Computational Complexity

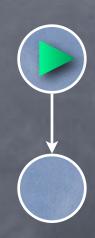
Lecture 1
in which we talk about
Time Complexity, P, NP and coNP

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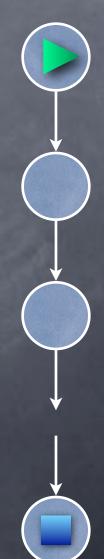
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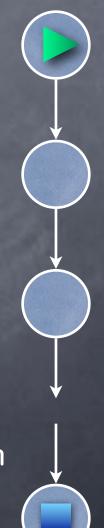
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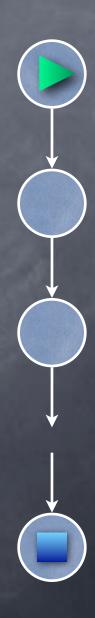


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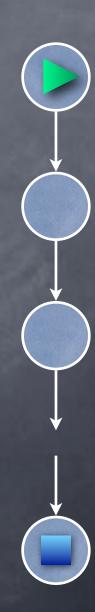


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 - input explicitly encoded in the initial configuration
- At every step the configuration evolves
- Until computation terminates: final configuration
 - output explicitly encoded in the final configuration (say, in the control-state)





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- Time Complexity of language L (worst case): if there is a TM that decides L (correct on all instances), and for any input instance of size n, it takes at most T(n) steps then L in class DTIME(T)
 - (Note: complexity T is a <u>function</u> of n)

If a problem is in DTIME(T) and T(n)=O(n^c) for some c, then the problem is in P

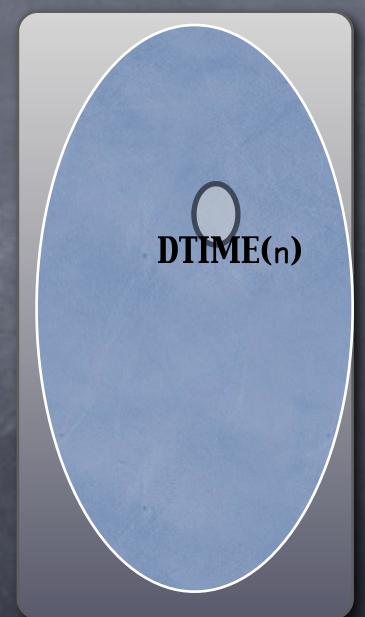
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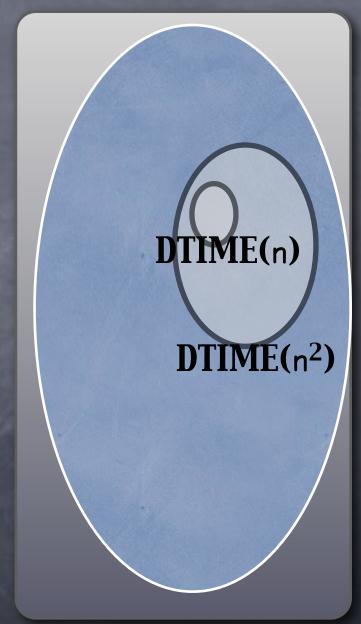
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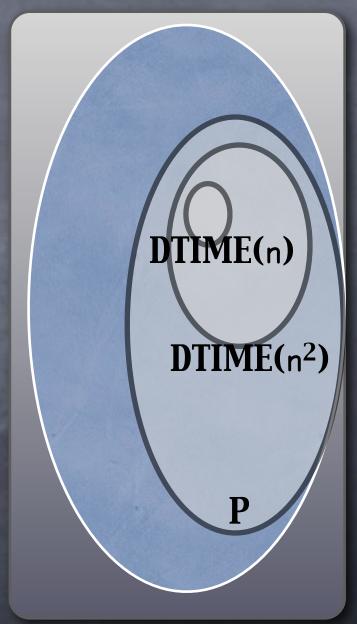
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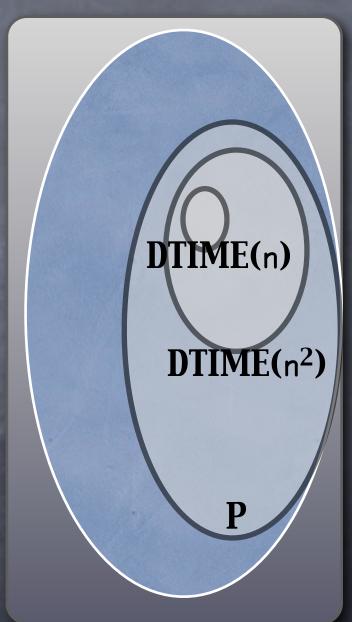


