# ECE 220 <br> Lecture x0002-01/18 TRAPs \& Subroutines 

## Recap from "01/16"

- Consider "echo" routine:

| DPOLL | LDI | R1, DSR |
| :--- | :--- | :--- |
|  | BRzp | DPOLL |
|  | STI | R0, DDR |


|  | BRnzp | NEXT_TASK |
| :--- | :--- | :--- |
| KBSR | .FILL | xFE00 |
| KBDR | .FILL | xFE02 |
| DSR | .FILL | xFE04 |
| DSR | .FILL | xFE06 |

- Reading \& writing from keyboard or display is common task
- Inefficient to keep repeating this code
- Need to free up R1 and R0 for use whenever blocks run
- Save/restore current values before/after these blocks run


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- Reading \& writing from keyboard or display is common task
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## Repeating code

- Consider $f(x)=x^{4}+4 x^{3}+3 x^{2}+2 x+1$
- Evaluate $f(2)$
- How many multiplications?


## Repeating code

- Consider $f(x)=x^{4}+4 x^{3}+3 x^{2}+2 x+1$
- Evaluate $f(2)$
- How many multiplications?
- Suppose we wish to evaluate $f(x)$ for many values of $x$
- Why? E.g. Newton-Raphson method for finding roots of $f(x)$


## Aside: NR method

Suppose $f(x)$ such that $x, f(x) \in \mathbb{R}$ and $f^{\prime}(x)$ is well defined. Let $x_{0}$ be an initial guess for some root $\bar{x}$ of $f(x)$. Then the terates $x_{n}$

$$
x_{1}=x_{0}-\frac{f(x)}{f^{\prime}\left(x_{0}\right)} \text { and } x_{n+1}=x_{n}-\frac{f\left(x_{n}\right)}{f^{\prime}\left(x_{n}\right)}
$$

successively improve on the guess $x_{0}$ as an approximation to $\bar{x}$ (roughly doubling the number of correct digits at each step).

## Aside: Calculating $\sin (x)$

- Can you think of another instance where evaluating polynomials shows up?
- Hint: Some power series from Calc 1 or 2
- It is one way most calculators can compute trigonometric values?

> Most don't use the power series expansions but other more efficient methods (e.g. lookup + interpolation, CORDIC, etc.)

- Example:

$$
\sin (x) \approx x-\frac{x^{3}}{3!}+\frac{x^{5}}{5!}-\frac{x^{7}}{7!}+\ldots
$$

## Subroutines

- Subroutines are blocks/pieces of code that do something specific. Examples:
- Multiply two numbers
- Sort a list of integers
- Reads keyboard press into a register
- Often called functions, methods, procedures, service calls, etc.
- Different from functions in mathematics or functional programming languages


## Functions vs. subroutines

- In mathematics, a function $f(x)$ takes a value from a set and returns a value in a(nother) set. If you call $f$ with some particular value $x_{0}$ then it always returns $f\left(x_{0}\right)$.
- In CS/programming, a function foo is a piece of code that can be called, perhaps with inputs, and does some stuff and maybe returns something.
- In functional languages (in theory at least), you can replace a function call with its return value and nothing should break.


## Subroutines

- User invokes or calls subroutine
- Subroutine code performs operation / task
- Returns control to user program with no other unexpected changes

| $X$ |
| :---: |
| $A$ |
| $Y$ |
| $A$ |
| $Z$ |
| $A$ |
| $W$ |

(a) Without subroutines

(b) With subroutines

Figure 8.2 - P\&P 3rd Ed.

## Subroutines in LC3

- Recall instructions that change program flow
- Subroutines make use of the $\operatorname{JSR}(R)$ and RET commands.


| RET | 1100 | 000 | 111 | 000 | 0000 |  |
| :--- | :--- | :---: | :---: | :---: | :---: | :---: |
| RTI | 1000 |  | 1 | 0000000 |  |  |

- Exercise: What is/are the difference(s) between BR/JMP and JSR/JSRR?

TRAP
1111
0000
trapvect8

Figure "A.2" - P\&P 3rd Ed.

