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# **ECE 398GG – ELECTRICAL VEHICLES**

## **9. Electric Drives for EVs**

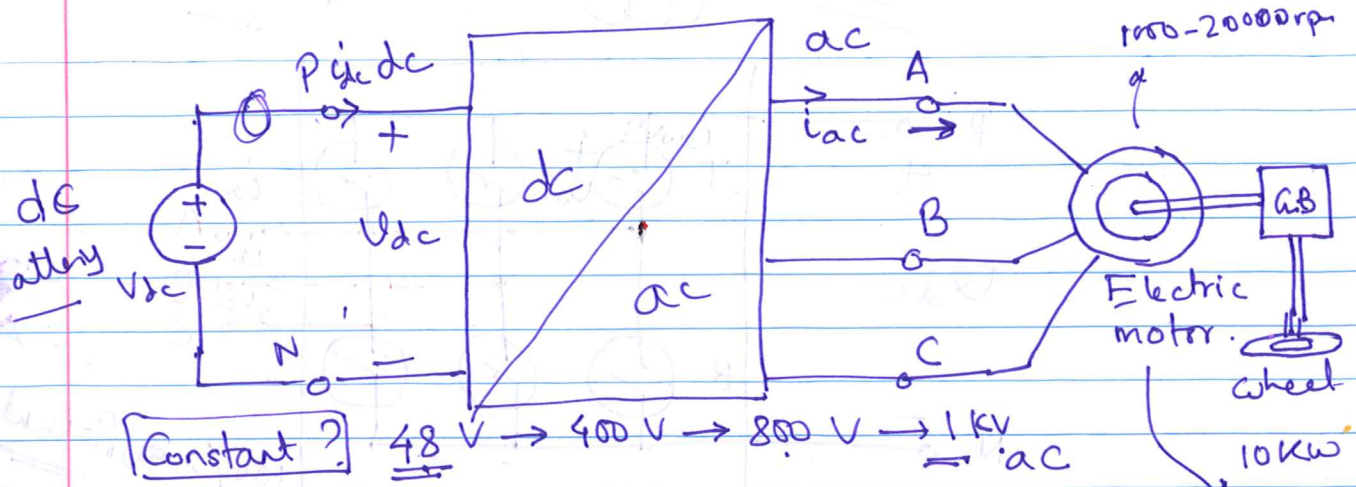
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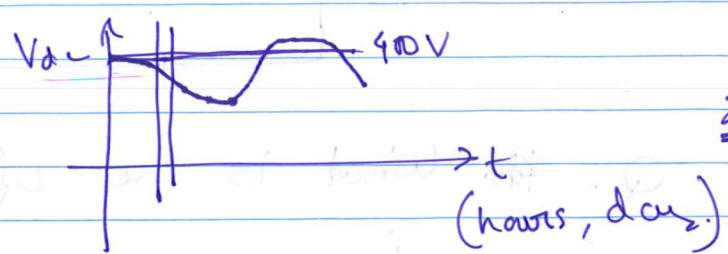
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$$\omega_0 \propto \text{rpm}$$



Constant?  $48 \text{ V} \rightarrow 400 \text{ V} \rightarrow 800 \text{ V} \rightarrow 1 \text{ kV}$   
 Variable?  $\rightarrow \text{ac}$

