### **Last lecture**

Independent RV (Ch 4.4)

Examples

Sum of joint RVs (Ch 4.5)

- Motivation
- Discrete RVs & Examples

## **Agenda**

Sum of joint RVs (Ch 4.5)

- Continuous RVs & Examples
- Sum of Gaussians

More examples on joint RVs (Ch 4.6)

- Max of two RVs
- Buffon's needle problems
- Maximum likelihood estimator

### **Sums of Continuous RVs**

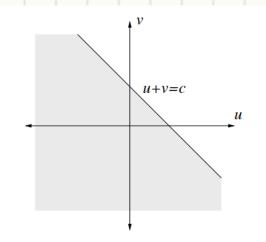
Let 
$$S = X + Y$$

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•  $F_S(c) = P\{S \le c\} =$ 

• 
$$f_S(c) = \frac{dF_S(c)}{dc} =$$

If X and Y are independent

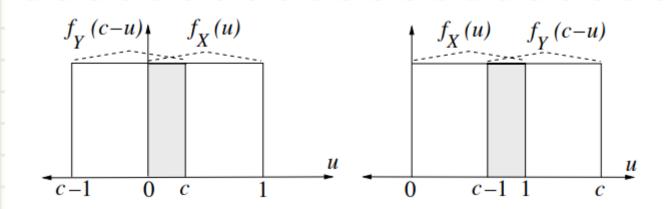
• 
$$f_S(c) =$$



## **Examples**

Suppose *X* and *Y* are independent,  $X, Y \sim Uniform[0, 1]$ . Find the pdf of S = X + Y

- $f_S = f_X * f_Y$
- What is  $f_Y(c-u)$ ?



- If  $0 < c \le 1$ ,  $f_X * f_Y =$
- If  $1 < c \le 2$ ,  $f_X * f_Y =$

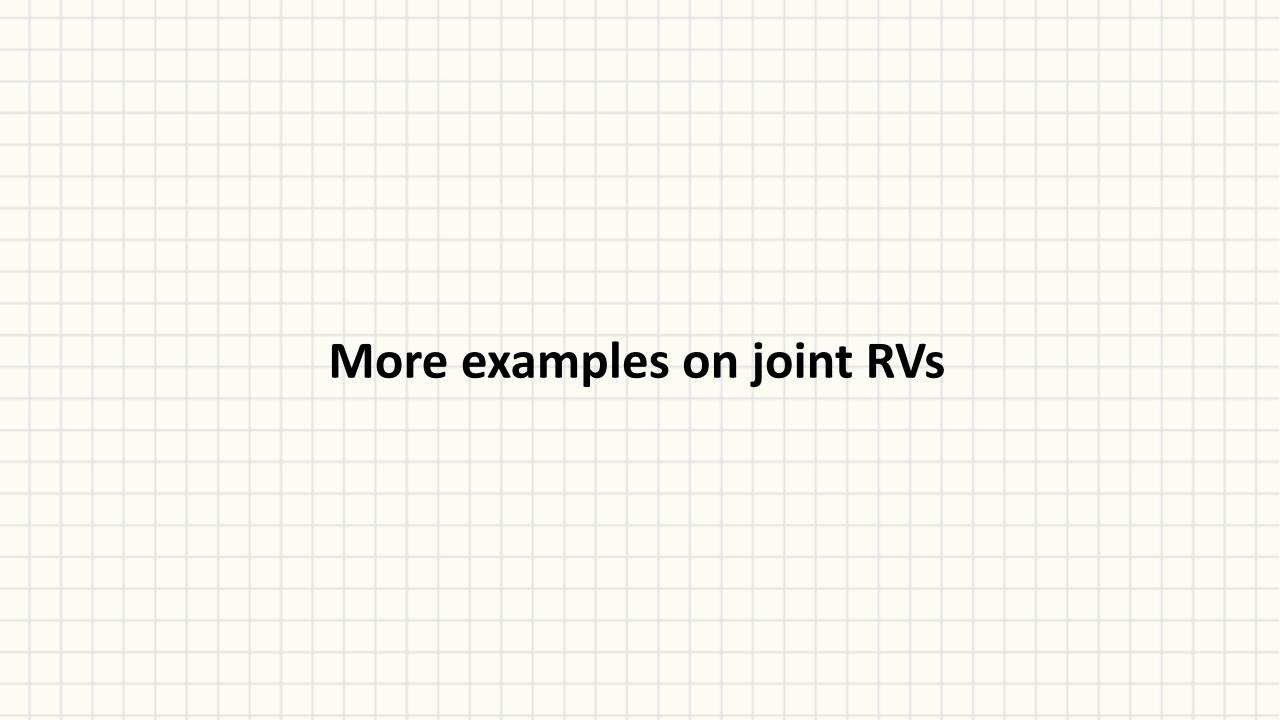
#### **Notes on Gaussian**

Assume  $X \sim N(0, \sigma_1^2)$ ,  $Y \sim N(0, \sigma_1^2)$ 

- Sum of two Gaussian of same mean
  - Mean keeps the same

• 
$$\sigma_S^2 = \sigma_X^2 + \sigma_Y^2$$

- Tedious proof in textbook formula (4.20)
- But high-level idea approximate by Binomials...



#### Max of two RVs

Let 
$$W = \max(X, Y)$$

• 
$$F_W(t) = P\{W \le t\} =$$

• 
$$f_W(t) = \frac{dF_W(t)}{dt} =$$

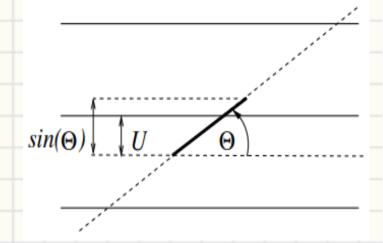
Abstract – on  $P\{W \in (t, t+h]\} = f_W(t)h + o(h)$ 

- Case (a):  $Y \le t, X \in (t, t+h]$
- Case (b):  $X \le t, Y \in (t, t+h]$
- Case (c):  $X \in (t, t + h], Y \in (t, t + h]$

## Buffon's needle problem

- Draw many parallel horizontal lines
  - Space 1 inch between two lines
  - Throw a needle of 1 inch length on the plane
  - Find P{ "The needle intersect with a line" }

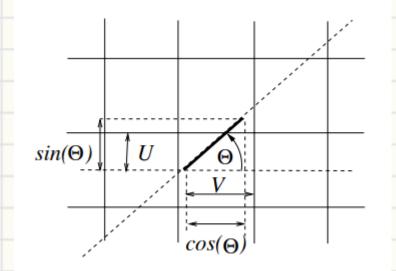
Define U = "distance from the needle lower end to the first line above



# **Buffon's needle problem (2)**

What if there are "horizontal" and "vertical" lines?

Let  $M_h$  denotes "missing horizontal lines"  $M_v$  denotes "missing vertical lines"



### **Maximum Likelihood Estimator**

A drone is accelerating constantly with unknown rate

- At time t, the location is bt
- Measurement  $X_t = bt + W_t$ 
  - $W_t \sim N(0,1)$  is the independent random noise
- Given  $X_{1:T} = u_{1:T}$  as the observation, find  $\hat{b}_{ML}$
- Is  $\hat{b}_{ML}$  unbiased, i.e.,  $\hat{b}_{ML}(\mu_{1:T}) = b$