

Topics in Automated Deduction (CS 576)

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Basic Induction Heuristics

- Theorems about recursive functions are proved by induction
- If f defined by induction on i th argument, proof is by induction of i th argument of f

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Example: Tail Recursive Reverse

```
primrec itrev :: 'a list ⇒ 'a list ⇒ 'a list where
  itrev [ ] ys = ys |
  itrev (x#xs) ys = itrev xs (x#ys)

lemma itrev xs [ ] = rev xs
```

This direction is easier to prove/use
lhs "more complex" than rhs

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Demo: first attempt at itrev = rev

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Generalization (first kind)

Replace constant arguments ([]) by variables:

```
lemma itrev xs ys = rev xs @ ys
```

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Demo: second attempt at itrev = rev

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Generalization (second kind)

Quantify all free variables by \forall ,
except the induction variable

`lemma \forall ys. itrev xs ys = rev xs @ ys`

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Proof Basics

- Isabelle uses *Natural Deduction* proofs
 - Uses *sequent* encoding
- Rule notation:

| Rule | Sequent Encoding |
|--|--|
| $\frac{A_1 \dots A_n}{A}$ | $\llbracket A_1, \dots, A_n \rrbracket \Longrightarrow A$ |
| $\frac{B}{A_1 \dots \frac{\vdots}{A_i} \dots A_n}$ | $\llbracket A_1, \dots, B \rrbracket \Longrightarrow A_i, \dots, A_n \rrbracket \Longrightarrow A$ |

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Natural Deduction

For each logical operator \oplus , have two kinds of rules:

Introduction: How can I prove $A \oplus B$?

$$\frac{?}{A \oplus B}$$

Elimination: What can I prove using $A \oplus B$?

$$\frac{\dots A \oplus B \dots}{?}$$

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Operational Reading

$$\frac{A_1 \dots A_n}{A}$$

Introduction rule:

To prove A it suffices to prove $A_1 \dots A_n$.

Elimination rule:

If we know A_1 and we want to prove A
it suffices to prove $A_2 \dots A_n$

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Natural Deduction for Propositional Logic

| | |
|--|--|
| $\frac{A \quad B}{A \wedge B}$ conjI | $\frac{A \wedge B \quad \llbracket A; B \rrbracket \Longrightarrow C}{C}$ conjE |
| $\frac{A \quad B}{A \vee B} \quad \frac{A \vee B}{A \vee B}$ disjI1/2 | $\frac{A \vee B \quad A \Longrightarrow C \quad B \Longrightarrow C}{C}$ disjE |
| $\frac{A \Longrightarrow B}{A \longrightarrow B}$ impI | $\frac{A \longrightarrow B \quad A \quad B \Longrightarrow C}{C}$ impE |

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Natural Deduction for Propositional Logic

| | |
|---|--|
| $\frac{A \Longrightarrow B \quad B \Longrightarrow A}{A = B}$ iffI | $\frac{A = B \quad A}{B}$ iffD1 |
| | $\frac{A = B \quad B}{A}$ iffD2 |
| $\frac{A \Longrightarrow \text{False}}{\neg A}$ notI | $\frac{\neg A \quad A}{B}$ notE |

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Equality

$$\frac{}{t = t} \text{ refl} \quad \frac{s = t}{t = s} \text{ sym} \quad \frac{r = s \quad s = t}{r = t} \text{ trans}$$

$$\frac{s = t \quad A(s)}{A(t)} \text{ subst}$$

`subst` rarely needed explicitly – used implicitly by `simp`

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More Rules

$$\frac{A \wedge B}{A} \text{ conjunct1} \quad \frac{A \wedge B}{B} \text{ conjunct2}$$

$$\frac{A \longrightarrow B \quad A}{B} \text{ mp}$$

Compare to elimination rules:

$$\frac{A \wedge B \quad [A; B] \Longrightarrow C}{C} \text{ conjE} \quad \frac{A \longrightarrow B \quad A \quad B \Longrightarrow C}{C} \text{ impE}$$

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“Classical” Rules

$$\frac{A \Longrightarrow \text{False}}{A} \text{ ccontr} \quad \frac{A \Longrightarrow A}{A} \text{ classical}$$

- `ccontr` and `classical` are not derivable from the Natural Deduction rules.
- They make the logic “classical”, i.e. “non-constructive” or “non-intuitionistic”.

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Proof by Assumption

$$\frac{A_1 \dots A_i \dots A_n}{A_i}$$

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Rule Application: The Rough Idea

Applying rule $[A_1; \dots; A_n] \Longrightarrow A$ to subgoal C :

- Unify A and C
- Replace C with n new subgoals: $A'_1 \dots A'_n$

Backwards reduction, like in Prolog

Example: rule: $[?P; ?Q] \Longrightarrow ?P \wedge ?Q$
 subgoal: 1. $A \wedge B$

Result: 1. A
 2. B

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Rule Application: More Complete Idea

Applying rule $[A_1; \dots; A_n] \Longrightarrow A$ to subgoal C :

- Unify A and C with (meta)-substitution σ
- Specialize goal to $\sigma(C)$
- Replace C with n new subgoals: $\sigma(A_1) \dots \sigma(A_n)$

Note: schematic variables in C treated as existential variables

Does there exist value for $?X$ in C that makes C true?
 (Still not the whole story)

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rule Application

Rule: $\llbracket A_1; \dots; A_n \rrbracket \implies A$
Subgoal: 1. $\llbracket B_1; \dots; B_m \rrbracket \implies C$
Substitution: $\sigma(A) \equiv \sigma(C)$
New subgoals: 1. $\llbracket \sigma(B_1); \dots; \sigma(B_m) \rrbracket \implies \sigma(A_1)$
 :
 $n. \llbracket \sigma(B_1); \dots; \sigma(B_m) \rrbracket \implies \sigma(A_n)$
Proves: $\llbracket \sigma(B_1); \dots; \sigma(B_m) \rrbracket \implies \sigma(C)$
Command: `apply (rule <rule-name>)`

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Proof by assumption

`apply assumption`

proves:

1. $\llbracket B_1; \dots; B_m \rrbracket \implies C$

by unifying C with one of the B_i

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Demo: Application of Introduction Rule

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Applying Elimination Rules

`apply (erule <elim-rule>)`

Like `rule` but also

- unifies first premise of rule with an assumption
- eliminates that assumption instead of conclusion

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Example

Rule: $\llbracket ?P \wedge ?Q; \llbracket ?P; ?Q \rrbracket \implies ?R \rrbracket \implies ?R$
Subgoal: 1. $\llbracket X; A \wedge B; Y \rrbracket \implies Z$
Unification: $?P \wedge ?Q \equiv A \wedge B$ and $?R \equiv Z$
New subgoal: 1. $\llbracket X; Y \rrbracket \implies \llbracket A; B \rrbracket \implies Z$
Same as: 1. $\llbracket X; Y; A; B \rrbracket \implies Z$

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