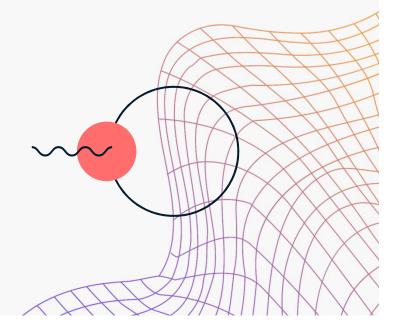
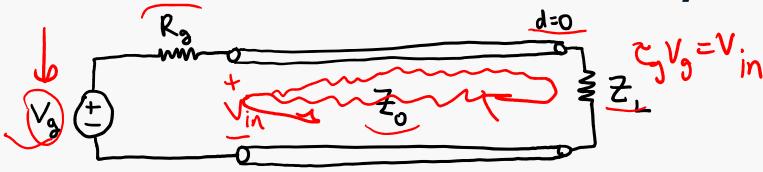


# ECE329: Tutorial Session 9

November 13th, 2024



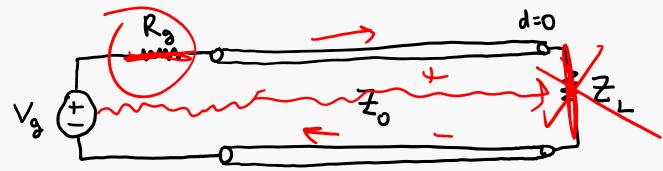
#### **Basic TL: Time Domain, Not Steady State**



Generator injection coefficient:  $\tau_g = \frac{Z_0}{R_g + Z_0} \neq 1 + \Gamma_g$ 

Load reflection coefficient  $\Gamma_{IJ} = \frac{Z_L - Z_0}{Z_L + Z_0}$ Generator reflection coefficient  $\Gamma_{IJ} = \frac{R_g - Z_0}{R_g + Z_0}$ 

#### **Basic TL: Time Domain, Not Steady State**



#### Special cases:

• What if 
$$Z_L = \infty$$
?

• What if  $Z_L = Z_0$ ?

#### **Problem 1: Bounce Diagrams**

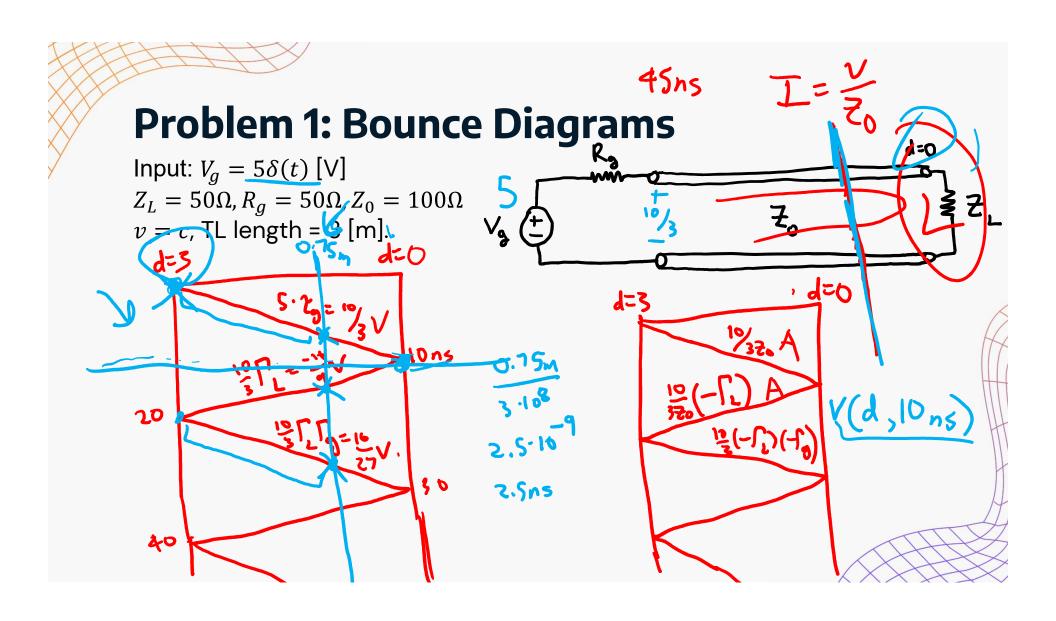
Input:  $V_g = 5u(t)$  [V]  $Z_L = 50\Omega$ ,  $R_g = 50\Omega$ ,  $Z_0 = 100\Omega$  v = c, TL length = 3 [m].



