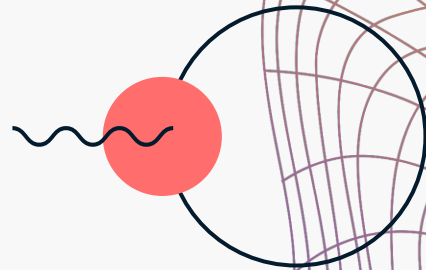





ECE329: Exam 1 Review Session

9/25/2025





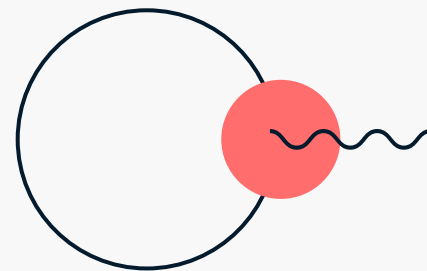
Exam 1 Content

- Vector Calculus
 - Coulomb's Law and Lorentz Force
 - Gauss's Law & electric flux
 - Electrostatic potential
 - Boundary Conditions
 - Conductors
 - Dielectrics
 - Capacitance & Conductance
 - Charge flux
- 



1.

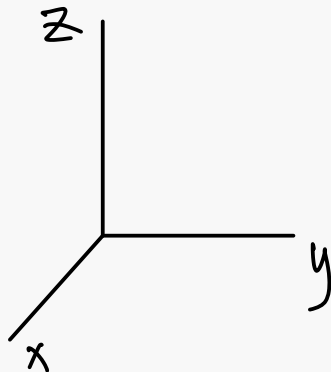
Math ☹️



Coordinate Systems

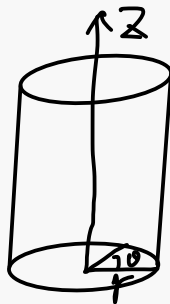
Cartesian 3D

$$dx dy dz$$



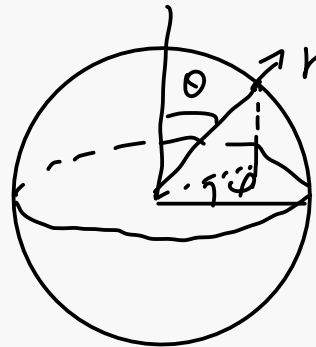
Cylindrical

$$r dr d\theta dz$$



Spherical

$$r^2 \sin\theta dr d\theta d\phi$$



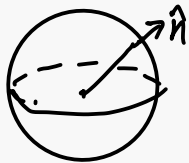
Line, Surface, & Volume integrals

Volume

$$\iiint \rho \, dV$$

Surface

$$\begin{aligned} \iint \vec{E} \cdot d\vec{S} \\ = \iint \vec{E} \cdot \vec{n} \, dS \end{aligned}$$



Line

$$\int \vec{E} \cdot d\vec{l}$$

$$E = P\hat{x} + Q\hat{y} + R\hat{z}$$

$$\begin{aligned} &= \int \vec{E} \cdot \vec{v} \, dt \\ &= \int \vec{E} \cdot \left(\frac{dx}{dt} \hat{x} + \frac{dy}{dt} \hat{y} + \frac{dz}{dt} \hat{z} \right) dt \\ &= \int P dx + Q dy + R dz \end{aligned}$$



Divergence & Divergence Theorem

Divergence = How much the field is DIVERGING at a certain point.

- Notation: $\nabla \cdot \vec{D}$
- Input: Vector field
- Output: Scalar field

Divergence Theorem: $\oiint \vec{D} \cdot d\vec{S} = \iiint \nabla \cdot \vec{D} dV$




Curl & Stoke's Theorem

Curl = How much the field is CURLING around a certain point.

- Notation: $\nabla \times \vec{E}$
- Input: Vector field
- Output: Vector field, with direction indicating how the field right-hand curls around.

Stoke's Theorem: $\oint \vec{E} \cdot d\vec{l} = \iint (\nabla \times \vec{E}) \cdot d\vec{S}$



5. (12 pts) For $\mathbf{E} = yz\hat{x} + (y + zx)\hat{y} + xy\hat{z}$ V/m

a) Evaluate the potential difference $V_A - V_B$ for $\mathbf{A} = (2, 1, 1)$ and $\mathbf{B} = (1, 4, \frac{1}{2})$

Method

$$\textcircled{1} \nabla \times \mathbf{E} = 0$$

$$-V = xyz + \frac{1}{2}y^2 + \text{Const}$$

$$\Rightarrow V_A - V_B = -\left[2 + \frac{1}{2} - \left(2 + 8\right)\right] = 7.5 \text{ V}$$

$$\textcircled{2} \text{ integral } (2, 1, 1) \xrightarrow{x} (1, 1, 1) \xrightarrow{y} (1, 4, 1) \xrightarrow{z} (1, 4, \frac{1}{2})$$

$$V_A - V_B = \int_2^1 1 dx + \int_1^4 (y+1) dy + \int_1^{\frac{1}{2}} 4 dz = -1 + 10.5 - 2 = 7.5 \text{ V}$$

$$\textcircled{3} \mathbf{r}(t) = (1-t) \cdot (2, 1, 1) + t(1, 4, \frac{1}{2}) = (2-t, 1+3t, 1-\frac{1}{2}t) = (x, y, z)$$

$$\mathbf{v}(t) = \frac{d\mathbf{r}}{dt} = (-1, 3, -\frac{1}{2})$$

$$V_A - V_B = \int_0^1 \left\{ (1+3t)(1-\frac{1}{2}t)\hat{x} + [1+3t+(2-t)(1-\frac{1}{2}t)]\hat{y} + [(2-t)(1+3t)]\hat{z} \right\} \cdot (-1, 3, -\frac{1}{2}) dt$$



Gradient & Gradient Theorem


Gradient = How much the scalar function changes (or its GRADE).

- Notation: ∇V
- Input: Scalar field
- Output: Vector field, with direction indicating steepest **uphill**.

Fundamental theorem of calculus: $\int_a^b f'(t) \cdot dt = f(b) - f(a)$

Similarly:

Gradient theorem: $\int_a^b \nabla V \cdot d\vec{l} = V(b) - V(a) = \text{Voltage gain from a to b.}$



Laplacian

Laplacian (scalar) = How much the scalar function LAPLACES.



Laplacian (scalar) = How much the rate of change of the scalar function varies (aka stress).

