

ECE 417 Multimedia Signal Processing

Solutions to Homework 4

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Assigned: Tuesday, 10/12/2021; Due: Tuesday, 10/19/2021
Reading: L.R. Rabiner, A Tutorial on Hidden Markov Models and Selected Applications in Speech Recognition, 1989

Problem 4.1

In a first-order Markov model, the state at time t depends only on the state at time $t - 1$. A **second-order Markov model** is a model in which the state at time t depends on a short list of recent states. For example, consider a model in which q_t depends on the most recent **two** frames. Let's suppose the model is fully defined by the following three types of parameters:

- **Initial segment probability:** $\pi_{ij} \equiv p(q_1 = i, q_2 = j | \Lambda)$
- **Transition probability:** $a_{ijk} \equiv p(q_t = k | q_{t-1} = j, q_{t-2} = i, \Lambda)$
- **Observation probability:** $b_k(\vec{x}) \equiv p(\vec{x}_t = \vec{x} | q_t = k, \Lambda)$

Design an algorithm similar to the forward algorithm that is able to compute $p(X | \Lambda)$ with a computational complexity of at most $\mathcal{O}\{TN^3\}$. Provide a proof that your algorithm has at most $\mathcal{O}\{TN^3\}$ complexity — this can be an informal proof in the form of a bullet list, as was provided during lecture 12 for the standard forward algorithm.

Solution: Define $\alpha_t(i, j) = p(\vec{x}_1, \dots, \vec{x}_t, q_{t-1} = i, q_t = j | \Lambda)$. Compute it as

- **Initialize:**

$$\alpha_2(i, j) = \pi_{ij} b_i(\vec{x}_1) b_j(\vec{x}_2), \quad 1 \leq i, j \leq N$$

- **Iterate:**

$$\alpha_t(j, k) = \sum_{i=1}^N \alpha_{t-1}(i, j) a_{ijk} b_k(\vec{x}_t), \quad 1 \leq t \leq T, \quad 1 \leq j, k \leq N$$

- **Terminate:**

$$p(X | \Lambda) = \sum_{i=1}^N \sum_{j=1}^N \alpha_T(i, j)$$

The highest-complexity part of the algorithm is the iteration step, which requires:

- for each of T different time steps t ,
- for each of N different values of j ,
- for each of N different values of k ,
- we must compute a summation with N terms,

hence it has $\mathcal{O}\{TN^3\}$ complexity.

Problem 4.2

Suppose you have a sequence of $T = 100$ consecutive observations, $X = [x_1, \dots, x_T]$. Suppose that the observations are discrete, $x_t \in \{1, \dots, 20\}$. You have it on good information that these data can be modeled by an HMM with $N = 10$ states, whose parameters are

- **Initial state probability:** $\pi_i \equiv p(q_1 = i | \Lambda)$
- **Transition probability:** $a_{ij} \equiv p(q_t = j | q_{t-1} = i, \Lambda)$
- **Observation probability:** $b_j(x) \equiv p(x_t = x | q_t = j, \Lambda)$

In terms of these model parameters, and in terms of the forward probabilities $\alpha_t(i)$ and backward probabilities $\beta_t(i)$ (for any values of i, j, t, x that are useful to you), what is $p(q_{17} = 7, x_{18} = 3 | x_1, \dots, x_{17}, x_{19}, \dots, x_{100}, \Lambda)$?

Solution: Conditional = joint / marginal. The joint probability is

$$p(q_{17} = 7, x_1, \dots, x_{17}, x_{18} = 3, x_{19}, \dots, x_{100}) = \sum_{j=1}^{10} \alpha_{17}(7) a_{7j} b_j(3) \beta_{18}(j)$$

The marginal is

$$p(x_1, \dots, x_{17}, x_{19}, \dots, x_{100}) = \sum_{i=1}^{10} \sum_{j=1}^{10} \sum_{k=1}^{20} \alpha_{17}(i) a_{ij} b_j(k) \beta_{18}(j)$$

So the conditional is

$$p(q_{17} = 7, x_{18} = 3 | x_1, \dots, x_{17}, x_{19}, \dots, x_{100}) = \frac{\sum_{j=1}^{10} \alpha_{17}(7) a_{7j} b_j(3) \beta_{18}(j)}{\sum_{i=1}^{10} \sum_{j=1}^{10} \sum_{k=1}^{20} \alpha_{17}(i) a_{ij} b_j(k) \beta_{18}(j)}$$

