



# Lecture 14

## Games and Nash Equilibrium

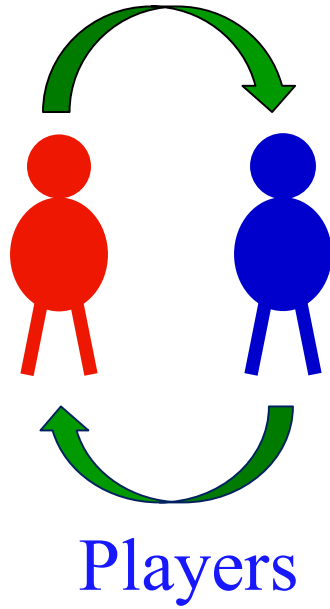
CS 580

6<sup>th</sup> October 2022

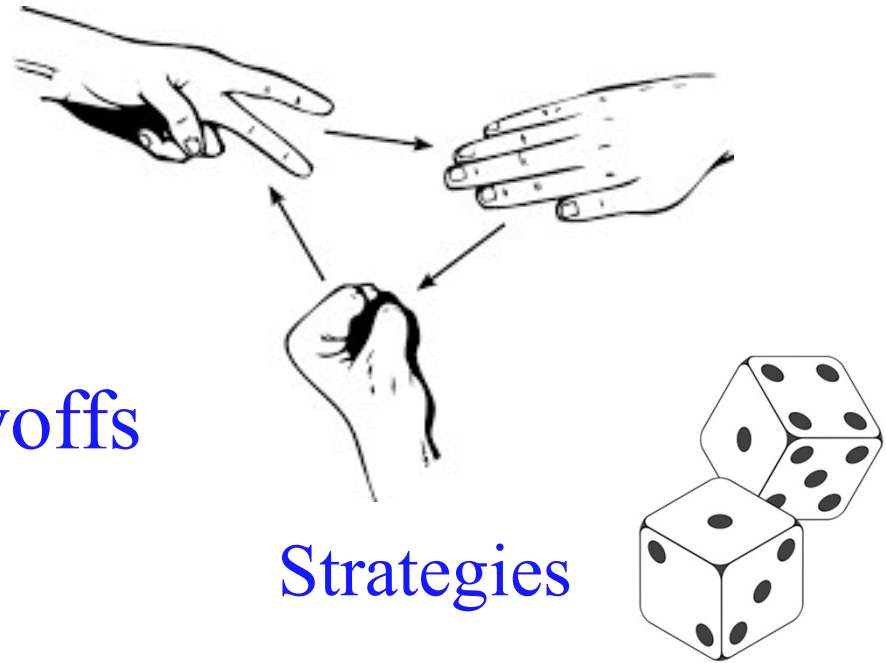
Instructor: [Ruta Mehta](#)



# Games

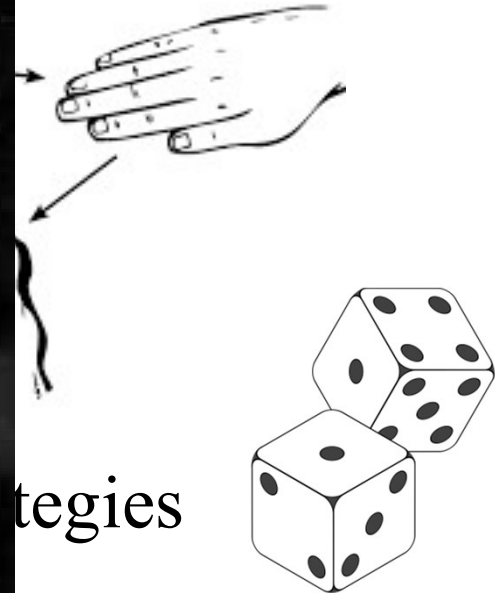
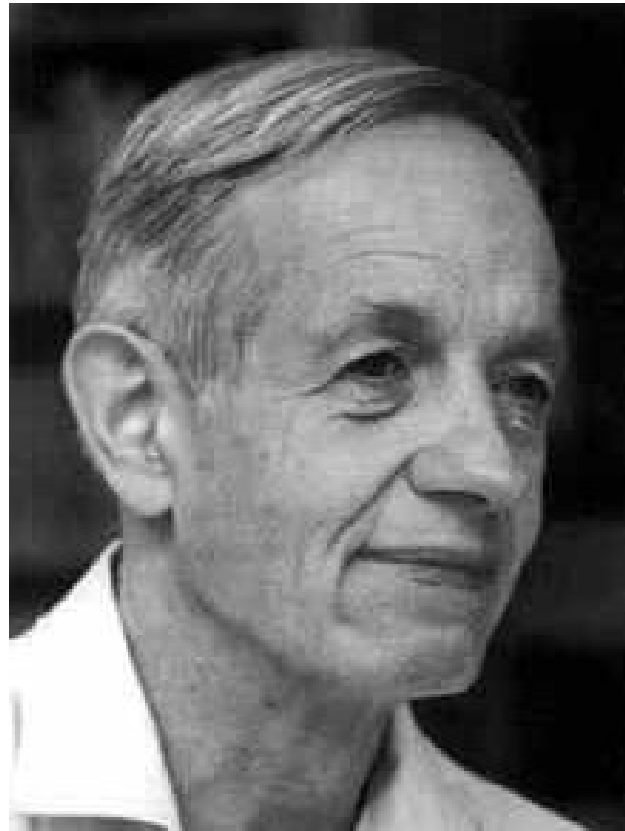
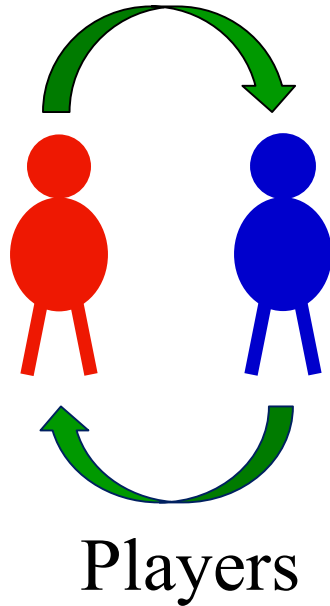


Payoffs



Randomize!

# Games



Randomize!

Nash (1950):

There exists a (stable) state where no player gains by unilateral deviation.

Nash equilibrium (NE)

