

# Topics in Automated Deduction (CS 576)

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# Basic Induction Heuristics

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- Theorems about recursive functions are proved by induction
- If  $f$  defined by induction on  $i$ th argument, proof is by induction of  $i$ th argument of  $f$

# Example: Tail Recursive Reverse

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```
primrec itrev :: 'a list  $\Rightarrow$  'a list  $\Rightarrow$  'a list where
  itrev [ ]      ys = ys |
  itrev (x#xs)  ys = itrev xs (x#ys)
```

```
lemma itrev xs [] = rev xs
```

This direction is easier to prove/use

lhs “more complex” than rhs

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Demo: first attempt at  $\text{itrev} = \text{rev}$

# Generalization (first kind)

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Replace constant arguments ([ ]) by variables:

```
lemma itrev xs ys = rev xs @ ys
```

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Demo: second attempt at  $itrev = rev$

# Generalization (second kind)

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Quantify all free variables by  $\forall$ ,  
except the induction variable

`lemma  $\forall$  ys. itrev xs ys = rev xs @ ys`

# Proof Basics

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- Isabelle uses *Natural Deduction* proofs
  - Uses *sequent* encoding
- Rule notation:

$$\frac{\text{Rule} \quad A_1 \dots A_n}{A}$$

Sequent Encoding

$$\llbracket A_1, \dots, A_n \rrbracket \Longrightarrow A$$

$$\frac{A_1 \dots \frac{B}{\vdots} A_i \dots A_n}{A}$$

$$\llbracket A_1, \dots, B \rrbracket \Longrightarrow A_i, \dots, A_n \rrbracket \Longrightarrow A$$

# Natural Deduction

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For each logical operator  $\oplus$ , have two kinds of rules:

**Introduction:** How can I prove  $A \oplus B$ ?

$$\frac{?}{A \oplus B}$$

**Elimination:** What can I prove using  $A \oplus B$ ?

$$\frac{\dots A \oplus B \dots}{?}$$

# Operational Reading

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$$\frac{A_1 \dots A_n}{A}$$

**Introduction** rule:

To prove  $A$  it suffices to prove  $A_1 \dots A_n$ .

**Elimination** rule:

If we know  $A_1$  and we want to prove  $A$   
it suffices to prove  $A_2 \dots A_n$

# Natural Deduction for Propositional Logic

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$$\frac{A \quad B}{A \wedge B} \text{ conjI}$$

$$\frac{A \wedge B \quad [A; B] \Longrightarrow C}{C} \text{ conjE}$$

$$\frac{A}{A \vee B} \quad \frac{B}{A \vee B} \text{ disjI1/2}$$

$$\frac{A \vee B \quad A \Longrightarrow C \quad B \Longrightarrow C}{C} \text{ disjE}$$

$$\frac{A \Longrightarrow B}{A \longrightarrow B} \text{ impI}$$

$$\frac{A \longrightarrow B \quad A \quad B \Longrightarrow C}{C} \text{ impE}$$

# Natural Deduction for Propositional Logic

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$$\frac{A \implies B \quad B \implies A}{A = B} \text{ iffI} \qquad \frac{A = B \quad A}{B} \text{ iffD1}$$

$$\frac{A = B \quad B}{A} \text{ iffD2}$$

$$\frac{A \implies \text{False}}{\neg A} \text{ notI}$$

$$\frac{\neg A \quad A}{B} \text{ notE}$$

# Equality

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$$\frac{}{t = t} \text{ refl} \quad \frac{s = t}{t = s} \text{ sym} \quad \frac{r = s \quad s = t}{r = t} \text{ trans}$$
$$\frac{s = t \quad A(s)}{A(t)} \text{ subst}$$

`subst` rarely needed explicitly – used implicitly by `simp`

# More Rules

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$$\frac{A \wedge B}{A} \text{ conjunct1} \quad \frac{A \wedge B}{B} \text{ conjunct2}$$

$$\frac{A \longrightarrow B \quad A}{B} \text{ mp}$$

Compare to elimination rules:

$$\frac{A \wedge B \quad [A; B] \Longrightarrow C}{C} \text{ conjE}$$

$$\frac{A \longrightarrow B \quad A \quad B \Longrightarrow C}{C} \text{ impE}$$

# “Classical” Rules

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$$\frac{\cancel{A} \implies \text{False}}{A} \text{ ccontr} \qquad \frac{\cancel{A} \implies A}{A} \text{ classical}$$

- `ccontr` and `classical` are not derivable from the Natural Deduction rules.
- They make the logic “*classical*”, i.e. “*non-constructive* or “*non-intuitionistic*”.

# Proof by Assumption

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$$\frac{A_1 \dots A_i \dots A_n}{A_i}$$

# Rule Application: The Rough Idea

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Applying rule  $\llbracket A_1; \dots; A_n \rrbracket \implies A$  to subgoal  $C$ :

- Unify  $A$  and  $C$
- Replace  $C$  with  $n$  new subgoals:  $A'_1 \dots A'_n$

Backwards reduction, like in Prolog

Example: rule:  $\llbracket ?P; ?Q \rrbracket \implies ?P \wedge ?Q$

subgoal: 1.  $A \wedge B$

Result: 1.  $A$   
2.  $B$

# Rule Application: More Complete Idea

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Applying rule  $\llbracket A_1; \dots; A_n \rrbracket \implies A$  to subgoal  $C$ :

- Unify  $A$  and  $C$  with (meta)-substitution  $\sigma$
- Specialize goal to  $\sigma(C)$
- Replace  $C$  with  $n$  new subgoals:  $\sigma(A_1) \dots \sigma(A_n)$

Note: schematic variables in  $C$  treated as existential variables

Does there exist value for  $?X$  in  $C$  that makes  $C$  true?  
(Still not the whole story)

## rule Application

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Rule:  $\llbracket A_1; \dots; A_n \rrbracket \implies A$

Subgoal: 1.  $\llbracket B_1; \dots; B_m \rrbracket \implies C$

Substitution:  $\sigma(A) \equiv \sigma(C)$

New subgoals: 1.  $\llbracket \sigma(B_1); \dots; \sigma(B_m) \rrbracket \implies \sigma(A_1)$   
:  
 $n.$   $\llbracket \sigma(B_1); \dots; \sigma(B_m) \rrbracket \implies \sigma(A_n)$

Proves:  $\llbracket \sigma(B_1); \dots; \sigma(B_m) \rrbracket \implies \sigma(C)$

Command: `apply (rule <rulename>)`

# Proof by assumption

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apply assumption

proves:

1.  $\llbracket B_1; \dots; B_m \rrbracket \implies C$

by unifying  $C$  with one of the  $B_i$

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## Demo: Application of Introduction Rule

# Applying Elimination Rules

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`apply (erule <elim-rule>)`

Like `rule` but also

- unifies first premise of rule with an assumption
- eliminates that assumption instead of conclusion

# Example

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Rule:  $\llbracket ?P \wedge ?Q; \llbracket ?P; ?Q \rrbracket \Longrightarrow ?R \rrbracket \Longrightarrow ?R$

Subgoal: 1.  $\llbracket X; A \wedge B; Y \rrbracket \Longrightarrow Z$

Unification:  $?P \wedge ?Q \equiv A \wedge B$  and  $?R \equiv Z$

New subgoal: 1.  $\llbracket X; Y \rrbracket \Longrightarrow \llbracket A; B \rrbracket \Longrightarrow Z$

Same as: 1.  $\llbracket X; Y; A; B \rrbracket \Longrightarrow Z$