Problem 4.3

A **partially-observed Markov model** is a model in which some part of the state variable is observed, while other parts are not observed. For example, consider a model with 2 states in which q_1 is observed to be $q_1 = 1$, and q_3 is observed to be $q_3 = 2$, but q_2 is not observed. This model has no output vectors (no \vec{x}): your only observations are the two state IDs, q_1 and q_3 . All parts of this problem are cumulative; in your answer to any part, you may use any assumptions that were specified in any previous part.

- (a) What is the visible dataset, \mathcal{D}_v ? What is the hidden dataset, \mathcal{D}_h ?

Solution:

$$\begin{aligned} \mathcal{D}_v &= \{q_1, q_3\} \\ \mathcal{D}_h &= \{q_2\} \end{aligned}$$

(b) Suppose that you have a transition probability matrix A , whose $(i, j)^{\text{th}}$ element is

$$a_{ij} = p(q_t = j | q_{t-1} = i)$$

Find a formula in terms of the elements of A for

$$\gamma_2(j) = p(q_2 = j | q_1 = 1, q_3 = 2, A)$$

Solution:

$$\gamma_2(j) = \frac{a_{1j}a_{j2}}{\sum_{i=1}^2 a_{1i}a_{i2}}$$

(c) The EM Q-function, also known as the expected log likelihood, can be defined as

$$Q(A', A) = E [\ln p(q_1 = 1, q_2 = j, q_3 = 2 | A') | q_1 = 1, q_3 = 2, A]$$

Find a formula for $Q(A', A)$ in terms of the elements of A and A' , and/or in terms of $\gamma_2(j)$.

Solution:

$$Q(A', A) = \sum_{j=1}^2 \gamma_2(j) (\ln a'_{1j} + \ln a'_{j2})$$

(d) The Lagrangian method for optimization works as follows. Suppose we are trying to find values of a'_{ij} that maximize $Q(A', A)$, subject to the stochastic constraint that

$$\sum_{j=1}^2 a'_{ij} = 1$$

The Lagrangian method creates a Lagrangian function $L(A)$ by creating a “constraint term” $(1 - \sum_j a'_{ij})$ that must be zero if the constraint is satisfied, multiplying the constraint term by a “Lagrangian multiplier” λ_i , and then adding the result to $Q(A', A)$, resulting in :

$$L(A') = Q(A', A) + \sum_{i=1}^2 \lambda_i \left(1 - \sum_{j=1}^2 a'_{ij} \right)$$

In terms of the elements of A' , $\gamma_2(j)$, and the Lagrangian multipliers λ_1 and λ_2 , what are the values of $dL(A')/da'_{ij}$ for each value of $i, j \in \{1, 2\}$?

Solution:

$$\begin{aligned} \frac{dL(A')}{da'_{11}} &= \frac{\gamma_2(1)}{a'_{11}} - \lambda_1 \\ \frac{dL(A')}{da'_{12}} &= \frac{1}{a'_{12}} - \lambda_1 \\ \frac{dL(A')}{da'_{21}} &= -\lambda_2 \\ \frac{dL(A')}{da'_{22}} &= \frac{\gamma_2(2)}{a'_{22}} - \lambda_2 \end{aligned}$$

- (e) Set $\frac{dL(A')}{da'_{11}} = 0$ and $\frac{dL(A')}{da'_{12}} = 0$. Doing so will give you the new model parameters, a'_{11} and a'_{12} , in terms of both $\gamma_2(j)$ and λ_i . Choose a value of λ_i so that $a'_{11} + a'_{12} = 1$.

Solution:

$$a'_{11} = \frac{\gamma_2(1)}{1 + \gamma_2(1)}$$
$$a'_{12} = \frac{1}{1 + \gamma_2(1)}$$

Note: you are not asked to solve for a'_{21} because there's a trick: dL/da'_{21} cannot be set to zero. As long as $\lambda_2 > 0$, $dL/da'_{21} < 0$. The conclusion is that you should make a'_{21} as small as possible, thus:

$$a'_{21} = 0$$
$$a'_{22} = 1$$