

Parametric search

disadvantages

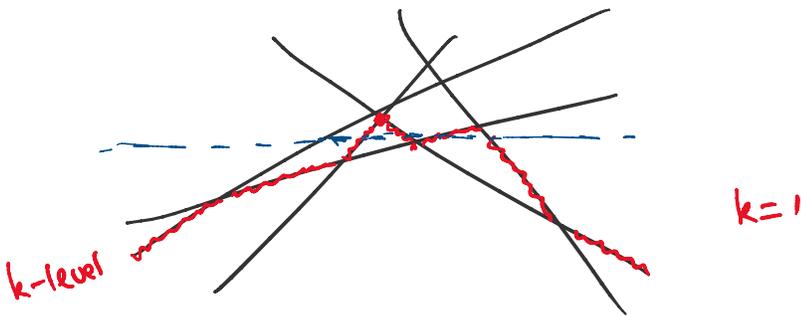
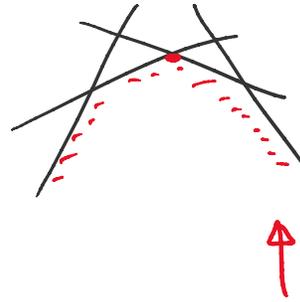
- extra log
- need parallelization
- complicated

=> simpler alternative?

Ex 2D linear program (LP) with k violations

Given n ^{lower} halfplanes in 2D, & k ,

find highest pt inside all halfplanes but k

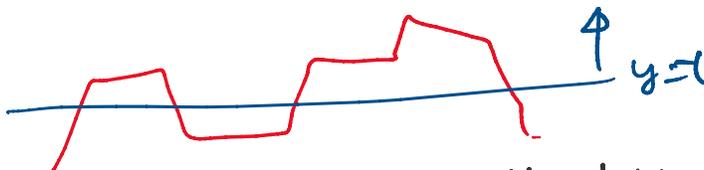


equiv: find highest pt on the k -level

$k=0$: standard LP: $O(n)$ time

Decision Problem:

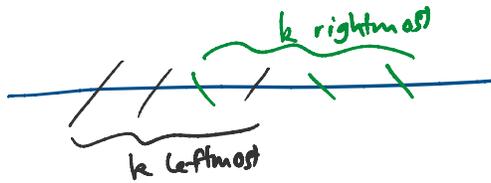
given t , decide whether k -level intersects $y=t$



$T_D = O(n \log n)$ by sorting intersections along $y=t$ & linear scan

(more carefully: $T_D = O(n + k \log n)$)
i. ...

(more carefully: $T_D = O(n + k \log n)$)



by parametric search, $T = O(n)$ \Rightarrow $O(n \log^3 n)$
 $T_D = O(k \log n)$ time

(alternative: by binary search using slope selection)

rand. search: $O(n \log n) \dots$

Warm-Up Exercise

find min of l numbers a_1, \dots, a_l

randomly permute $a_1 \rightarrow a_l$

$\min \leftarrow \infty$

for $i = 1, \dots, l$

if $a_i < \min$

$\min = a_i$ (*)

$O(l)$ time

how many times (*) is done?

worst case: l

expected?

backwards analysis:

\Pr [in last iteration, (*) is done]

$= \Pr$ [$a_l = \min(a_1, \dots, a_l)$]

↑
rand.

fixed

$= \frac{1}{l}$

\Rightarrow expected total $= \frac{1}{l} + \frac{1}{l-1} + \dots + 1$

$\leq \ln l + 1 = O(\log l)$

Now, imagine a_1, \dots, a_ℓ are unknown:

- decision oracle: given i, t , is $a_i < t$?
in T_D time

- evaluation oracle: given i , compute a_i
in T_E time ($T_D \ll T_E$)

goal: compute $\min(a_1, \dots, a_\ell)$

naive sol'n: $O(T_E \ell)$ time

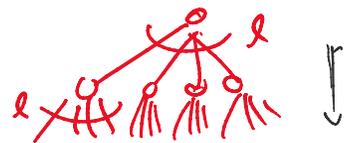
rand. sol'n: $O(T_D \ell + T_E \log \ell)$ expected time

