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Solution:

Z-transform of $x[n]$:

$$X(z) = \sum_{n=1}^{\infty} \left(\frac{1}{2}\right)^n z^{-n} = \sum_{n=1}^{\infty} \left(\frac{1}{2}z^{-1}\right)^n = \frac{\frac{1}{2}z^{-1}}{1 - \frac{1}{2}z^{-1}}, \quad \text{ROC: } |z| > \frac{1}{2}.$$

Z-transform of $h[n]$:

$$H(z) = \sum_{n=-\infty}^{-1} (-2^n)z^{-n}. \text{ Let } m = -n:$$

$$H(z) = -\sum_{m=1}^{\infty} \left(\frac{z}{2}\right)^m = -\frac{\frac{z}{2}}{1 - \frac{z}{2}} = \frac{1}{1 - 2z^{-1}} \quad \text{ROC: } |z| < 2.$$

Now we can compute Z-transform of $y[n]$:

$$Y(z) = H(z)X(z) \tag{1}$$

$$= \frac{\frac{1}{2}z^{-1}}{\left(1 - \frac{1}{2}z^{-1}\right)\left(1 - 2z^{-1}\right)} \quad \text{ROC: } \frac{1}{2} < |z| < 2 \tag{2}$$

$$= \frac{-\frac{1}{3}}{1 - \frac{1}{2}z^{-1}} + \frac{\frac{1}{3}}{1 - 2z^{-1}} \tag{3}$$

The region of convergence (ROC) of $Y(z)$ is $\frac{1}{2} < |z| < 2$ since it must at least contain the intersection of the original ROCs of $X(z)$ and $H(z)$. Now find the inverse Z-transform of individual terms:

- $\frac{1}{1 - \frac{1}{2}z^{-1}}$ corresponds to $\left(\frac{1}{2}\right)^n u[n]$
- $\frac{1}{1 - 2z^{-1}}$ corresponds to $-2^n u[-n - 1]$

Then final answer: $y[n] = -\frac{1}{3} \left(\frac{1}{2}\right)^n u[n] - \frac{1}{3} 2^n u[-n - 1]$

Grading: 20 points

- +5 for correct $H(z)$
- +5 for correct $X(z)$
- +3 for correct $Y(z)$, +2 for correct ROC of $Y(z)$
- +5 for correct $y[n]$

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Solution:

(a) $y[n] = (x[n])^2$.

Stable, because the square of any finite number will also be finite.

$$|x[n]| \leq M_x < \infty \longrightarrow |y[n]| = |x[n]|^2 \leq M_x^2 < \infty$$

(b) $y[n] = n(x[n])$.

Not stable, because as $n \longrightarrow \infty$, $y[n] \longrightarrow \infty$.

(c) $y[n] = (x * u)[n]$.

Not stable, consider the following bounded input which produces an unbounded output:

$$x[n] = 1 \quad \forall n$$

$$y[n] = (x * u)[n] = \sum_{k=-\infty}^{\infty} 1u[n-k] = \sum_{k=-\infty}^n 1 = \infty$$

Another valid solution is to consider the Z-transform of the unit step function $u[n]$, which is $\frac{1}{1-z^{-1}}$. If a system's impulse response was the unit step, we can see from its Z-transform that there is a pole at 1, so the ROC is $|z| > 1$. Since the ROC does not contain the unit circle, the system is **not stable**.

Grading: 20 points

- +6 pts correct part (a)
- +6 pts correct part (b)
- +8 pts correct part (c)

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Solution:

(a)

We are considering the following LCCDE:

$$y[n] = \frac{1}{6}y[n-1] + \frac{1}{6}y[n-2] + 2x[n] + x[n-1]$$

which has Z-transform

$$Y(z) = \frac{1}{6}z^{-1}Y(z) + \frac{1}{6}z^{-2}Y(z) + 2X(z) + z^{-1}X(z)$$

$$Y(z) - \frac{1}{6}z^{-1}Y(z) - \frac{1}{6}z^{-2}Y(z) = 2X(z) + z^{-1}X(z)$$

$$Y(z) \left(1 - \frac{1}{6}z^{-1} - \frac{1}{6}z^{-2} \right) = X(z) (2 + z^{-1})$$

$$\frac{Y(z)}{X(z)} = H(z) = \frac{2 + z^{-1}}{1 - \frac{1}{6}z^{-1} - \frac{1}{6}z^{-2}}$$

$$H(z) = 2 \frac{1 + \frac{1}{2}z^{-1}}{(1 - \frac{1}{2}z^{-1})(1 + \frac{1}{3}z^{-1})}$$

The LCCDE represents a causal system because $y[n]$ only depends on current/past $x[n]$. Therefore the ROC is $|z| > \frac{1}{2}$.