# Our focus: Two-player games



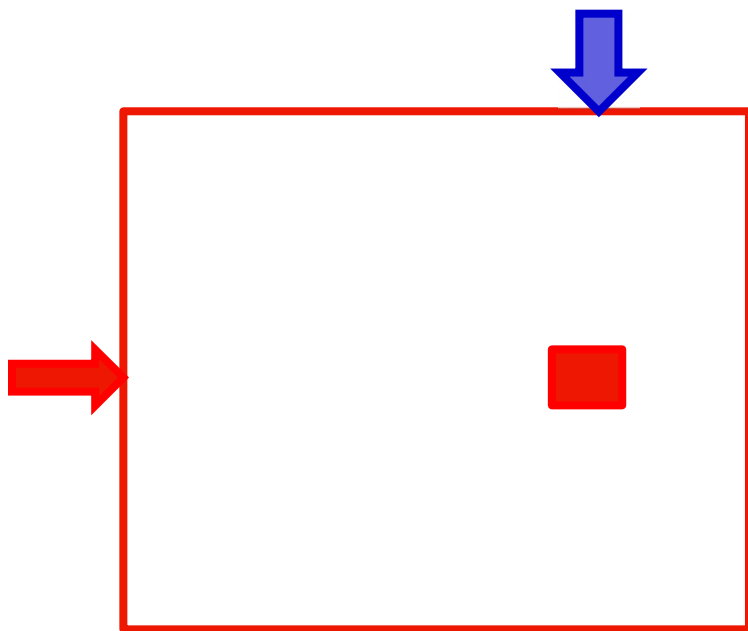
Alice

m strategies

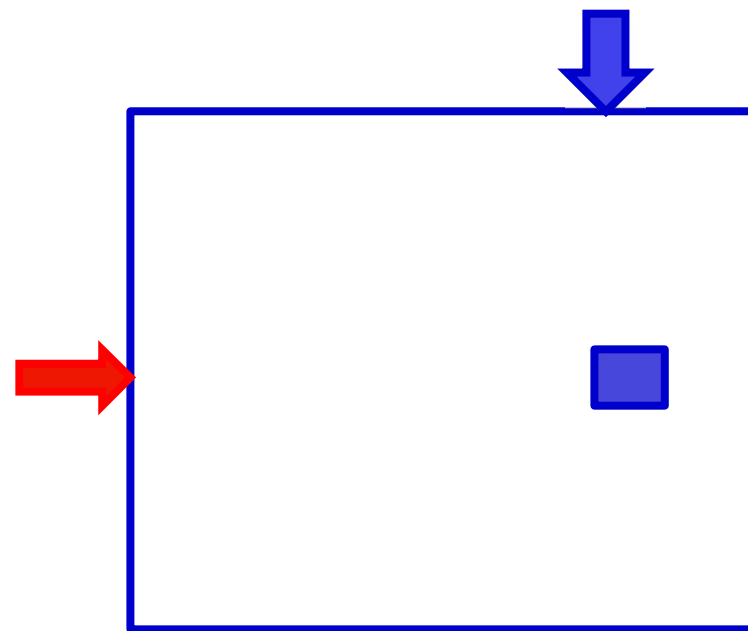


Bob

n strategies



$A_{m \times n}$



$B_{m \times n}$

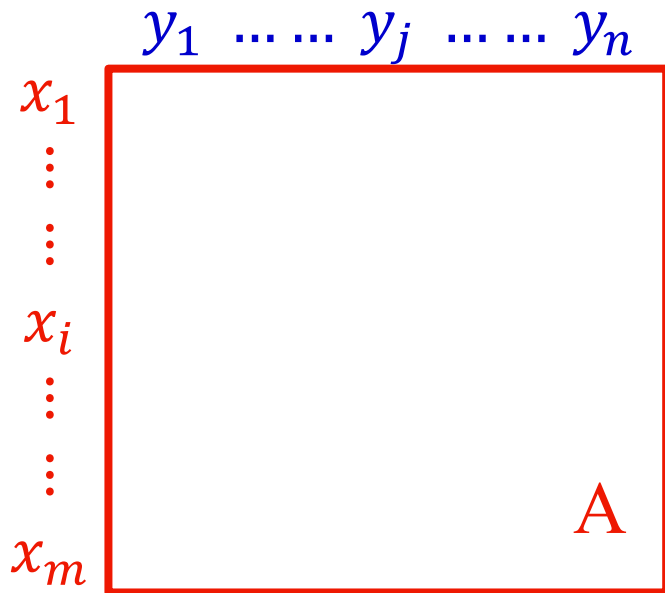


Alice

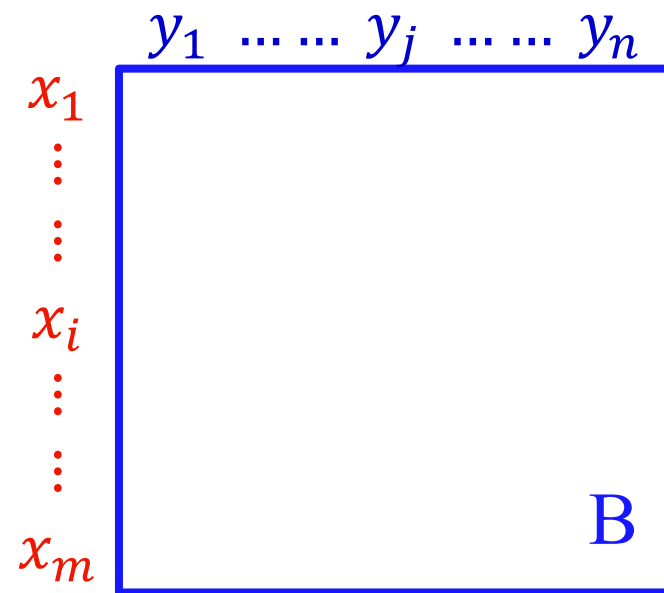


Bob

Randomize



$$x_1, \dots, x_m \geq 0$$
$$\sum_{i=1}^m x_i = 1$$

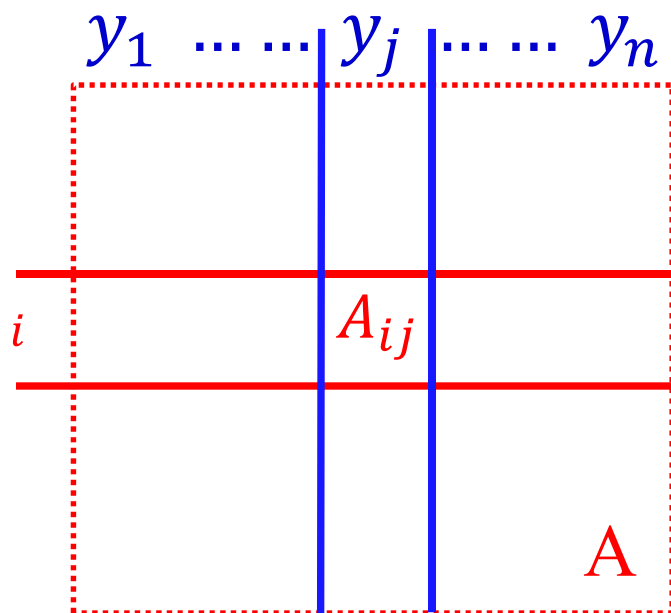


$$y_1, \dots, y_n \geq 0$$
$$\sum_{j=1}^n y_j = 1$$

# 2-Nash Characterization



- For Alice,  $i^{th}$  strategy gives

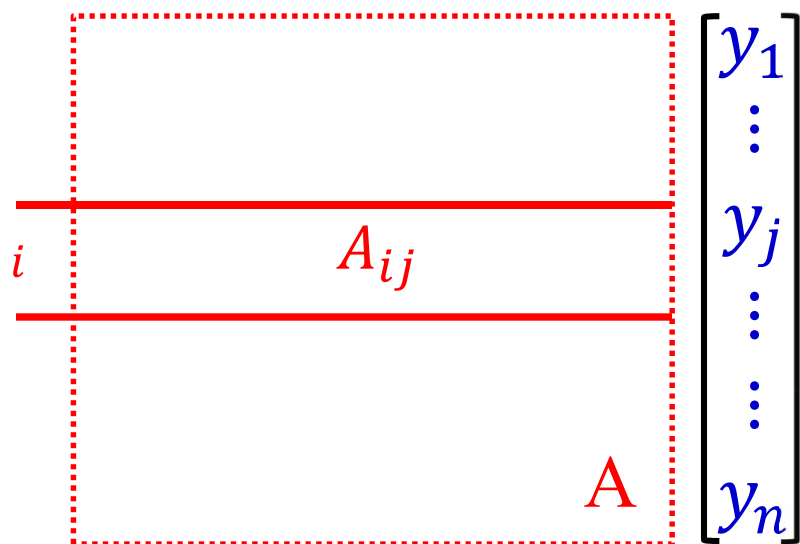


$$\longrightarrow \sum_j A_{ij} y_j$$

# 2-Nash Characterization



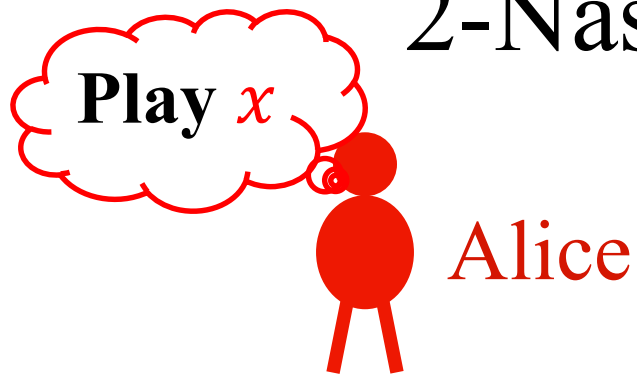
- For Alice,  $i^{th}$  strategy gives



The diagram illustrates the calculation of the  $i^{th}$  component of the product  $Ay$ . It shows a matrix  $A$  with a row  $i$  highlighted by a red dashed box. The elements of this row are  $A_{ij}$  for  $j=1, \dots, n$ . To the right of the matrix is a column vector  $y$  with elements  $y_1, \dots, y_j, \dots, y_n$ . An arrow points from the diagram to the equation:

$$\sum_j A_{ij} y_j = (Ay)_i$$

# 2-Nash Characterization



- Alice's expected payoff is

$$\begin{array}{c} x_1 \\ \vdots \\ x_i \\ \vdots \\ x_m \end{array} \begin{array}{c} \vdots \\ \vdots \\ \vdots \\ \vdots \\ \vdots \end{array} \begin{array}{c} y_1 \\ \vdots \\ y_j \\ \vdots \\ y_n \end{array} \begin{array}{c} A_{ij} \\ A \end{array} \rightarrow \sum_i x_i (Ay)_i = x^T A y$$

