

CS 573: Algorithms, Fall 2014

Reductions and NP

Lecture 2

August 28, 2014

Part I

Reductions Continued

Propositional Formulas

Definition

Consider a set of boolean variables x_1, x_2, \dots, x_n .

- A **literal** is either a boolean variable x_i or its negation $\neg x_i$.
- A **clause** is a disjunction of literals.
For example, $x_1 \vee x_2 \vee \neg x_4$ is a clause.
- A **formula in conjunctive normal form** (CNF) is propositional formula which is a conjunction of clauses
 - $(x_1 \vee x_2 \vee \neg x_4) \wedge (x_2 \vee \neg x_3) \wedge x_5$ is a CNF formula.
- A formula φ is a 3CNF:
A CNF formula such that every clause has **exactly** 3 literals.
 - $(x_1 \vee x_2 \vee \neg x_4) \wedge (x_2 \vee \neg x_3 \vee x_1)$ is a 3CNF formula, but $(x_1 \vee x_2 \vee \neg x_4) \wedge (x_2 \vee \neg x_3) \wedge x_5$ is not.

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Satisfiability

SAT

Instance: A CNF formula φ .

Question: Is there a truth assignment to the variable of φ such that φ evaluates to true?

3SAT

Instance: A 3CNF formula φ .

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Satisfiability

SAT

Given a CNF formula φ , is there a truth assignment to variables such that φ evaluates to true?

Example

- 1 $(x_1 \vee x_2 \vee \neg x_4) \wedge (x_2 \vee \neg x_3) \wedge x_5$ is satisfiable; take x_1, x_2, \dots, x_5 to be all true
- 2 $(x_1 \vee \neg x_2) \wedge (\neg x_1 \vee x_2) \wedge (\neg x_1 \vee \neg x_2) \wedge (x_1 \vee x_2)$ is not satisfiable.

3SAT

Given a 3CNF formula φ , is there a truth assignment to variables such that φ evaluates to true?

(More on 2SAT in a bit...)

Importance of **SAT** and **3SAT**

- **SAT**, **3SAT**: basic constraint satisfaction problems.
- Many different problems can be reduced to them:
simple+powerful expressivity of constraints.
- Arise in many hardware/software verification/correctness applications.
- ... fundamental problem of **NP-Completeness**.

$SAT \leq_P 3SAT$

How **SAT** is different from **3SAT**?

In **SAT** clauses might have arbitrary length: $1, 2, 3, \dots$ variables:

$$(x \vee y \vee z \vee w \vee u) \wedge (\neg x \vee \neg y \vee \neg z \vee w \vee u) \wedge (\neg x)$$

In **3SAT** every clause must have *exactly 3* different literals.

Reduce from **SAT** to **3SAT**: make all clauses to have 3 variables...

Basic idea

- Pad short clauses so they have 3 literals.
- Break long clauses into shorter clauses.
- Repeat the above till we have a 3CNF.

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- 3SAT \leq_P SAT.
- Because...
A 3SAT instance is also an instance of SAT.

$SAT \leq_P 3SAT$

Claim

$SAT \leq_P 3SAT$.

Given φ a **SAT** formula we create a **3SAT** formula φ' such that

- φ is satisfiable iff φ' is satisfiable.
- φ' can be constructed from φ in time polynomial in $|\varphi|$.

Idea: if a clause of φ is not of length 3, replace it with several clauses of length exactly 3.

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A clause with a single literal

Reduction Ideas

Challenge: Some clauses in φ # literals $\neq 3$.

\forall clauses with $\neq 3$ literals: construct set logically equivalent clauses.

- **Clause with one literal:** $c = \ell$ clause with a single literal.
 u, v be new variables. Consider

$$\begin{aligned} c' = & (\ell \vee u \vee v) \wedge (\ell \vee u \vee \neg v) \\ & \wedge (\ell \vee \neg u \vee v) \wedge (\ell \vee \neg u \vee \neg v). \end{aligned}$$

Observe: c' satisfiable $\iff c$ is satisfiable

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Reduction Ideas: 2 and more literals

- **Case clause with 2 literals:** Let $c = \ell_1 \vee \ell_2$. Let u be a new variable. Consider

$$c' = (\ell_1 \vee \ell_2 \vee u) \wedge (\ell_1 \vee \ell_2 \vee \neg u).$$

c is satisfiable $\iff c'$ is satisfiable

Breaking a clause

Lemma

For any boolean formulas X and Y and z a new boolean variable. Then

$X \vee Y$ is satisfiable

if and only if, z can be assigned a value such that

$(X \vee z) \wedge (Y \vee \neg z)$ is satisfiable

(with the same assignment to the variables appearing in X and Y).