(b)

By inspection of the transfer function $H(z)$:

Zeros: $z = -\frac{1}{2}, 0$

Poles: $z = \frac{1}{2}, -\frac{1}{3}$

(c)

To find $h[n]$, we need to perform partial fraction decomposition on $H(z)$

$$H(z) = 2 \left(\frac{1 + \frac{1}{2}z^{-1}}{(1 - \frac{1}{2}z^{-1})(1 + \frac{1}{3}z^{-1})} \right) = 2 \left(\frac{A}{1 - \frac{1}{2}z^{-1}} + \frac{B}{1 + \frac{1}{3}z^{-1}} \right)$$

$$A = \frac{1 + \frac{1}{2}(\frac{1}{2})^{-1}}{1 + \frac{1}{3}(\frac{1}{2})^{-1}} = \frac{1 + 1}{1 + \frac{2}{3}} = \frac{2}{\frac{5}{3}} = \frac{6}{5}$$

$$B = \frac{1 + \frac{1}{2}(-\frac{1}{3})^{-1}}{1 - \frac{1}{2}(-\frac{1}{3})^{-1}} = \frac{1 - \frac{3}{2}}{1 + \frac{3}{2}} = \frac{-\frac{1}{2}}{\frac{5}{2}} = -\frac{1}{5}$$

$$H(z) = 2 \left(\frac{\frac{6}{5}}{1 - \frac{1}{2}z^{-1}} - \frac{\frac{1}{5}}{1 + \frac{1}{3}z^{-1}} \right)$$

$$h[n] = 2 \left(\frac{6}{5} \left(\frac{1}{2}\right)^n u[n] - \frac{1}{5} \left(-\frac{1}{3}\right)^n u[n] \right)$$

(d)

Stable, because the ROC contains the unit circle.

(e)

To find the output $y[n]$ for the given input, we can take the Z-transform of $x[n]$, multiply by $H(z)$, then inverse Z-transform the result.

$$x[n] = 3\delta[n] + \delta[n - 1]$$

$$X(z) = 3 + z^{-1} = 3\left(1 + \frac{1}{3}z^{-1}\right)$$

$$Y(z) = H(z)X(z) = 2 \left(\frac{1 + \frac{1}{2}z^{-1}}{(1 - \frac{1}{2}z^{-1})(1 + \frac{1}{3}z^{-1})} \right) 3\left(1 + \frac{1}{3}z^{-1}\right)$$

$$Y(z) = 6 \left(\frac{(1 + \frac{1}{2}z^{-1})(1 + \frac{1}{3}z^{-1})}{(1 - \frac{1}{2}z^{-1})(1 + \frac{1}{3}z^{-1})} \right)$$

$$Y(z) = 6 \left(\frac{1 + \frac{1}{2}z^{-1}}{1 - \frac{1}{2}z^{-1}} \right)$$

$$Y(z) = 6 \left(\frac{1}{1 - \frac{1}{2}z^{-1}} + \frac{1}{2}z^{-1} \frac{1}{1 - \frac{1}{2}z^{-1}} \right)$$

$$y[n] = 6 \left(\left(\frac{1}{2}\right)^n u[n] + \frac{1}{2} \left(\frac{1}{2}\right)^{n-1} u[n - 1] \right)$$

$$y[n] = 6\left(\frac{1}{2}\right)^n u[n] + 3\left(\frac{1}{2}\right)^{n-1} u[n - 1]$$

Grading: 20 points

- +4 pts each correct part

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Solution:

Z-transform of $h_1[n]$: $H_1(z) = -z + 2 - z^{-1}$

ROC: $0 < |z| < \infty$ (entire z -plane except possibly 0 and ∞). ROC includes the unit circle, hence $h_1[n]$ system is BIBO stable

Z-transform of $h_2[n]$:

$$\begin{aligned}h_2[n] &= (n + 1)u[n] \\H_2(z) &= \mathcal{Z}\{(n + 1)u[n]\} \\H_2(z) &= \mathcal{Z}\{u[n]\} + \mathcal{Z}\{nu[n]\} \\ \mathcal{Z}\{u[n]\} &= \frac{1}{1 - z^{-1}}, \quad |z| > 1 \\ \mathcal{Z}\{nu[n]\} &= \frac{z^{-1}}{(1 - z^{-1})^2}, \quad |z| > 1 \\ H_2(z) &= \frac{1}{1 - z^{-1}} + \frac{z^{-1}}{(1 - z^{-1})^2} = \frac{1}{(1 - z^{-1})^2}, \quad |z| > 1\end{aligned}$$

ROC does not include the unit circle, hence $h_2[n]$ system is not BIBO stable

Overall system:

$$\begin{aligned}H(z) &= H_1(z)H_2(z) \\H(z) &= (-z + 2 - z^{-1}) \frac{1}{(1 - z^{-1})^2} \\H(z) &= \left(-\frac{(z - 1)^2}{z}\right) \left(\frac{z^2}{(z - 1)^2}\right) \\H(z) &= -z \quad \text{ROC: } 0 \leq |z| < \infty\end{aligned}$$

ROC includes the unit circle, hence overall $h[n]$ system is BIBO stable. even though $h_2[n]$ is unstable, the overall system cancels the pole/zero factors, and leads a stable overall system.