- Notation: $\nabla^2 V = \nabla \cdot \nabla V$
- Input: Scalar field
- Output: Scalar field



P.S.: Helmholtz Theorem

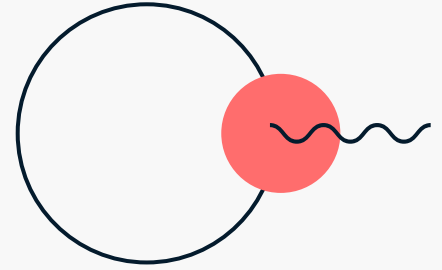
A vector field \vec{E} is specified completely by its divergence and curl.



A decorative orange wireframe grid on the left side of the slide, curving upwards and to the right.

2.

Physics 😊



All* the concepts

Q

$$\rho_f = \rho$$

\vec{D}

ρ_s

C

$\rho_{b,s}$

V

\vec{E}

\vec{P}


ρ_b



In the beginning...

There exists positive free electric charge and negative free electric charge.

Coulomb's Law:

$$\vec{F} = \frac{q_1 q_2}{4\pi\epsilon r^2} \hat{r}$$


Fields

Electric field [Newtons/Coulomb] OR [Volts/meter]: the effect that a charge has on its surroundings.

$$\vec{F} = \frac{q_1 q_2}{4\pi\epsilon r^2} \hat{r}$$

$$\vec{E} = \frac{q_2}{4\pi\epsilon r^2} \hat{r}$$

$$\vec{F} = q_1 \vec{E}$$

Superposition

$$\vec{F} = q_1 \sum^n \frac{q_n}{4\pi\epsilon |\vec{r}_n|^2} \frac{\vec{r}_n}{|\vec{r}_n|} dV \quad \vec{E} = \sum^n \frac{q_n}{4\pi\epsilon |\vec{r}_n|^2} \frac{\vec{r}_n}{|\vec{r}_n|}$$

Summation can become an integral!

Electric Field Flux

'Electric field flux', or '**Flux**' [$\text{N}\cdot\text{m}^2/\text{C}$] OR [$\text{V}\cdot\text{m}$].

$$E: [N/C] \quad [V/m]$$

$$\frac{F}{Q} \quad -\frac{dV}{dx}$$

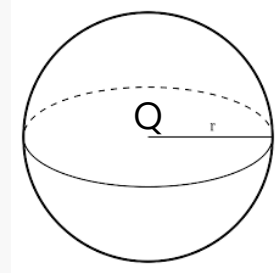
$$\iint \vec{E} \cdot d\vec{S}$$

$$\vec{E} = \frac{Q}{4\pi\epsilon r^2} \hat{r}$$

Gauss's Law: Electric

For closed surfaces only:

- If there is more electric field flux,
- Then there is more electric field flowing out of the surface,
- Then, more free charge must be enclosed in the surface.



This is **Gauss's Law**!

$$\epsilon \oint \vec{E} \cdot d\vec{S} = Q_{\text{enclosed}}$$

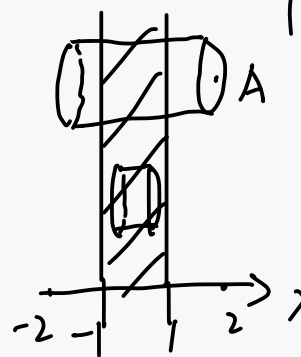
2. Two parts of the following question are independent:

a) Consider an infinite slab of width $W = 2$ m occupying the region $|x| < 1$ m. The charge density within the slab is $\rho = 4$ C/m³ and it is zero outside the slab.

i. (4 pts) Determine the electric field vector $\mathbf{E}(x, 0, 0)$ for $x = 2$ m and $x = -2$ m.

ii. (4 pts) Determine the electric field vector $\mathbf{E}(x, 0, 0)$ for $-1 < x < 1$ m within the slab.

summer20



i. $\oint \mathbf{E} \cdot d\mathbf{S} = \iiint \rho \, dV / \epsilon_0$

$2 \cdot A \cdot E = \rho \cdot A \cdot W / \epsilon_0$

$E = 4 / \epsilon_0 \hat{n} \frac{\text{V}}{\text{m}} = \begin{cases} 4 / \epsilon_0 & \hat{x} \\ -4 / \epsilon_0 & \hat{x} \end{cases} \frac{\text{V}}{\text{m}}$

$x = 2 \text{ m}$

$x = -2 \text{ m}$

ii. $2 \cdot A \cdot E = \rho \cdot A \cdot 2|x| / \epsilon_0$

$E = \frac{4x}{\epsilon_0} \hat{x} \frac{\text{V}}{\text{m}}$

All* the concepts

Q

$$\rho_f = \rho$$

\vec{D}

ρ_s

Coulomb's Law

\vec{E}

V

\vec{P}

$\rho_{b,s}$

ρ_b

Gauss's Law: Magnetic

There do not exist positive magnetic charges or negative magnetic charges!

$$\epsilon \oint \vec{E} \cdot d\vec{S} = Q_{\text{enclosed}}$$

$$\oint \vec{B} \cdot d\vec{S} = 0$$

Displacement Field

$$\epsilon \oint \vec{E} \cdot d\vec{S} = Q_{\text{enclosed}}$$

Recall vector field $\vec{D} = \epsilon \vec{E}$.

Electric displacement field: \vec{D} [C/m²]

Electric displacement flux: Closed surface integral of vector field \vec{D} .

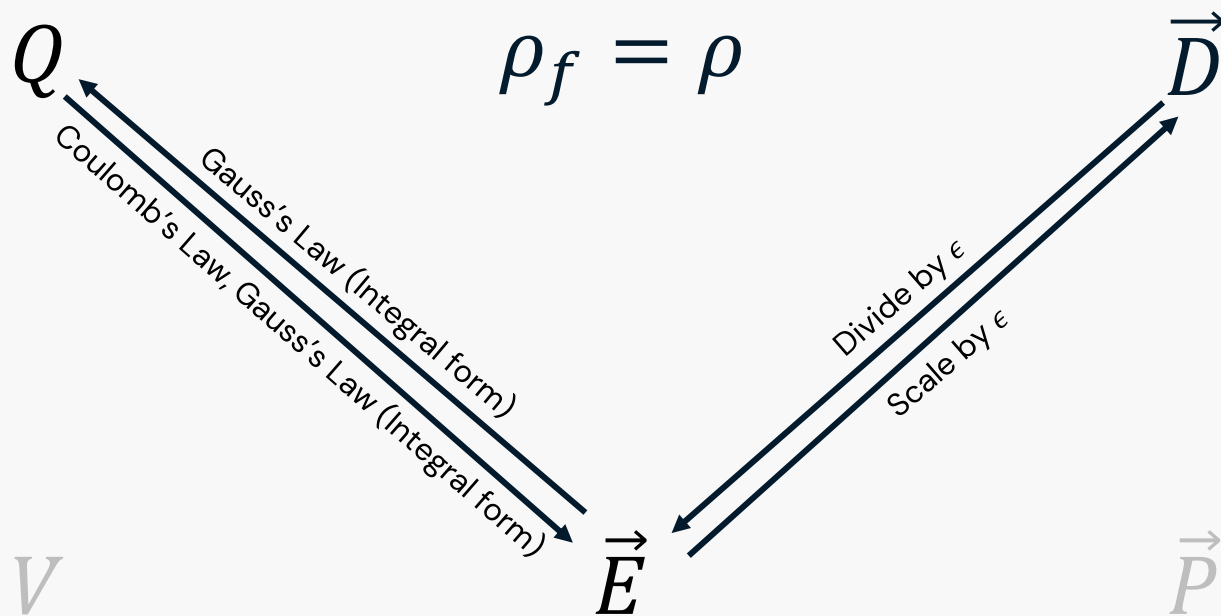
$$\oint \underset{\text{m}^2}{\vec{D} \cdot d\vec{S}} = \underset{\mathcal{L}}{Q_{\text{enclosed}}}$$