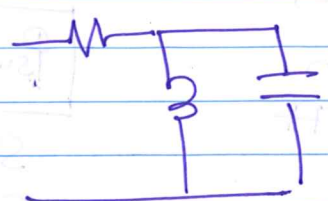


200 Kw  
 400 A, 50 V  
 20 A, 1 kV

$$P_{\text{input}} = V_{dc} \cdot i_{dc}$$

$$V_a = V_m \cos \omega_0 t$$

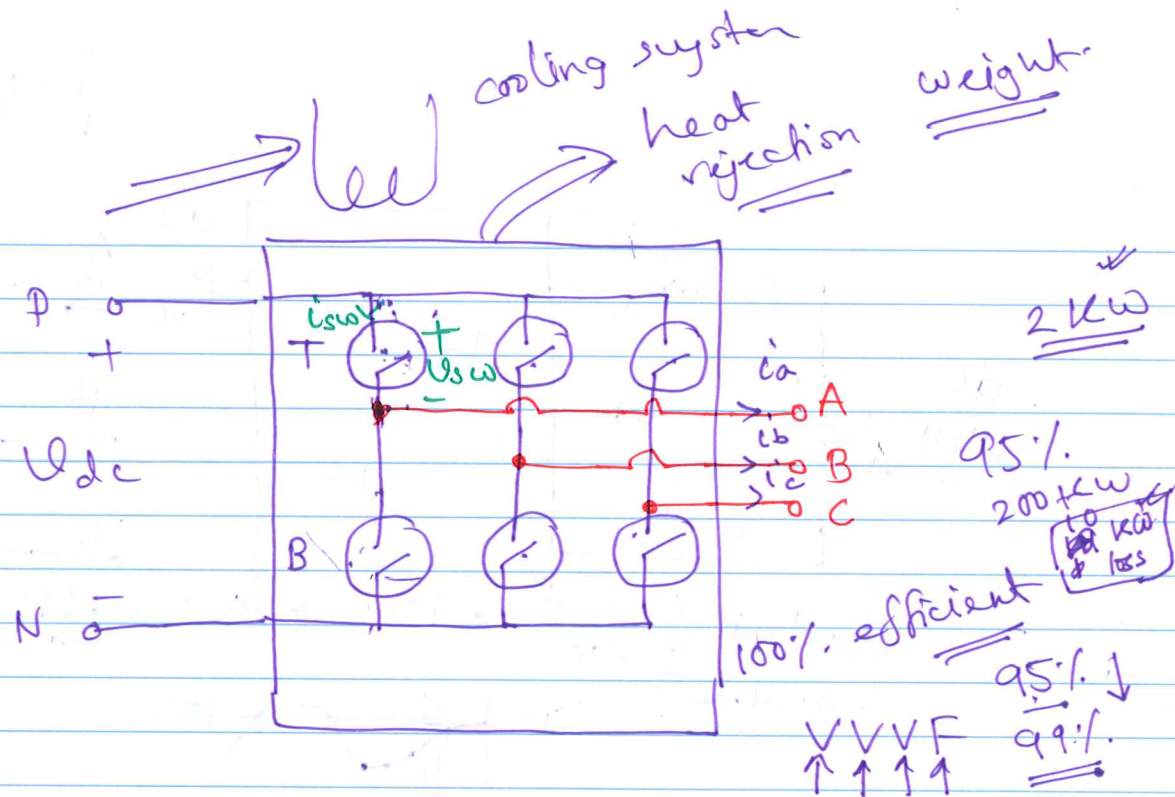
$$i_a = I_m \cos(\omega_0 t + \phi)$$



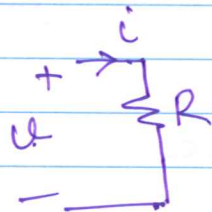
\* Non-linear circuit  $\rightarrow$  frequency transformation