## JSR \& JSRR

- When $\operatorname{JSR}(R)$ is encountered $R 7$ is loaded with $\mathrm{PC}^{+}$and then PC is set in one of two ways:
- JSR and JSRR differ in addressing modes (signified by bit \#11).
- PC $\leftarrow \mathrm{PC}+\mathrm{SEXT}($ PCoffset11)
- PC $\leftarrow$ BaseR
- After subroutine ends, RET is used to return to caller


Appendix A, P\&P 3rd Ed.

## RET \& JMP

- JMP \& RET are relatives; opcode is the same
- JMP: PC $\leftarrow$ BaseR
- RET: PC $\leftarrow \mathrm{R7}$
- Note: JSR (R) \& RET rely on R7 to provide return-linkage.
- What if R7 was being used?

JMP
RET

Return from Subroutine

Assembler Formats
JMP BaseR
RET
Encoding


## Using subroutines

Saving \& restoring registers

- To use a subroutine the user must know:
- It's address (or label)
- It's arguments (where to pass in data, if any)
- It's return values (where to get computed data, if any)
- What it does
- Maybe not all the gory details but definitely registers it may use or overwrite!


## Using subroutines

Saving \& restoring registers
Generally we have two strategies depending on who saves/restores registers:

- Caller-saved: Onus on user to save/restore registers that will be needed later; may not know what registers subroutine will use
- User saves/restore registers they will need (or know could get destroyed)
- Callee-saved: Subroutine knows registers it will alter/use, but cannot know what the user will need later
- Subroutine saves/restores registers it will use


# Using subroutines 

Saving \& restoring registers

Good practices:

- Keep R7 unused, especially for nested subroutines
- Use callee-save, except for return values (should be caller saved)
- Restore incoming arguments to their original values unless intended to be overwritten by return value


## Example

Multiplication
; LC3 subroutine to multiply two numbers
; Inputs: R0 (multiplicand), R1 (multiplier)
; Output: R2 (result)

MULTIPLY:
ST R0, MulSaveR0 ; Callee save registers

missing piece.<br>Try to complete MULTIPLY subroutine by filling in the

ST R1, MulSaveR1
AND R2, R2, \#0
ADD R2, R0, \#0
ADD R1, R1, \#-1
MUL_LOOP:

## MUL_DONE:

LD R0, MulSaveR0 ; Restore registers
LD R1, MulSaveR1
RET ; Return from the subroutine

## Example

Multiplication
Try to complete MULTIPLY subroutine by filling in the missing piece.
; LC3 subroutine to multiply two numbers

```
; Inputs: R0 (multiplicand), R1 (multiplier)
```

; Output: R2 (result)
MULTIPLY:
ST R0, MulSaveR0
ST R1, MulSaveR1
AND R2, R2, \#0 ; Clear R2 to be used as result
ADD R2, R0, \#0 ; Load multiplicand into R2
ADD R1, R1, \#-1 ; Use R1 as counter
MUL_LOOP:
BRz MUL_DONE ; If R1 == 0, multiplication done
ADD R2, R0, R2
ADD R1, R1, \#-1 ; Decrement the counter in R1
BR MUL_LOOP ; Jump back to MUL_LOOP
MUL_DONE:
LD R0, MulSaveR0 ; Restore registers
LD R1, MulSaveR1
RET ; Return from the subroutine

## Exercise

## Exponentiation

Use the
MULTIPLY
subroutine in the previous slide to write an LC3
subroutine that performs exponentiation.
; LC3 subroutine to that performs exponentiation
; Inputs: R0 (base), R1 (exponent)
; Loop counter: R2
; Output: R2 (result)
; POW knows it should call MULTIPLY and it knows
; MULTIPLY overwrites the value in R2
POW :

```
POW_LOOP:
    BRz POW_DONE ; If R2==0, loop complete
    ST R2, PowSaveR2 ; Caller save
    JSR MULTIPLY ; Result in R2
    ADD R1, R2, #0 ; Copy result for next multiply
    LD R2, PowSaveR2 ; Caller restore
    ADD R2, R2, #-1 ; Decrement counter
    BR POW_LOOP
```

POW_DONE:

