UNIVERSITY OF ILLINOIS AT URBANA-CHAMPAIGN Department of Electrical and Computer Engineering

ECE 417 Multimedia Signal Processing Fall 2023

EXAM 2

Tuesday, October 31, 2023

- This is a CLOSED BOOK exam.
- You are permitted one sheet of handwritten notes, 8.5x11.
- Calculators and computers are not permitted.
- Don't simplify explicit numerical expressions.
- If you're taking the exam online, you will need to have your webcam turned on. Your exam will appear on Gradescope at exactly 9:30am; you will need to photograph and upload your answers by exactly 11:00am.
- There are a total of 100 points in the exam. Each problem specifies its point total. Plan your work accordingly.
- You must SHOW YOUR WORK to get full credit.

Name:

NetID:

Neural Nets

$$
a_{i,k}^{(\ell)} = g(\xi_{i,k}^{(\ell)}), \qquad \xi_{i,k}^{(\ell)} = b_k^{(\ell)} + \sum_{j=1}^p w_{k,j}^{(\ell)} a_{i,j}^{(\ell-1)}
$$

$$
\frac{d\mathcal{L}}{d\xi_{i,k}^{(\ell)}} = \frac{d\mathcal{L}}{da_{i,k}^{(\ell)}} \dot{g}(\xi_{i,k}^{(\ell)}), \qquad \dot{\sigma}(x) = \sigma(x)(1 - \sigma(x))
$$

$$
\frac{d\mathcal{L}}{da_{i,j}^{(\ell-1)}} = \sum_k \frac{d\mathcal{L}}{d\xi_{i,k}^{(\ell)}} w_{k,j}^{(\ell)}, \qquad \frac{d\mathcal{L}}{dw_{k,j}^{(\ell)}} = \sum_i \frac{d\mathcal{L}}{d\xi_{i,k}^{(\ell)}} a_{i,j}^{(\ell-1)}
$$

$$
w_{k,j}^{(\ell)} \leftarrow w_{k,j}^{(\ell)} - \eta \frac{d\mathcal{L}}{dw_{k,j}^{(\ell)}}
$$

Viola-Jones

$$
II[m, n] = \sum_{m'=1}^{m} \sum_{n'=1^n} I[m', n'], \quad 1 \leq m \leq M, 1 \leq n \leq N
$$

$$
\epsilon_t = \sum_i w_t(x_i) |y_i - h_t(x_i)|, \quad w_{t+1}(x_i) = \beta_t w_t(x_i), \quad \beta_t = \frac{\epsilon_t}{1 - \epsilon_t}
$$

$$
h(x) = \begin{cases} 1 & \sum_t \alpha_t h_t(x) > \frac{1}{2} \sum_t \alpha_t \\ 0 & \text{otherwise} \end{cases}, \quad \alpha_t = -\ln \beta_t
$$

Hidden Markov Model

$$
\alpha_{t}(j) = \sum_{i=1}^{N} \alpha_{t-1}(i)a_{i,j}b_{j}(\boldsymbol{x}_{t}), \quad 1 \leq j \leq N, \quad 2 \leq t \leq T, \quad \hat{\alpha}_{t}(j) = \frac{\sum_{i=1}^{N} \hat{\alpha}_{t-1}(i)a_{i,j}b_{j}(\boldsymbol{x}_{t})}{\sum_{j'=1}^{N} \sum_{i=1}^{N} \hat{\alpha}_{t-1}(i)a_{i,j}b_{j'}(\boldsymbol{x}_{t})}
$$
\n
$$
\beta_{t}(i) = \sum_{j=1}^{N} a_{i,j}b_{j}(\boldsymbol{x}_{t+1})\beta_{t+1}(j), \quad 1 \leq i \leq N, \quad 1 \leq t \leq T-1
$$
\n
$$
\gamma_{t}(i) = \frac{\alpha_{t}(i)\beta_{t}(i)}{\sum_{k=1}^{N} \alpha_{t}(k)\beta_{t}(k)}, \quad \xi_{t}(i,j) = \frac{\alpha_{t}(i)a_{i,j}b_{j}(\boldsymbol{x}_{t+1})\beta_{t+1}(j)}{\sum_{k=1}^{N} \sum_{\ell=1}^{N} \alpha_{t}(k)a_{k,\ell}b_{\ell}(\boldsymbol{x}_{t+1})\beta_{t+1}(\ell)}
$$
\n
$$
a'_{i,j} = \frac{\sum_{t=1}^{T-1} \xi_{t}(i,j)}{\sum_{j=1}^{N} \sum_{t=1}^{T-1} \xi_{t}(i,j)}, \quad b'_{j}(k) = \frac{\sum_{t:x_{t}=k}^{T} \gamma_{t}(j)}{\sum_{t=1}^{T} \gamma_{t}(j)}
$$