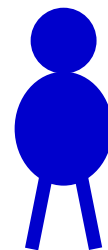
$\downarrow$   
 $\max_i (Ay)_i \leq \leq \max_i (Ay)_i$



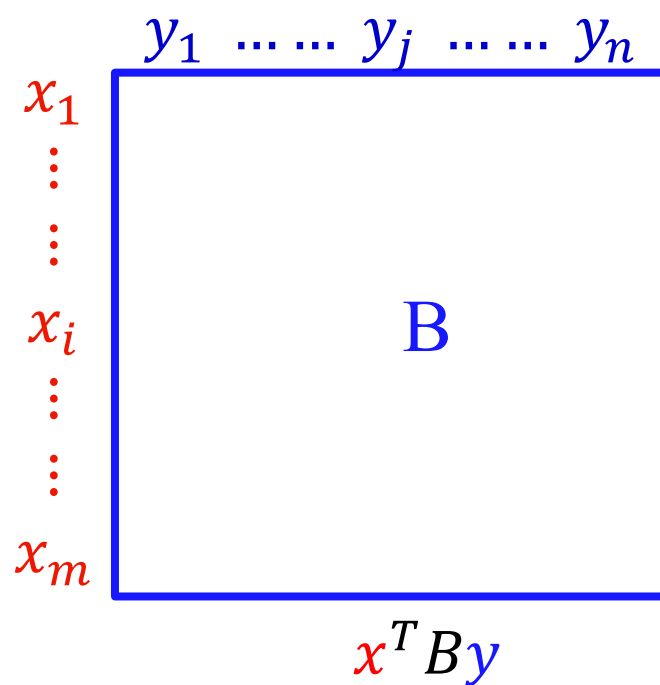
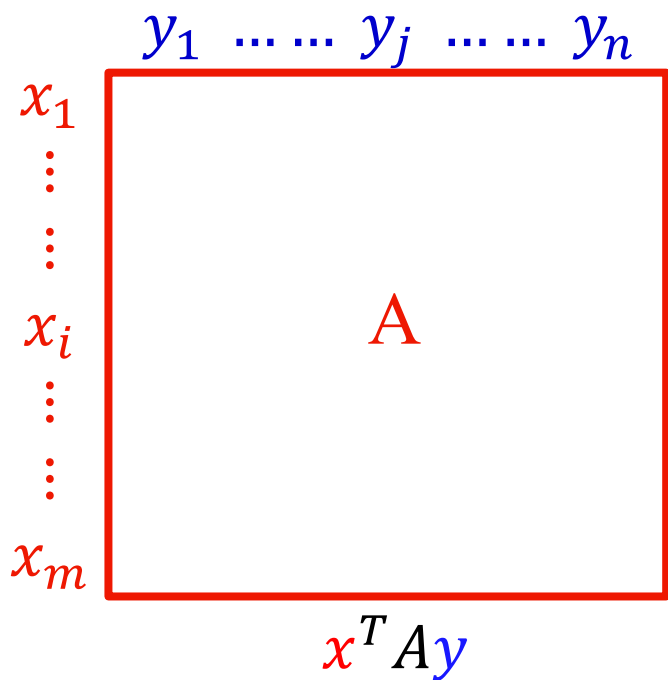


Alice

Randomize



Bob



NE: No unilateral deviation is beneficial

$$x^T A y \geq z^T A y, \quad \forall z \in \Delta_m$$

$$x^T B y \geq x^T B z, \quad \forall z \in \Delta_n$$

# Example: Matching Pennies

NE

	H $\frac{1}{2}$	T $\frac{1}{2}$
H $\frac{1}{2}$	1 -1	-2 2
T $\frac{1}{2}$	-2 2	1 -1

