

$G = (V, E)$ undir graph

$w: E \rightarrow \mathbb{R}_+$ edge weights.

Recall $H = (V, F)$ $w': F \rightarrow \mathbb{R}_+$

is an ε -approximate spectral sparsifier of G if

$$(1-\varepsilon) \mathcal{L}_G \preceq \mathcal{L}_H \preceq (1+\varepsilon) \mathcal{L}_G.$$

In previous lecture we saw a random sampling algorithm that shows that for any $\varepsilon > 0$ ε -approximate spectral sparsifiers with $O\left(\frac{n \log n}{\varepsilon^2}\right)$ edges exist.

Recall the algorithm:

We see

$$L_G = \sum_{e \in E} w_e L_e$$

$$\text{where } L_{uv} = (x_u - x_v)(x_u - x_v)^T$$

is a rank-1 matrix

corresponding to edge uv .

We obtained H by importance sampling:

$$L_H = \sum_e X_e$$

where $X_e = \frac{w_e}{p_e} L_e$ with prob p_e
 $= 0$ otherwise.

And we choose $\beta_e = \frac{c \log n}{\epsilon^2} R_{\text{eff}}(e)$

Since the "importance" or "influence"
of $w_e Z_e$ on Z_n is $R_{\text{eff}}(e)$

Captured by the two lemmas.

$$\textcircled{1} \quad w_e Z_e \leq R_{\text{eff}}(e) Z_n$$

$$\textcircled{2} \quad \sum_e R_{\text{eff}}(e) = n-1.$$

the extra $\frac{\log n}{\epsilon^2}$ in the probability

is standard when using
Chernoff-type concentration ineq.
and is ^{often} necessary if one uses

independent random sampling.

Two questions

- ① Can we derandomize?
- ② Is $\frac{n \log n}{\epsilon^2}$ a tight bound?

One standard derandomization strategy when using Chernoff type inequalities is to use pessimistic estimators. In the context of Chernoff bounds this yields a variant of the well-known Multiplicative

Weight Update method that
(MWU)

relies on exponential potential function. In the context of Matrix Chernoff bound one needs to use the Matrix MWU which is technical but most likely yields a deterministic algorithm but since it essentially relies on the analysis of the randomized algorithm and will also lead to a sparsifier with $\Omega\left(\frac{n \log n}{\epsilon^2}\right)$ edges in the

work case.

[Patson-Spielman-Srivadāra]
used another potential function
and an elegant analysis to
obtain a deterministic algorithm
that yields a sparsifier with

$O\left(\frac{n}{\epsilon^2}\right)$ edges which is optimal.

The initial algorithm was
slow (n^4) but subsequent
work has yielded faster
deterministic and randomized
algorithms.

Recall that $L_H \approx_\varepsilon L_h$ iff
all eigenvalues of L_H are
roughly same as those of L_h .

Even in the sampling algorithm
we found it easier to work
with $L_h^{+1/2} L_h L_h^{+1/2} = \mathbb{I}$ which
is identity on space \perp to $\bar{\mathbb{I}}$.

The reason for this is that
the min and max eigen values
of $\bar{\mathbb{I}}$ are 1 and hence
ensuring that λ_{\min} and λ_{\max}

are well-approximated ensures that all eigen values are approximated.

To this end this is the main theorem of [RSS]

Main Theorem

Let $\bar{v}_1, \bar{v}_2, \dots, \bar{v}_m \in \mathbb{R}^n$ s.t

$$\sum_{i=1}^m v_i v_i^T = \mathbf{I} \quad (\bar{v}_1, \dots, \bar{v}_m \text{ are in isotropic position})$$

Then for any $\epsilon > 0$ \exists a set

$S \subseteq [m]$ and $c_i, i \in S$ s.t

$$\textcircled{1} |S| = O\left(\frac{n}{\epsilon^2}\right)$$

$$\textcircled{2} (1-\epsilon)\mathbb{I} \preceq \sum_{i \in E} c_i v_i v_i^T \preceq (1+\epsilon)^2 \mathbb{I}$$

Exercise: Use above theorem to derive $O\left(\frac{n}{\epsilon^2}\right)$ sized ϵ -approximate spectral sparsifier of a n -vertex graph.

Hint:

$$\begin{aligned} L_n^{+1/2} L_n L_n^{+1/2} &= \sum_{e \in E} L_n^{+1/2} w_e L_n L_n^{+1/2} \\ &= \sum_{e \in E} v_e v_e^T \end{aligned}$$

Proof of Main Theorem

The algorithmic idea is the following.