$\rightarrow$  Power electronics  $\rightarrow$  processing power

$\rightarrow$  X signal electronics information



Q. What is the efficiency of the system?



$$v = iR$$

$$p = v \cdot i$$

instantaneous power

Top switch  
to be ON

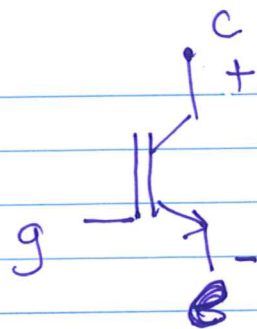
Bottom switch  
to be OFF

$$P_{sw} = U_{sw} \cdot i_{sw}$$

Switch ON  $\Rightarrow U_{sw} = 0$

Switch OFF  $\Rightarrow i_{sw} = 0$

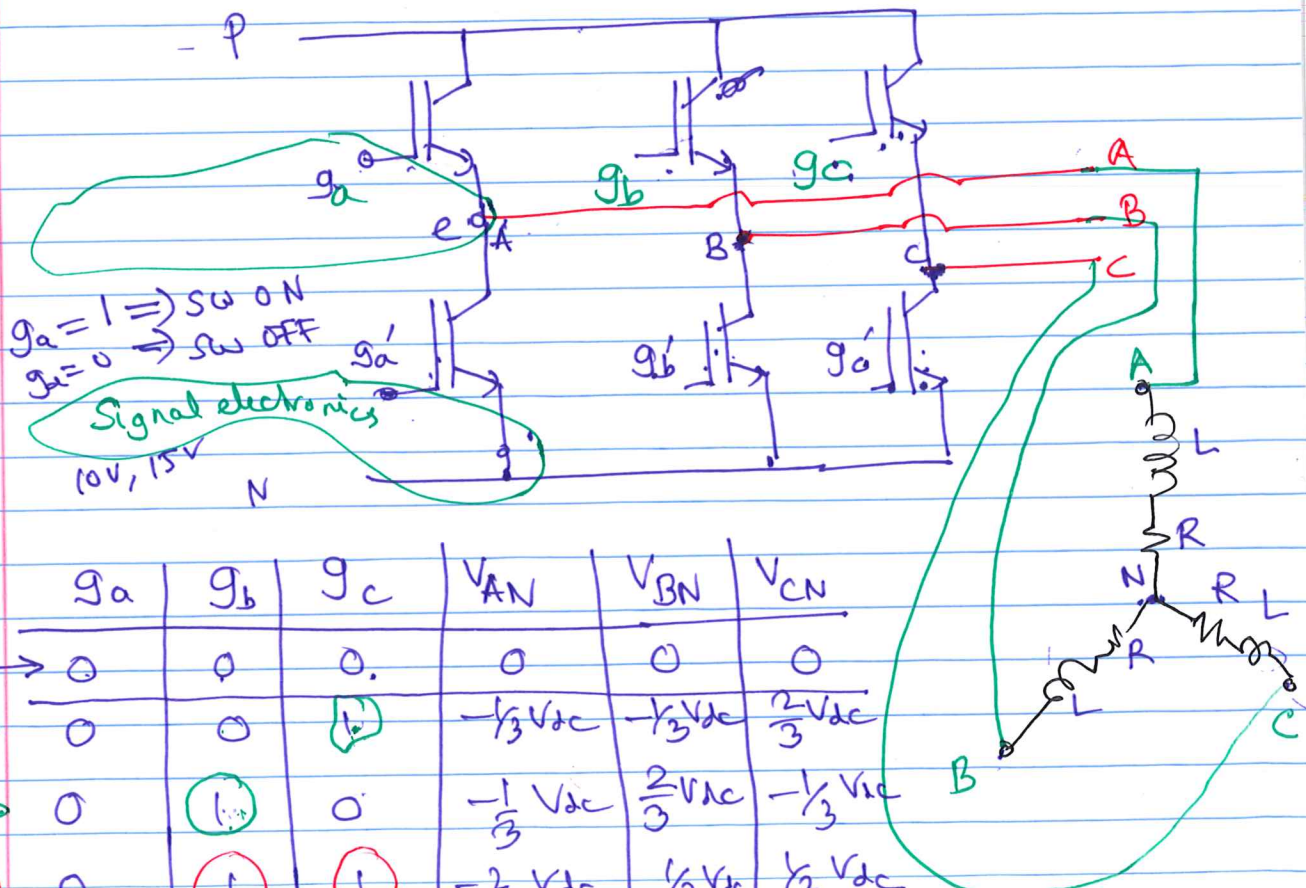
$\forall t \Rightarrow P_{sw} = 0$



IGBT (Silicon devices)

Power Semiconductor devices

$V_{ge} > V_{th}$  SiC (Silicon carbide MOSFET)



	$g_a$	$g_b$	$g_c$	$V_{AN}$	$V_{BN}$	$V_{CN}$
→	0	0	0	0	0	0
→	0	0	1	$-\frac{1}{3}V_{dc}$	$-\frac{1}{3}V_{dc}$	$\frac{2}{3}V_{dc}$
→	0	1	0	$-\frac{1}{3}V_{dc}$	$\frac{2}{3}V_{dc}$	$-\frac{1}{3}V_{dc}$
→	0	1	1	$-\frac{2}{3}V_{dc}$	$\frac{1}{3}V_{dc}$	$\frac{1}{3}V_{dc}$
→	1	0	0	$\frac{2}{3}V_{dc}$	$-\frac{1}{3}V_{dc}$	$-\frac{1}{3}V_{dc}$
→	1	0	1	$\frac{1}{3}V_{dc}$	$-\frac{2}{3}V_{dc}$	$\frac{1}{3}V_{dc}$
→	1	1	0	$\frac{1}{3}V_{dc}$	$\frac{1}{3}V_{dc}$	$-\frac{2}{3}V_{dc}$
	1	1	1	0	0	0