Charge Density

Charge density: ρ [C/m³]

$$\epsilon \oint \vec{E} \cdot d\vec{S} = \oint \vec{D} \cdot d\vec{S} = \iiint \underset{\substack{\downarrow \\ \frac{C}{m^3}}}{\rho} dV = Q_{\text{enclosed}}$$

All* the concepts



Gauss's Law: Differential form

$$\oiint \vec{D} \cdot d\vec{S} = \iiint \rho_{\text{enclosed}} dV$$

||

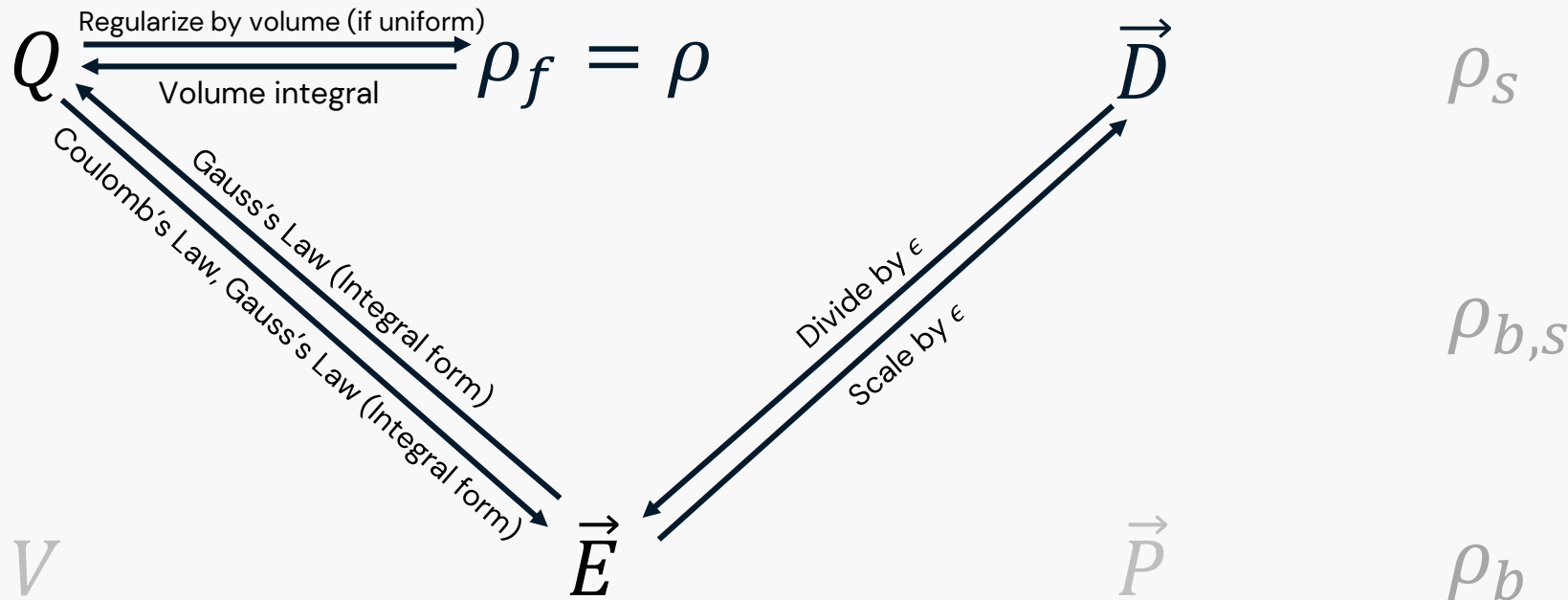
$$\iiint \nabla \cdot \vec{D} dV$$

$$\nabla \cdot \vec{D} = \rho$$

$$\oiint \vec{B} \cdot d\vec{S} = 0$$

$$\nabla \cdot \vec{B} = 0$$

All* the concepts

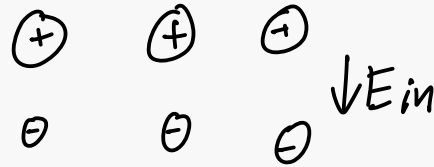


P fields: The intuition



E_{ext}
↑

Dielectric



$$E_{\text{ext}} + E_{\text{in}} = E_{\text{tot}}$$

$$\epsilon_0 E = \vec{D} - \vec{P}$$

↓
free charge

$$\nabla \cdot \vec{D} = \rho_f$$

↓
bound charge

$$-\nabla \cdot \vec{P} = \rho_b$$

P fields: The math

$\vec{D} = \epsilon_0 \vec{E} + \vec{P}$: The defining equation.

$$\begin{aligned}\vec{D} &= \epsilon_0 \vec{E} + \vec{P} = \epsilon_0 (1 + \chi_e) \vec{E} \\ &= \epsilon \vec{E} \\ &= \epsilon_0 \epsilon_r \vec{E}\end{aligned}$$

Assumption: Dielectric is 'isotropic', so \vec{P} is collinear to \vec{E} . Then:

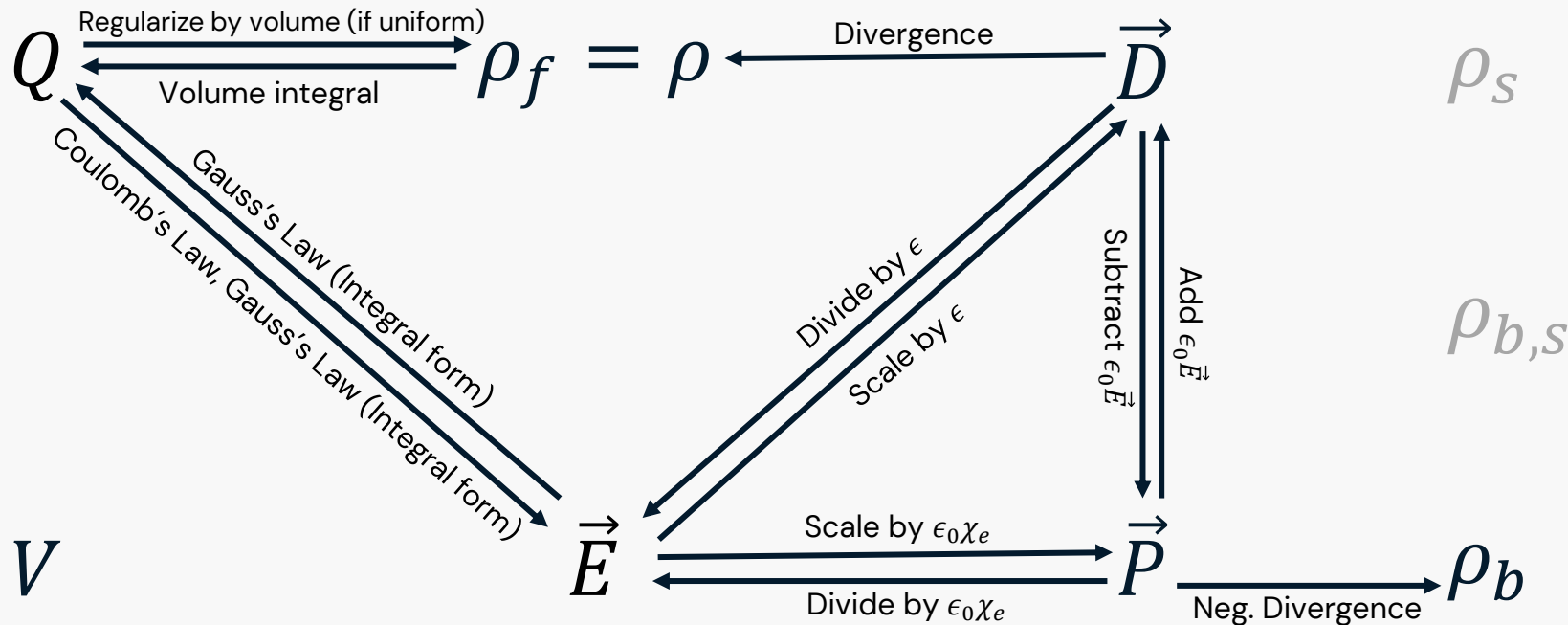
- $\vec{P} = \epsilon_0 \chi_e \vec{E}$ with **electric susceptibility** $\chi_e \geq 0$ nearly always in this class.
- Let **electric permittivity** be $\epsilon = \epsilon_0 (1 + \chi_e)$.
- Let **relative electric permittivity** be $\epsilon_r = 1 + \chi_e$
- $\vec{D} = \epsilon \vec{E}$

P fields: The math

Divergences:

- Gauss's Law: $\nabla \cdot \epsilon_0 \vec{E} = \rho_f + \rho_b$
- Gauss's Law: $\nabla \cdot \vec{D} = \rho_f = \rho$
- Therefore, $\rho_b = -\nabla \cdot \vec{P}$

All* the concepts



Conservative Fields

The following are equivalent for vector field \vec{E} :

- $\nabla \times \vec{E} = 0$
- \vec{E} is conservative
- $\oint \vec{E} \cdot d\vec{l} = 0$
- $\int_a^b \vec{E} \cdot d\vec{l}$ is path-independent
- $\vec{E} = -\nabla V$ for some scalar field V
- \vec{E} field arises from electrostatics

a) Consider the electric field $\mathbf{E} = \mathbf{E}_1 + \mathbf{E}_2$, where $\mathbf{E}_1 = \hat{x} \sin(\pi x/2)$ V/m and $\mathbf{E}_2 = \hat{x} \sin(\pi y/2)$ V/m.

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i. (4 pts) Which one of \mathbf{E}_1 and \mathbf{E}_2 satisfies the electrostatic field conditions? Explain.

$$\nabla \times \mathbf{E}_1 = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \partial_x & \partial_y & \partial_z \\ \sin \frac{\pi x}{2} & 0 & 0 \end{vmatrix} = 0 \quad \checkmark$$

$$\nabla \times \mathbf{E}_2 = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \partial_x & \partial_y & \partial_z \\ \sin \frac{\pi y}{2} & 0 & 0 \end{vmatrix} = (0, 0, -\frac{\pi}{2} \cos \frac{\pi y}{2}) \neq 0$$

$$\nabla \times \mathbf{E}_2 = -\frac{\partial B}{\partial t}$$

Electrostatic Potential

Work done by the electric field to move a charge from a to b, causing drop in electrostatic potential energy U :

$$W = -\Delta U = -[U(b) - U(a)] = \int_a^b q \vec{E} \cdot d\vec{l}$$

$$U(b) - U(a) = \int_a^b \vec{E} q d\vec{l}$$

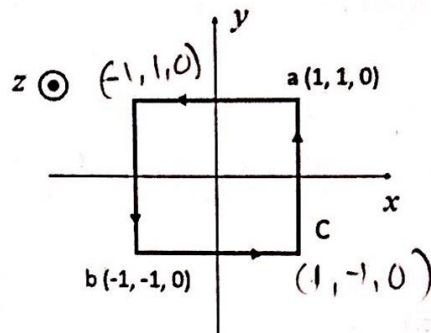
Volts = work per unit charge (take $q = 1$).

U/q = electrostatic potential energy per unit charge = V = **electrostatic potential**:

$$V_{ab} = V(b) - V(a) = - \int_a^b \vec{E} \cdot d\vec{l}$$

Example

2. (25 points) Considering electric field \mathbf{E} in free space and path C indicated in figure below, answer the following questions:



Spring 18

a) If the electric field is $\mathbf{E} = 2\hat{x} - 3\hat{y} + 5\hat{z}$ V/m,

i. (7 pts) what is the circulation $\oint \mathbf{E} \cdot d\mathbf{l}$ around path C ? Show your work.

ii. (7 pts) what is the electrostatic potential drop from point a to b (i.e. $V(a) - V(b)$)?

$$a) \quad i. \quad \oint \mathbf{E} \cdot d\mathbf{l} = \int_{(1,1,0)}^{(-1,1,0)} 2 dx + \int_{(-1,1,0)}^{(-1,-1,0)} -3 dy + \int_{(-1,-1,0)}^{(1,-1,0)} 2 dx + \int_{(1,-1,0)}^{(1,1,0)} -3 dy = 0$$

$$\nabla \times \mathbf{E} = 0, \quad \oint \mathbf{E} \cdot d\mathbf{l} = \int_S \nabla \times \mathbf{E} \cdot d\mathbf{S} = 0$$

$$ii) \quad V(a) - V(b) = \int_a^b \mathbf{E} \cdot d\mathbf{l} = \int_b^a -\mathbf{E} \cdot d\mathbf{l} = -4 + 6 = 2V$$