Create a voltage bounce diagram for the first 45 nanoseconds. Create a current bounce diagram for the first 45 nanoseconds.

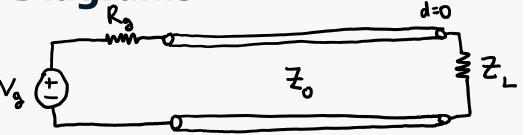
$$\int_{L} = \frac{2^{2} - 20}{2^{2} + 20} = \frac{1}{3} \qquad \left[ q = \frac{k_{0} - 20}{R_{0} + 20} = \frac{1}{3} \right]$$

$$\frac{3}{3.108} = 10^{-8} = 10.16^{-9} = 10 \text{ ns}$$

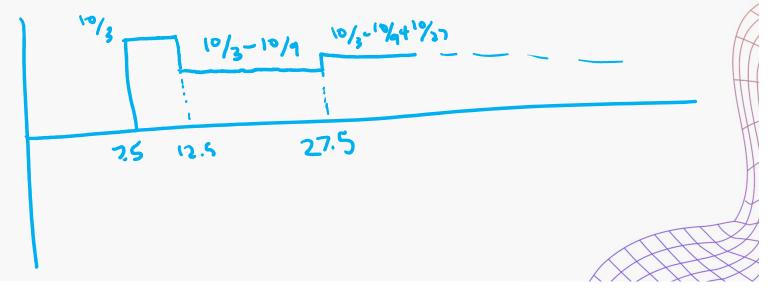


#### **Problem 2: Bounce Diagrams**

Input:  $V_g = \underline{5u(t)}$  [V]  $Z_L = 50\Omega$ ,  $R_g = 50\Omega$ ,  $Z_0 = 100\Omega$  v = c, TL length = 3 [m].

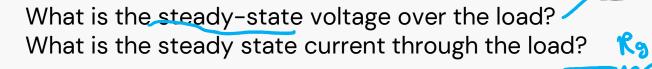


Plot V(0.75m, t) for the first 45 nanoseconds.

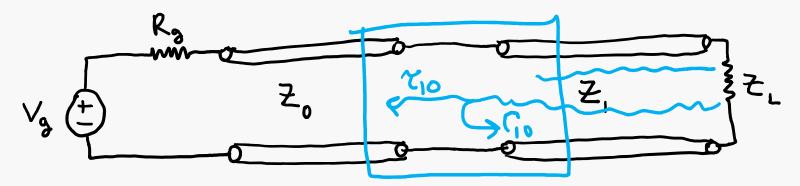




Input:  $V_g = 5u(t)$  [V]  $Z_L = 50\Omega$ ,  $R_g = 50\Omega$ ,  $Z_0 = 100\Omega$  v = c, TL length = 3 [m].



#### **Multiline TL Circuits**



When we travel FROM line j TO line k:

$$\Gamma_{jk} = \frac{Z_k - Z_j}{Z_k + Z_j}$$

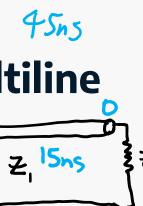
$$\tau_{jk} = 1 + \Gamma_{jk}$$

#### Problem 3: Bounce Diagrams w/ Multiline

Input: 
$$V_g = 5u(t) [V]$$
 $Z_L = 50\Omega, R_g = 50\Omega$ 
 $Z_0 = 100\Omega, Z_1 = 200\Omega$ 
 $V_3$ 
 $V_4$ 
 $V_5$ 
 $V_6$ 
 $V_7$ 
 $V_8$ 
 $V_8$ 
 $V_8$ 
 $V_9$ 
 $V_9$ 