$\text{SAT} \leq_P 3\text{SAT}$ (contd)

Clauses with more than 3 literals

Let $c = \ell_1 \vee \dots \vee \ell_k$. Let u_1, \dots, u_{k-3} be new variables.
Consider

$$\begin{aligned} c' = & (\ell_1 \vee \ell_2 \vee u_1) \wedge (\ell_3 \vee \neg u_1 \vee u_2) \\ & \wedge (\ell_4 \vee \neg u_2 \vee u_3) \wedge \\ & \dots \wedge (\ell_{k-2} \vee \neg u_{k-4} \vee u_{k-3}) \wedge (\ell_{k-1} \vee \ell_k \vee \neg u_{k-3}). \end{aligned}$$

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Another way to see it — reduce size clause by one & repeat :

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$$\begin{aligned}\varphi = & (\neg x_1 \vee \neg x_4) \wedge (x_1 \vee \neg x_2 \vee \neg x_3) \\ & \wedge (\neg x_2 \vee \neg x_3 \vee x_4 \vee x_1) \wedge (x_1) .\end{aligned}$$

Equivalent form:

$$\begin{aligned}\psi = & (\neg x_1 \vee \neg x_4 \vee z) \wedge (\neg x_1 \vee \neg x_4 \vee \neg z) \\ & \wedge (x_1 \vee \neg x_2 \vee \neg x_3) \\ & \wedge (\neg x_2 \vee \neg x_3 \vee y_1) \wedge (x_4 \vee x_1 \vee \neg y_1) \\ & \wedge (x_1 \vee u \vee v) \wedge (x_1 \vee u \vee \neg v) \\ & \wedge (x_1 \vee \neg u \vee v) \wedge (x_1 \vee \neg u \vee \neg v) .\end{aligned}$$

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Overall Reduction Algorithm

Reduction from **SAT** to **3SAT**

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ReduceSATTo3SAT( $\varphi$ ):  
  //  $\varphi$ : CNF formula.  
  for each clause  $c$  of  $\varphi$  do  
    if  $c$  does not have exactly 3 literals then  
      construct  $c'$  as before  
    else  
       $c' = c$   
   $\psi$  is conjunction of all  $c'$  constructed in loop  
  return Solver3SAT( $\psi$ )
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Correctness (informal)

φ is satisfiable $\iff \psi$ satisfiable

... $\forall c \in \varphi$: new 3CNF formula c' is equivalent to c .

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What about **2SAT**?

- **2SAT** can be solved in poly time! (specifically, linear time!)
- No poly time reduction from **SAT** (or **3SAT**) to **2SAT**.
- If \exists reduction \implies **SAT**, **3SAT** solvable in polynomial time.

Why the reduction from **3SAT** to **2SAT** fails?

$(x \vee y \vee z)$: clause.

convert to collection of **2CNF** clauses. Introduce a fake variable α , and rewrite this as

$(x \vee y \vee \alpha) \wedge (\neg \alpha \vee z)$ (bad! clause with 3 vars)

or $(x \vee \alpha) \wedge (\neg \alpha \vee y \vee z)$ (bad! clause with 3 vars).

(In animal farm language: **2SAT** good, **3SAT** bad.)

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A challenging exercise: Given a **2SAT** formula show to compute its satisfying assignment...

(Hint: Create a graph with two vertices for each variable (for a variable x there would be two vertices with labels $x = 0$ and $x = 1$). For ever **2CNF** clause add two directed edges in the graph. The edges are implication edges: They state that if you decide to assign a certain value to a variable, then you must assign a certain value to some other variable.

Now compute the strong connected components in this graph, and continue from there...)

Independent Set

Independent Set

Instance: A graph G , integer k .

Question: Is there an independent set in G of size k ?

