

UNIVERSITY OF ILLINOIS AT URBANA-CHAMPAIGN  
Department of Electrical and Computer Engineering

ECE 417 MULTIMEDIA SIGNAL PROCESSING  
Fall 2019

**PRACTICE EXAM 2**

Tuesday, October 22, 2019

- This is a **PRACTICE** exam. On the real exam, you'll be allowed to use one sheet (front and back) of handwritten notes.
- No calculators are permitted. You need not simplify explicit numerical expressions.
- The real exam will have a total of 50 points. Each problem specifies its point total. Plan your work accordingly.
- You must **SHOW YOUR WORK** to get full credit.

## Possibly Useful Formulas

### YPbPr and Sobel Mask

$$\begin{bmatrix} Y \\ P_b \\ P_r \end{bmatrix} = \begin{bmatrix} 0.299 & 0.587 & 0.114 \\ -0.168736 & -0.331264 & 0.5 \\ 0.5 & -0.418688 & -0.081312 \end{bmatrix} \begin{bmatrix} R \\ G \\ B \end{bmatrix}$$

$$G_x[n_1, n_2] = \begin{bmatrix} 1 & 0 & -1 \\ 2 & 0 & -2 \\ 1 & 0 & -1 \end{bmatrix} ** I[n_1, n_2], \quad G_y[n_1, n_2] = \begin{bmatrix} 1 & 2 & 1 \\ 0 & 0 & 0 \\ -1 & -2 & -1 \end{bmatrix} ** I[n_1, n_2]$$

### Integral Image and Lowpass Filter

$$ii[n_1, n_2] = \sum_{m_1=0}^{n_1} \sum_{m_2=0}^{n_2} i[m_1, m_2]$$

$$H(\omega_1, \omega_2) = \begin{cases} 1 & |\omega_1| < \phi_1, \quad |\omega_2| < \phi_2 \\ 0 & \text{otherwise} \end{cases} \quad h[n_1, n_2] = \left(\frac{\phi_1}{\pi}\right) \left(\frac{\phi_2}{\pi}\right) \text{sinc}(\phi_1 n_1) \text{sinc}(\phi_2 n_2)$$

### Orthogonality Principle and LPC

$$\varepsilon = E \left[ \left( x[n] - \sum_{m=1}^p \alpha_m x[n-m] \right)^2 \right], \quad \frac{\partial \varepsilon}{\partial \alpha_k} = -2E \left[ x[n-k] \left( x[n] - \sum_{m=1}^{12} \alpha_m x[n-m] \right) \right]$$

$$R_{xx}[k] = \sum_{m=1}^{12} \alpha_m R_{xx}[k-m]$$

### Autocorrelation and Power Spectrum

$$R_{xx}[n] = E \{ x[m] x[m-n] \} \leftrightarrow S_{xx}(\omega) = \sum_{n=-\infty}^{\infty} R_{xx}[n] e^{-j\omega n}$$

$$r_{xx}[n] = \sum_{m=-\infty}^{\infty} x[m] x[m-n] \leftrightarrow s_{xx}(\omega) = \sum_{n=-\infty}^{\infty} r_{xx}[n] e^{-j\omega n}$$

### Fourier Series

$$x[n] = \sum_{k=0}^{P-1} X_k e^{j2\pi kn/P} \quad X_k = \frac{1}{P} \sum_{n=0}^{P-1} x[n] e^{-j2\pi kn/P}$$

### Autocorrelation and Power Spectrum

$$R_{xx}[n] = E \{ x[m] x[m-n] \} \leftrightarrow S_{xx}(\omega) = \sum_{n=-\infty}^{\infty} R_{xx}[n] e^{-j\omega n}$$

$$r_{xx}[n] = \sum_{m=-\infty}^{\infty} x[m] x[m-n] \leftrightarrow s_{xx}(\omega) = \sum_{n=-\infty}^{\infty} r_{xx}[n] e^{-j\omega n}$$

**Problem 1 (30 points)**

Suppose you have an RGB image  $i[n_1, n_2, n_3]$  with  $0 \leq n_1 < N_1$  rows,  $0 \leq n_2 < N_2$  columns, and  $0 \leq n_3 < 3$  color planes. The matched filter in part (d) of this problem is of size  $M_1 \times M_2$ . Use big- $\mathcal{O}$  notation, in terms of the variables  $N_1, N_2, M_1$  and  $M_2$ , to express the complexity of each of the following operations:

- (a) Converting from RGB to YPbPr color space.
- (b) Computing the horizontal and vertical gradients of each color plane using a Sobel mask.
- (c) Lowpass filtering (after zero-padding, so that the output is of the same size,  $N_1 \times N_2 \times 3$ , as the input) with a separable ideal anti-aliasing filter whose frequency response is

$$H(\omega_1, \omega_2) = \begin{cases} 1 & |\omega_1| < \frac{\pi}{3}, \quad |\omega_2| < \frac{\pi}{3} \\ 0 & \text{otherwise} \end{cases}$$

- (d) Filtering with a matched filter of size  $M_1$  rows,  $M_2$  columns.
- (e) Calculating the integral image  $ii[n_1, n_2] = \sum_{m_1=0}^{n_1} \sum_{m_2=0}^{n_2} i[m_1, m_2, 0]$  for all  $0 \leq n_1 < N_1$  and  $0 \leq n_2 < N_2$ .
- (f) Given the integral image, find the box-summation  $f[b_1, b_2, e_1, e_2]$  defined as

$$f[b_1, b_2, e_1, e_2] = \sum_{n_1=b_1}^{e_1} \sum_{n_2=b_2}^{e_2} i[n_1, n_2, 0]$$

for all values  $0 \leq b_1 \leq N_1 - 1$ ,  $0 \leq e_1 \leq N_1 - 1$ ,  $0 \leq b_2 \leq N_2 - 1$ ,  $0 \leq e_2 \leq N_2 - 1$ .