NE

$$E^A[H] = 1 \cdot \frac{1}{2} - 2 \cdot \frac{1}{2} = -\frac{1}{2}$$

$$E^A[T] = -2 \cdot \frac{1}{2} + 1 \cdot \frac{1}{2} = -\frac{1}{2}$$

$$E^A[(1T + 0H)] = 1 \cdot -\frac{1}{2} + 0 \cdot -\frac{1}{2} = -\frac{1}{2}$$

$$E^B[H] = 1 \cdot -1 + 0 \cdot 2 = -1$$

$$E^B[T] = 1 \cdot 2 + 0 \cdot (-1) = 2$$

$$E^B[\left(\frac{1}{2}H + \frac{1}{2}T\right)]$$

$$= -1 \cdot \frac{1}{2} + 2 \cdot \frac{1}{2} = \frac{1}{2}$$

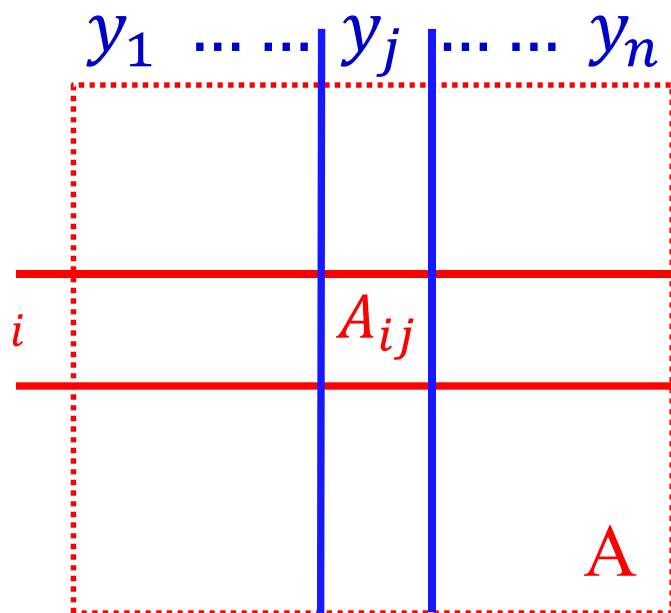


## 2-Nash Characterization

# 2-Nash Characterization



- For Alice,  $i^{th}$  strategy gives

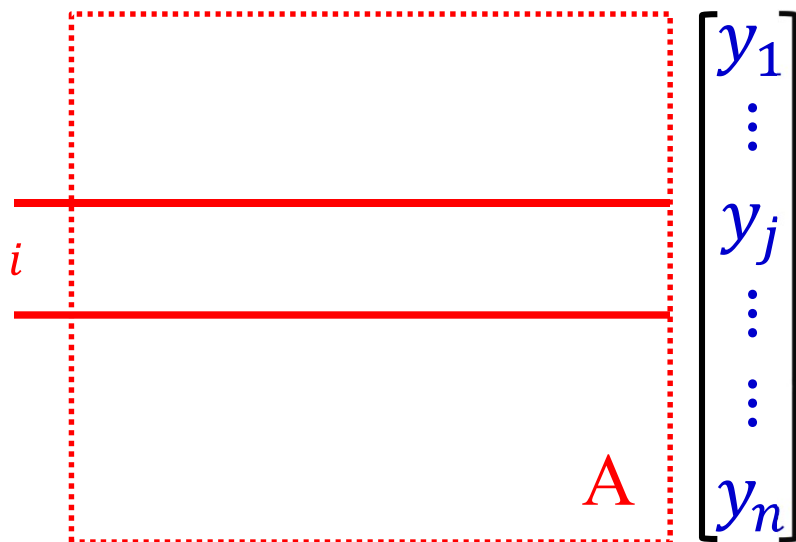


$$\longrightarrow \sum_j A_{ij} y_j$$

# 2-Nash Characterization

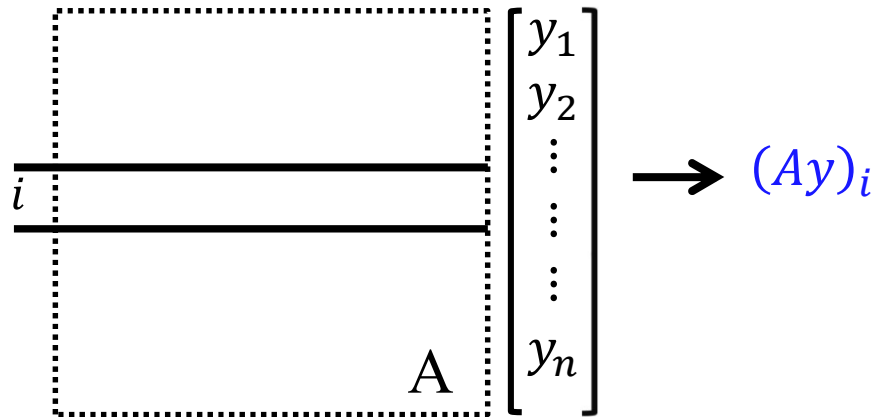


- For Alice,  $i^{th}$  strategy gives



$$\rightarrow \sum_j A_{ij} y_j = (Ay)_i$$

- $i^{th}$  strategy gives Alice



- Max possible payoff:  $\max_i e_i A y$

- $x$  achieves max payoff iff

$$x^T A y \geq (A y)_i, \quad \forall i$$

$$\equiv$$

$$\forall k, \quad x_k > 0 \Rightarrow k \in \operatorname{argmax}_i (A y)_i$$

**Complementarity**

- Max possible payoff:  $\max_i e_i A y$

- $x$  achieves max payoff iff

$$\forall i, \quad x^T A y \geq (A y)_i$$

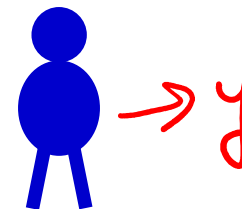
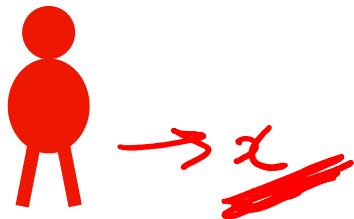
$$\equiv$$

$$\forall k, \quad x_k > 0 \Rightarrow (A y)_k = \max_i (A y)_i$$

**Complementarity**

	H	T
H	1 -1	-2 2
T	-2 2	1 -1

# Polyhedra



$$\text{max-payoff} \leq \pi_A$$

$$P \quad \forall i, (Ay)_i \leq \pi_A$$

$$y \in \Delta_n$$

$$\text{max-payoff} \leq \pi_B$$

$$Q \quad \forall j, (\underline{x}^T B)_j \leq \pi_B$$

$$x \in \Delta_m$$

$$\max_i (Ay)_i \leq \pi_A$$

max-payoff  
of Alice  
against y

$$x^T A y \leq \pi_A$$

$$x^T B y \leq \pi_B$$

↓

$$x^T A y - \pi_A \leq 0 \quad + \quad x^T B y - \pi_B \leq 0$$

$$x^T (A+B) y - (\pi_A + \pi_B) \leq 0$$

$$\rightarrow x^T A y + x^T B y - \pi_A - \pi_B \leq 0$$





$P$

$$\forall i, (Ay)_i \leq \pi_A \\ y \in \Delta_n$$



$Q$

$$\forall j, (x^T B)_j \leq \pi_B \\ x \in \Delta_m$$

$$(y, \pi_A) \in P, \quad (x, \pi_B) \in Q$$

Sum of payoffs

At least the sum of  
max payoffs

$$\underbrace{x^T (A + B) y}_{\text{Sum of payoffs}} - \underbrace{(\pi_A + \pi_B)}_{\text{At least the sum of max payoffs}} \leq 0$$

$$P \quad \begin{array}{l} \forall i, (Ay)_i \leq \pi_A \\ y \in \Delta_n \end{array}$$

$$Q \quad \begin{array}{l} \forall j, (x^T B)_j \leq \pi_B \\ x \in \Delta_m \end{array}$$

$$(y, \pi_A) \in P, \quad (x, \pi_B) \in Q$$

Sum of payoffs

At least the sum of  
max payoffs

$$x^T (A + B) y - (\pi_A + \pi_B) \quad = 0$$



Complementarity

1.  $(x, y)$  is a NE
2.  $\pi_A$  and  $\pi_B$  are the max payoffs

$$P \quad \boxed{\begin{array}{l} \forall i, (Ay)_i \leq \pi_A \\ y \in \Delta_n \end{array}}$$

$$Q \quad \boxed{\begin{array}{l} \forall j, (x^T B)_j \leq \pi_B \\ x \in \Delta_m \end{array}}$$

**Claim.** For  $(y, \pi_A) \in P$ ,  $(x, \pi_B) \in Q$

(i)  $x^T (A + B)y - (\pi_A + \pi_B) \leq 0$ . ✓

(ii)  $x^T (A + B)y - (\pi_A + \pi_B) = 0$  if and only if  $(x, y)$  is a NE.

$\Leftarrow (x^*, y^*)$  is a NE.  $\pi_A^* = x^{*T} A y^*$ ,  $\pi_B^* = x^{*T} B y^*$

$\Downarrow$

$x^{*T} (A + B) y^* - (\pi_A^* + \pi_B^*) = 0$  ✓

$\forall i = 1, \dots, n, (Ay^*)_i \leq x^{*T} A y^* = \pi_A^*$ ,  $y^* \in \Delta_n \Rightarrow (y^*, \pi_A^*) \in P$

$\forall j = 1, \dots, m, (x^{*T} B)_j \leq x^{*T} B y^* = \pi_B^*$ ,  $x^* \in \Delta_m \Rightarrow (x^*, \pi_B^*) \in Q$ .

$P$ 

$$\forall i, (Ay)_i \leq \pi_A$$

$$y \in \Delta_n$$

 $Q$ 

$$\forall j, (x^T B)_j \leq \pi_B$$

$$x \in \Delta_m$$

**Claim.** For  $(y, \pi_A) \in P$ ,  $(x, \pi_B) \in Q$   $x^T A y - \pi_A \leq 0$ ,  $x^T B y - \pi_B \leq 0$

(i)  $x^T (A + B) y - (\pi_A + \pi_B) \leq 0$ .

(ii)  $x^T (A + B) y - (\pi_A + \pi_B) = 0$  if and only if  $(x, y)$  is a NE.

( $\Rightarrow$ ) Let  $(\tilde{y}, \tilde{\pi}_A) \in P$ ,  $(\tilde{x}, \tilde{\pi}_B) \in Q$  s.t.

$$\tilde{x}^T A \tilde{y} + \tilde{x}^T B \tilde{y} - \tilde{\pi}_A - \tilde{\pi}_B = 0$$

$$\Rightarrow \tilde{x}^T A \tilde{y} - \tilde{\pi}_A = 0 \Rightarrow \tilde{x}^T A \tilde{y} = \tilde{\pi}_A \geq (A \tilde{y})_i \quad \forall i$$

$$\Rightarrow \tilde{x}^T A \tilde{y} = \max_i (A \tilde{y})_i$$

$\Rightarrow \tilde{x}$  gives the max payoff to Alice against  $\tilde{y}$

$$P \quad \begin{array}{l} \forall i, (Ay)_i \leq \pi_A \\ y \in \Delta_n \end{array}$$

$$Q \quad \begin{array}{l} \forall j, (x^T B)_j \leq \pi_B \\ x \in \Delta_m \end{array}$$

$$(y, \pi_A) \in P, \quad (x, \pi_B) \in Q$$

Sum of  
2-Nash payoffs

At least the sum of  
max payoffs

$$\max: x^T (A + B) y - (\pi_A + \pi_B) \quad = 0$$

$$\text{s.t. } (y, \pi_A) \in P, (x, \pi_B) \in Q \quad \text{Complementarity}$$

1.  $(x, y)$  is a NE
2.  $\pi_A$  and  $\pi_B$  are the max payoffs

$$P \quad \begin{array}{l} \forall i, (Ay)_i \leq \pi_A \\ y \in \Delta_n \end{array}$$

$$Q \quad \begin{array}{l} \forall j, (x^T B)_j \leq \pi_B \\ x \in \Delta_m \end{array}$$


$$(y, \pi_A) \in P, \quad (x, \pi_B) \in Q$$

**Theorem.** If  $(A, B)$  is zero-sum, i.e.,  $A + B = 0$ , then

2-Nash  $\rightarrow$  linear programming

$$\max: \cancel{x^T (A + B) y} - (\pi_A + \pi_B)$$

$$\text{s.t. } (y, \pi_A) \in P, \quad (x, \pi_B) \in Q$$


$$P \quad \begin{array}{l} \forall i, (Ay)_i \leq \pi_A \\ y \in \Delta_n \end{array}$$

$$Q \quad \begin{array}{l} \forall j, (x^T B)_j \leq \pi_B \\ x \in \Delta_m \end{array}$$

$$(y, \pi_A) \in P, \quad (x, \pi_B) \in Q$$

**Theorem.** If  $(A, B)$  is zero-sum, i.e.,  $A + B = 0$ , then  
2-Nash  $\rightarrow$  linear programming

$$\begin{array}{ll} \text{max:} & -(\pi_A + \pi_B) \\ \text{s.t.} & (y, \pi_A) \in P, \quad (x, \pi_B) \in Q \end{array}$$

~~$(A, -A)$~~ 

A

$$\max_x \min_y x^T A y \stackrel{\text{NE}}{=} \min_y \max_x x^T A y \quad \& \text{ the max-min is NE.}$$

Let  $x^* = \arg\min_x \max_y x^T A y$ ,  $y^* = \arg\min_y \max_x x^T A y$ , then  $(x^*, y^*)$  is a NE.

