

UNIVERSITY OF ILLINOIS AT URBANA-CHAMPAIGN  
Department of Electrical and Computer Engineering

ECE 417 MULTIMEDIA SIGNAL PROCESSING  
Spring 2016

**EXAM 2**

Thursday, March 31, 2016

- This is a **CLOSED BOOK** exam. You may use one sheet (front and back) of hand-written notes.
- No calculators are permitted. You need not simplify explicit numerical expressions.
- There are a total of 100 points in the exam. Each problem specifies its point total. Plan your work accordingly.
- You must **SHOW YOUR WORK** to get full credit.

Problem	Score
1	
2	
3	
4	
5	
Total	

Name: \_\_\_\_\_

## Possibly Useful Formulas

**Gaussian (Normal) Distribution** A Gaussian is parameterized by  $\vec{\mu}$ ,  $\Sigma$ , and  $D = \dim(\vec{\mu})$  as

$$\mathcal{N}(\vec{x}|\vec{\mu}, \Sigma) = \frac{1}{(2\pi)^{D/2}|\Sigma|^{1/2}} e^{-\frac{1}{2}(\vec{x}-\vec{\mu})^T \Sigma^{-1}(\vec{x}-\vec{\mu})}$$

**Gaussian Mixture Model (GMM)** A GMM is parameterized by  $c_k$ ,  $\vec{\mu}_k$ , and  $\Sigma_k$  for  $1 \leq k \leq K$  as

$$p_X(\vec{x}) = \sum_{k=1}^K c_k \mathcal{N}(\vec{x}|\vec{\mu}_k, \Sigma_k)$$

**Hidden Markov Model (HMM)** An HMM is parameterized by  $\lambda = \{\pi_i, a_{ij}, b_j(\vec{x})\}$ , where

$$\begin{aligned} \pi_i &= p(q_1 = i|\lambda), \quad 1 \leq i \leq N \\ a_{ij} &= p(q_{t+1} = j|q_t = i, \lambda), \quad 1 \leq i, j \leq N \\ b_j(\vec{x}) &= p(\vec{x}|q_t = j, \lambda), \quad 1 \leq j \leq N \end{aligned}$$

The acoustic model  $b_j(\vec{x})$  might be GMM, for example, in which case the HMM parameters include

$$\begin{aligned} c_{jk} &= p(g_t = k|q_t = j) \\ \vec{\mu}_{jk} &= E[\vec{x}_t|q_t = j, g_t = k] \\ \Sigma_{jk} &= E[(\vec{x}_t - \vec{\mu}_{jk})(\vec{x}_t - \vec{\mu}_{jk})^T|q_t = j, g_t = k] \end{aligned}$$

## Scaled Forward Algorithm

$$\begin{aligned} \hat{\alpha}_1(i) &= \pi_i b_i(\vec{x}_1), \quad 1 \leq i \leq N \\ g_1 &= \sum_{i=1}^N \hat{\alpha}_1(i) \\ \tilde{\alpha}_1(i) &= \frac{1}{g_1} \hat{\alpha}_1(i) \\ \hat{\alpha}_t(j) &= \sum_{i=1}^N \tilde{\alpha}_{t-1}(i) a_{ij} b_j(\vec{x}_t) \\ g_t &= \sum_{j=1}^N \hat{\alpha}_t(j) \\ \tilde{\alpha}_t(j) &= \frac{1}{g_t} \hat{\alpha}_t(j) \\ p(\vec{x}_1, \dots, \vec{x}_t|\lambda) &= \prod_{t=1}^T g_t \end{aligned}$$

**Problem 1 (20 points)**

You want to classify zoo animals. Your zoo only has two species: elephants and giraffes. There are more elephants than giraffes: if  $Y$  is the species,

$$\begin{aligned}p_Y(\text{elephant}) &= \frac{e}{e+1} \\p_Y(\text{giraffe}) &= \frac{1}{e+1}\end{aligned}$$

where  $e = 2.718\dots$  is the base of the natural logarithm. The height of giraffes is Gaussian, with mean  $\mu_G = 5$  meters and variance  $\sigma_G^2 = 1$ . The height of elephants is also Gaussian, with mean  $\mu_E = 3$  and variance  $\sigma_E^2 = 1$ . Under these circumstances, the minimum probability of error classifier is

$$\hat{y}(x) = \begin{cases} \text{giraffe} & x > \theta \\ \text{elephant} & x < \theta \end{cases}$$

Find the value of  $\theta$  that minimizes the probability of error.

