

# Last lecture

## Joint Gaussian Distribution ([Ch 4.11](#))

- Motivation
- Facts
- Examples

# Agenda

## Final Remarks about the course

- Where can I apply probabilities?
- Correlated advanced courses
- Probability mindset

## Final Review I (Pre-midterm2)

- Discrete and continuous Distributions
- Poisson distribution/ process
- Gaussian and  $\Phi / Q$  functions

# **Final Remarks**

# Where can I apply probability?

- ML – VAE, Diffusion, Bayesian DL, RL
  - Law of Large Number is everywhere in data. Noise is inherent
- Communication networks – Queueing, error coding, fading
  - Every bits is a Bernoulli
- Signal Processing – Kalman filter, Wiener filter, spectral analysis
  - Noise is the signal's shadow — learn the shadow, and you master the signal
- Robotics & control – Tracking, SLAM, sensor fusion
  - Model the unknowns – That's reality

# Where can I apply probability?

- Computer Security – Cryptography strength, side channel attacks
  - Security is fundamentally a probability game
- Semiconductor Devices – Reliability & lifetime analysis
  - At microscopic scales, randomness is the rule, not the exception

# What advanced courses are correlated

- ECE 418 — Image & Video Processing
- ECE 420 / 551 — DSP and Advanced DSP
- ECE 438 — Communication Networks
- ECE 434 — Real-World Algorithms for IoT and Data Science
- ECE 448/449/494 — AI/ ML
- ECE 486 / 489 / 515 — Control Systems
- ECE 498/598RR — Deep Generative Models
- ECE 534 — Random Process
- ECE 543 — Statistical Learning Theory
- ECE 561 — Statistical Inference for Engineers and Data Scientists
- And more...

# Probability mindset

- What is the value? → What is the distribution?
  - Always assume a RV, collapse to constant when  $\sigma \approx 0$
- Uncertainty is a chance, not a nuisance
  - Model Gaussian, and focus on None-Gaussian
- What distribution would generate observation  $X$ ?
  - Diffusion, Kalman, Markov model, Likelihood
- When in doubt: model uncertainty explicitly
  - What varies? How does it affect the output

# Closing Messages

- Probability isn't a chapter in the textbook—it's the operating system of the real world.
- If there is one habit to carry forward from ECE 313, let it be: Whenever something looks uncertain, irregular, or 'noisy'—don't guess, don't simplify—model it.
- Great engineers don't eliminate randomness; they understand it, quantify it, and use it.