- Start with matrix $A = 0$ (zeros)
- For some # of steps do
 - Find an index $i \in [m]$
and a step size c
and update $A \leftarrow A + cv_i v_i^T$

Basically it follows an iterative scheme where in each step

We add a small amount of
some $\bar{v}_i v_i^T$ to current matrix
 A to get it close to I .

Recall we want $\lambda_{\min}(A) > 1 + \epsilon$

$$\text{and } \lambda_{\max}(A) \leq 1 + \epsilon$$

at the end.

Of course we can simply add
all of the v_i 's with step size 1
but then we won't sparsify.

Idea is to use $O\left(\frac{n}{\epsilon^2}\right)$ iterations
so we get a sparsifier

Some mathematical background

$$\text{Trace}(A) = \sum_{i=1}^n A_{ii} \quad \begin{array}{l} \text{Sum of diagonal} \\ \text{entries} \\ \text{of a } \underline{n \times n} \text{ matrix.} \end{array}$$

① $\text{Tr}(A) = \sum_i \lambda_i$ of eigen values

Why? λ 's are roots of

$$\text{Characteristic poly } \det(A - \lambda I) = 0.$$

② $\text{Tr}(A+B) = \text{Tr}(A+B)$ clear.

③ Less clear: cyclic property

$$\text{Tr}(AB) = \text{Tr}(BA) \text{ whenever}$$

AB is ~~a~~ square matrix

(A, B may not be square!).

Easy to verify.

Lemma:
$$\sum_{i=1}^m v_i^T M \bar{v}_i = \text{Tr} \left(\left(\sum_{i=1}^m v_i v_i^T \right) M \right)$$

and hence if $\sum_{i=1}^m v_i v_i^T = I$ then

$$\sum_{i=1}^m \bar{v}_i^T M \bar{v}_i = \text{Tr}(M).$$

Proof:
$$\sum_{i=1}^m v_i^T M \bar{v}_i = \sum_{i=1}^m \text{Tr} (v_i^T M \bar{v}_i)$$

$\uparrow \# \qquad \qquad \qquad \uparrow \#$

$$= \sum_{i=1}^m \text{Tr} (v_i v_i^T M)$$

by
cyclic prop
of Trace

$$= \text{Tr} \left(\left(\sum_{i=1}^m v_i v_i^T \right) M \right)$$

$$= \text{Tr}(IM) = \overline{\text{Tr}(M)}.$$

□.

Sherman-Morrison-Woodbury Formula

Theorem: Let A be a symmetric
non-singular matrix and let
 c be a real # and \bar{v} be a vector.

Then

$$(A - c \bar{v} \bar{v}^T)^{-1} = A^{-1} + c \frac{A^{-1} \bar{v} \bar{v}^T A^{-1}}{1 - c \bar{v}^T A^{-1} \bar{v}}.$$

Proof: Check by multiplying.

or view A as $\sum_i \lambda_i \bar{u}_i \bar{u}_i^T$ □.

n eigen values.

Barrier functions

We define two barrier functions.
"upper" and "lower".

Let A be a $n \times n$ symmetric matrix with eigen values

$$\lambda_1 \leq \lambda_2 \leq \dots \leq \lambda_n.$$

For $u > \lambda_n$ we let

$$\begin{aligned} \Phi_u(A) &= \sum_{i=1}^n \frac{1}{u - \lambda_i} \\ &= \text{Tr}((uI - A)^{-1}). \end{aligned}$$

For $l < \lambda_1$ we let

$$\Phi_l(A) = \sum_{i=1}^n \frac{1}{\lambda_i - l}$$

$$= \text{Tr} \left((A - lI)^{-1} \right).$$

As $u \rightarrow \infty$ $\phi_u(A) \rightarrow 0$

and as $u \rightarrow \lambda_n$ $\phi_u(A) \rightarrow \infty$.

As $l \rightarrow -\infty$ $\phi_l(A) \rightarrow 0$

$l \rightarrow \lambda_1$ $\phi_l(A) \rightarrow \infty$.

We need to understand how
the barrier functions change
as u and l change.

Claim: $\Phi_{u+\delta}(A) < \Phi_u(A)$ for $\delta > 0$

Claim: $\lambda_n < u - \frac{1}{\Phi_u(A)}$

Claim: $l + \frac{1}{\Phi_l(A)} \leq \lambda_1$.