## Exercise

## Exponentiation

## Use the

MULTIPLY subroutine in the previous slide to write an LC3
subroutine that performs exponentiation.

```
; LC3 subroutine to that performs exponentiation
; Inputs: R0 (base), R1 (exponent)
; Loop counter: R2
; Output: R2 (result)
; POW knows it should call MULTIPLY and it knows
; MULTIPLY overwrites the value in R2
POW:
    ST R0, PowSaveR0 ; Callee save registers
    ST R1, PowSaveR1
    ADD R2, R1, #-1 ; Initialize counter
    ; Why can't we use R1 as counter?
    ADD R1, R0, #0 ; Set up to call MULTIPLY
POW_LOOP:
    BRz POW_DONE ; If R2==0, loop complete
    ST R2, PowSaveR2 ; Caller save
    JSR MULTIPLY ; Result in R2
    ADD R1, R2, #0 ; Copy result for JSR to multiply
    LD R2, PowSaveR2 ; Caller restore
    ADD R2, R2, #-1 ; Decrement counter
    BR POW_LOOP
POW_DONE:
    ADD R2, R1, #0 ; Move result to R2
    LD R0, PowSaveR0 ; Callee restore
    LD R1, PowSaveR1
    RET
```


## Exercise

## Exponentiation

## Use the

MULTIPLY subroutine in the previous slide to write an LC3
subroutine that performs exponentiation.

## Will this program halt?

Why? Why not?

```
; LC3 subroutine to that performs exponentiation
; Inputs: R0 (base), R1 (exponent)
; Output: R2 (result)
; POW knows it should call MULTIPLY and it knows
; MULTIPLY overwrites the value in R2
```

POW:
ST R0, PowSaveR0 ; Callee save registers
ST R1, PowSaveR1
ADD R2, R1, \#-1 ; Initialize counter
; Why can't we use R1 as counter?
ADD R1, R0, \#0 ; Set up to call MULTIPLY
POW_LOOP:
BRz POW_DONE ; If R2==0, loop complete
ST R2, PowSaveR2 ; Caller save
JSR MULTIPLY ; Result in R2
ADD R1, R2, \#0 ; Copy result for JSR to multiply
LD R2, PowSaveR2 ; Caller restore
ADD R2, R2, \#-1 ; Decrement counter
BR POW_LOOP
POW_DONE:
ADD R2, R1, \#0 ; Move result to R2
LD R0, PowSaveR0 ; Callee restore
LD R1, PowSaveR1
RET

```
Exercise
```


## Exponentiation

C3 subroutine to that performs exponentiation
; Inputs: R0 (base), R1 (exponent)
; Output: R2 (result)
; POW knows it should call MULTIPLY and it knows
; MULTIPLY overwrites the value in R2

```
```

; LC3 subroutine to that performs exponentiation

```
```

; LC3 subroutine to that performs exponentiation

```

\section*{Exercise}

Use the
MULTIPLY subroutine in the previous slide to write an LC3 subroutine that performs exponentiation.

Nested subroutines better save R7!

POW:
```