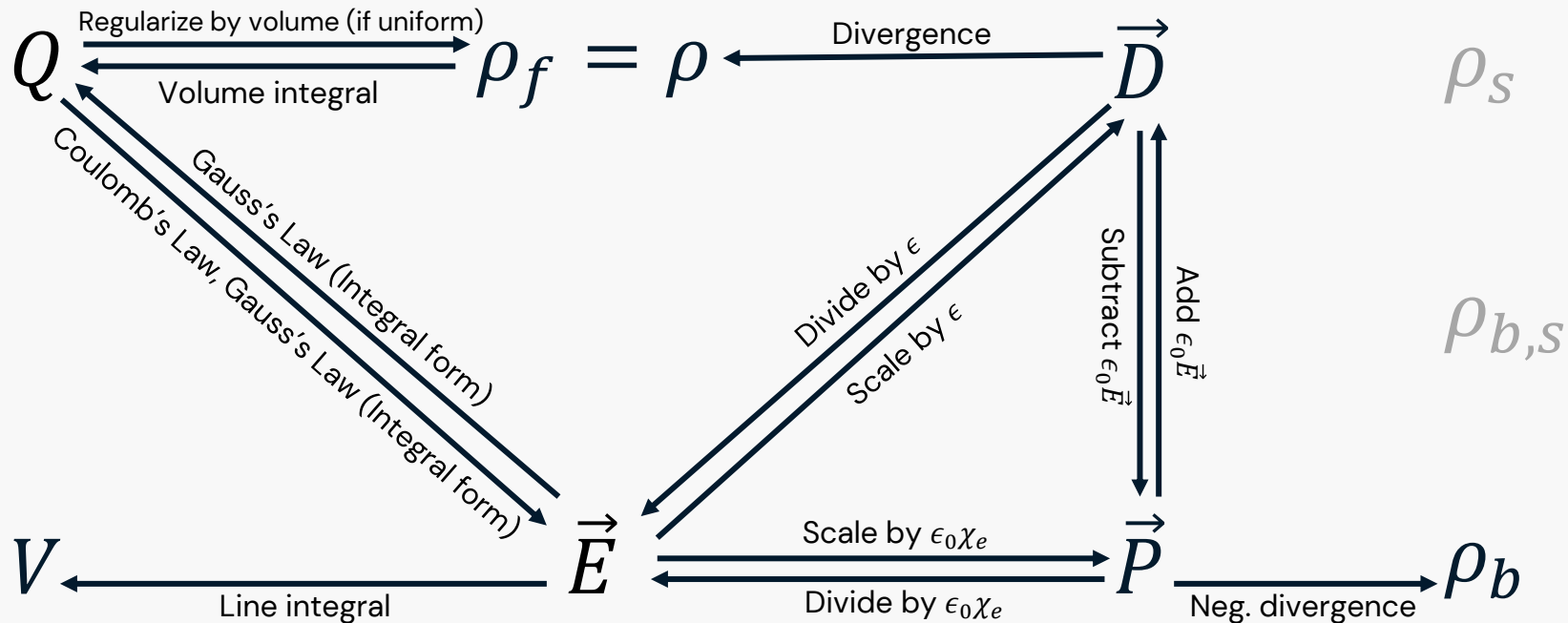
E to V

$$V_{ab} = V(b) - V(a) = - \int_a^b \vec{E} \cdot d\vec{l}$$

$$E = -\nabla V$$

$$+ \begin{array}{c} E \\ \longrightarrow \end{array} \quad - \begin{array}{c} \nabla V \\ \longleftarrow \end{array}$$

All* the concepts



Poisson's Equation

$$\nabla^2 V = -\frac{\rho}{\epsilon}$$

Laplace's Equation

$$\nabla^2 V = 0$$

$$\nabla \cdot \vec{D} = \rho_f$$

$$\nabla \cdot \epsilon \vec{E} = \rho_f$$

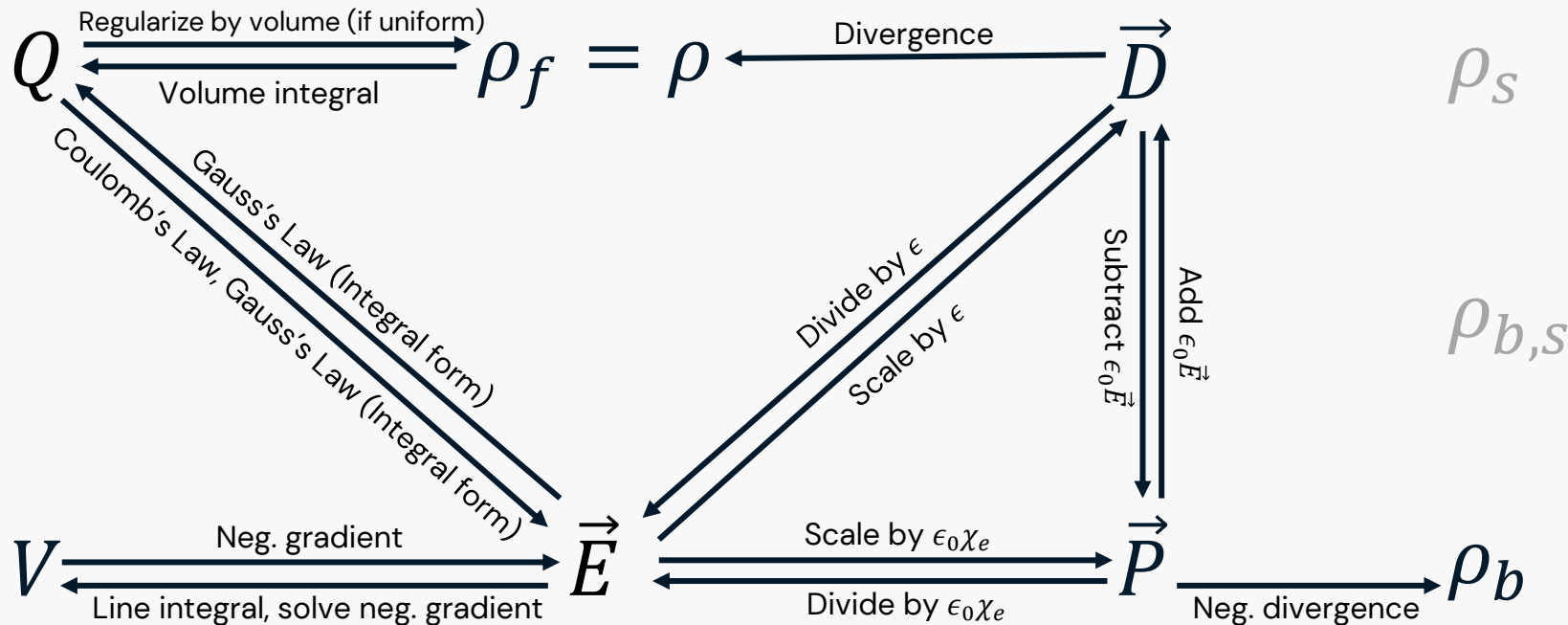
$$\nabla^2 (\epsilon \vec{E}) = \rho_f \quad \text{if } \rho_f = 0$$

