

1. (5 points) In electrostatics, we generate a curl-free vector field  $\mathbf{E}(x, y, z)$  if we take the gradient of a scalar function  $V(x, y, z)$ . Therefore,  $\nabla \times \mathbf{E} = \nabla \times (-\nabla V) = 0$ .

$$\begin{aligned}\nabla \times \mathbf{E} &= \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ z & -y & x \end{vmatrix} \\ &= 0.\end{aligned}$$

2. (5 points) Following the logic from last question,

$$\begin{aligned}\mathbf{E} = -\nabla V &= -\nabla V \\ &= -\nabla(\sin(x)e^{-y}z^2) \\ &= (-\cos(x)e^{-y}z^2, \sin(x)e^{-y}z^2, -2\sin(x)e^{-y}z) \frac{V}{m}\end{aligned}$$

We use the differential form of Gauss's Law for calculating the static charge density,

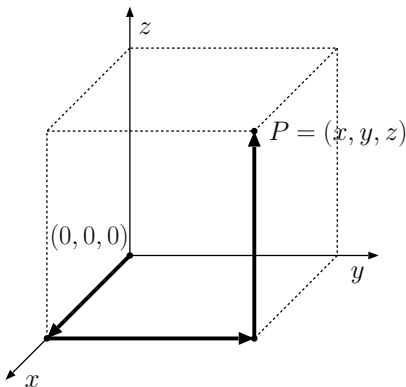
$$\rho = \nabla \cdot \mathbf{D} = -2\epsilon_0 \sin(x)e^{-y}$$

The close loop line integral of a vector field  $\mathbf{E}(x, y, z)$  generated from a scalar potential,

$$\int_P^P \mathbf{E} \cdot d\mathbf{l} = \int_P^P -\nabla V \cdot d\mathbf{l} = V(P) - V(P) = 0$$

Hence, it is conservative.

3. (10 points) The electrostatic potential  $V$  at any point  $P = (x, y, z)$  can be calculated by performing a vector line integral by using the path shown in the below figure.

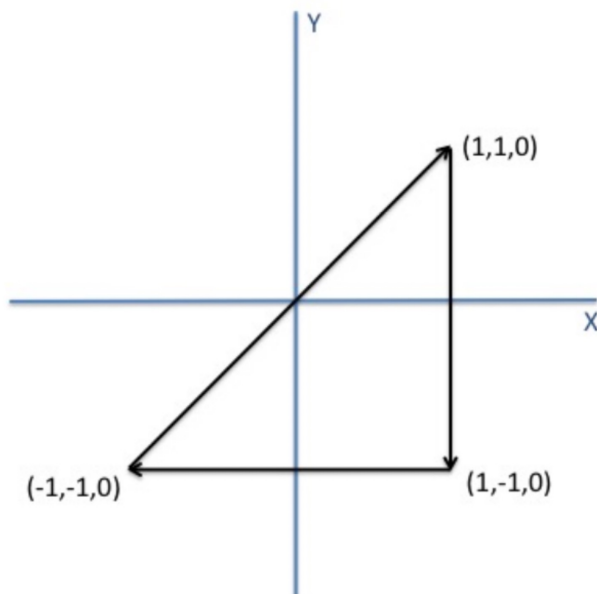


Therefore, we can write

$$\begin{aligned}V(P) - V(0) &= -\int_0^P \mathbf{E} \cdot d\mathbf{l} \\ &= -\int_0^x E_x(x, 0, 0)dx - \int_0^y E_y(x, y, 0)dy - \int_0^z E_z(x, y, z)dz \\ &= -1 - 2\sin(3)V.\end{aligned}$$

Given that  $V(0) = 3V$ , the electrostatic potential at  $P = (1, 2, 3)$  is  $V(1, 2, 3) = 2 - 2\sin(3)$  [V].

4. (a) (6 points) The triangular path defined in the problem is sketched in the figure below.



Referring to the hint given in the problem, we can write

$$\oint_C \mathbf{E} \cdot d\mathbf{l} = \int_{l_1} \mathbf{E}(x, -1, 0) \cdot d\mathbf{l}_1 + \int_{l_2} \mathbf{E}(x, x, 0) \cdot d\mathbf{l}_2 + \int_{l_3} \mathbf{E}(1, y, 0) \cdot d\mathbf{l}_3.$$

Evaluating this equation for the field  $\mathbf{E}$  with the + sign, we obtain

$$\oint_C \mathbf{E}_1 \cdot d\mathbf{l} = \int_1^{-1} (-\hat{x} + \hat{y}x) \cdot (\hat{x}) dx + \int_{-1}^1 (\hat{x}x + \hat{y}x) \cdot (\hat{x} + \hat{y}) dx + \int_1^{-1} (\hat{x}y + \hat{y}) \cdot (\hat{y}) dy = 0 \text{ [V]}.$$

Likewise, we have

$$\oint_C \mathbf{E}_2 \cdot d\mathbf{l} = \int_1^{-1} (-\hat{x} - \hat{y}x) \cdot (\hat{x}) dx + \int_{-1}^1 (\hat{x}x - \hat{y}x) \cdot (\hat{x} + \hat{y}) dx + \int_1^{-1} (\hat{x}y - \hat{y}) \cdot (\hat{y}) dy = 4 \text{ [V]}.$$

for the field  $\mathbf{E}$  with the - sign.

