Demo: Application of Introduction Rule

• unifies first premise of rule with an assumption

Applying Elimination Rules

- eliminates that assumption instead of conclusion
- proof (rule ...) generally does the work of erule in Isar.

apply (erule <elim-rule>)

EL 1.6 .

Like rule but also

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 $[\![?P \land ?Q; [\![?P;?Q]\!] \Longrightarrow ?R]\!] \Longrightarrow ?R$ 

Example

Rule:

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Subgoal: 1.  $[X; A \land B; Y] \Longrightarrow Z$ 

Unification:  $?P \land ?Q \equiv A \land B \text{ and } ?R \equiv Z$ 

New subgoal: 1.  $[\![X;Y]\!] \Longrightarrow [\![A;B]\!] \Longrightarrow Z$ 

 $\text{Same as:} \qquad \quad 1. [\![X;Y;A;B]\!] \Longrightarrow Z$ 

How to Prove in Natural Deduction

ullet Intro rules decompose formulae to the  $\emph{right}$  of  $\Longrightarrow$ 

apply (rule <intro-rule>)
proof (rule <intro-rule>)

ullet Elim rules decompose formulae to the left of  $\Longrightarrow$ 

apply (erule <elim-rule>)
proof (rule <elim-rule>)

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Safe and Unsafe Rules

Safe rules preserve provability:

conjI, impI, notI, iffI, refl, ccontr, classical, conjE, disjE

Unsafe rules can reduce a provable goal to one that is not:

disjI1, disjI2, impE, iffD1, iffD2, notE

Try safe rules before unsafe ones

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Demo: Examples

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### $\Longrightarrow$ vs $\longrightarrow$

• Theorems usually more useful written as

$$[\![A_1;\ldots;A_n]\!] \Longrightarrow A$$

instead of  $A_1 \wedge \ldots \wedge A_n \longrightarrow A$  (easier to apply)

- Exception: (in apply-style): induction variable must not occur in
- Example: For induction on x, transform:

$$[A; B(x)] \Longrightarrow C(x) \rightsquigarrow A \Longrightarrow B(x) \longrightarrow C(x)$$

• Reverse transformation (after proof):

```
lemma abc [rule_format]: A \Longrightarrow B(x) \longrightarrow C(x)
```

Demo: Further Techniques

# lpha-Conversion and Scope of Variables

•  $\forall x$ . P x: x can appear in P x.

Example:  $\forall x. \ x = x$  is obtained by  $P \mapsto \lambda u. \ u = u$ 

•  $\forall x$ . P: x cannot appear in P

Example:  $P \mapsto x = x$  yields  $\forall x'$ . x = x

Bound variables are renamed automatically to avoid name clashes with other variables.

# Natural Deduction Rules for Quantifiers

$$\frac{\text{Ax. P x}}{\forall \text{x.P x}} \, \text{allI} \qquad \frac{\forall \text{x. P x} \quad \text{P ?x} \Longrightarrow R}{R} \, \text{allE}$$

$$\frac{P ? x}{\exists x. \ P \ x} \ exI \qquad \frac{\exists x. \ P \ x \qquad \Lambda x. \ P \ x \Longrightarrow R}{R} \ exE$$

- allI and exE introduce new parameters  $(\Lambda x)$
- allE and exI introduce new unknowns (?x)

# Safe and Unsafe Rules

Safe: allI, exE

Unsafe: allE, exI

Create parameters first, unknowns later

# Instantiating Variables in Rules

proof (rule\_tac x = "term" in rule)

Like rule, but ?x in rule is instantiated with term before application. ?x must be schematic variable occurring in statement of rule.

Similar: erule\_tac

! x is in rule, not in goal!

# 

# Two Unsuccessful Apply-Style Proof Attempts

```
1. \exists y. \ \forall x. \ x = y

apply(rule_tac apply (rule exI)

x = ???? \text{ in exI})

1. \forall x. \ x = ?y

apply(rule allI)

1. \land x. \ x = ?y

apply(rule refl)

?y \mapsto x \text{ yields } \land x'. \ x' = x
```

Principles: ?f  $x_1 \dots x_n$  can only be replaced by term t if  $params(t) \subseteq \{x_1, \dots, x_n\}$ 

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#### Parameter Names

Parameter names are chosen by Isabelle

```
    ∀x. ∃y. x = y apply(rule allI)
    Λx. ∃y. x = y apply(rule_tac x = "x" in exI)
```

Works, but is brittle!!

Better to use Isar, where you choose the name.

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Rule:  $\|A_1; \dots; A_m\| \Longrightarrow A$ 

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#### Forward Proofs: frule and drule

```
"Forward" rule: A_1 \Longrightarrow A
Subgoal: 1. \ [B_1; \ldots; B_n] \Longrightarrow C
Substitution: \sigma(B_i) \equiv \sigma(A_1)
```

New subgoal: 1.  $\sigma([B_1; ...; B_n; A] \Longrightarrow C)$ 

Command:

apply(frule < rulename >)

Like **frule** but also deletes B<sub>i</sub>:

apply(drule < rulename >)

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frule and drule: The General Case

```
Creates additional subgoals:  \begin{aligned} 1. \ \sigma( \| B_1; \dots; B_n \| \Longrightarrow A_2 ) \\ \vdots \\ m-1. \ \sigma( \| B_1; \dots; B_n \| \Longrightarrow A_m ) \\ m. \ \sigma( \| B_1; \dots; B_n; A \| \Longrightarrow C ) \end{aligned}
```

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#### Forward Proofs: OF

```
r [OF r_1 ... r_n]
```

Prove assumption 1 of theorem r with theorem  $r_1$ , and assumption 2 with theorem  $r_2$ , etc.