3SAT \leq_P Independent Set

The reduction **3SAT \leq_P Independent Set**

Input: Given a 3CNF formula φ

Goal: Construct a graph G_φ and number k such that G_φ has an independent set of size k if and only if φ is satisfiable.

G_φ should be constructable in time polynomial in size of φ

- **Importance of reduction:** Although 3SAT is much more expressive, it can be reduced to a seemingly specialized Independent Set problem.
- **Notice:** Handle only 3CNF formulas (fails for other kinds of boolean formulas).

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Interpreting 3SAT

There are two ways to think about 3SAT

- Assign 0/1 (false/true) to vars \implies formula evaluates to true.
Each clause evaluates to true.
- Pick literal from each clause & find assignment s.t. all true.

Use second view of 3SAT for reduction.

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The Reduction

- G_φ will have one vertex for each literal in a clause
- Connect the 3 literals in a clause to form a triangle; the independent set will pick at most one vertex from each clause, which will correspond to the literal to be set to true
- Connect 2 vertices if they label complementary literals; this ensures that the literals corresponding to the independent set do not have a conflict
- Take k to be the number of clauses

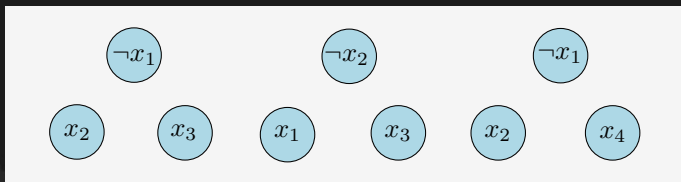


Figure: $\varphi = (\neg x_1 \vee x_2 \vee x_3) \wedge (x_1 \vee \neg x_2 \vee x_3) \wedge (\neg x_1 \vee x_2 \vee x_4)$

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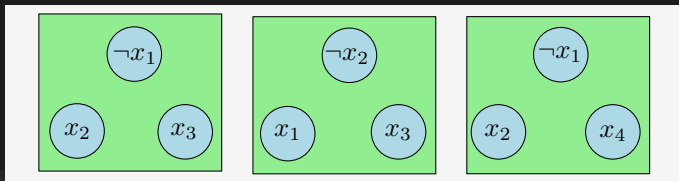


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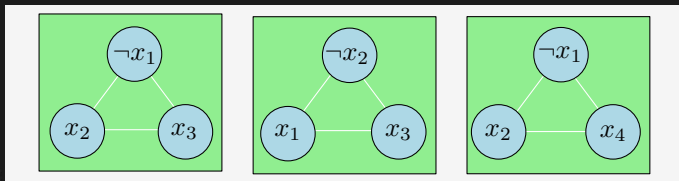


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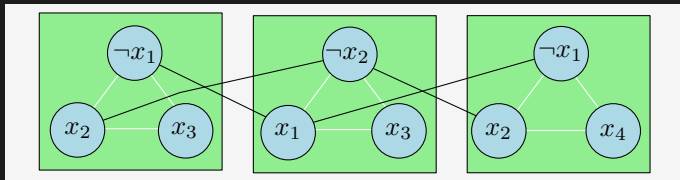


Figure: $\varphi = (\neg x_1 \vee x_2 \vee x_3) \wedge (x_1 \vee \neg x_2 \vee x_3) \wedge (\neg x_1 \vee x_2 \vee x_4)$

The Reduction

- G_φ will have one vertex for each literal in a clause
- Connect the 3 literals in a clause to form a triangle; the independent set will pick at most one vertex from each clause, which will correspond to the literal to be set to true
- Connect 2 vertices if they label complementary literals; this ensures that the literals corresponding to the independent set do not have a conflict
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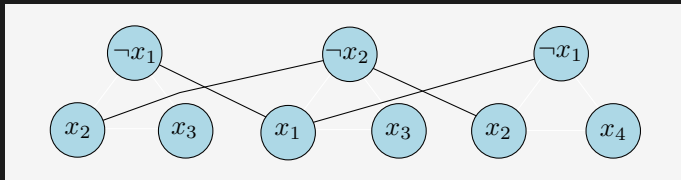


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Correctness

Proposition

φ is satisfiable $\iff G_\varphi$ has an independent set of size k
 k : number of clauses in φ .

Proof.