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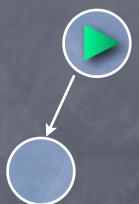


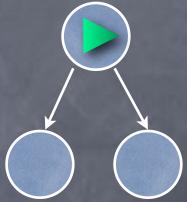
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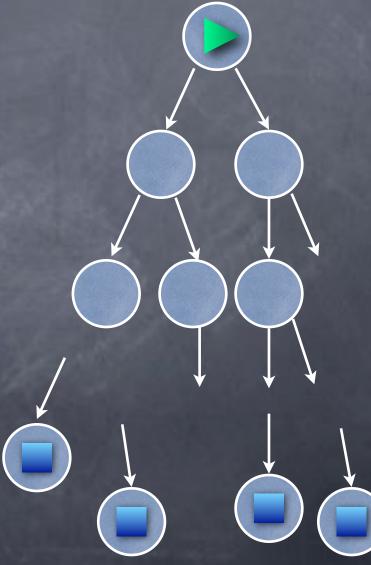
- Θ P = $\bigcup_{a,b,c > 0}$ DTIME(a.n^c+b)
- DTIME(T) depends on the specifics of the TM model (no. of tapes, alphabet size)
- But P is robust: Models can simulate each other with only "polynomial slow down"







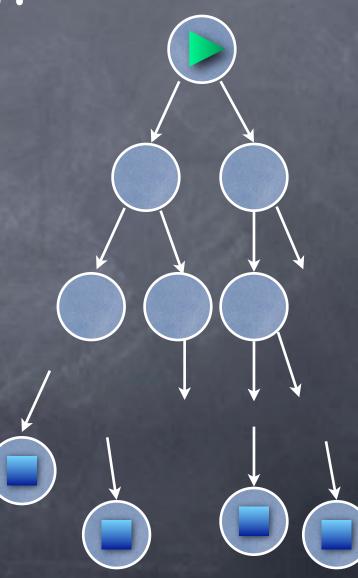




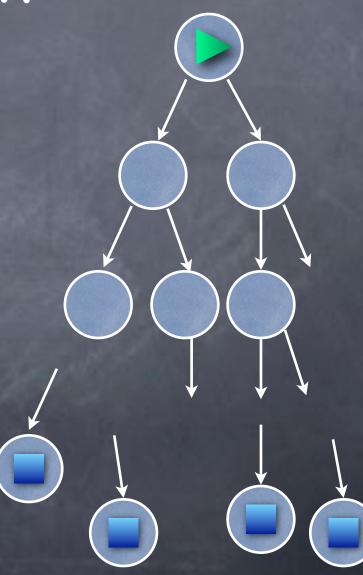
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- □ L ∈ NTIME(T): an NTM decides L in time at most T



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 - Finding a certificate (or even finding if there exists a certificate) may take longer

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- input: x and cert. w

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- Note: Completeness and soundness

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- All problems in P (empty certificate)

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- Solve all sorts of optimization problems efficiently!