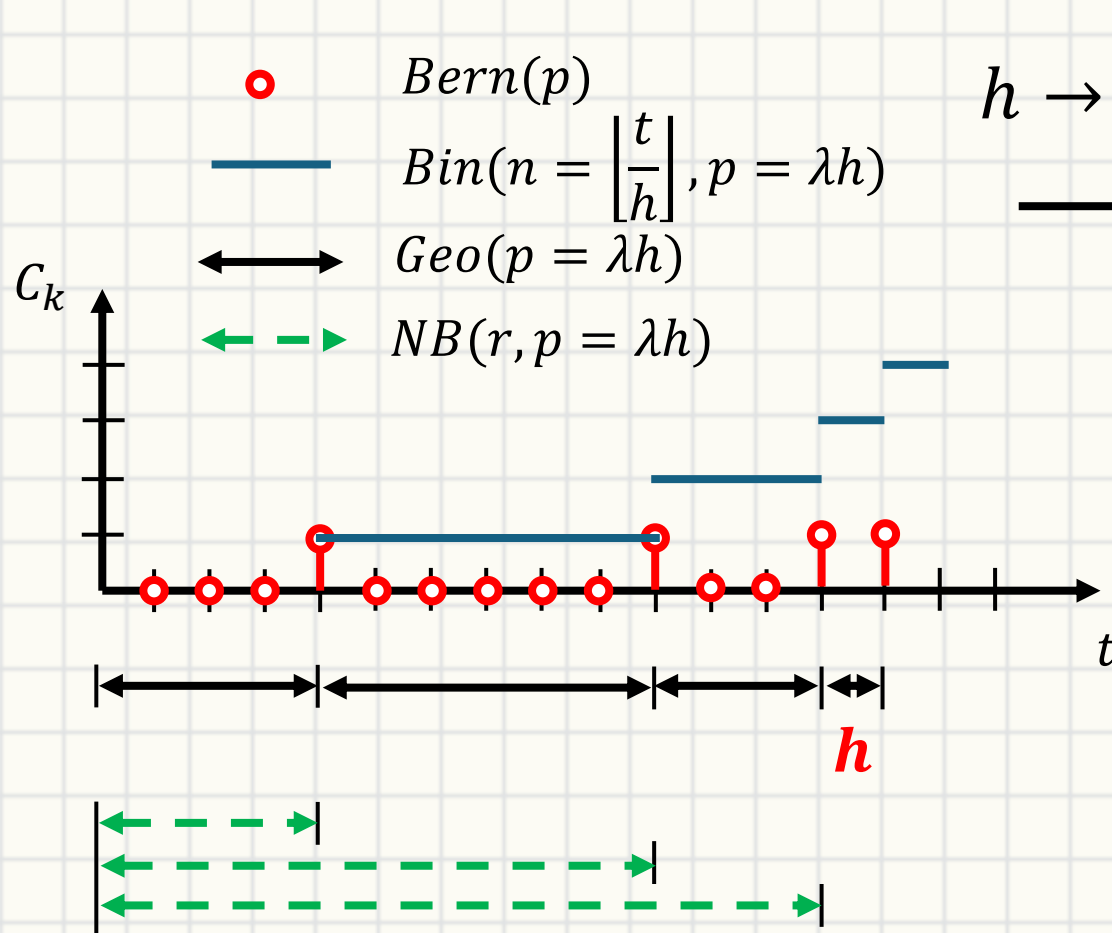
# **Final Review I (Pre-midterm2)**

# Bernoulli Process

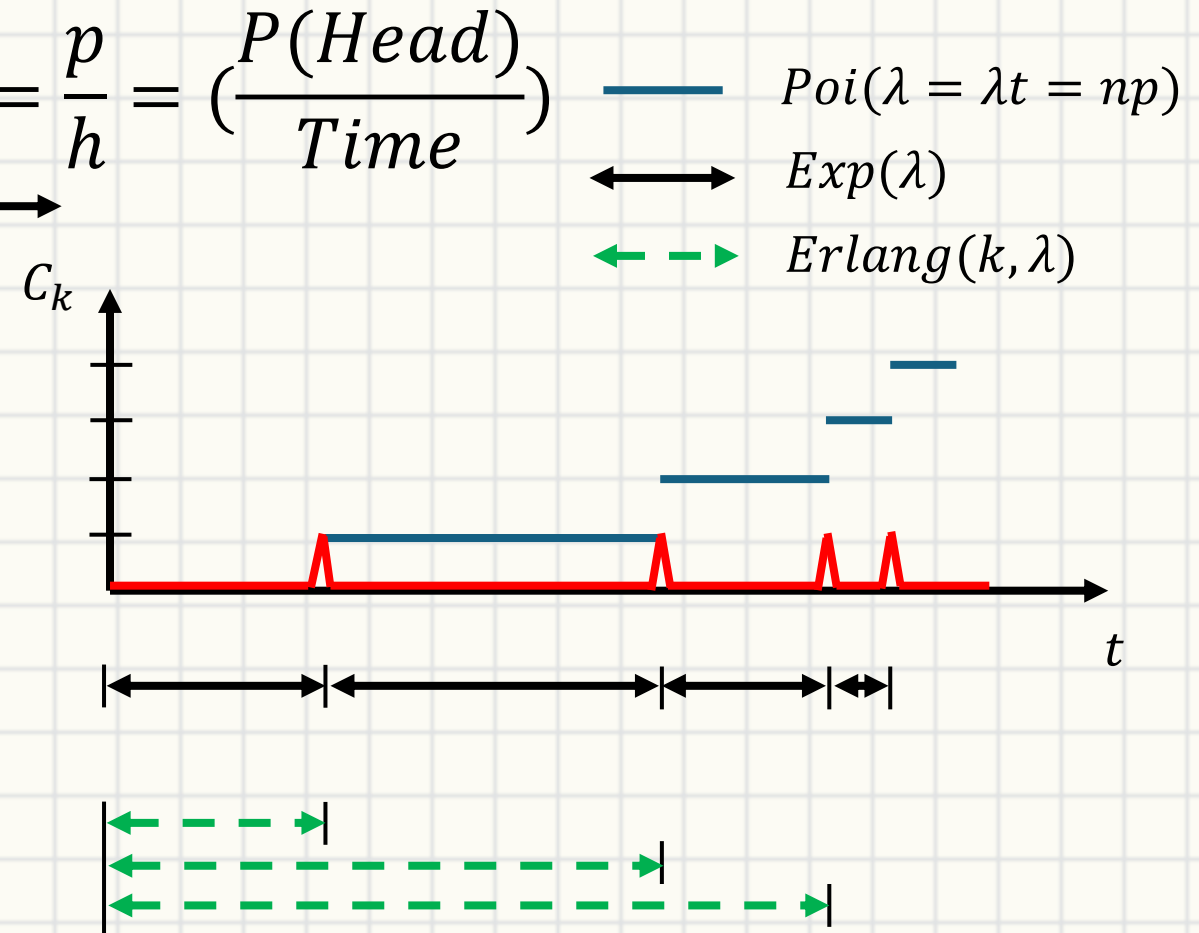
$$h \rightarrow 0, \lambda = \frac{p}{h}$$