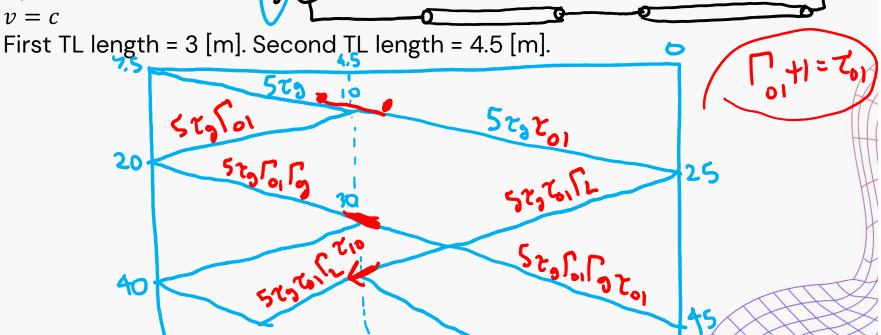
First TL length = 3 [m]. Second TL length = 4.5 [m].

Create a voltage bounce diagram for the first 45 nanoseconds. Create a current bounce diagram for the first 45 nanoseconds.



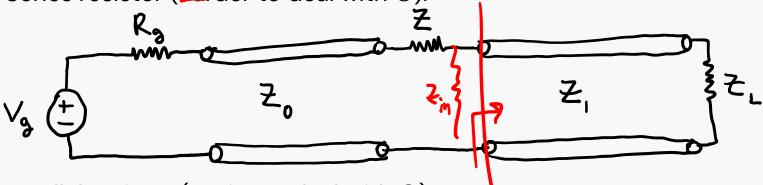
Problem 3: Bounce Diagrams w/ Multiline

Input: 
$$V_g = 5\delta(t)$$
 [V]  $Z_L = 50\Omega$ ,  $R_g = 50\Omega$   $Z_0 = 100\Omega$ ,  $Z_1 = 200\Omega$   $v = c$ 

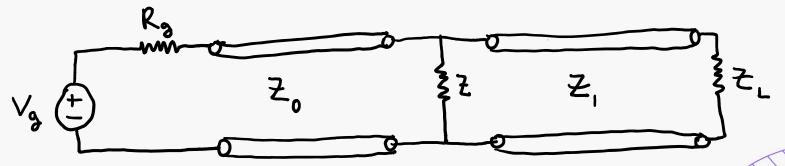


2 10 no

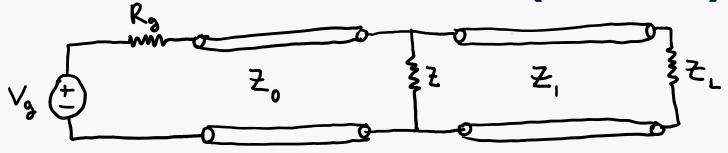


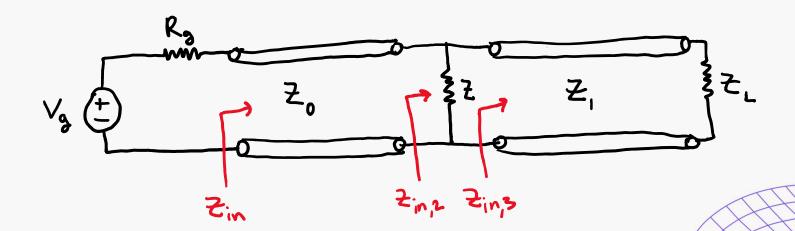


Parallel resistor (easier to deal with ©):