A Recursive Rand. Technique: (C.'98)

Lemma Let f be a problem with

- decision oracle: given input I of size n , value t ,
decide whether $f(I) < t$?
in $T_D(n)$ time

- decomposition scheme: given input I of size n ,
can form smaller inputs I_1, \dots, I_ℓ of size $\frac{n}{b}$
s.t. $f(I) = \min \{ f(I_1), \dots, f(I_\ell) \}$
for some const $\ell, b > 1$



Then can evaluate $f(I)$ in $O(T_D(n))$ expected time
(in $\ll T_D(n)$ time)

assuming $T_D(n) \gg n^\epsilon$

(more precisely, $T_D(n)/n^\epsilon$ is increas.)

Pf: Let $T(n)$ be expected time to evaluate $f(I)$ for $|I|=n$.

$$\Rightarrow T(n) \leq O(T_D(n) \cdot l) + T\left(\frac{n}{b}\right) \cdot (\ln l + 1)$$

$$\Rightarrow T(n) \leq (\ln l + 1) \cdot T\left(\frac{n}{b}\right) + O(T_D(n))$$

Master Thm

$$\Rightarrow T(n) = O(T_D(n))$$

if $T_D(n) \gg n^{\log_b(\ln l + 1) + \epsilon}$ (†)

What if (†) not true?

repeat k times for large const k

$$l \rightarrow l^k$$

$$b \rightarrow b^k$$

$$\log_{b^k}(\ln l^k + 1)$$

$$= \frac{\log(k \ln l + 1)}{k \log b}$$

$$\rightarrow 0 \text{ as } k \rightarrow \infty$$

D

Ex 1: Closest pair of a set P of n pts in \mathbb{R}^d
 divide P into P_1, \dots, P_r of size $\frac{n}{r}$ for const r

$$\Rightarrow f(P) = \min_{i, j \in \{1, \dots, r\}} f(P_i \cup P_j)$$

$$\Rightarrow \binom{r}{2} \text{ subproblems of size } \leq \frac{2n}{r}$$

$$l = \binom{r}{2}, \quad b = r/2.$$

$$\text{e.g. } r=3, \quad l=3, \quad b=3/2.$$

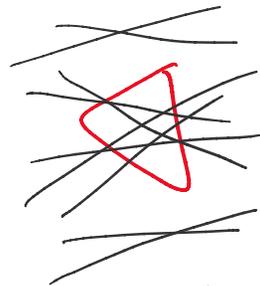
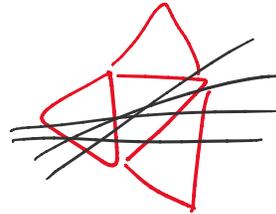
\dots $n \cdot \log(n) \Rightarrow$ closest pair \dots time

e.g. $1 \rightarrow$, $x \rightarrow$

$T_D(n) = O(n \log n)$ \Rightarrow closest pair
by grid in $O(n \log n)$ time

Ex 2 2D LP with k violations

Apply Cutting lemma to n lines



inside Δ ,
 k -level of H
 $\equiv (k - x_\Delta)$ -level
of H_Δ

$O(r^2)$ subproblems of size $\frac{n}{r}$ for r const

for each cell Δ ,
let $H_\Delta =$ halfplanes whose lines intersect Δ
($|H_\Delta| \leq \frac{n}{r}$)

$x_\Delta =$ # lines strictly below Δ

$$\Rightarrow f(H, k) = \max_{\Delta} f(H_\Delta, k - x_\Delta)$$

$$l = O(r^2), b = r$$

$$\Rightarrow T_D(n) = O(n \log n) \Rightarrow \boxed{O(n \log n)}$$

expected time.

alternatively:

$$T_D(n) = O(n + k \log n)$$
$$= O(n + k^{1-\epsilon} n^\epsilon \log n)$$

$$\boxed{O(n + k^{1-\epsilon} n^\epsilon \log n)}$$

expected time

(open: $O(n + k \log n)$?)