- (b) (4 points) Evaluating  $\nabla \times \mathbf{E}$  for both the fields, first  $\mathbf{E}$  with the + sign,

$$\begin{aligned} \nabla \times \mathbf{E}_1 &= \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ y & x & 0 \end{vmatrix} \\ &= 0 \end{aligned}$$

and the - sign  $\mathbf{E}$ ,

$$\begin{aligned} \nabla \times \mathbf{E}_2 &= \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ y & -x & 0 \end{vmatrix} \\ &= -2\hat{z}. \end{aligned}$$

Using Stokes' equation,

$$\int_S (\nabla \times \mathbf{E}_1) \cdot d\mathbf{S} = 0$$

and similarly,

$$\int_S (\nabla \times \mathbf{E}_2) \cdot d\mathbf{S} = 2 \times \text{Area} = 4.$$

The result confirms the calculations carried out in part (a).

5. (5 points) Using vector line integral equation from question 3, the voltage drop is given by,

$$\begin{aligned} V(2) - V(-2) &= - \int_{-2}^2 \mathbf{E} \cdot d\mathbf{l} \\ &= 4 \int_{-2}^2 dz \\ &= 16 \text{ [V]}. \end{aligned}$$

6. (a) (3 points) Using formula for static charge sheet from Lecture 3,

$$\mathbf{D} = \begin{cases} \hat{z} \frac{\rho_0}{2}, & \text{for } z > 0 \\ -\hat{z} \frac{\rho_0}{2}, & \text{for } z < 0 \end{cases}$$

- (b) (2 points) With the substitutions,

$$\begin{aligned} \mathbf{D}_1 &= \hat{a}_n \frac{\rho_0}{2} \left[ \frac{\text{C}}{\text{m}^2} \right] \\ \mathbf{D}_2 &= -\hat{a}_n \frac{\rho_0}{2} \left[ \frac{\text{C}}{\text{m}^2} \right] \end{aligned}$$

from which it is easy to see that  $\hat{a}_n \cdot (\mathbf{D}_1 - \mathbf{D}_2) = \rho_0$ .

7. (a) (2 points) We use the boundary condition outlined in question 6(b),

$$\rho'_0 = \hat{y} \cdot (\mathbf{D}|_{y=2^+} - \mathbf{D}|_{y=2^-}) = -1 \left[ \frac{\text{C}}{\text{m}^2} \right].$$

- (b) (2 points) Since, there is no static charge distribution dependence in  $z$ , the field component in  $\hat{z}$  will be equal across the  $y = 2$  static charge sheet. Therefore,

$$\mathbf{D}(0, y, 0) = \hat{y} - 2\hat{z} \left[ \frac{\text{C}}{\text{m}^2} \right] \text{ for } y > 2$$

- (c) (2 points) The  $y$  component of the field is given by

$$\rho|_{y=0} = \hat{y} \cdot (\mathbf{D}|_{y=0^+} - \mathbf{D}|_{y=0^-}),$$

which results in

$$\mathbf{D}|_{y=0^-} = -1 \left[ \frac{\text{C}}{\text{m}^2} \right].$$

And since the  $\hat{z}$  component is unchanged, we have

$$\mathbf{D}(0, y, 0) = -\hat{y} - \hat{z} 2 \left[ \frac{\text{C}}{\text{m}^2} \right] \text{ for } y < 0.$$

- (d) (4 points) Possible volumetric charge densities for infinite charge sheets can be either  $-4\delta(z + 30) \left[ \frac{\text{C}}{\text{m}^3} \right]$  or  $4\delta(z - 30) \left[ \frac{\text{C}}{\text{m}^3} \right]$ .

8. (10 points) The given scalar field is  $f = x + yz$  and the given vector field  $\mathbf{A} = (x+z)y\hat{x} + (x-z)\hat{z}$ . The proof of the first identity  $\nabla \times \nabla f = 0$  is given below. For

$$\nabla f = (1, z, y),$$

taking curl,

$$\begin{aligned} \nabla \times \nabla f &= \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ 1 & z & y \end{vmatrix} \\ &= 0 \end{aligned}$$

Hence, L.H.S = R.H.S.

The second identity  $\nabla \cdot \nabla \times \mathbf{A} = 0$  is proved below:

$$\begin{aligned} \nabla \times \mathbf{A} &= \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ (x+z)y & 0 & x-z \end{vmatrix} \\ &= (0, y-1, -x-z) \end{aligned}$$

Taking divergence,

$$\nabla \cdot \nabla \times \mathbf{A} = 1 - 1 = 0$$

L.H.S=R.H.S.

The third identity is  $\nabla \times (\nabla \times \mathbf{A}) = \nabla(\nabla \cdot \mathbf{A}) - \nabla^2 \mathbf{A}$ ,

$$\begin{aligned} \nabla \times (\nabla \times \mathbf{A}) &= \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ 0 & y-1 & -x-z \end{vmatrix} \\ &= (0, 1, 0). \end{aligned}$$

Evaluating R.H.S,

$$\nabla(\nabla \cdot \mathbf{A}) = \nabla(y-1) = \hat{y}$$

and

$$\nabla^2 \mathbf{A} = 0.$$

We see that L.H.S = R.H.S =  $\hat{y}$ .