Rule r  $[\![A_1;\ldots;A_m]\!] \Longrightarrow A$ Rule  $r_1$  $[\![B_1;\ldots;B_n]\!] \Longrightarrow B$ Substitution  $\sigma(B) \equiv \sigma(A_1)$ 

 $r [OF r_1]$  $\sigma(\llbracket B_1; \ldots; B_n; A_2; \ldots; A_m \rrbracket \Longrightarrow A)$ 

# Forwards Proofs: THEN

 $r_1$ [THEN  $r_2$ ]  $r_2[OF r_1]$ means

#### Forward Proofs: of

Given a theorem like gcd\_mult\_distrib2:

?k \* gcd (?m, ?n) = gcd (?k \* ?m, ?k \* ?n) We want to replace ?m by 1. of instantiates variables left to right In above the order is ?k, ?m, and ?n [of k 1] replaces ?k by k, and ?m by 1. 

Forward Proofs: 1emmas

k = gcd (k, k \* ?n)

#### Forward Proofs: where

Alternately, with where you can specify the variable to get the term: gcd\_mult\_distrib2 [where m = "1"] yields
?k \* gcd (1, ?n) = gcd (?k \* 1, ?k \* ?n)
Same result given by gcd\_mult\_distrib2 [of \_ 1] and gcd\_mult\_distrib2 [where m = "1" and k = "k"] yields k \* gcd (1, ?n) = gcd (k \* 1, k \* ?n)

Caution: of and where cannot use goal parameters

# Forward Proofs: lemmas

• Can use lemmas to capture result of forward proof: • Can combine multiple steps together: lemmas gcd\_mult0 = gcd\_mult\_distrib2 [of k 1] lemmas gcd\_mult =

```
gcd_mult_distrib2 [of _ 1, simplified, THEN sym]
gcd (?k, ?k * ?n) = ?k
```

• [simplified] applies simp to theorem

• Can follow on with more forward reasoning:

lemmas gcd\_mult1 = gcd\_mult0 [simplified] yields

### Adding Assumptions to Goals

```
lemminsert, thm insert, thm: as new assumption to current subgoal
"[\![ \gcd(\mathtt{k},\mathtt{n}) = 1; \ \mathtt{k} \ \mathtt{dvd} \ \mathtt{m} * \mathtt{n} ]\![ \Longrightarrow \mathtt{k} \ \mathtt{dvd} \ \mathtt{m}"
apply (insert gcd_mult_distrib2 [of m k n])
[\gcd(k,n)=1; k \text{ dvd } m*n; m*\gcd(k,n)=\gcd(m*k,m*n)] \Longrightarrow k \text{ dvd}
```

# Adding Assumptions to Goals

Note: of and where can use only original user variables, but not Isabelle generated parameters

cut\_tac k="m" and m="k" and n="n" in gcd\_mult\_distrib2 yields same result as above

cut\_tac can use parameters

Adding Assumptions to Goals: subgoal\_tac

yields

 $1. \quad \llbracket A_1; \ldots; A_n \rrbracket \Longrightarrow A$ 

apply (subgoal\_tac "asm")

 $\textbf{1.}\quad [\![\textbf{A}_1;\ldots;\textbf{A}_n;\texttt{asm}]\!] \Longrightarrow \textbf{A}$  $2. \quad \llbracket \mathtt{A}_1; \ldots; \mathtt{A}_n \rrbracket \Longrightarrow \mathtt{asm}$ 

# Adding Assumptions to Goals: subgoal\_tac

- Can always add assumption asm to current subgoal with apply (subgoal\_tac "asm")
- Statement can use Isabelle parameters
- Adds new subgoal asm with same assumptions as current subgoal

#### Removing Assumptions: thin\_tac

- Can remove unwanted assumption asm from current subgoal with apply (thin\_tac "asm")
  - $\textbf{1.}\quad \llbracket \textbf{A}_1;\ldots;\textbf{A}_{i-1};\textbf{A}_i;\textbf{A}_{i+1};\ldots;\textbf{A}_n\rrbracket \Longrightarrow \textbf{A}$ apply (thin\_tac "A;")

yields

 $\textbf{1.}\quad [\![\textbf{A}_1;\ldots;\textbf{A}_{i-1};\textbf{A}_{i+1};\ldots;\textbf{A}_n;\texttt{asm}]\!] \Longrightarrow \textbf{A}$ 

# "Clarifying" the Goal

- proof (intro ...) Repeated application of intro rules
  - Example: proof (intro allI)
- proof (elim ...)

Repeated application of elim rules

- Example: proof (elim conjE)
- proof (clarify)

Repeated application of safe rules without splitting goal

• proof (clarsimp simp add: ...) Combination of clarify and simp

# Other Automated Proof Methods

- blast Isabelle's most powerful classical reasoner.
   Useful for goals stated using only predicate logic and set theory
   Can be extended with rules (with [iff] attribute) to handler broader classes of goals
- auto

Applies to all subgoals.

Combines classical reasoning with simplification

Does what it can; leaves unfinished subgoals

Splits subgoals

• force

Similar to  ${\tt auto}$ , but only applies to one goal, and either finishes or fails.

• safe

Like clarify but also splits goals

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Demo: Proof Methods

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