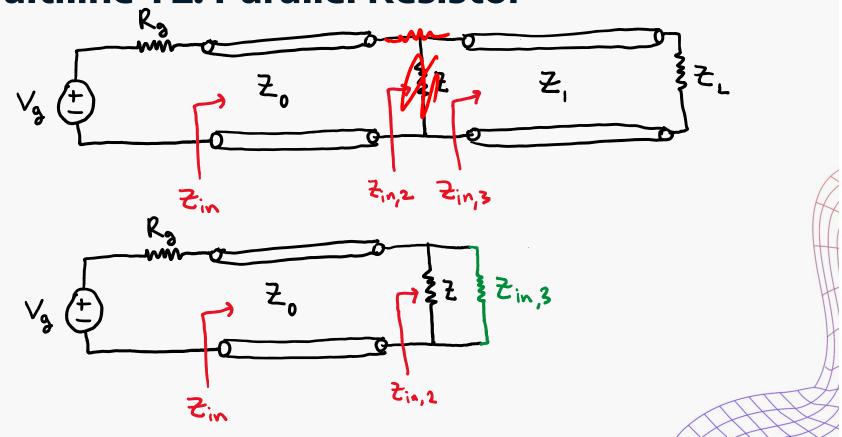


## Multiline TL: Parallel Resistor (HW Hint)

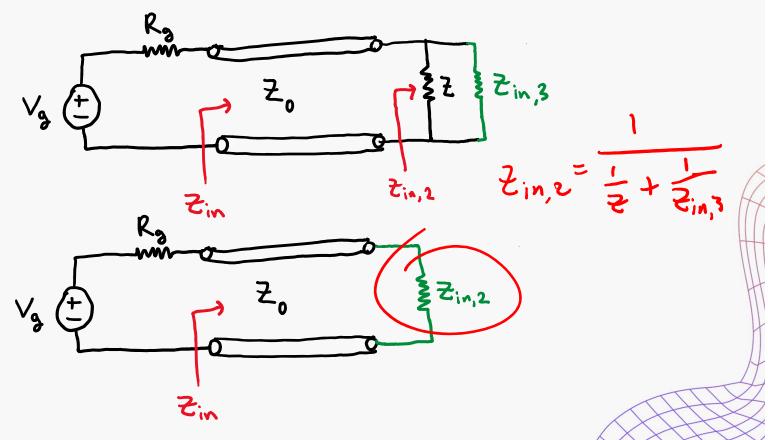




### **Multiline TL: Parallel Resistor**

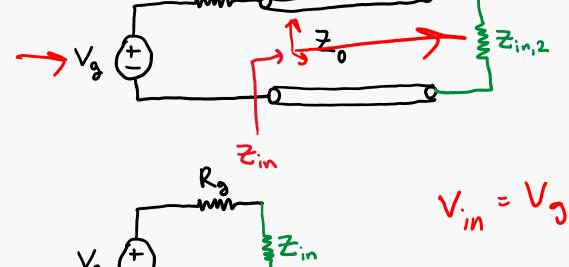


#### **Multiline TL: Parallel Resistor**



### **Multiline TL: Parallel Resistor**





#### **Bounce Diagrams: General Formulation**

This is an LTI system!

Input:  $\delta(t)$ 

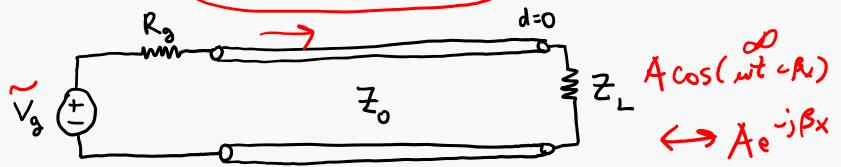
Output (at position d): V(t)

Time to travel down the line:  $t_0$ .

$$V(d,t) = \tau_g \sum_{n=0}^{\infty} \left(\Gamma_L \Gamma_g\right)^n \delta(t + \frac{d}{v} - nt_0) + \tau_g \Gamma_L \sum_{n=0}^{\infty} \left(\Gamma_L \Gamma_g\right)^n \delta(t - \frac{d}{v} - (n+1)t_0)$$

For any general input: convolve!

