

# Chapter 12

## Network Flow II

CS 573: Algorithms, Fall 2014

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### 12.0.1 Accountability

#### 12.0.1.1 Accountability



BEFORE I DECIDE TO INVEST  
TIME AND ENERGY LEARNING  
NETWORK FLOWS, I WANT TO  
KNOW HOW MUCH IT'S GOING  
TO INCREASE MY POSTDOCTORAL  
SALARY! **I DEMAND  
ACCOUNTABILITY!!**



<http://www.cs.berkeley.edu/~jrs/Calvin>

#### 12.0.1.2 Accountability

- (A) People that do not know maximum flows: essentially everybody.
- (B) Average salary on earth  $\approx$  \$5,000
- (C) People that know maximum flow – most of them work in programming related jobs and make at least \$10,000 a year.

- (D) Salary of people that learned maximum flows:  $> \$10,000$
- (E) Salary of people that did not learn maximum flows:  $< \$5,000$ .
- (F) Salary of people that know Latin: 0 (unemployed).

Conclusion *Thus, by just learning maximum flows (and not knowing Latin) you can double your future salary!*

## 12.0.2 The Ford-Fulkerson Method

### 12.0.2.1 Ford Fulkerson

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algFordFulkerson( $G, s, t$ )
  Initialize flow  $f$  to zero
  while  $\exists$  path  $\pi$  from  $s$  to  $t$  in  $G_f$  do
     $c_f(\pi) \leftarrow \min \{ c_f(u, v) \mid (u \rightarrow v) \in \pi \}$ 
    for  $\forall (u \rightarrow v) \in \pi$  do
       $f(u, v) \leftarrow f(u, v) + c_f(\pi)$ 
       $f(v, u) \leftarrow f(v, u) - c_f(\pi)$ 

```

**Lemma 12.0.1.** *If the capacities on the edges of  $G$  are integers, then **algFordFulkerson** runs in  $O(m |f^*|)$  time, where  $|f^*|$  is the amount of flow in the maximum flow and  $m = |E(G)|$ .*

### 12.0.2.2 Proof of Lemma...

*Proof:* Observe that the **algFordFulkerson** method performs only subtraction, addition and min operations. Thus, if it finds an augmenting path  $\pi$ , then  $c_f(\pi)$  must be a *positive* integer number. Namely,  $c_f(\pi) \geq 1$ . Thus,  $|f^*|$  must be an integer number (by induction), and each iteration of the algorithm improves the flow by at least 1. It follows that after  $|f^*|$  iterations the algorithm stops. Each iteration takes  $O(m + n) = O(m)$  time, as can be easily verified. ■

### 12.0.2.3 Integrality theorem

**Observation 12.0.2 (Integrality theorem).** *If the capacity function  $c$  takes on only integral values, then the maximum flow  $f$  produced by the **algFordFulkerson** method has the property that  $|f|$  is integer-valued. Moreover, for all vertices  $u$  and  $v$ , the value of  $f(u, v)$  is also an integer.*

## 12.0.3 The Edmonds-Karp algorithm

### 12.0.3.1 Edmonds-Karp algorithm

**Edmonds-Karp:** modify **algFordFulkerson** so it always returns the shortest augmenting path in  $G_f$ .

**Definition 12.0.3.** For a flow  $f$ , let  $\delta_f(v)$  be the length of the shortest path from the source  $s$  to  $v$  in the residual graph  $G_f$ . Each edge is considered to be of length 1.

Assume the following key lemma:

**Lemma 12.0.4.**  $\forall v \in V \setminus \{s, t\}$  the function  $\delta_f(v)$  increases.

### 12.0.3.2 The disappearing/reappearing lemma

**Lemma 12.0.5.** *During execution **Edmonds-Karp**, edge  $(u \rightarrow v)$  might disappear/reappear from  $G_f$  at most  $n/2$  times,  $n = |V(G)|$ .*

- Proof:* (A) iteration when edge  $(u \rightarrow v)$  disappears.  
(B)  $(u \rightarrow v)$  appeared in augmenting path  $\pi$ .  
(C) Fully utilized:  $c_f(\pi) = c_f(uv)$ .  $f$  flow in beginning of iter.  
(D) till  $(u \rightarrow v)$  “magically” reappears.  
(E) ... augmenting path  $\sigma$  that contained the edge  $(v \rightarrow u)$ .  
(F)  $g$ : flow used to compute  $\sigma$ .  
(G) We have:  $\delta_g(u) = \delta_g(v) + 1 \geq \delta_f(v) + 1 = \delta_f(u) + 2$   
(H) distance of  $s$  to  $u$  had increased by 2. QED.

### 12.0.3.3 Comments...

- (A)  $\delta_f(u)$  might become infinity.  
(B)  $u$  is no longer reachable from  $s$ .  
(C) By monotonicity, the edge  $(u \rightarrow v)$  would never appear again.