**Problem 2 (10 points)**

Suppose you have an input image with 8-bit integer pixel values,  $0 \leq i[n_1, n_2, n_3] \leq 255$ , where  $n_1$  is the row index,  $n_2$  is the column index, and  $n_3$  is the color plane. What are the minimum and maximum pixel values that result as the outputs of the following operations:

- (a) Convert to a YPbPr color space. What are the minimum and maximum possible values of  $Y$ ,  $P_b$ , and  $P_r$ ?
- (b) Compute the horizontal and vertical gradients using a Sobel mask. What are the minimum and maximum possible values of each of the two gradient images?

**Problem 3 (5 points)**

Consider the infinite-sized image  $i[n_1, n_2] = \delta[n_1 - 5]$ , i.e.,

$$i[n_1, n_2] = \begin{cases} 1 & n_1 = 5 \\ 0 & \text{otherwise} \end{cases}$$

Use a Sobel mask to find the resulting images  $G_x[n_1, n_2]$  and  $G_y[n_1, n_2]$ .

**Problem 4 (5 points)**

Suppose you want to find the horizon line in a grayscale image  $i[n_1, n_2]$ . Suppose the horizon line is defined to be the row index  $n_1$  that maximizes the brightness difference  $BD[n_1]$ , defined as

$$BD[n_1] = \sum_{m_2=0}^{N_2-1} \left( \left( \frac{1}{n_1} \sum_{m_1=0}^{n_1-1} i[m_1, m_2] \right) - \left( \frac{1}{N_1 - n_1} \sum_{m_1=n_1}^{N_1-1} i[m_1, m_2] \right) \right)$$

You are given the integral image  $ii[n_1, n_2] = \sum_{m_1=0}^{n_1} \sum_{m_2=0}^{n_2} i[m_1, m_2, 0]$ . Devise a formula that uses  $ii[n_1, n_2]$  to compute  $BD[n_1]$  with a small constant number of operations per candidate horizon line.

**Problem 5 (5 points)**

Consider the problem of upsampling, by a factor of 2, the infinite-sized image

$$x[n_1, n_2] = \delta[n_1 - 5] = \begin{cases} 1 & n_1 = 5 \\ 0 & \text{otherwise} \end{cases}$$

Suppose that the image is upsampled, then filtered, as

$$y[n_1, n_2] = \begin{cases} x[n_1/2, n_2/2] & n_1/2 \text{ and } n_2/2 \text{ both integers} \\ 0 & \text{otherwise} \end{cases} \quad z[n_1, n_2] = y[n_1, n_2] * *h[n_1, n_2]$$

Let  $h[n_1, n_2]$  be the ideal anti-aliasing filter with frequency response

$$H(\omega_1, \omega_2) = \begin{cases} 1 & |\omega_1| < \frac{\pi}{2}, \quad |\omega_2| < \frac{\pi}{2} \\ 0 & \text{otherwise} \end{cases}$$

Find  $z[n_1, n_2]$ .

**Problem 6 (5 points)**

The stochastic autocorrelation of a periodic signal is periodic,  $R_{xx}[P] = R_{xx}[0]$ . How about the signal autocorrelation? Suppose that the frame length is an integer multiple of the number of periods,  $L = kP$ , so that

$$x[n] = \begin{cases} \text{periodic with period } P & 0 \leq n \leq kP - 1 \\ 0 & \text{otherwise} \end{cases}$$

Find  $r_{xx}[P]$  in terms of  $r_{xx}[0]$ .

**Problem 7 (10 points)**

Consider the signal  $x[n] = \beta^n u[n]$ , where  $u[n]$  is the unit step function.

(a) Find the LPC coefficient,  $\alpha$ , that minimizes  $\varepsilon$ , where

$$\varepsilon = \sum_{n=-\infty}^{\infty} e^2[n], \quad e[n] = x[n] - \alpha x[n-1]$$

- (b) Find the signal  $e[n]$  that results from your choice of  $\alpha$  in part (a).

**Problem 8 (10 points)**

Consider the LPC synthesis filter  $s[n] = e[n] + \alpha s[n - 1]$ .

- (a) Under what condition on  $\alpha$  is the synthesis filter stable?
- (b) Assume that the synthesis filter is stable. Suppose that  $e[n]$  is the pulse train  $e[n] = \sum_{p=-\infty}^{\infty} \delta[n - pP]$ . As a function of  $\alpha$ ,  $P$ , and  $\omega$ , what is the DTFT  $S(e^{j\omega})$ ? You need not simplify, but your answer should contain no integrals or infinite sums.