$$\nabla^2 (\epsilon \vec{E}) = 0$$

$$\epsilon = \text{const}$$

$$\nabla^2 V = 0$$

All* the concepts



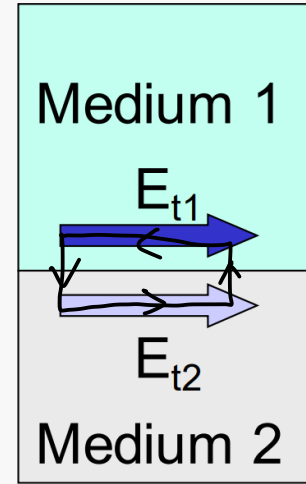
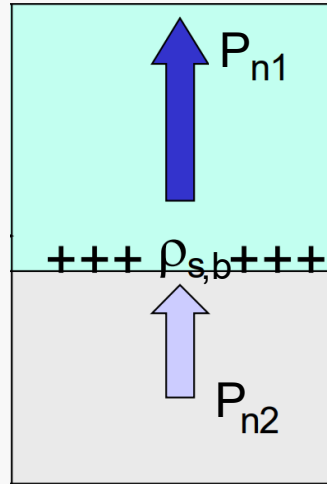
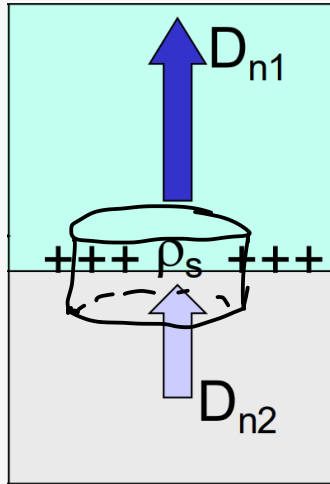
Boundary Conditions

$$\nabla \cdot \vec{D} = \rho_s$$

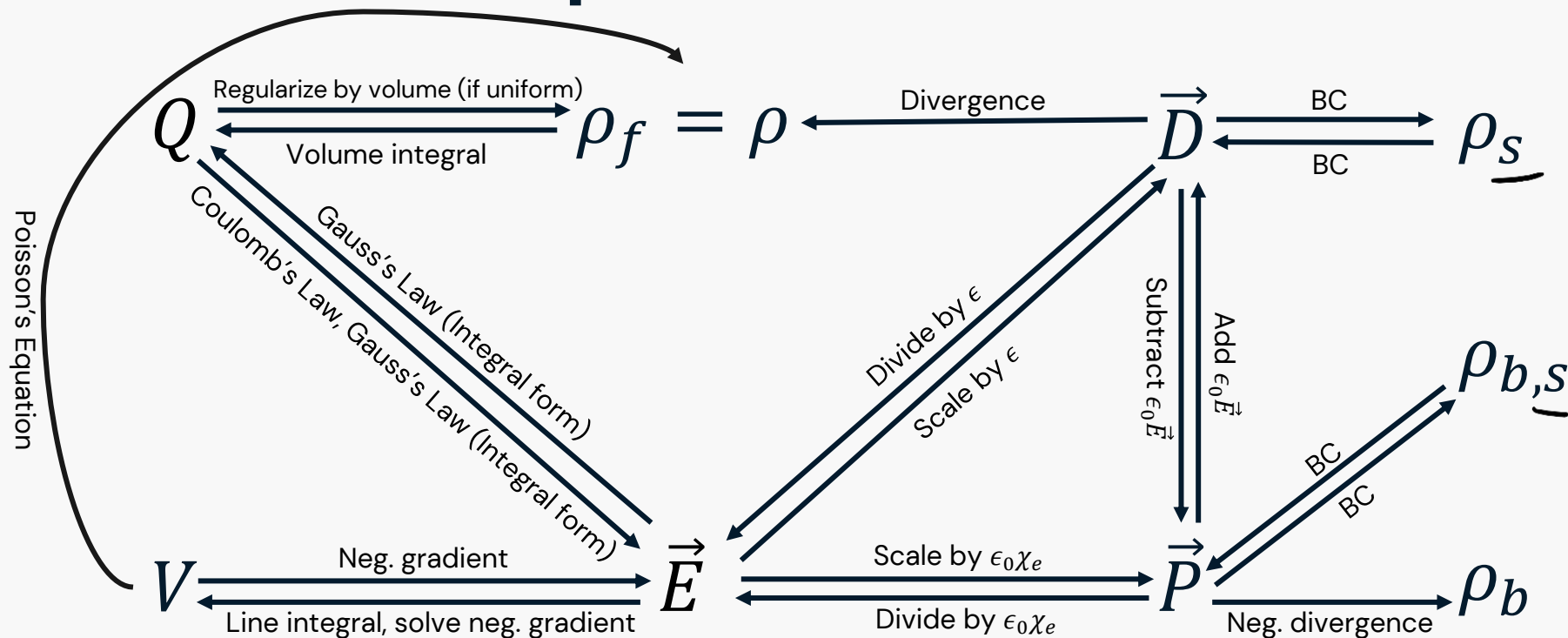
$$\nabla \cdot \vec{P} = -\rho_{b,s}$$

$$\nabla \times \vec{E} = 0$$

$$\hat{n} \cdot (\vec{D}_1 - \vec{D}_2) = \rho_s \quad \hat{n} \cdot (\vec{P}_1 - \vec{P}_2) = -\rho_{b,s} \quad \hat{n} \times (\vec{E}_1 - \vec{E}_2) = 0$$



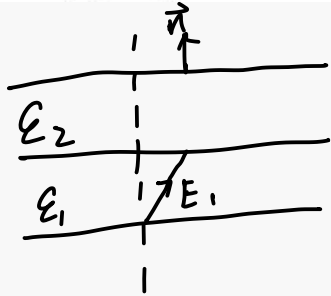
All* the concepts



6. Two dielectric media with permittivities $\epsilon_1 = \epsilon_0$ and $\epsilon_2 = 4\epsilon_0$ are separated by a charge free boundary. The electric field in medium 1 has magnitude of $10 \frac{\text{V}}{\text{m}}$ at an angle 30° degrees from the normal.