**Observation 12.0.6.** *For every iteration/augmenting path of **Edmonds-Karp** algorithm, at least one edge disappears from the residual graph  $G_f$ .*

### 12.0.3.4 Edmonds-Karp # of iterations

**Lemma 12.0.7.** **Edmonds-Karp** handles  $O(nm)$  augmenting paths before it stops.

*Its running time is  $O(nm^2)$ , where  $n = |V(G)|$  and  $m = |E(G)|$ .*

- Proof:* (A) Every edge might disappear at most  $n/2$  times.  
(B) At most  $nm/2$  edge disappearances during execution **Edmonds-Karp**.  
(C) In each iteration, by path augmentation, at least one edge disappears.  
(D) **Edmonds-Karp** algorithm perform at most  $O(mn)$  iterations.  
(E) Computing augmenting path takes  $O(m)$  time.  
(F) Overall running time is  $O(nm^2)$ .

### 12.0.3.5 Shortest distance increases during Edmonds-Karp execution

**Lemma 12.0.8.** **Edmonds-Karp** run on  $G = (V, E)$ ,  $s, t$ , then  $\forall v \in V \setminus \{s, t\}$ , the distance  $\delta_f(v)$  in  $G_f$  increases monotonically.

*Proof*

- (A) By Contradiction.  $f$ : flow before (first fatal) iteration.  
(B)  $g$ : flow after.  
(C)  $v$ : vertex s.t.  $\delta_g(v)$  is minimal, among all counter example vertices.  
(D)  $v$ :  $\delta_g(v)$  is minimal and  $\delta_g(v) < \delta_f(v)$ .

### 12.0.3.6 Proof continued...

- (A)  $\pi = s \rightarrow \dots \rightarrow u \rightarrow v$ : shortest path in  $G_g$  from  $s$  to  $v$ .
- (B)  $(u \rightarrow v) \in E(G_g)$ , and thus  $\delta_g(u) = \delta_g(v) - 1$ .
- (C) By choice of  $v$ :  $\delta_g(u) \geq \delta_f(u)$ .
  - (i) If  $(u \rightarrow v) \in E(G_f)$  then

$$\delta_f(v) \leq \delta_f(u) + 1 \leq \delta_g(u) + 1 = \delta_g(v) - 1 + 1 = \delta_g(v).$$

This contradicts our assumptions that  $\delta_f(v) > \delta_g(v)$ .

### 12.0.3.7 Proof continued II

- (ii)  $(u \rightarrow v) \notin E(G_f)$ :
  - (A)  $\pi$  used in computing  $g$  from  $f$  contains  $(v \rightarrow u)$ .
  - (B)  $(u \rightarrow v)$  reappeared in the residual graph  $G_g$  (while not being present in  $G_f$ ).
  - (C)  $\implies \pi$  pushed a flow in the other direction on the edge  $(u \rightarrow v)$ . Namely,  $(v \rightarrow u) \in \pi$ .
  - (D) Algorithm always augment along the shortest path. By assumption  $\delta_g(v) < \delta_f(v)$ , and definition of  $u$ :

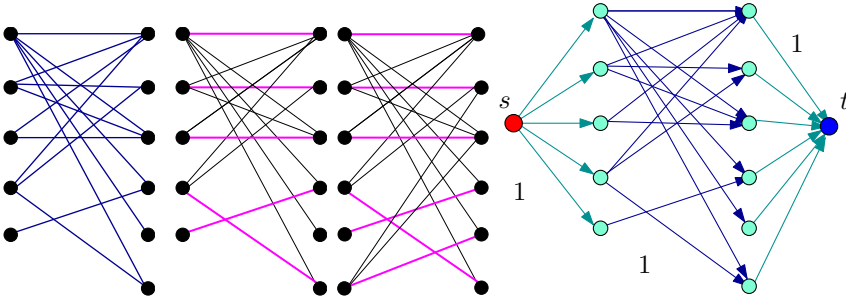
$$\delta_f(u) = \delta_f(v) + 1 > \delta_g(v) = \delta_g(u) + 1,$$

- (E)  $\implies \delta_f(u) > \delta_g(u)$ 
  - $\implies$  monotonicity property fails for  $u$ .
  - But:  $\delta_g(u) < \delta_g(v)$ . A contradiction. ■

## 12.1 Applications and extensions for Network Flow

### 12.1.1 Maximum Bipartite Matching

#### 12.1.1.1 Bipartite Matching



#### 12.1.1.2 Bipartite matching

Definition 12.1.1.  $G = (V, E)$ : undirected graph.

$M \subseteq E$ : **matching** if all vertices  $v \in V$ , at most one edge of  $M$  is incident on  $v$ .

$M$  is **maximum matching** if for any matching  $M'$ :  $|M| \geq |M'|$ .

$M$  is **perfect** if it involves all vertices.

### 12.1.1.3 Computing bipartite matching

**Theorem 12.1.2.** *Compute maximum bipartite matching in  $O(nm)$  time.*

- Proof:* (A)  $G$ : bipartite graph  $G$ . ( $n$  vertices and  $m$  edges)  
(B) Create new graph  $H$  with source on left and sink right.  
(C) Direct all edges from left to right. Set all capacities to one.  
(D) By Integrality theorem, flow in  $H$  is 0/1 on edges.  
(E) A flow of value  $k$  in  $H \implies$  a collection of  $k$  vertex disjoint  $s-t$  paths  $\implies$  matching in  $G$  of size  $k$ .  
(F)  $M$ : matching of  $k$  edge in  $G$ ,  $\implies$  flow of value  $k$  in  $H$ .  
(G) Running time of the algorithm is  $O(nm)$ . Max flow is  $n$ , and as such, at most  $n$  augmenting paths.

■

### 12.1.1.4 Extension: Multiple Sources and Sinks

**Question** Given a flow network with several sources and sinks, how can we compute maximum flow on such a network?

**Solution** The idea is to create a super source, that send all its flow to the old sources and similarly create a super sink that receives all the flow.

Clearly, computing flow in both networks is equivalent.

### 12.1.1.5 Proof by figures