Pf:

$$\max_x \min_y x^T A y = \min_y \max_x x^T A y \leq x^*{}^T A y^* \leq \max_x x^T A y^* \rightarrow \textcircled{1}$$
$$= \min_y \max_x x^T A y$$

Let  $(\tilde{x}, \tilde{y})$  be a NE.

Let  $(x, y) \in \mathbb{R}^n \times \mathbb{R}^n$

$$\min_y x^* A y \geq \min_y \tilde{x} A y = \tilde{x} A \tilde{y} = \max_x x A \tilde{y} \geq \max_x x A y^* \rightarrow \textcircled{2}$$

$(\because \uparrow \det \sigma \tilde{x})$      $(\because \uparrow \text{NE})$      $(\because \text{NE})$      $(\because \uparrow \text{NE})$      $(\because \det \sigma y^*)$



$$\begin{aligned} \max_x x^T A y^* &= x^*{}^T A y^* = \min_y x^*{}^T A y = \max_x \min_y x^T A y \\ \min_y \max_x x^T A y & \end{aligned}$$

$\Rightarrow (x^*, y^*)$  is a NE.

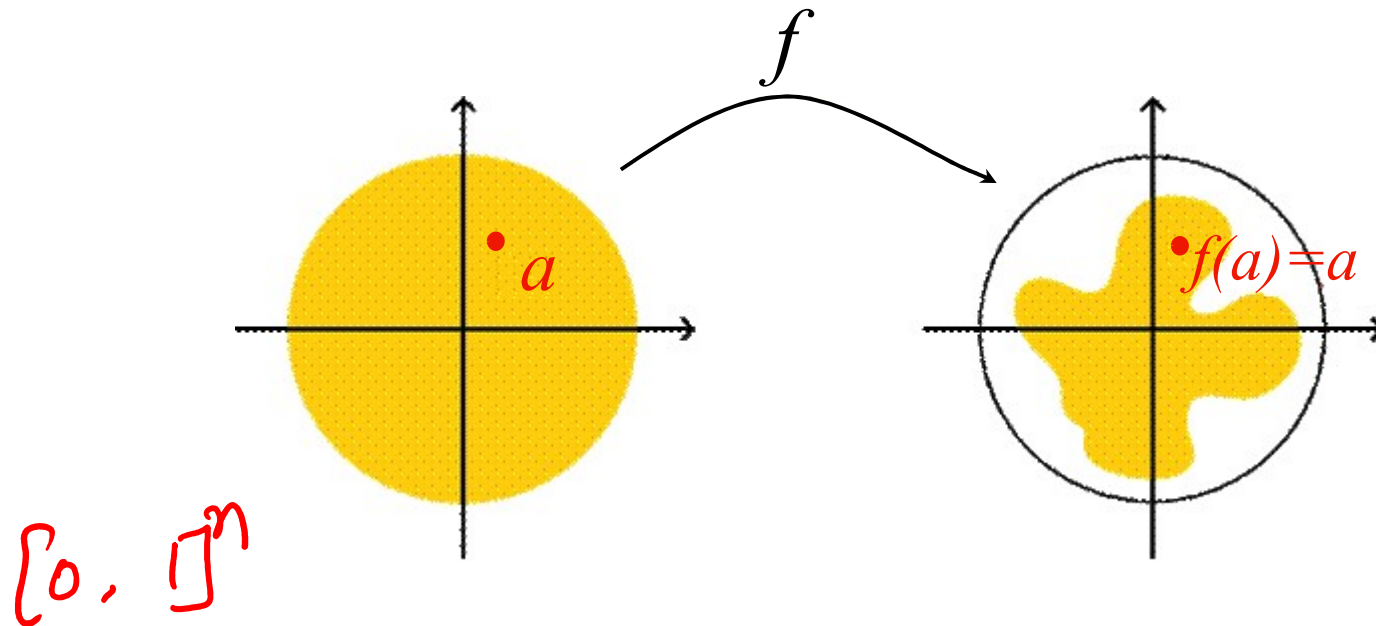
$\Rightarrow$  Convex set is NE

$\Rightarrow$  Same payoff at all NE.

$\vdots$

# Computation in general?

NE existence via fixed-point theorem.



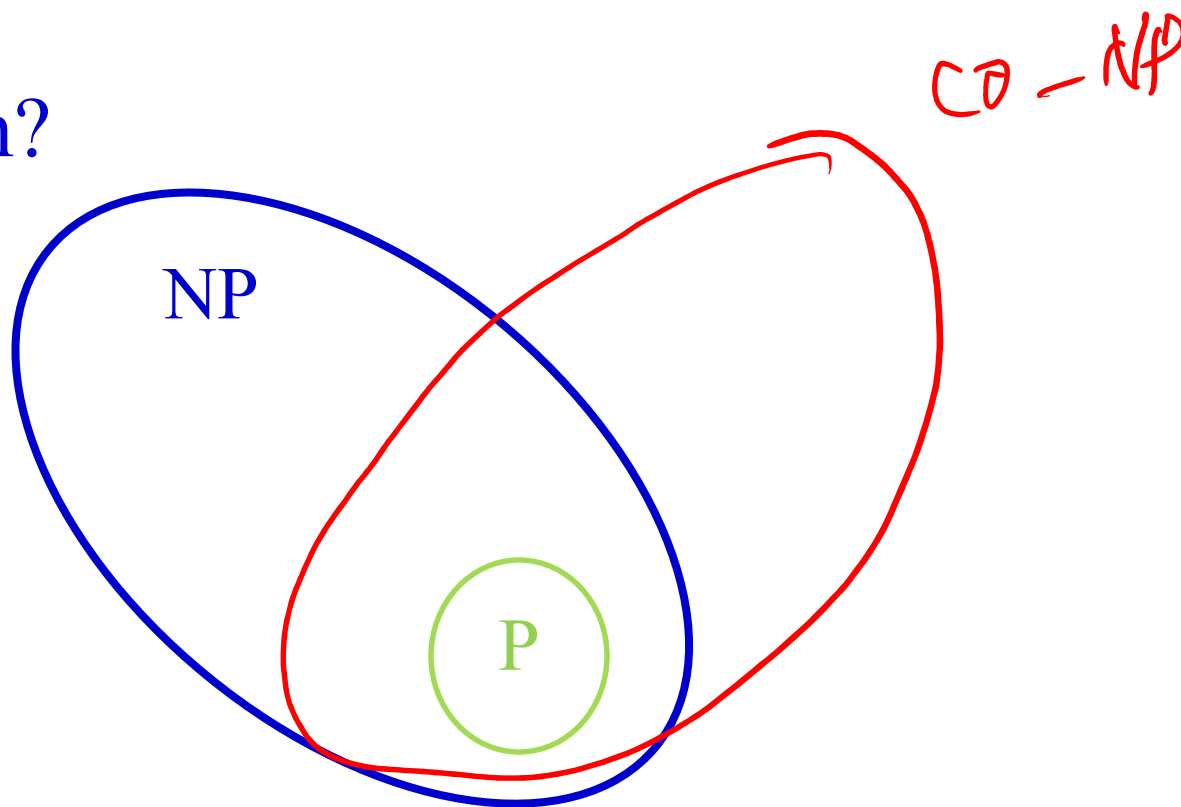
# Computation? (in Econ)

- Special cases: Dantzig'51, Lemke-Howson'64, Elzen-Talman'88, Govindan-Wilson'03, ...
- Scarf'67: Approximate fixed-point.
  - Numerical instability
  - Not efficient!
- ...

# Computation? (in CS)

Not easy!

$\exists$  solution?



What if solution always exists, like Nash Eq.?

# Computation? (in CS)

Megiddo and Papadimitriou'91 :

Nash is NP-hard  $\Rightarrow$  NP=Co-NP

NP-hardness is ruled out!