# Poisson Process

- Assume each trial takes  $h$  duration to complete



$$h \rightarrow 0, \lambda = \frac{p}{h} = \left( \frac{P(Head)}{Time} \right)$$



# Properties

	$Bern(p)$	$Bin(n, p)$	$Poi(\lambda = np)$	$Geo(p)$	$NB(r, p)$
Def	$X_i$	$\sum_n X_i$	$\sum_n X_i, n \rightarrow \infty$	$Y_i$	$\sum_n Y_i$
$\mu$	$p$	$np$	$\lambda$	$1/p$	$r/p$
$\sigma^2$	$p(1 - p)$	$np(1 - p)$	$\lambda$	$\frac{1 - p}{p^2}$	$\frac{r(1 - p)}{p^2}$
$f_X/p_X(k)$	$p$ or $1 - p$	$\binom{n}{k} p^k (1 - p)^{n-k}$	$\frac{\lambda^k e^{-\lambda}}{k!}$	$(1 - p)^{k-1} p$	$\binom{k-1}{r-1} (1 - p)^{k-r} p^r$
Special		$(p + q)^n$	$Poi(np) \approx Bin(n, p)$	Memoryless	

# Properties

	$Exp(\lambda)$	$Poi(\lambda = \lambda t)$	$Uni[a, b]$	$N(\mu, \sigma^2)$
Def	$T_i$	$\sum_n X_i, n \rightarrow \infty$		
$\mu$	$1/\lambda$	$\lambda$	$\frac{a+b}{2}$	$\mu$
$\sigma^2$	$1/\lambda^2$	$\lambda$	$\frac{(b-a)^2}{12}$	$\sigma^2$
$f_X/p_X(k)$	$\lambda e^{-\lambda t}$	$\frac{\lambda^k e^{-\lambda}}{k!}$	$\frac{1}{b-a}$	$\frac{1}{\sqrt{2\pi}\sigma} \exp(-\frac{(x-\mu)^2}{2\sigma^2})$
Special	Memoryless			$F_N(x) \triangleq \Phi(x)$

# Examples – Poisson Process

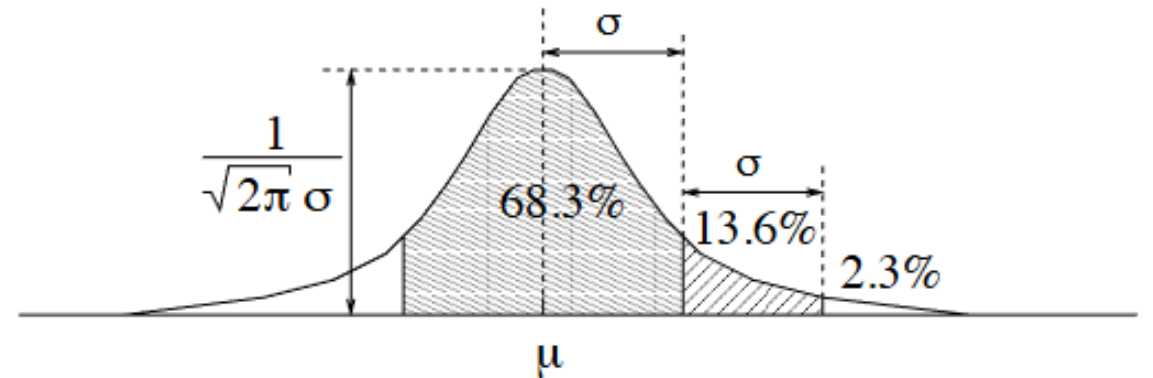
- Let  $N_t$  denotes a Poisson process of rate  $\lambda$
- $P\{N_8 = 5 | N_5 - N_4 = 3\}$
- $P\{N_5 - N_3 = 3 | N_4 - N_2 = 1\}$

# Gaussian – Standard Normal

$$f(x) = \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left(-\frac{(x - \mu)^2}{2\sigma^2}\right)$$

$$Z \sim N(0,1)$$

- $\Phi(u) \triangleq F_Z(u) =$
- $Q(u) = 1 - \Phi(u)$



# Gaussian – General Gaussian

$$f(x) = \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left(-\frac{(x - \mu)^2}{2\sigma^2}\right)$$

$$X \sim N(\mu, \sigma^2)$$

- $F_X(x) =$

# Binary Hypothesis Testing

- Likelihood matrix/ function
  - $f_i(k) = P\{X = k|H_i\}$
  - Likelihood Ratio  $\Lambda(k) = \frac{f_1(k)}{f_0(k)}$
  - ML method -  $f_1(k)$  vs.  $f_0(k)$  or  $\Lambda(k) > 1$ ?
- Joint Probability Matrix  $P(X_i H_i)$ 
  - MAP method -  $\Lambda(k) > \tau_{MAP} = \frac{\pi_0}{\pi_1}$



## Example -

Let  $f_1 \sim N(\mu = 1, \sigma^2 = 2)$  and  $f_0 \sim N(\mu = 0, \sigma^2 = 1)$

- Find ML rule and MAP rule corresponding  $P_{miss}, P_{false\ alarm}$

# Wednesday Review Session

- Joint Probability
- Estimators
- Functions of RV