More technical

Claim: Let $l < \lambda_1$ and $\delta < \frac{1}{\Phi_l(A)}$

$$\Phi_{l+\delta}(A) \leq \frac{1}{\frac{1}{\Phi_l(A)} - \delta}$$

— ^{basic} Need algebra. See Spielman notes.

How do we use barrier function?

Initially $A = 0$ · $\lambda_1 = \lambda_2 \dots = \lambda_n = 0$.

We set $l_0 = -n$

and $u_0 = n$

so that $\Phi_{u_0}(A) = \Phi_{l_0}(A) = 1$.

Our goal is essentially to make

A have the property that

$$\frac{\lambda_{\max}(A)}{\lambda_{\min}(A)} \approx \Theta(1).$$

$\lambda_{\min}(A)$

ideally $(1-\epsilon)$.

Plan: Show that in each iteration we can find scalar c and v_i and δ_u and δ_l s.t.

$$\Phi_{u+\delta_u}(A + c \bar{v}_i \bar{v}_i^T) \leq \Phi_u(A) \leq 1$$

$$\Phi_{l+\delta_l}(A + t \bar{v}_i \bar{v}_i^T) \leq \Phi_l(A) \leq 1$$

We want δ_u and δ_l to be fixed constants. Suppose we can do that. ^{We} run algorithm for $\Omega(n)$ steps.

For concreteness say $\delta_u = 2$ $\delta_l = \frac{1}{3}$.
and we run for $\frac{1}{2}n$ steps.

A.1. end $u = 13n$ and $\Phi_{13n}(A) \leq 1$.

$$\Rightarrow \lambda_n \leq u - \frac{1}{\Phi_n(A)} \leq 13n.$$

$$l \gg -u + 6n \times \frac{1}{3} \gg n.$$

$$\lambda_1 \gg l + \frac{1}{\Phi_l(A)} \gg n.$$

$$\Rightarrow \frac{\lambda_{\max}(A)}{\lambda_{\min}(A)} \leq 13.$$

We need to scale A by $6n$
to normalize.

How to show existence of c
 δ_u, δ_d . Note that for given
 $c, v_i, \delta_u, \delta_d$ we can
compute all desired quantities
and check if conditions hold.
So issue is proving existence.

Updating barrier function

We want to change

$$A \text{ to } A + c v v^T$$

rank-1 update.

How does ϕ_u change?

$$\phi_u(A) = \text{Tr}((uI - A)^{-1})$$

$$\phi_u(A + cv\bar{v}^T) = \text{Tr}((uI - A - cvv^T)^{-1})$$

we use SMW formula ↗.

$$= \text{Tr} \left[(uI - A)^{-1} + c \frac{(uI - A)^{-1} \bar{v} \bar{v}^T (uI - A)^{-1}}{1 - c \bar{v}^T (uI - A)^{-1} \bar{v}} \right]$$

$$= \phi_u(A) + \text{Tr} \left(\begin{array}{c} \downarrow \\ \cdot \end{array} \right)$$

$$= \phi_u(A) + \frac{c \bar{v}^T (uI - A)^{-2} \bar{v}}{1 - c \bar{v}^T (uI - A)^{-1} \bar{v}}$$

because $\text{Tr}(XY) = \text{Tr}(YX)$.

$$= \phi_u(A) + \frac{c \bar{v}^T (uI - A)^{-2} \bar{v}}{1 - c \bar{v}^T (uI - A)^{-1} \bar{v}}$$



+ve since $c > 0$

and PSD of $(uI - A)^{-1}$.

So adding $c \bar{v} \bar{v}^T$ increases

ϕ_u .

(intuitively λ 's

increase

$\Rightarrow \sum \frac{1}{u - \lambda_i} \uparrow$).

To keep $\phi_u(A + c \bar{v} \bar{v}^T) \leq 1$

we increase u to $u' = u + \delta_u$.