# Complexity Classes

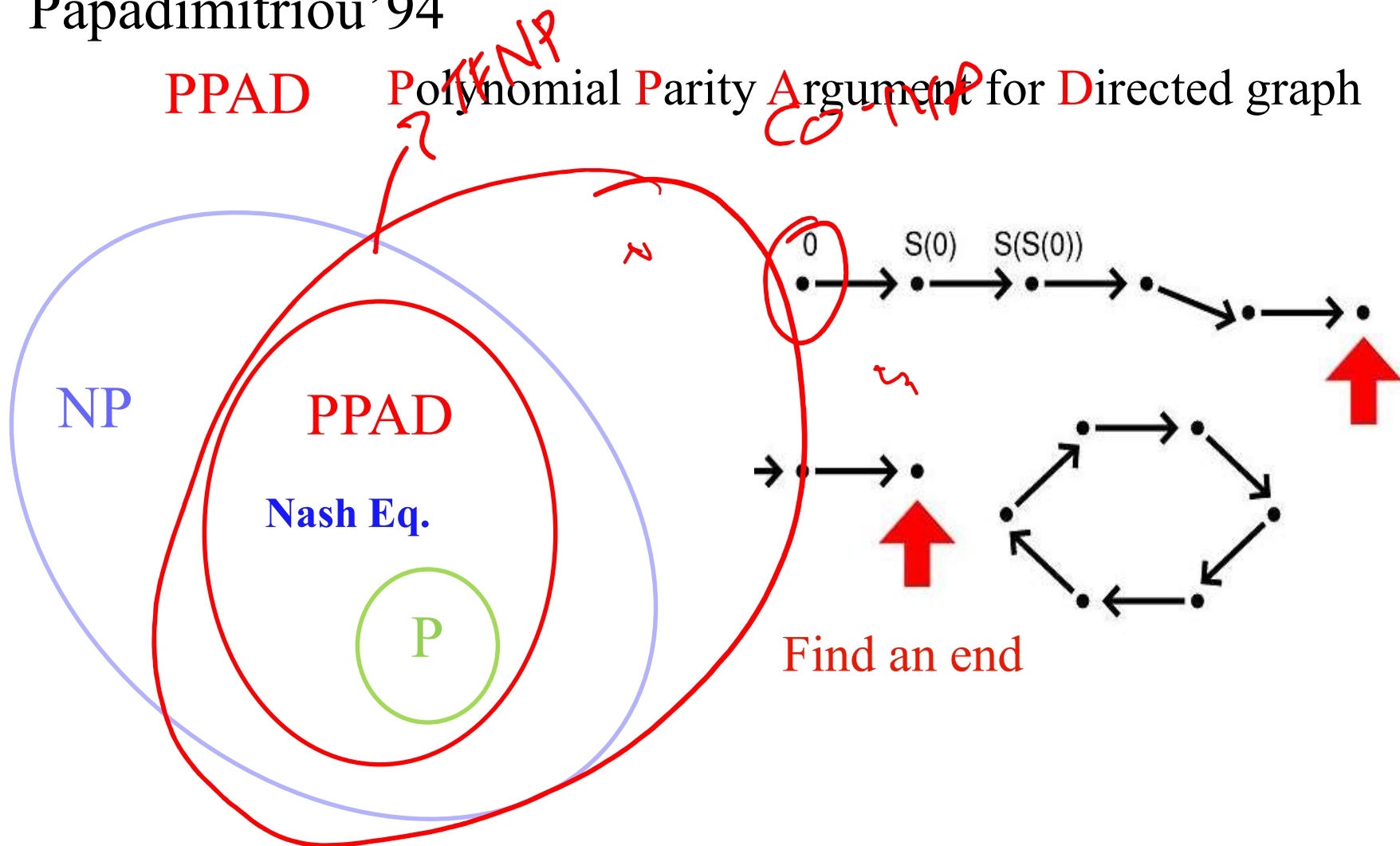
2-Nash is PPAD-complete!

[DGP'06, CDT'06]

Papadimitriou'94

PPAD

Polynomial Parity Argument for Directed graph



# Brute-force Algorithm?

$$P \quad \boxed{\begin{array}{l} \forall i, (A\mathbf{y})_i \leq \pi_A \\ \mathbf{y} \in \Delta_n \end{array}}$$

$$Q \quad \boxed{\begin{array}{l} \forall j, (\mathbf{x}^T B)_j \leq \pi_B \\ \mathbf{x} \in \Delta_m \end{array}}$$

Let  $(x, y)$  be a NE. Suppose we know  $\text{supp}(x)$  and  $\text{supp}(y)$ .

Now can we find a NE?







Can we do better?

**Not so far. And may be never!**

It is one of the hardest problems in PPAD.



# What about special cases/approximation?

- $\text{Rank}(A)$  or  $\text{rank}(B)$  is constant
- $O(1)$ -approximate NE: quasi-polynomial time algorithm
- Constant rank games:  $\text{rank}(A+B)$  is a constant
  - FPTAS

$$P \quad \begin{array}{l} \forall i, (Ay)_i \leq \pi_A \\ y \in \Delta_n \end{array}$$

$$Q \quad \begin{array}{l} \forall j, (x^T B)_j \leq \pi_B \\ x \in \Delta_m \end{array}$$

$$(y, \pi_A, x, \pi_B) \in P \times Q$$

**Theorem.** If  $(A, B)$  is zero-sum, i.e.,  $A + B = 0$ , then  
 2-Nash  $\rightarrow$  linear programming

$$\text{max: } -(\pi_A + \pi_B)$$

$$\text{s.t. } (y, \pi_A, x, \pi_B) \in P \times Q$$

**Rank of a game: rank(A+B)**

Zero-sum  $\equiv$  Rank-0 games

# Rank 1 Game

$$A + B = u \cdot v^T$$

$\downarrow$   
 $\in R^m$

$\searrow$   
 $\in R^n$

Bilinear

2-Nash

$$\max: x^T (A + B) y - (\pi_A + \pi_B)$$

$$\text{s.t. } (y, \pi_A, x, \pi_B) \in P \times Q$$

# Rank 1 Game [AGM.S'11]

$$A + B = u \cdot v^T$$

2-Nash

Product of two  
linear terms

$$\begin{aligned} \max: & \quad (x^T u)(v^T y) - (\pi_A + \pi_B) \\ \text{s.t.} & \quad (y, \pi_A, x, \pi_B) \in P \times Q \end{aligned}$$

Rank 1 QP is NP-hard in general



# Rank 1 Game [AGM.S'11]

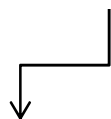
$$A + B = u \cdot v^T \longrightarrow (A, u, v)$$

## 2-Nash

$$\max: (x^T u)(v^T y) - (\pi_A + \pi_B)$$

s.t.

$$P \times Q$$



$$(x^T u)v^T - x^T A$$



# Think Big!

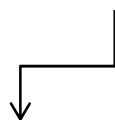
Consider game space  $\mathcal{S} = (A, *, v)$

## 2-Nash

$$\max: (x^T *)(v^T y) - (\pi_A + \pi_B)$$

s.t.

$$P \times Q$$



$$(x^T *)v^T - x^T A$$

# Think Big!

Consider game space  $S = (A, *, v)$  All NE of  $S$

**Complementarity**

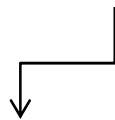
Captures

LP( $\lambda$ )

$$\max: \lambda(v^T y) - (\pi_A + \pi_B)$$

s.t.

$$P \times Q$$



$$\lambda v^T - x^T A$$

Solutions of LP( $\lambda$ )

$$\forall \lambda \in \mathbb{R}$$



**Claim.** For any  $\lambda \in \mathbb{R}$ , optimal value of  $\text{LP}(\lambda)$  is zero.

$$\begin{array}{ll}
 \text{max:} & \lambda(v^T y) - (\pi_A + \pi_B) \\
 \text{s.t.} & \begin{array}{c} P \times Q \\ \downarrow \end{array} \\
 \text{LP}(\lambda) & \lambda v^T - x^T A
 \end{array}$$

$\lambda$

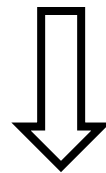


LP( $\lambda$ )



$(y, \pi_R, x, \pi_C)$

Goal: NE of  $(R, \mathbf{u}, v)$



$(m-1)$ -dimensional  
space in  $\mathcal{S}$

If  $\mathbf{u}$  one of them  
then done!