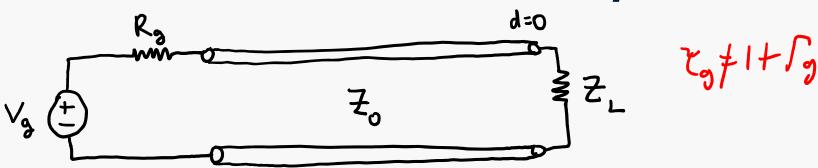
## Basic TL: Phasor Domain, Steady State



On TL: Forward-going voltage wave + backward-going voltage wave

On TL: Forward-going current wave + backward-going current wave

### **Basic TL: Phasor Domain, Steady State**



Impedance as a function of position?

$$Z_0 \neq Z(J) = \frac{V(J)}{\Gamma(J)}$$

#### Midterm 1 equations, in one place

$$\vec{F} = \frac{q_1 q_2}{4\pi\epsilon_0 r^2} \hat{r}$$

$$\vec{F} = q_1 \vec{E} + q_1 (\vec{v}_1 \times \vec{B})$$

$$\vec{E} = \frac{q_2}{4\pi\epsilon_0 r^2} \hat{r}$$

$$\hat{n} \times (\vec{E}_1 - \vec{E}_2) = 0$$

 $\hat{n} \cdot (\vec{D}_1 - \vec{D}_2) = \rho_s$ 

$$\hat{n}\cdot\left(\vec{P}_1-\vec{P}_2\right)=-\rho_{b,s}$$

$$\epsilon \oiint ec{E} \cdot dec{S} = Q_{ ext{enclosed}} \ \oiint ec{D} \cdot dec{S} = Q_{ ext{enclosed}} \ \oiint ec{
ho} dV = Q_{ ext{enclosed}} \ \oiint ec{B} \cdot dec{S} = 0 \ I = \oiint ec{J} \cdot dec{S} = -rac{\partial Q_{ ext{enclosed}}}{\partial t}$$

$$\epsilon = \epsilon_0 (1 + \chi_e)$$

$$\vec{P} = \epsilon_0 \chi_e \vec{E}$$

$$\vec{D} = \epsilon_0 \vec{E} + \vec{P} = \epsilon \vec{E}$$

$$\vec{J} = \sigma \vec{E}$$

$$\rho_b = -\nabla \cdot \vec{P}$$

$$\nabla \cdot \epsilon_0 \vec{E} = \rho_f + \rho_b$$

$$\nabla \cdot \vec{D} = \rho$$

$$\nabla \cdot \vec{D} = \rho$$

$$\nabla \cdot \vec{J} = -\frac{\partial}{\partial \rho}$$

$$-\nabla^2 V = \frac{\rho}{\epsilon}$$

$$\nabla \times \vec{E} = 0$$

$$\vec{E} = -\nabla V$$

$$\oint \vec{E} \cdot d\vec{l} = 0$$

$$V_{ab} = V(b) - V(a) = -\int_{a}^{b} \vec{E} \cdot d\vec{l}$$

$$\nabla \cdot \vec{D} = \rho$$

$$\nabla \cdot \vec{J} = -\frac{\partial \rho}{\partial t}$$

$$-\nabla^{2}V = \frac{\rho}{\epsilon}$$

$$\oint \vec{D} \cdot d\vec{S} = \iiint \nabla \cdot \vec{D} dV$$

$$\oint \vec{E} \cdot d\vec{l} = \iint (\nabla \times \vec{E}) \cdot d\vec{S}$$

$$\int_{a}^{b} \nabla V \cdot d\vec{l} = V(b) - V(a)$$



#### Midterm 2 equations, in one place

$$\vec{B} = \frac{\mu I}{2\pi r} \hat{\phi}$$

$$d\vec{B} = \frac{\mu I d\vec{\ell} \times \hat{r}}{4\pi^2}$$

$$\oint_C \vec{H} \cdot d\vec{\ell} = \iint_S \vec{J} \cdot d\vec{S}$$

$$\oint_{C} \vec{B} \cdot d\vec{\ell} = \mu I_{\text{encl}} \qquad \oint_{C} \vec{E} \cdot d\vec{l} = \varepsilon$$

$$\nabla \times \vec{H} = \vec{J} + \frac{\partial \vec{D}}{\partial t}$$

$$\nabla \cdot \vec{B} = 0$$

$$\Psi = \iint_{S} \vec{B} \cdot d\vec{S} \qquad v = \frac{\omega}{\beta} = \lambda f = \frac{1}{\sqrt{\mu \epsilon}}$$

