

Topics in Automated Deduction (CS 576)

Elsa L. Gunter

2112 Siebel Center

egunter@illinois.edu

<http://www.cs.illinois.edu/class/sp10/cs576/>

More Rules

$$\frac{A \wedge B}{A} \text{ conjunct1} \quad \frac{A \wedge B}{B} \text{ conjunct2}$$

$$\frac{A \longrightarrow B \quad A}{B} \text{ mp}$$

Compare to elimination rules:

$$\frac{A \wedge B \quad [A; B] \Longrightarrow C}{C} \text{ conjE}$$

$$\frac{A \longrightarrow B \quad A \quad B \Longrightarrow C}{C} \text{ impE}$$

“Classical” Rules

$$\frac{\neg A \implies \text{False}}{A} \text{ ccontr} \qquad \frac{\neg A \implies A}{A} \text{ classical}$$

- `ccontr` and `classical` are not derivable from the Natural Deduction rules.
- They make the logic “*classical*”, i.e. “*non-constructive* or “*non-intuitionistic*”.

Proof by Assumption

$$\frac{A_1 \dots A_i \dots A_n}{A_i}$$

Rule Application: The Rough Idea

Applying rule $\llbracket A_1; \dots; A_n \rrbracket \implies A$ to subgoal C :

- Unify A and C
- Replace C with n new subgoals: $A'_1 \dots A'_n$

Backwards reduction, like in Prolog

Example: rule: $\llbracket ?P; ?Q \rrbracket \implies ?P \wedge ?Q$

subgoal: 1. $A \wedge B$

Result: 1. A
2. B

Rule Application: More Complete Idea

Applying rule $\llbracket A_1; \dots; A_n \rrbracket \implies A$ to subgoal C :

- Unify A and C with (meta)-substitution σ
- Specialize goal to $\sigma(C)$
- Replace C with n new subgoals: $\sigma(A_1) \dots \sigma(A_n)$

Note: schematic variables in C treated as existential variables

Does there exist value for $?X$ in C that makes C true?
(Still not the whole story)

rule Application

Rule: $\llbracket A_1; \dots; A_n \rrbracket \implies A$

Subgoal: 1. $\llbracket B_1; \dots; B_m \rrbracket \implies C$

Substitution: $\sigma(A) \equiv \sigma(C)$

New subgoals: 1. $\llbracket \sigma(B_1); \dots; \sigma(B_m) \rrbracket \implies \sigma(A_1)$
:
 $n.$ $\llbracket \sigma(B_1); \dots; \sigma(B_m) \rrbracket \implies \sigma(A_n)$

Proves: $\llbracket \sigma(B_1); \dots; \sigma(B_m) \rrbracket \implies \sigma(C)$

Command: `apply (rule <rulename>)`

Proof by assumption

apply assumption

proves:

1. $\llbracket B_1; \dots; B_m \rrbracket \implies C$

by unifying C with one of the B_i

Demo: Application of Introduction Rule

Applying Elimination Rules

`apply (erule <elim-rule>)`

Like `rule` but also

- unifies first premise of rule with an assumption
- eliminates that assumption instead of conclusion

Example

Rule: $\llbracket ?P \wedge ?Q; \llbracket ?P; ?Q \rrbracket \Longrightarrow ?R \rrbracket \Longrightarrow ?R$

Subgoal: 1. $\llbracket X; A \wedge B; Y \rrbracket \Longrightarrow Z$

Unification: $?P \wedge ?Q \equiv A \wedge B$ and $?R \equiv Z$

New subgoal: 1. $\llbracket X; Y \rrbracket \Longrightarrow \llbracket A; B \rrbracket \Longrightarrow Z$

Same as: 1. $\llbracket X; Y; A; B \rrbracket \Longrightarrow Z$

How to Prove in Natural Deduction

- *Intro* rules decompose formulae to the *right* of \implies
`apply (rule <intro-rule>)`
- *Elim* rules decompose formulae to the *left* of \implies
`apply (erule <elim-rule>)`

Demo: Examples

Safe and Unsafe Rules

Safe rules preserve provability:

`conjI, impI, notI, iffI, refl, ccontr, classical, conje, disjE`

Unsafe rules can reduce a provable goal to one that is not:

`disjI1, disjI2, impE, iffD1, iffD2, notE`

Try safe rules before unsafe ones

\Longrightarrow **VS** \longrightarrow

- Theorems usually more useful written as

$$\llbracket A_1; \dots; A_n \rrbracket \Longrightarrow A$$

instead of $A_1 \wedge \dots \wedge A_n \longrightarrow A$ (easier to apply)

- **Exception:** (in `apply`-style): induction variable must not occur in premises

- Example: For induction on x , transform:

$$\llbracket A; B(x) \rrbracket \Longrightarrow C(x) \rightsquigarrow A \Longrightarrow B(x) \longrightarrow C(x)$$

Reverse transformation (after proof):

$$\text{lemma abc [rule_format]: } A \Longrightarrow B(x) \longrightarrow C(x)$$

Demo: Further Techniques

Parameters

Subgoal:

1. $\Lambda x_1 \dots x_n. Formula$

The x_i are called *parameters* of the subgoal

Intuition: local constants, i.e. arbitrary fixed values

Rules are automatically lifted passed $\Lambda x_1 \dots x_n$ and applied directly to *Formula*

Scope

- Scope of parameters: whole subgoal
- Scope of \forall , \exists , ...: ends with ; or \implies , or enclosing)

$$\Lambda xy. \llbracket \forall y. P y \longrightarrow Q z y; Q x y \rrbracket \implies \exists x. Q x y$$

means

$$\Lambda xy. \llbracket (\forall y_1. P y_1 \longrightarrow Q z y_1); Q x y \rrbracket \implies \exists x_1. Q x_1 y$$

α -Conversion and Scope of Variables

- $\forall x. P \ x$: x can appear in $P \ x$.

Example: $\forall x. x = x$ is obtained by $P \mapsto \lambda u. u = u$

- $\forall x. P$: x cannot appear in P

Example: $P \mapsto x = x$ yields $\forall x'. x = x$

Bound variables are renamed automatically to avoid name clashes with other variables.

Natural Deduction Rules for Quantifiers

$$\frac{\Lambda x. P x}{\forall x. P x} \text{ allI}$$

$$\frac{\forall x. P x \quad P ?x \implies R}{R} \text{ allE}$$

$$\frac{P ?x}{\exists x. P x} \text{ exI}$$

$$\frac{\exists x. P x \quad \Lambda x. P x \implies R}{R} \text{ exE}$$

- **allI** and **exE** introduce new parameters (Λx)
- **allE** and **exI** introduce new unknowns ($?x$)

Safe and Unsafe Rules

Safe: `allI`, `exE`

Unsafe: `allE`, `exI`

Create parameters first, unknowns later

Instantiating Variables in Rules

```
apply (rule_tac  $x = \textit{term}$  in  $rule$ )
```

Like `rule`, but $?x$ in $rule$ is instantiated with $term$ before application.

$?x$ must be schematic variable occurring in statement of $rule$.

Similar: `erule_tac`

! x is in rule, not in goal !

Two Successful Proofs

1. $\forall x. \exists y. x = y$
`apply (rule allI)`
1. $\Lambda x. \exists y. x = y$

Better practice:

`apply(rule_tac x = "x" in exI)`
1. $\Lambda x. x = x$
`apply (rule refl)`

simpler & cleaner

Exploration:

`apply (rule exI)`
1. $\Lambda x. x = ?yx$
`apply (rule refl)`
 $?y \mapsto \lambda u. u$

shorter & trickier