- Find the magnitude and direction of the electric field in medium 2.
- Suppose the electric field in medium 1 is the same, but the electric field in medium 2 is now $10 \frac{\text{V}}{\text{m}}$. Find the surface charge on the boundary.
- Suppose the boundary is charge-free and medium 2 is now a slab of finite thickness with medium 3 ($\epsilon_3 = \epsilon_0$) on the other side. What is the angle from normal of the electric field in medium 3?

HW3



$$a) E_{1n} = E_1 \cos 30^\circ = 5\sqrt{3} \text{ V/m}$$

$$E_{1t} = 5 \text{ V/m}$$

$$E_{2t} = E_{1t}, \quad E_{2n} = \frac{\epsilon_1}{\epsilon_2} E_{1n} = \frac{5\sqrt{3}}{4} \text{ V}$$

$$(b) E_{2t} = E_{1t} = 5 \text{ V/m}, \quad E_{2n} = \sqrt{E_2^2 - E_{2t}^2}$$

$$P_s = \epsilon_2 E_{2n} - \epsilon_1 E_{1n}$$

$$(c) 30^\circ \text{ deg}, 10 \frac{\text{V}}{\text{m}}$$

Capacitance

Capacitance: the ability of something to collect and store energy in the form of electrical charge.

This energy is stored as opposite electric charges being held apart (and thus creating a difference in electric potential, aka a voltage drop).

$$J = \sigma E$$

$[A] \quad [V/m]$

$$[F] \\ Q = CV$$

$$G = \frac{\sigma}{\epsilon} C$$

$[Si]$
 $= [A/V]$

$$[S] \\ R = \frac{1}{G}$$

3. Two parts of the following question are independent:

a) (15 pts) Consider the following *spherically* symmetric configuration of composite materials in steady-state equilibrium:

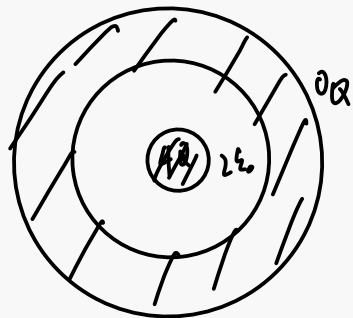
- The region defined by $r \leq 1$ m, where $r = \sqrt{x^2 + y^2 + z^2}$ is the radial distance from the center of the spherical configuration, has $\epsilon = \epsilon_0$, $\sigma = 10^6$ S/m, and holds a net charge of $Q = +4$ C distributed uniformly over its spherical surface.
- A perfect dielectric shell with $\epsilon = 2\epsilon_0$ occupies the region $1 < r < 2$ m.
- Region $2 \leq r \leq 3$ m has the same material properties as region $r \leq 1$ m and holds zero net charge.
- Region $r > 3$ m is occupied by free space. In all four regions we have $\mu = \mu_0$.

Determine, in all four regions, (a) \mathbf{D} , (b) \mathbf{E} and (c) \mathbf{P} , and (d) the surface charge densities, in C/m² units, at each of the three material boundaries at $r = 1, 2$, and 3 m. **Hint:** Make use of Gauss's law in integral form, $\oint_S \mathbf{D} \cdot d\mathbf{S} = \int_V \rho dV$, with $\mathbf{D} = \epsilon \mathbf{E} = \epsilon_0 \mathbf{E} + \mathbf{P}$, and a crucial fact about steady-state fields within conducting materials.

Summer 18

$$\mathbf{E} = \frac{\mathbf{D}}{\epsilon}$$

$$\mathbf{P} = \mathbf{D} - \epsilon_0 \mathbf{E}$$



$$r < 1$$

$$\mathbf{D} \left[\frac{\text{C}}{\text{m}^2} \right] \quad 0$$

$$\mathbf{E} \left[\frac{\text{V}}{\text{m}} \right] \quad 0$$

$$\mathbf{P} \left[\frac{\text{C}}{\text{m}^2} \right] \quad 0$$

$$1 < r < 2$$

$$\frac{1}{\pi r^2} \hat{r}$$

$$\frac{1}{2\epsilon_0 \pi r^2} \hat{r}$$

$$\frac{1}{2\pi r^2} \hat{r}$$

$$2 < r < 3$$

$$0$$

$$0$$

$$0$$

$$r > 3$$

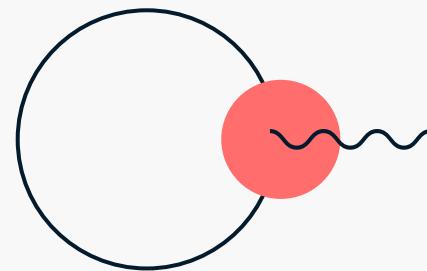
$$\frac{1}{\pi r^2} \hat{r}$$

$$\frac{1}{\epsilon_0 \pi r^2} \hat{r}$$

$$0$$

$$\rho = \frac{1}{\pi}, \quad -\frac{1}{4\pi}, \quad \frac{1}{9\pi}$$

3. Some random stuff



P.S.: Maxwell's Equations

Maxwell collected these equations.
Don't worry about where it came from.

$$\nabla \cdot \vec{D} = \rho \quad \text{Gauss's Law (electric)}$$

$$\nabla \cdot \vec{B} = 0 \quad [T] \quad \left[\frac{W_b}{m^2} \right] \text{Gauss's Law (magnetic)}$$

$$\nabla \times \vec{E} = -\frac{\partial \vec{B}}{\partial t} \quad \text{Faraday's Law}$$

$$\nabla \times \vec{H} = \vec{J} + \frac{\partial \vec{D}}{\partial t} \quad \text{Ampere's Law (with Maxwell's correction)}$$

$$\vec{B} = \mu \vec{H}$$




P.S.: Lorentz Force

Currents create magnetic fields for some reason.

Magnetic fields also exert force on moving charges for some reason.

So, here's an equation to describe that.

Lorentz Force equation

$$\vec{F} = q_1 \vec{E} + q_1 (\vec{v}_1 \times \vec{B})$$


P.S. Current Density

Current: movement of charge, denoted I [Amps] = [Coulomb/second].

Charge flux: movement of charge through a surface.