$$d\vec{B} = \frac{\mu I d\vec{\ell} \times \hat{r}}{4\pi r^2} \qquad -\frac{d}{dt} \iint_{S} \vec{B} \cdot d\vec{S} = \oint_{C} \vec{E} \cdot d\vec{l} \qquad \omega = 2\pi f = \frac{2\pi}{T}$$

$$dt \iint_{S} d\vec{s} \quad \vec{J}_{c}^{L} \quad d\vec{s} \quad \vec{J}_{c}^{L}$$

$$\eta = \frac{\sqrt{\mu}}{\sqrt{\epsilon}}$$

$$abla imes ec{E} = -rac{\partial ec{B}}{\partial t}$$

$$\oint_{\mathcal{L}} \vec{E} \cdot d\vec{l} = \varepsilon$$

$$\nabla \times \vec{H} = \vec{J} + \frac{\partial \vec{D}}{\partial t}$$
  $\qquad \qquad \varepsilon = \frac{W}{q} = \oint_C \frac{\vec{F}}{q} \cdot d\vec{l}$ 

$$\Psi = LI$$

$$\varepsilon = IR$$

$$\vec{S} = \vec{E} \times \vec{H}$$

$$\tilde{S} = \tilde{E} \times \tilde{H}^*$$

 $\nabla^2 \vec{E} = \mu \epsilon \frac{\partial^2 \vec{E}}{\partial t^2}$ 

 $\beta = \omega \sqrt{\mu \epsilon}$ 

$$\langle \vec{S} \rangle = \frac{1}{2} \operatorname{Re} \{ \tilde{E} \times \tilde{H}^* \}$$

$$\tilde{S} = \tilde{E} \times \tilde{H}^* 
< \vec{S} > = \frac{1}{2} \operatorname{Re} \{ \tilde{E} \times \tilde{H}^* \} 
\frac{\partial}{\partial t} \left( \frac{1}{2} \epsilon \vec{E} \cdot \vec{E} + \frac{1}{2} \mu \vec{H} \cdot \vec{H} \right) + \nabla \cdot \vec{S} + \vec{J} \cdot \vec{E} = 0$$

$$Q = CV$$

$$G = \frac{\sigma}{\epsilon} C \qquad R = \frac{1}{G}$$

$$\vec{J}_b = \frac{\partial \vec{P}}{\partial t} + \nabla \times \vec{M}$$

$$\vec{B} = \vec{B}$$

$$\vec{H} = \frac{\vec{B}}{\mu_0} - \vec{M}$$

$$\vec{M} = \chi_m \vec{H}$$

$$\vec{B} = \mu_0 \mu_r \vec{H} = \mu \vec{H}$$

$$A\cos(\omega t - \beta x)\hat{z} \longleftrightarrow Ae^{-j\beta x}\hat{z}$$

$$\hat{n} \cdot \left( \vec{B}_1 - \vec{B}_2 \right) = 0$$

$$\hat{n} \times \left( \vec{H}_1 - \vec{H}_2 \right) = \vec{J}_s$$

$$\hat{n} \times \left( \vec{M}_1 - \vec{M}_2 \right) = \vec{J}_{b,s}$$

#### Midterm 3 equations, in one place

Waves:

	Condition	β	$\alpha$	$ \eta $	au	$\lambda = \frac{2\pi}{\beta}$	$\delta = \frac{1}{\alpha}$
Perfect	$\sigma = 0$	$\omega\sqrt{\epsilon\mu}$	0	$\sqrt{\frac{\mu}{\epsilon}}$	0	$2\pi$	$\infty$
dielectric		ωγιμ	· ·	V ε	, in the second	$\omega\sqrt{\epsilon\mu}$	
Imperfect	$\frac{\sigma}{\omega\epsilon} \ll 1$	$\sim \omega \sqrt{\epsilon \mu}$	$\rho 1 \sigma = \sigma \cdot / \overline{\mu}$	<u>/</u> E	$\sim rac{\sigma}{2\omega\epsilon}$	$\sim \frac{2\pi}{\omega\sqrt{\epsilon\mu}}$	$\frac{2}{2} \sqrt{\epsilon}$
dielectric	$\omega\epsilon$	ωγιμ	$\rho = 2 \omega \epsilon = 2 V$	νε	$2\omega\epsilon$	$\omega\sqrt{\epsilon\mu}$	σ $\bigvee \mu$
Good	$\sigma \sim 1$	$\alpha = \sqrt{\pi} f \mu \sigma$	$a + \sqrt{\pi} f u \sigma$	$\sqrt{\omega\mu}$	45	$2\pi$	1
conductor	$\frac{\sigma}{\omega\epsilon} \gg 1$	$\sqrt{\pi j \mu o}$	$\sim \sqrt{\pi f \mu \sigma}$	$\sqrt{\sigma}$	45	$\sqrt{\pi f \mu \sigma}$	$\sqrt{\pi f \mu \sigma}$
Perfect	$\sigma = \infty$	$\infty$	$\infty$	0		0	0
conductor	0 – 00		$\sim$	U	ñ	U	U

$$\Gamma = \frac{\eta_2 - \eta_1}{\eta_2 + \eta_1} \qquad \tau = \frac{2\eta_2}{\eta_2 + \eta_1} = 1 + \Gamma$$

$$v = \frac{\omega}{\beta} = \lambda f$$

 $\nabla^2 \tilde{E} = (j\omega\mu)(\sigma + j\omega\epsilon)\tilde{E}$ 

$$\Gamma_L = \frac{Z_L - Z_0}{Z_L + Z_0}$$

$$\tau_g = \frac{Z_0}{R_g + Z_0}$$

$$\Gamma_{jk} = \frac{Z_k - Z_j}{Z_k + Z_j}$$

$$\tau_{jk} = 1 + \Gamma_{jk}$$

$$\Gamma_g = \frac{R_g - Z_0}{R_g + Z_0}$$
Half-wave:
$$V_{in} = -V_{out}$$

$$I_{in} = -I_{out}$$

$$Z_{in} = Z_{out}$$

$$\Gamma_{jk} = \frac{Z_k - Z_j}{Z_k + Z_j}$$

$$\tau_{jk} = 1 + \Gamma_{jk}$$

$$egin{aligned} & \mathsf{Half-wave:} \ & V_{in} = -V_{out} \ & I_{in} = -I_{out} \ & Z_{in} = Z_{out} \end{aligned}$$

#### Quarter-wave:

$$V_{in} = jI_{out}Z_0$$

$$I_{in} = \frac{jV_{out}}{Z_0}$$

$$Z_{in} = \frac{Z_0^2}{Z_{out}}$$



#### **Units**

Charge Q: C

Current I: A

Electric field strength  $\vec{E}$ : N/C or V/m

Electric flux density  $\vec{D}$ : C/m<sup>2</sup>

Polarization field  $\vec{P}$ : C/m<sup>2</sup>

Electric potential V: V

Capacitance C: F

Magnetic flux density  $\vec{B}$ : T or Wb/m<sup>2</sup>

Magnetic field strength  $\vec{H}$ : A/m

Magnetic flux Ψ: Wb

Electromotive force  $\varepsilon$ : V

Inductance L: H

Electric permittivity  $\epsilon$ : F/m

Magnetic permeability  $\mu$ : H/m

Conductivity  $\sigma$ : Si/m

Charge density  $\rho$ : C/m<sup>3</sup>

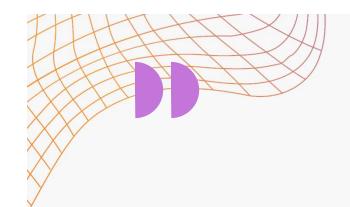
Surface charge density  $\rho_s$ : C/m<sup>2</sup>

Current density  $\vec{J}$ : A/m<sup>2</sup>

Intrinsic impedance  $\eta$ : Ohm

Wave number  $\beta$ : rad/m

Characteristic impedance Z: Ohm



# **Office Hours**

Any questions?