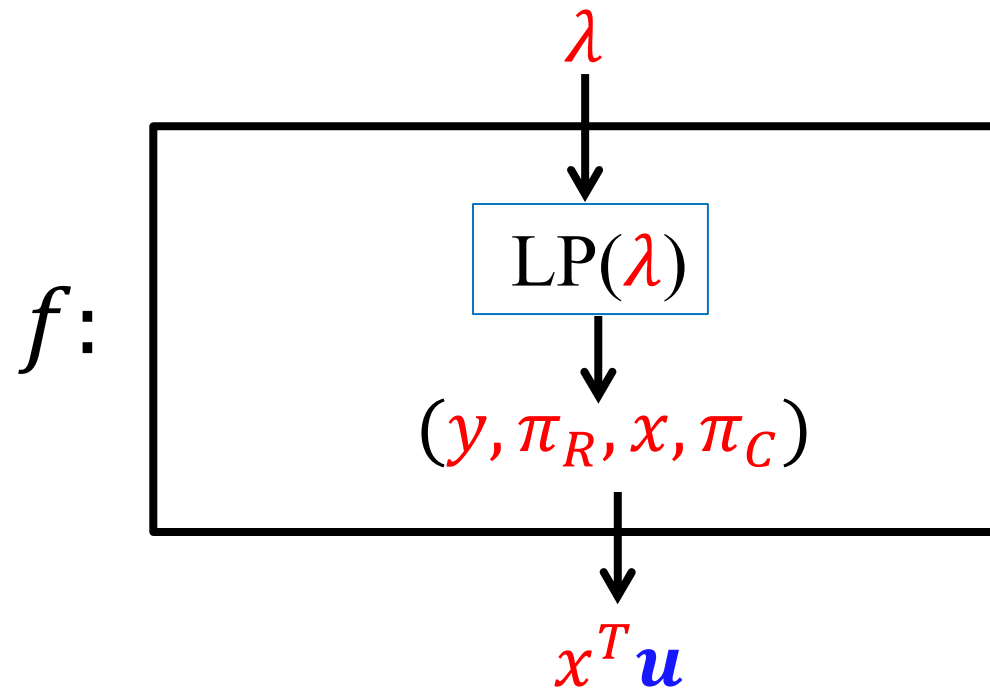
**Claim:**

$\forall \mathbf{c}$  s.t.  $x^T \mathbf{c} = \lambda,$

$(x, y)$  is a NE of game  $(R, \mathbf{c}, v)$

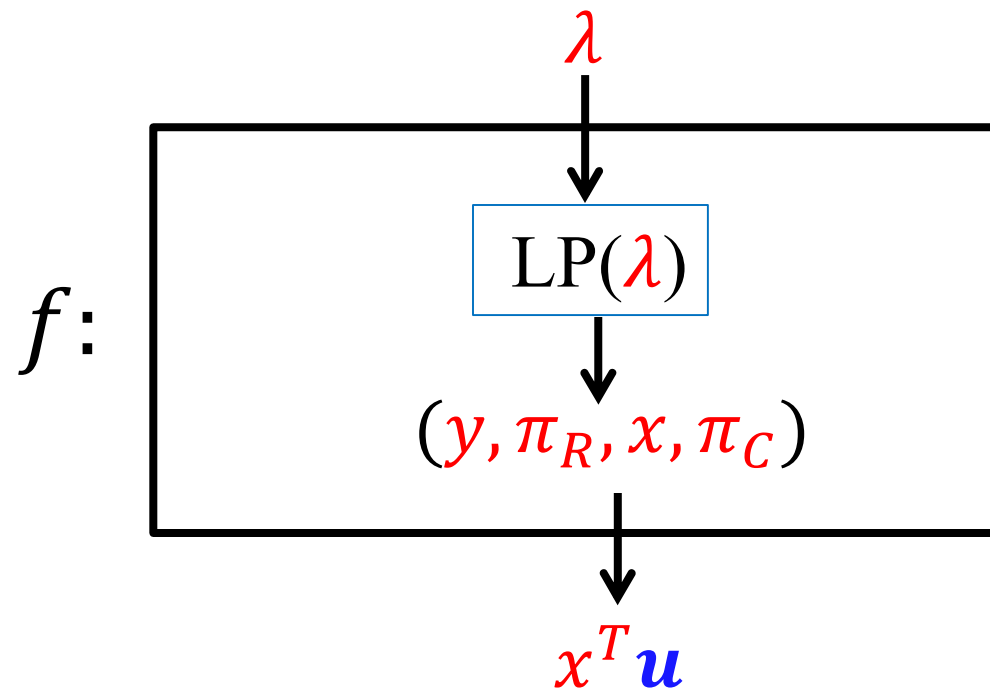


Goal: NE of game  $(R, \mathbf{u}, \mathbf{v})$



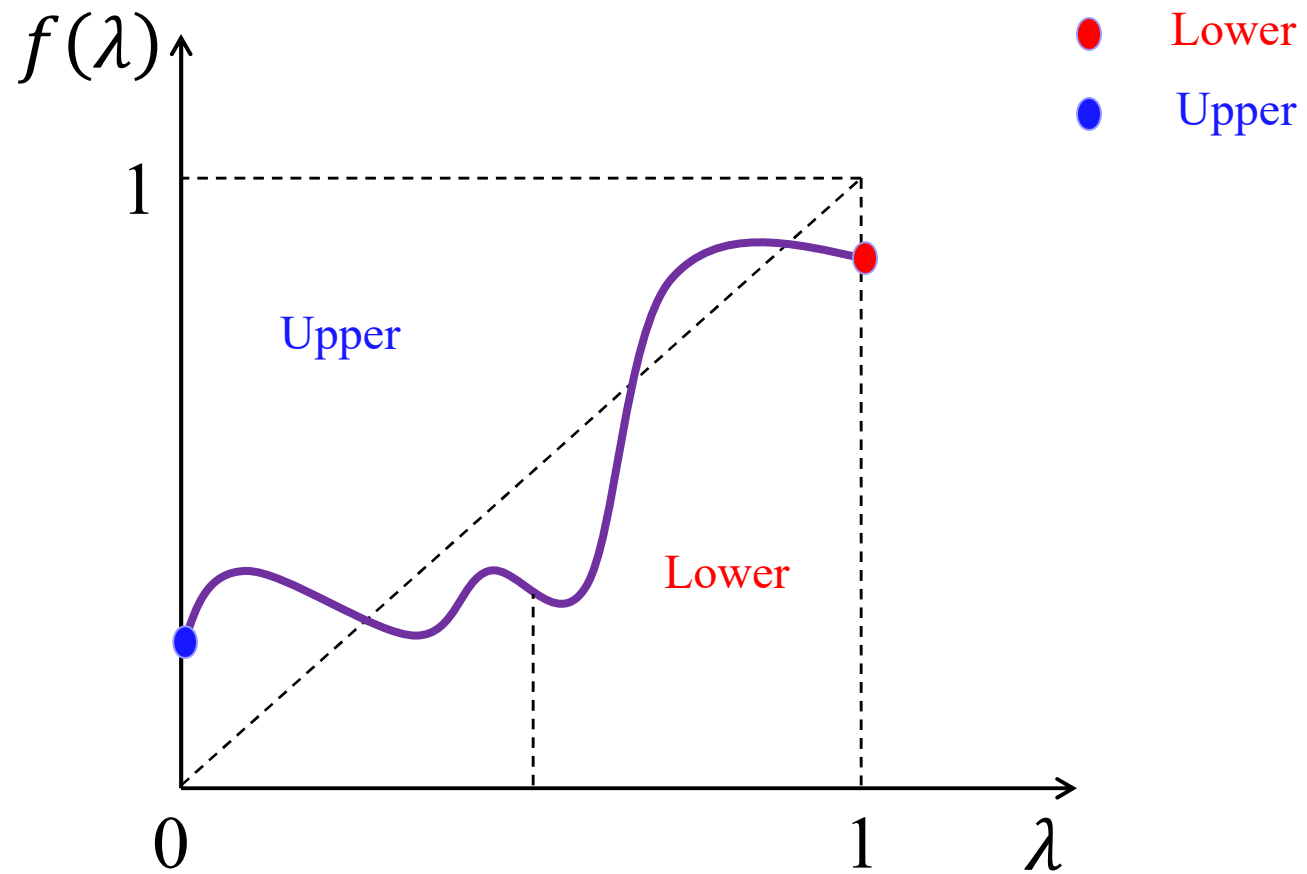
If  $x^T \mathbf{u} = \lambda$  then done!