Q: how much should we
increase u s.t.

$$\phi_{u+\delta u}(A + c v \bar{v}^T) \leq \phi_u(A).$$

From above derivation

$$\begin{aligned} & \phi_{u'}(A + \bar{v} \bar{v}^T) \\ &= \phi_{u'}(A) + \frac{c \bar{v}^T (u' I - A)^{-2} \bar{v}}{1 - c \bar{v}^T (u' I - A)^{-1} \bar{v}} \end{aligned}$$

Thus to ensure

$$\phi_{u'}(A + c \bar{v} \bar{v}^T) \leq \phi_u(A)$$

it suffices to have

$$\phi_u(A) - \phi_{u'}(A) \geq \frac{c \bar{v}^T (u' I - A)^{-2} \bar{v}^T}{1 - c \bar{v}^T (u' I - A)^{-1} \bar{v}}$$

$$\Rightarrow \frac{1}{c} \geq \frac{\bar{v}^T (u' I - A)^{-2} \bar{v}}{\phi_u(A) - \phi_{u'}(A)} + \bar{v}^T (u' I - A)^{-1} \bar{v}$$

$$\text{Let } U_A = \frac{(u' I - A)^{-2}}{\phi_u(A) - \phi_{u'}(A)} + (u' I - A)^{-1}$$

Lemma: Fix u , δu and \bar{v}

Then $\max c$ s.t. $\phi_{u+\delta u}(A + c v v^T) \leq \phi_u(A)$ is given by.

$$\frac{1}{c} \geq \bar{v}^T U_A \bar{v} .$$

Very clean dependence on A
 u and δu and v is
"outside".

What happens when we
increase l to δ_l ? $l' = l + \delta_l$.

$\Phi_{l'}(A)$ increases. But when
we add $c \bar{v} \bar{v}^T$ to A

$\Phi_l(A + t \bar{v} \bar{v}^T)$ decreases.
(since λ 's intuitively
increase).

How much? Etc.

Want $\phi_{\ell'}(A + \epsilon v \bar{v}^T) \leq \phi_{\ell}(A)$.

Lemma:

$$\text{Let } L_A = \frac{(A - \ell' I)^{-2}}{\phi_{\ell'}(A) - \phi_{\ell}(A)} - (A - \ell' I)^{-1}$$

If $\frac{1}{c} \leq \bar{v}^T L_A \bar{v}$ then

$$\phi_{\ell'}(A + c v \bar{v}^T) \leq \phi_{\ell}(A).$$

Inductive argument.

Given u , A , δ_u , δ_l and \bar{v}
we have seen that

$$\Phi_{u+\delta_u}(A + c v \bar{v}^t) \leq \Phi_u(A)$$

$$\text{if } \frac{1}{c} \geq \bar{v}^T U_A \bar{v}$$

$$\text{and } \Phi_{l+\delta_l}(A + c v \bar{v}^T) \leq \Phi_l(A)$$

$$\text{if } \frac{1}{c} \leq \bar{v}^T L_A \bar{v}.$$

$$\text{Recall } \sum_{i=1}^m v_i v_i^T = \underline{I}$$

Fix δ_u and δ_l .

Want to find scalars $c > 0$ and

\bar{v}_i s.t. we can

update A to $A + c v_u v_i^T$ without
violating barriers.

Lemma:
$$\sum_{i=1}^m v_i^T U_A \bar{v}_i \leq \frac{1}{\delta_u} + \phi_u(A).$$

Lemma:
$$\begin{aligned} \sum v_i^T L_A \bar{v}_i &\geq \frac{1}{\delta_l} - \frac{1}{\frac{1}{\phi_l(A)} - \delta_l} \\ &\geq \frac{1}{\delta_l} - \phi_l(A). \end{aligned}$$

Thus if we have that

$$\frac{1}{\delta_u} + \phi_u(A) \leq \frac{1}{\delta_\ell} - \phi_\ell(A).$$

$$\Rightarrow \exists v_i \text{ s.t. } \bar{v}_i^T U_A \bar{v}_i \leq \bar{v}_i^T L_A \bar{v}_i$$

and

Then we can find c and \bar{v}_i to
add to A .

Parameter settings

$$d \text{ fixed constant } d = \frac{1}{\varepsilon^2}.$$

$$l_0 = -\sqrt{d} n. \quad \phi_{l_0}(0) = \frac{1}{\sqrt{d}}$$

$$u_0 = \frac{d + \sqrt{d}}{\sqrt{d} - 1} n \quad \phi_{u_0}(0) = \frac{\sqrt{d} - 1}{d + \sqrt{d}}.$$

$$\delta_l = 1, \quad \delta_u = \frac{\sqrt{d} + 1}{\sqrt{d} - 1}.$$

Initially:

$$\frac{1}{\delta_u} + \phi_u(A) = \frac{\sqrt{d} - 1}{\sqrt{d} + 1} + \frac{\sqrt{d} - 1}{d + \sqrt{d}}.$$

$$= \frac{\sqrt{d} - 1}{\sqrt{d} + 1} \left(1 + \frac{1}{\sqrt{d}} \right).$$

$$= \frac{\sqrt{d} - 1}{\sqrt{d}} = 1 - \frac{1}{\sqrt{d}}$$

$$\frac{1}{\delta_\epsilon} - \frac{1}{\phi_\epsilon(0) - \delta_\epsilon} = 1 - \frac{1}{\sqrt{d} - 1}$$

Hence we satisfy the condition.

