2}} e^{-\frac{1}{2}(x-\mu)^{T} \Sigma^{-1}(x-\mu)}$$
$$\mu'_{i} = \frac{\sum_{t=1}^{T} \gamma_{t}(i) x_{t}}{\sum_{t=1}^{T} \gamma_{t}(i)}, \quad \Sigma'_{i} = \frac{\sum_{t=1}^{T} \gamma_{t}(i) (x_{t} - \mu_{i}) (x_{t} - \mu_{i})^{T}}{\sum_{t=1}^{T} \gamma_{t}(i)}$$

1. (20 points) Consider a new type of neural network called a Fourier network, invented for this problem. Given an input vector $\boldsymbol{x} \in \Re^{n_x}$, a Fourier network computes $\boldsymbol{y} \in \Re^{n_y}$ as

$$y = R\cos(Px) + S\sin(Qx),$$

where the functions $\cos(\cdot)$ and $\sin(\cdot)$ are element-wise scalar cosine and sine, respectively, and where $P, Q \in \Re^{n_h \times n_x}$ and $R, S \in \Re^{n_y \times n_h}$ are weight matrices that must be learned from training data. Suppose the loss is

$$\mathcal{L} = \frac{1}{2} \|\boldsymbol{y} - \boldsymbol{t}\|_2^2$$

for some target vector \boldsymbol{t} . Express either $\frac{\partial \mathcal{L}}{\partial q_{\ell,m}}$, where $q_{\ell,m}$ is the $(\ell,m)^{\text{th}}$ element of \boldsymbol{Q} , in terms of any of the elements of the vectors $\boldsymbol{t}, \boldsymbol{x}, \boldsymbol{y}$ and/or any of the matrices $\boldsymbol{P}, \boldsymbol{Q}, \boldsymbol{R}, \boldsymbol{S}$.

2. (20 points) Consider a 1D convnet with input x[n] and output y[n] related according to

$$z[k] = \sum_{m=0}^{M-1} h[m]x[k-m],$$

$$y[n] = \max(z[2n], z[2n+1]),$$

where h[n] is a set of learned filter weights. Suppose the loss is

$$\mathcal{L} = \frac{1}{2} \sum_{n=0}^{N-1} (y[n] - s[n])^2,$$

where s[n] is a target output. In terms of h[n], s[n], x[n], y[n], z[n], M, N, and/or ℓ , what is $\frac{\partial \mathcal{L}}{\partial h[\ell]}$?

3. (20 points) A particular Adaboost classifier is being trained using 6 training examples, x_1 through x_6 . In the first round of training, all 6 have equal weight, so that $w_1(x_1) = \ldots = w_1(x_6) = \frac{1}{6}$. The first weak classifier is able to correctly classify tokens x_1 through x_4 , but it incorrectly classifies tokens x_5 and x_6 , so its weighted error is $\epsilon_1 = \frac{1}{3}$. After computing the weights $w_2(x_i)$ for $1 \le i \le 6$, a second weak classifier is chosen. The second weak classifier correctly classifies tokens x_3 through x_6 , but incorrectly classifies x_1 and x_2 . What is ϵ_2 ?

4. (20 points) In a given length-T observation sequence, the sixth observation is missing, because at the moment x_6 should have been recorded, a cyberattack caused the sensor to briefly go offline. Therefore, you have valid observations of x_1, \ldots, x_5 and of x_7, \ldots, x_T , but the observation x_6 is unknown. The observations are drawn from a discrete finite set $x_t \in \{1, \ldots, K\}$, and are known to have been generated by an N-state HMM with known model parameters $\Lambda = \{\pi_i, a_{i,j}, b_j(k) \forall 1 \leq i, j \leq N, 1 \leq k \leq K\}$.

Note that, because of the limited observations, you can only find the forward probabilities $\alpha_t(i)$ for $1 \le t \le 5$. Similarly, you can only find the backward probabilities $\beta_t(i)$ for $6 \le t \le T$.

Suppose you want to find the following quantity:

$$\zeta_6(\ell) = \Pr\{x_6 = \ell | x_1, \dots, x_5, x_7, \dots, x_T, \Lambda\}, \quad 1 \le \ell \le K$$

Find an expression for $\zeta_6(\ell)$ in terms of the model parameters, and in terms of the forward and backward probabilities at times for which they are known. Make sure that your answer is a function of no random variable other than ℓ .

5. (20 points) Consider an N-state Gaussian HMM with D-dimensional observations, $\boldsymbol{x} \in \Re^D$, in which all states have the same already-known covariance matrix, $\Sigma_1 = \ldots = \Sigma_N = \Sigma$, but their mean vectors are distributed as $\boldsymbol{\mu}_i = \boldsymbol{\mu}_0 + \boldsymbol{\delta}_i$, where $\boldsymbol{\mu}_0 \in \Re^D$ is a known global mean, and $\boldsymbol{\delta}_i \in \Re^D, 1 \leq i \leq N$, is an unknown state-dependent offset vector. Suppose you are given a training sequence $\boldsymbol{X} = [\boldsymbol{x}_1, \ldots, \boldsymbol{x}_T]$, for which it is known that $q_1 = q_2 = \ldots = q_T = 5$, i.e., all of these observations were generated by the fifth HMM state. Find the maximum-likelihood estimate of the parameter vector $\boldsymbol{\delta}_5$ in terms of the known parameters $\boldsymbol{\mu}_0$ and $\boldsymbol{\Sigma}$ and the observation vectors \boldsymbol{x}_1 through \boldsymbol{x}_T .

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