Goal: NE of game  $(R, \mathbf{u}, \mathbf{v})$

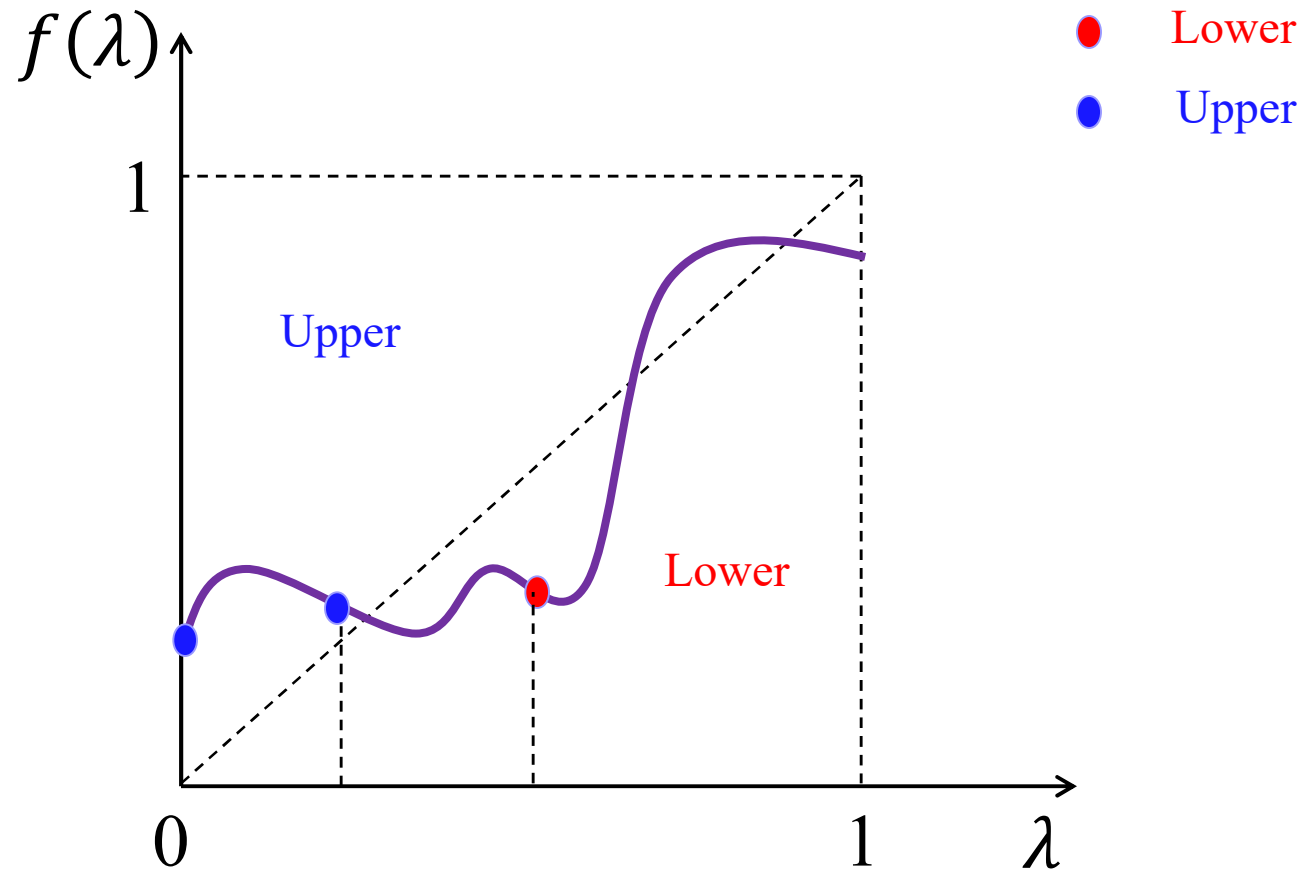


NE of game  $(R, \mathbf{u}, \mathbf{v}) \iff \lambda \leftarrow \text{Fixed points of } f$

# 1-D Fixed Point



# 1-D Fixed Point



And so on until the difference becomes small enough



What about rank-2 or more?



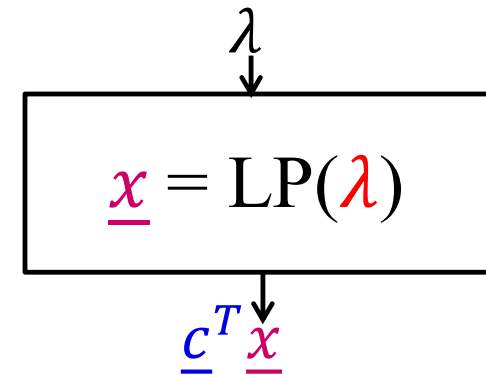
Rank-0 (zero-sum)  
games  $\text{rank}(A+B)=0$

$\longrightarrow$   
Von Neumann  
(1928)

LP

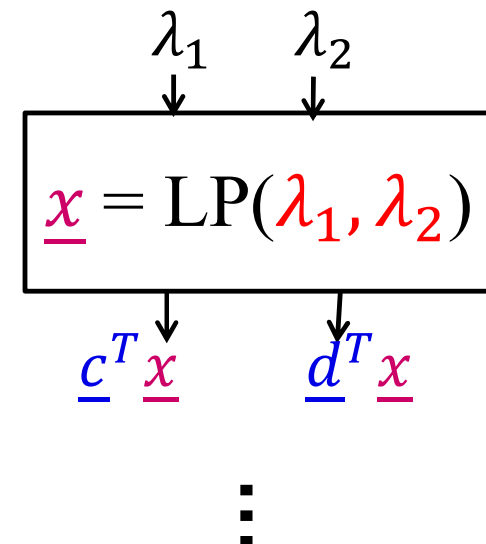
Rank-1 games  
 $\text{rank}(A+B)=1$


$\longrightarrow$



Rank-2 games  
 $\text{rank}(A+B)=2$

$\longrightarrow$





Rank-0 (zero-sum)  
games

→  
Von Neumann  
(1928)

LP

Rank-1 games



1-D Fixed  
Point

**In P**




Rank-2 games



2-D Fixed  
Point

⋮



Rank-0 (zero-sum)  
games

→  
Von Neumann  
(1928)

LP

Rank-1 games



1-D Fixed  
Point

**PPAD-hard  
in general**




Rank-2 games



2-D Fixed  
Point

⋮

⋮



Rank-0 (zero-sum)  
games

→  
Von Neumann  
(1928)

LP

Rank-1 games

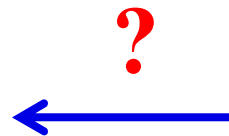


1-D Fixed  
Point

**PPAD-hard  
in general**



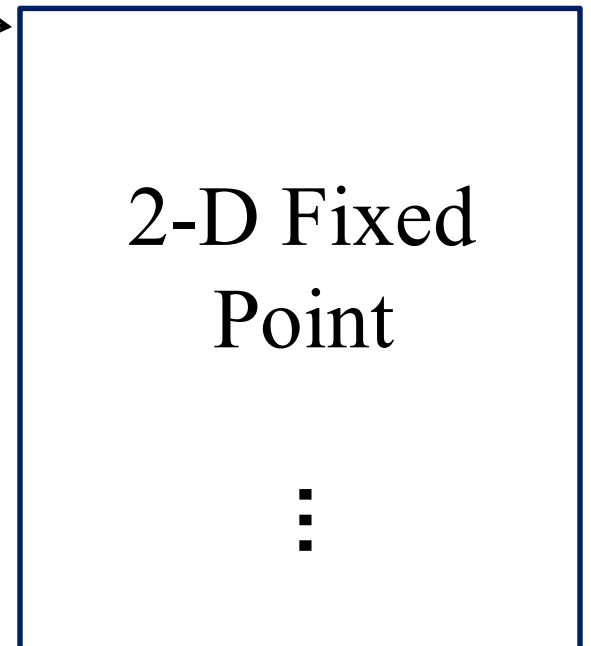
Rank-2 games




2-D Fixed  
Point

⋮

⋮





Rank-0 (zero-sum)  
games

→  
Von Neumann  
(1928)

LP

Rank-1 games



1-D Fixed  
Point

**PPAD-hard  
in general**



Rank-2 games

←  
[M.'14, COPY'16]

2-D Fixed  
Point

⋮

⋮