Gaussians

$$
p_{\mathbf{X}}(\mathbf{x}) = \frac{1}{(2\pi)^{D/2} |\mathbf{\Sigma}|^{1/2}} e^{-\frac{1}{2} (\mathbf{x} - \boldsymbol{\mu})^T \mathbf{\Sigma}^{-1} (\mathbf{x} - \boldsymbol{\mu})}
$$

$$
\boldsymbol{\mu}'_i = \frac{\sum_{t=1}^T \gamma_t(i) \mathbf{x}_t}{\sum_{t=1}^T \gamma_t(i)}, \quad \boldsymbol{\Sigma}'_i = \frac{\sum_{t=1}^T \gamma_t(i) (\mathbf{x}_t - \boldsymbol{\mu}_i) (\mathbf{x}_t - \boldsymbol{\mu}_i)^T}{\sum_{t=1}^T \gamma_t(i)}
$$

1. (20 points) Consider a new type of neural network called a Fourier network, invented for this problem. Given an input vector $x \in \mathbb{R}^{n_x}$, a Fourier network computes $y \in \mathbb{R}^{n_y}$ as

$$
\boldsymbol{y} = \boldsymbol{R}\cos(\boldsymbol{P}\boldsymbol{x}) + \boldsymbol{S}\sin(\boldsymbol{Q}\boldsymbol{x}),
$$

where the functions $cos(\cdot)$ and $sin(\cdot)$ are element-wise scalar cosine and sine, respectively, and where $P, Q \in \mathbb{R}^{n_h \times n_x}$ and $R, S \in \mathbb{R}^{n_y \times n_h}$ are weight matrices that must be learned from training data. Suppose the loss is

$$
\mathcal{L} = \frac{1}{2} \|\boldsymbol{y} - \boldsymbol{t}\|_2^2
$$

for some target vector t. Express either $\frac{\partial \mathcal{L}}{\partial q_{\ell,m}}$, where $q_{\ell,m}$ is the (ℓ,m) th element of Q, in terms of any of the elements of the vectors t, x, y and/or any of the matrices P, Q, R, S .

2. (20 points) Consider a 1D convnet with input $x[n]$ and output $y[n]$ related according to

$$
z[k] = \sum_{m=0}^{M-1} h[m]x[k-m],
$$

$$
y[n] = \max(z[2n], z[2n+1]),
$$

where $h\lbrack n\rbrack$ is a set of learned filter weights. Suppose the loss is

$$
\mathcal{L} = \frac{1}{2} \sum_{n=0}^{N-1} (y[n] - s[n])^2,
$$

where $s[n]$ is a target output. In terms of $h[n], s[n], x[n], y[n], z[n], M, N$, and/or ℓ , what is $\frac{\partial \mathcal{L}}{\partial h[\ell]}$?

3. (20 points) A particular Adaboost classifier is being trained using 6 training examples, x_1 through x_6 . In the first round of training, all 6 have equal weight, so that $w_1(x_1) = \ldots = w_1(x_6) = \frac{1}{6}$. The first weak classifier is able to correctly classify tokens x_1 through x_4 , but it incorrectly classifies tokens x_5 and x_6 , so its weighted error is $\epsilon_1 = \frac{1}{3}$. After computing the weights $w_2(x_i)$ for $1 \le i \le 6$, a second weak classifier is chosen. The second weak classifier correctly classifies tokens x_3 through x_6 , but incorrectly classifies x_1 and x_2 . What is ϵ_2 ?

4. (20 points) In a given length-T observation sequence, the sixth observation is missing, because at the moment x_6 should have been recorded, a cyberattack caused the sensor to briefly go offline. Therefore, you have valid observations of x_1, \ldots, x_5 and of x_7, \ldots, x_T , but the observation x_6 is unknown. The observations are drawn from a discrete finite set $x_t \in \{1, \ldots, K\}$, and are known to have been generated by an N-state HMM with known model parameters $\Lambda = \{\pi_i, a_{i,j}, b_j(k)\forall 1 \leq j \leq k\}$ $i, j \le N, 1 \le k \le K$.

Note that, because of the limited observations, you can only find the forward probabilities $\alpha_t(i)$ for $1 \leq t \leq 5$. Similarly, you can only find the backward probabilities $\beta_t(i)$ for $6 \leq t \leq T$.

Suppose you want to find the following quantity:

$$
\zeta_6(\ell) = \Pr\{x_6 = \ell | x_1, \dots, x_5, x_7, \dots, x_T, \Lambda\}, \quad 1 \le \ell \le K
$$

Find an expression for $\zeta_6(\ell)$ in terms of the model parameters, and in terms of the forward and backward probabilities at times for which they are known. Make sure that your answer is a function of no random variable other than ℓ .

5. (20 points) Consider an N-state Gaussian HMM with D-dimensional observations, $x \in \mathbb{R}^D$, in which all states have the same already-known covariance matrix, $\Sigma_1 = \ldots = \Sigma_N = \Sigma$, but their mean vectors are distributed as $\mu_i = \mu_0 + \delta_i$, where $\mu_0 \in \Re^{D}$ is a known global mean, and $\delta_i \in \Re^{D}, 1 \leq i \leq N$, is an unknown state-dependent offset vector. Suppose you are given a training sequence $\overline{\mathbf{X}} = [\mathbf{x}_1, \dots, \mathbf{x}_T]$, for which it is known that $q_1 = q_2 = \dots = q_T = 5$, i.e., all of these observations were generated by the fifth HMM state. Find the maximum-likelihood estimate of the parameter vector δ_5 in terms of the known parameters μ_0 and Σ and the observation vectors x_1 through x_T .

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