Grading: 20 points

- +6 First system (4 pts for derivation, 2 pts for correct ROC and BIBO stability of the first system)
- +6 Second system (4 pts for derivation, 2 pts for correct ROC and BIBO stability of the first system)
- +8 Overall system (6 pts for derivation, 2 pts for correct ROC and BIBO stability of the first system)

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Solution:

We are considering the following LCCDE

$$y[n] = x[n] + \frac{5}{2}x[n-1] + x[n-2]$$

(a) The impulse response can be derived by plugging in $\delta[n]$ for $x[n]$

$$h[n] = \delta[n] + \frac{5}{2}\delta[n-1] + \delta[n-2]$$

and the transfer function from the Z-transform of $h[n]$

$$H(z) = 1 + \frac{5}{2}z^{-1} + z^{-2}$$

The ROC is $z \neq 0$.

(b) The inverse system to $H(z)$ is given by the following

$$G(z) = \frac{1}{H(z)} = \frac{1}{1 + \frac{5}{2}z^{-1} + z^{-2}}$$

Because we want the *causal* inverse system, we keep everything in terms of *negative* powers of z . The difference equation can then be derived as

$$\begin{aligned}G(z) &= \frac{S(z)}{Y(z)} = \frac{1}{1 + \frac{5}{2}z^{-1} + z^{-2}} \\S(z)(1 + \frac{5}{2}z^{-1} + z^{-2}) &= Y(z) \\S(z) + \frac{5}{2}z^{-1}S(z) + z^{-2}S(z) &= Y(z) \\s[n] + \frac{5}{2}s[n-1] + s[n-2] &= y[n] \\s[n] &= -\frac{5}{2}s[n-1] - s[n-2] + y[n]\end{aligned}$$

(c) From part (a), we saw the ROC of $H(z)$ was $z \neq 0$, which contains the unit circle. Therefore, $H(z)$ is **stable**. For $G(z)$, we need to find the poles.

$$G(z) = \frac{1}{1 + \frac{5}{2}z^{-1} + z^{-2}} = \frac{1}{(1 + \frac{1}{2}z^{-1})(1 + 2z^{-1})}$$

$G(z)$ has poles at $z = -\frac{1}{2}, -2$. Because we chose $G(z)$ to be causal, its ROC is $|z| > 2$. Therefore, $G(z)$ is **not stable**.

(d) After factoring $G(z)$ in part (c), we can easily split it into two terms where $G_1(z) = \frac{1}{1 + \frac{1}{2}z^{-1}}$ and $G_2(z) = \frac{1}{1 + 2z^{-1}}$. The ROC of $G_1(z)$ is $|z| > \frac{1}{2}$, so it is **stable** and causal. For $G_2(z)$ to be stable, we need to implement it as an anti-causal system, so its ROC becomes $|z| < 2$.

For the difference equations, let $Y(z)$ represent the input to system $G_1(z)$, let $W(z)$ represent the output

of system $G_1(z)$ which is also the input to $G_2(z)$, and let $S(z)$ represent the output of system $G_2(z)$.

$$G_1(z) = \frac{W(z)}{Y(z)} = \frac{1}{1 + \frac{1}{2}z^{-1}}$$

$$W(z)(1 + \frac{1}{2}z^{-1}) = Y(z)$$

$$W(z) + \frac{1}{2}z^{-1}W(z) = Y(z)$$

$$w[n] + \frac{1}{2}w[n-1] = y[n]$$

$$w[n] = -\frac{1}{2}w[n-1] + y[n]$$

$$G_2(z) = \frac{S(z)}{W(z)} = \frac{1}{1 + 2z^{-1}} = \frac{z}{z + 2}$$

$$S(z)(z + 2) = zW(z)$$

$$zS(z) + 2S(z) = zW(z)$$

$$s[n+1] + 2s[n] = w[n+1]$$

$$s[n] = \frac{w[n+1] - s[n+1]}{2}$$

Grading: 20 points

- +5 pts for each correct part