**Problem 2 (20 points)**

A 3-nearest neighbor (3NN) estimator of  $p_{Y|X}(y_0|\vec{x}_0)$  is computed by finding the 3 nearest neighbors of vector  $\vec{x}_0 = [x_{10}, x_{20}]^T$ , then measuring

$$p_{Y|X}(y_0|\vec{x}_0) = \frac{\# \text{ neighbors from class } y_0}{3}$$

Suppose that the training dataset contains six labeled  $(\vec{x}_n, y_n)$  pairs, given by

$$[y_1, y_2, y_3, y_4, y_5, y_6] = [0, 0, 0, 1, 1, 1]$$

$$[\vec{x}_1, \vec{x}_2, \vec{x}_3, \vec{x}_4, \vec{x}_5, \vec{x}_6] = \begin{bmatrix} 0 & 0 & 0 & 2 & 2 & 2 \\ -1 & 0 & 1 & -3 & 0 & 3 \end{bmatrix}$$

Find the 3NN estimator  $p_{Y|X}(y_0 = 1 | \begin{bmatrix} x_{10} \\ 0 \end{bmatrix})$  as a function of  $\vec{x}_0 = \begin{bmatrix} x_{10} \\ 0 \end{bmatrix}$ , that is, for  $x_{20} = 0$ .

**Problem 3 (20 points)**

Random vector  $X$  is distributed as

$$p_X(\vec{x}) = \sum_{k=1}^2 c_k \mathcal{N}(\vec{x}|\vec{\mu}_k, \Sigma_k)$$

where  $c_1 = c_2 = 0.5$ , and

$$\vec{\mu}_1 = \begin{bmatrix} -2 \\ 0 \end{bmatrix}, \quad \vec{\mu}_2 = \begin{bmatrix} 2 \\ 0 \end{bmatrix}, \quad \Sigma_1 = \begin{bmatrix} 4 & 0 \\ 0 & 1 \end{bmatrix}, \quad \Sigma_2 = \begin{bmatrix} 1 & 0 \\ 0 & 4 \end{bmatrix}$$

Draw a contour plot showing  $p_X(\vec{x})$  as a function of  $\vec{x}$ . Mark the modes of the distribution, and draw contour lines at levels of  $e^{-1/2}$  and  $e^{-2}$  times the height of the modes.

**Problem 4 (20 points)**

A particular hidden Markov model is parameterized by  $\lambda = \{\pi_i, a_{ij}, b_j(\vec{x})\}$  where  $\pi_i$  is uniform ( $\pi_i = \frac{1}{N}$ ). Devise an algorithm to compute  $p(q_1 = k | \vec{x}_1, \dots, \vec{x}_T, \lambda)$ . Your algorithm should be similar to the forward algorithm, but with a different initialization.

**Problem 5 (20 points)**

The scaled forward algorithm is provided for you on the formula page at the beginning of this exam. In terms of the quantities  $\pi_i$ ,  $a_{ij}$ ,  $b_j(\vec{x})$ ,  $\hat{\alpha}_t(j)$ ,  $g_t$ , and/or  $\tilde{\alpha}_t(j)$ , find a formula for the quantity  $p(q_{t-1} = i, q_t = j, \vec{x}_{t-1}, \vec{x}_t | \vec{x}_1, \dots, \vec{x}_{t-2}, \lambda)$ .