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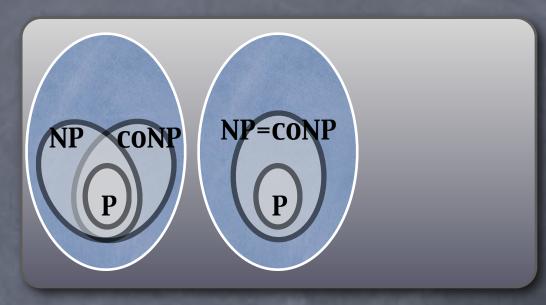
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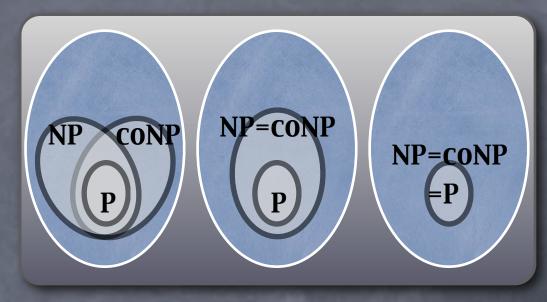
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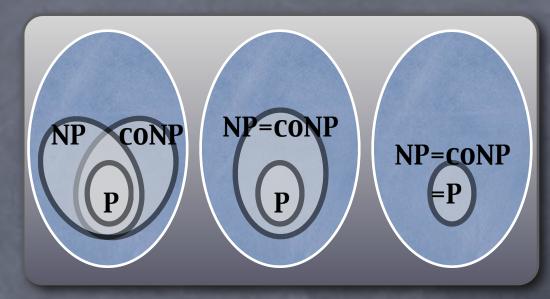
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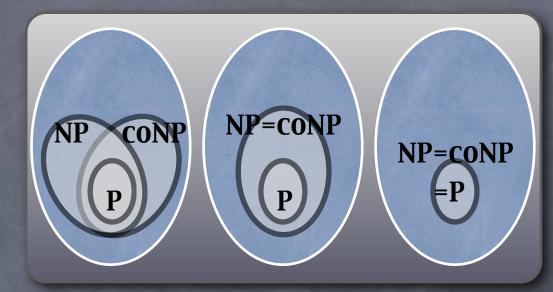




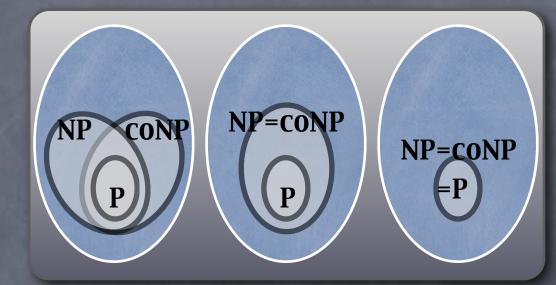
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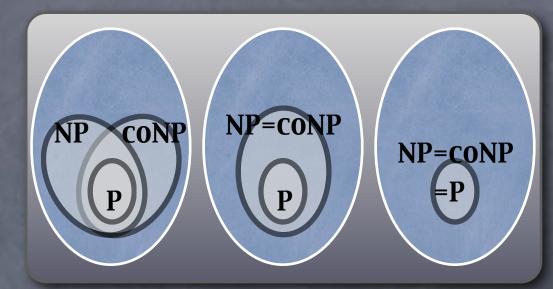


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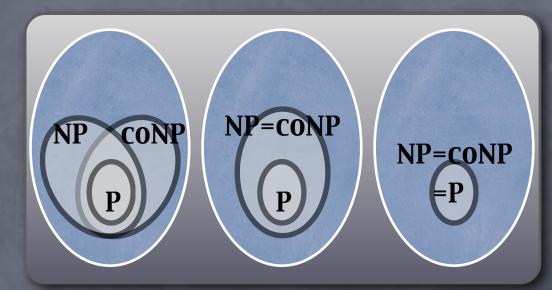
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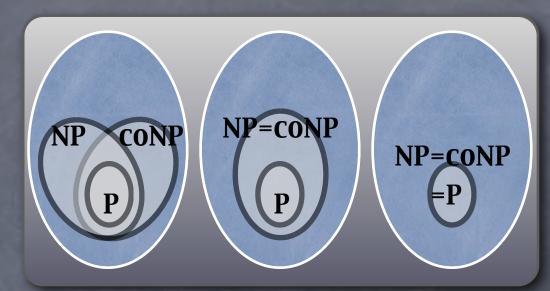
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- Also, EXP = NEXP [Exercise]
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- If P=NP, then the complexity landscape would get greatly simplified than believed (more later)

DTIME

- © DTIME
 - P, EXP

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 - Two views: non-determinism and certificate

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 - Two views: co-NTM and "no counter-example"

NP completeness

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 - a la reductions (of course)