Current density: Denoted \vec{J} [Amps/meter²]. Integrating current density over a surface yields charge flux!

$$\epsilon_0 \oint \vec{E} \cdot d\vec{S} = Q_{\text{enclosed}}$$

$$I = \oint \vec{J} \cdot d\vec{S} = - \frac{\partial Q_{\text{enclosed}}}{\partial t}$$

P.S. Current Flux

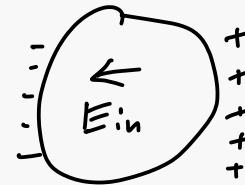
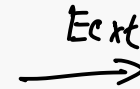
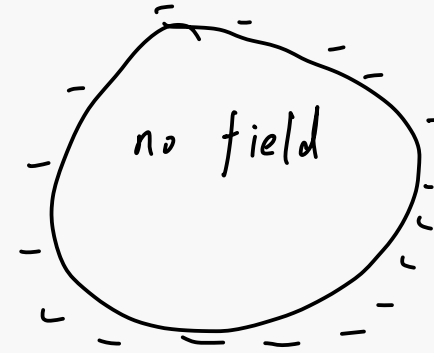
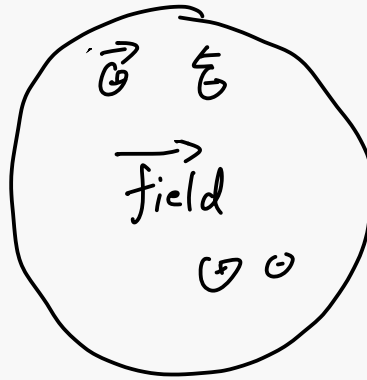
$$\oiint \vec{D} \cdot d\vec{S} = \iiint \rho dV$$

$$\oiint \vec{J} \cdot d\vec{S} = -\frac{\partial}{\partial t} \iiint \rho dV$$

$$\nabla \cdot \vec{J} = -\frac{\partial \rho}{\partial t}$$

charge conservation

P.S. Conductors: The intuition



$$E_{tot} = 0.$$




P.S. Conductors: The math

Described by σ , aka conductivity (units: Siemens/meter)

What to know:

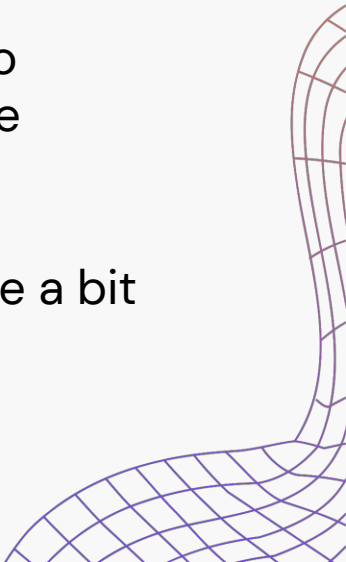
- $\vec{J} = \sigma \vec{E}$ (Ohm's Law)

Assumption: We are dealing with electrostatics, i.e. steady-state.

- If $\sigma \neq 0$, material has zero internal fields and finite surface charge densities.
- 



Exam 1 Prep

- Make your own 4"x6" notecard. Do not blindly copy other people's notecards. Make sure you understand what you are writing on your notecard.
 - Review HWs 1-4.
 - Do the tutorial problems and review the solutions. These also contain rubrics, which will be similar to how your exam will be graded.
 - Do the practice exams on course website.
 - Read over Professor Kudeki's notes if you have time. They are a bit dense.
- 

Exam 1 equations, in one place

$$\vec{F} = \frac{q_1 q_2}{4\pi\epsilon_0 r^2} \hat{r}$$

$$\vec{F} = q_1 \vec{E} + q_1 (\vec{v}_1 \times \vec{B})$$

$$\vec{E} = \frac{q_2}{4\pi\epsilon_0 r^2} \hat{r}$$

$$\hat{n} \cdot (\vec{D}_1 - \vec{D}_2) = \rho_s$$

$$\hat{n} \times (\vec{E}_1 - \vec{E}_2) = 0$$

$$\hat{n} \cdot (\vec{P}_1 - \vec{P}_2) = -\rho_{b,s}$$

$$Q = CV$$

$$G = \frac{\sigma}{\epsilon} C \quad R = \frac{1}{G}$$

$$\epsilon \oint \vec{E} \cdot d\vec{S} = Q_{\text{enclosed}}$$

$$\oint \vec{D} \cdot d\vec{S} = Q_{\text{enclosed}}$$

$$\iiint \rho dV = Q_{\text{enclosed}}$$

$$\oint \vec{B} \cdot d\vec{S} = 0$$

$$I = \oint \vec{J} \cdot d\vec{S} = -\frac{\partial Q_{\text{enclosed}}}{\partial t}$$

$$\epsilon = \epsilon_0(1 + \chi_e)$$

$$\vec{P} = \epsilon_0 \chi_e \vec{E}$$

$$\vec{D} = \epsilon_0 \vec{E} + \vec{P} = \epsilon \vec{E}$$

$$\vec{J} = \sigma \vec{E}$$

$$\rho_b = -\nabla \cdot \vec{P}$$

$$\nabla \cdot \epsilon_0 \vec{E} = \rho_f + \rho_b$$

$$\nabla \cdot \vec{D} = \rho$$

$$\nabla \cdot \vec{J} = -\frac{\partial \rho}{\partial t}$$

$$-\nabla^2 V = \frac{\rho}{\epsilon}$$

$$\nabla \cdot \vec{B} = 0$$

$$\nabla \times \vec{E} = 0$$

$$\vec{E} = -\nabla V$$

$$\oint \vec{E} \cdot d\vec{l} = 0$$

$$V_{ab} = V(b) - V(a) = -\int_a^b \vec{E} \cdot d\vec{l}$$

$$\oint \vec{D} \cdot d\vec{S} = \iiint \nabla \cdot \vec{D} dV$$

$$\oint \vec{E} \cdot d\vec{l} = \iint (\nabla \times \vec{E}) \cdot d\vec{S}$$

$$\int_a^b \nabla V \cdot d\vec{l} = V(b) - V(a)$$

$$\nabla \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$$

$$\nabla \times \vec{H} = \vec{J} + \frac{\partial \vec{D}}{\partial t}$$

Units

Charge Q : C

Electric field \vec{E} : N/C or V/m

Displacement field \vec{D} : C/m²

Polarization field \vec{P} : C/m²

Electric potential V : V

Capacitance C : F

Magnetic field \vec{B} : T or Wb/m²

Charge density ρ : C/m³

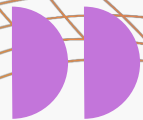
Surface charge density ρ_s : C/m²

Current density \vec{j} : A/m²

Electric permittivity ϵ : F/m

Magnetic permeability μ : H/m

Conductivity σ : Si/m



Good Luck!

Any questions?