Now run algorithm for d_n iterations. Let A be real matrix.

$$\frac{\lambda_{\max}(A)}{\lambda_{\min}(A)} \leq \frac{u_0 + d_n \delta_n}{l_0 + d_n \delta_\epsilon}$$

$$\leq \frac{d + 2\sqrt{d} + 1}{d - 2\sqrt{d} + 1}$$

$$\text{for } d = \frac{1}{\epsilon^2} \text{ above is } \frac{\frac{1}{\epsilon^2} + 2\frac{1}{\epsilon} + 1}{\frac{1}{\epsilon^2} - 2\frac{1}{\epsilon} + 1}$$

$$\frac{1 + 2\varepsilon + \varepsilon^2}{1 - 2\varepsilon + \varepsilon^2} \leftarrow \dots$$

Proofs of Lemmas

Lemma: $\sum_{i=1}^m v_i^T U_A \bar{v}_i \leq \frac{1}{\delta_u} + \phi_u(A).$

Proof: Recall.

$$\sum_{i=1}^m v_i^T U_A \bar{v}_i = \text{Tr}(U_A)$$

$$U_A = \frac{(u' I - A)^{-2}}{\phi_u(A) - \phi_{u'}(A)} + (u' I - A)^{-1}$$

$$\text{Tr}((u' I - A)^{-1}) = \phi_{u'}(A) \leq \phi_u(A).$$

$$\text{Tr}((u' I - A)^{-2}) ?$$

$$\phi_u(A) = \sum_{i=1}^n \frac{1}{u - \lambda_i}$$

$$\begin{aligned} \frac{d}{du} \phi_u(A) &= - \sum \frac{1}{(u - \lambda_i)^2} \\ &= - \text{Tr}((uI - A)^{-2}). \end{aligned}$$

Since $\phi_u(A)$ is convex in u .
we have.

$$\begin{aligned} \phi_u(A) - \phi_{u+\delta u}(A) &\geq -\delta u \phi'_{u+\delta u} \\ &\geq \delta u \text{Tr}((u'I - A)^{-2}). \end{aligned}$$

$$\Rightarrow \frac{1}{\delta u} \geq \frac{\text{Tr}((u'I - A)^{-2})}{\phi_u(A) - \phi_{u+\delta u}(A)}.$$

□.

Lemma: $\sum_{i=1}^m v_i^T L_A \bar{v}_i \geq \frac{1}{\delta_\ell} - \phi_\ell(A).$

Proof: Recall $\sum_{i=1}^m v_i^T L_A \bar{v}_i = \text{Tr}(L_A).$

$$L_A = \frac{(A - \ell' I)^{-2}}{\phi_{\ell'}(A) - \phi_\ell(A)} - (A - \ell' I)^{-1}$$

$$\text{Tr}(L_A) = \text{Tr} \left(\begin{matrix} \downarrow \\ \end{matrix} \right) + \text{Tr} \left(\begin{matrix} \downarrow \\ \end{matrix} \right)$$

$$\text{Tr} (A - l' I)^{-1} = \phi_{l'}(A) \leq \phi_l(A).$$

$$\text{Tr} ((A - l' I)^{-2}).$$

$$\phi_l(A) = \sum_{i=1}^n \frac{1}{\lambda_i - l}$$

$$\frac{d}{dl} \phi_l(A) = \sum_{i=1}^n \frac{1}{(\lambda_i - l)^2}$$

$\phi_l(A)$ is convex in l .

$$\Rightarrow \frac{\phi_{l+\delta_l}(A) - \phi_l(A)}{\delta_l} \leq \phi'_{l+\delta_l}(A)$$

$$\Rightarrow \frac{\text{Tr} ((A - l' I)^{-2})}{\phi_{l'}(A) - \phi_l(A)} \geq \frac{1}{\delta_l}.$$