    ST R0, PowSaveR0 ; Callee save registers
    ST R1, PowSaveR1
    ADD R2, R1, #-1 ; Initialize counter
    ; Why can't we use R1 as counter?
    ADD R1, R0, #0 ; Set up to call MULTIPLY
    POW_LOOP:
BRz POW_DONE ; If R2==0, loop complete
ST R2, PowSaveR2 ; Caller save
JSR MULTIPLY ; Result in R2
ADD R1, R2, \#0 ; Copy result for JSR to multiply
LD R2, PowSaveR2 ; Caller restore
ADD R2, R2, \#-1 ; Decrement counter
BR POW_LOOP

```
POW_DONE:
    ADD R2, R1, \#0 ; Move result to R2
    LD R0, PowSaveR0 ; Callee restore
    LD R1, PowSaveR1
    RET

\section*{User routine vs. service routine}
- Consider keyboard input:
- It's used often and has too many specific details for most programmers
- Improper usage could breach security of the system or mess up keyboard usage for other users/programs
- Solution: make this part of the OS
- User program \(\rightarrow\) invokes service routine (a.k.a OS call) \(\rightarrow\) OS performs operation \(\rightarrow\) returns control to user program

\section*{TRAP mechanism}

System calls in LC3 are achieved using the TRAP mechanism

TRAP
Assembler Format
TRAP trapvector8
Encoding


System Space
(Privileged Menory)
\begin{tabular}{|c|c|}
\hline x0000 & \(:\) \\
\hline \(\times 0020\) & X03E0 \\
\hline \(\times 0021\) & \(\times 0420\) \\
\hline \(\times 0022\) & \(\times 0460\) \\
\hline \(\times 0023\) & x04AO \\
\hline \(\times 0024\) & x04E0 \\
\hline \(\times 0025\) & \(\times 0520\) \\
\hline xOOFF & \(:\) \\
\hline
\end{tabular}

Figure A. 1 - P\&P 3rd Ed.

\section*{TRAP mechanism}

Table A. 3 of P\&P 3rd Ed.
\begin{tabular}{|ccc|}
\hline Vector & Symbol & Routine \\
\hline x20 & GETC & Read a single character (no echo) \\
\hline x21 & OUT & Output character to monitor \\
x22 & PUTS & Write a string to monitor \\
\hline x23 & IN & Print prompt to monitor, read and echo character from keyboard \\
\hline x24 & PUTSP & Write a string to monitor, two characters per memory location \\
x25 & HALT & Halt program \\
\hline x26 & & Write a number to monitor (undocumented) \\
\hline
\end{tabular}

Exercise: Try using each of these!

\section*{TRAP: Flow Control}
- Slight difference between editions of the textbook
- Edition 2: Last statement in TRAP is JMP R7 (i.e. RET)
- Edition 3: Last statement is RTI


Figure 9.11 In P\&P 3rd Ed.

\section*{TRAP Mechanism: 2nd Ed.}
- MAR \(\leftarrow \operatorname{SEXT}(t r a p v e c t 8)\)
- MDR \(\leftarrow \operatorname{MEM}[\) MAR]
- R7 \(\leftarrow \mathrm{PC}\)
- \(\mathrm{PC} \leftarrow \mathrm{MDR}\)
- ....
- JMP R7


\section*{TRAP example}
- What are the values in R0 and R 7 right before IN?
- How about right before HALT?
.ORIG x3000
\begin{tabular}{|c|c|}
\hline AND R0, R0, \#0 & ;init R0 \\
\hline ADD R0, R0, \#3 & ; set R0 to 3 \\
\hline ADD R7, R0, \#4 & ; set R7 to 7 \\
\hline ADD R0, R0, \#1 & ;increment R0 \\
\hline ADD R7, R7, \#1 & ;increment R7 \\
\hline IN & ; same as 'TRAP x23' \\
\hline ADD R0, R0, \#1 & ;increment R0 \\
\hline ADD R7, R7, \#0 & ;increment R7 \\
\hline HALT & \\
\hline . END & \\
\hline
\end{tabular}

\section*{RTI: Return from TRAP/Interrupt}
- 2nd edition: LC3 will overwrite R7
\begin{tabular}{|c|c|c|c|c|c|c|}
\hline BR & \[
0000
\] & n & z p & \multicolumn{2}{|r|}{PCoffset9} & \\
\hline & 1 & \multicolumn{2}{|r|}{\multirow[b]{2}{*}{000}} & & 1 & \\
\hline JMP & 1100 & & & BaseR & \multicolumn{2}{|l|}{000000} \\
\hline & & & & 1 & 1 & \\
\hline & \(1{ }^{1} 1\) & \multirow{3}{*}{1} & & P & 1 & \\
\hline JSR & 0100 & & & \multicolumn{2}{|c|}{PCoffset11} & \\
\hline & 1 & & 1 & 1 & , & \\
\hline & 11 & & 1 & 1 & 11 & \\
\hline JSRR & 0100 & 0 & 00 & BaseR & 000000 & \\
\hline
\end{tabular}
- 3rd edition: R7 will be left unchanged.

- Mechanism? Uses stacks \(\rightarrow\) next lecture.
TRAP

Figure "A.2" - P\&P 3rd Ed.

\section*{TRAP vs. subroutines}
- Service routines (TRAP) provide 3 main functions
- Shield programmers from system-specific details (KBDR, KBSR, etc.)
- Write frequently-used code just once
- Protect system recourses from malicious/clumsy programmers
- Subroutines provide the same functions for non-system (user) code
- Lives in user space
- Performs a well-defined task
- Is invoked (called) by another user program
- Returns control to the calling program when finished```