\Rightarrow a : truth assignment satisfying φ

- Pick one of the vertices, corresponding to true literals under a , from each triangle. This is an independent set of the appropriate size □

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Correctness (contd)

Proposition

φ is satisfiable $\iff G_\varphi$ has an independent set of size k
(= number of clauses in φ).

Proof.

$\Leftarrow S$: independent set in G_φ of size k

- S must contain exactly one vertex from each clause
- S cannot contain vertices labeled by conflicting clauses
- Thus, it is possible to obtain a truth assignment that makes the literals in S true; such an assignment satisfies one literal in every clause



Transitivity of Reductions

Lemma

$X \leq_P Y$ and $Y \leq_P Z$ implies that $X \leq_P Z$.

- **Note:** $X \leq_P Y$ does not imply that $Y \leq_P X$ and hence it is very important to know the FROM and TO in a reduction.
- To prove $X \leq_P Y$: show a reduction FROM X TO Y
... show \exists algorithm for Y implies an algorithm for X .

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Part II

Definition of NP

Recap . . .

Problems

- **Clique**
- **Independent Set**
- **Vertex Cover**
- **Set Cover**
- **SAT**
- **3SAT**

Recap . . .

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Relationship

Independent Set \leq_P Clique

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Independent Set \approx_P **Clique**

Independent Set \leq_P **Vertex Cover**

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Relationship

Independent Set \approx_P **Clique**

Independent Set \leq_P **Vertex Cover** \leq_P **Independent Set**

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Relationship

Vertex Cover \approx_P Independent Set \approx_P Clique

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Relationship

Vertex Cover \approx_P **Independent Set** \approx_P **Clique**
3SAT \leq_P **SAT**

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Vertex Cover \approx_P **Independent Set** \approx_P **Clique**
3SAT \leq_P **SAT** \leq_P **3SAT**

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3SAT \approx_P **SAT**

3SAT \leq_P **Independent Set**

Problems and Algorithms: Formal Approach

Decision Problems

- **Problem Instance:** Binary string s , with size $|s|$
- **Problem:** Set X of strings s.t. answer is "yes": members of X are **YES instances** of X .
Strings not in X are **NO instances** of X .

Definition

- **alg:** algorithm for problem X if $\text{alg}(s) = \text{"yes"} \iff s \in X$.
- **alg** have polynomial running time $\exists p(\cdot)$ polynomial s.t.
 $\forall s, \text{alg}(s)$ terminates in at most $O\left(p(|s|)\right)$ steps.

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Polynomial time (denoted by **P**): class of all (decision) problems that have an algorithm that solves it in polynomial time.

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Example

Problems in **P** include

- 1 Is there a shortest path from s to t of length $\leq k$ in G ?
- 2 Is there a flow of value $\geq k$ in network G ?
- 3 Is there an assignment to variables to satisfy given linear constraints?

Efficiency Hypothesis

Efficiency hypothesis.

A problem X has an efficient algorithm

$\iff X \in \mathbf{P}$, that is X has a polynomial time algorithm.

- Justifications:
 - Robustness of definition to variations in machines.
 - A sound theoretical definition.
 - Most known polynomial time algorithms for “natural” problems have small polynomial running times.

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Problems that are hard...

...with no known polynomial time algorithms

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 - ...but many problems want to solve: similar to above.
 - **Question:** What is common to above problems?

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Efficient Checkability

- Above problems have the property:

Checkability

For any **YES** instance I_X of X :

- (A) there is a proof (or certificate) C .
- (B) Length of certificate $|C| \leq \text{poly}(|I_X|)$.
- (C) Given C, I_x : efficiently check that I_x is YES instance.

- Examples:
 - **SAT** formula φ : proof is a satisfying assignment.
 - **Independent Set** in graph G and k :
Certificate: a subset S of vertices.

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Certifiers

Definition

Algorithm $C(\cdot, \cdot)$ is **certifier** for problem X : $\forall s \in X$ there $\exists t$ such that $C(s, t) = \text{"YES"}$, and conversely, if for some s and t , $C(s, t) = \text{"yes"}$ then $s \in X$.

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Definition (Efficient Certifier.)

Certifier C is **efficient certifier** for X if there is a polynomial $p(\cdot)$ s.t. for every string s :

- ★ $s \in X$ if and only if
- ★ there is a string t :
 - $|t| \leq p(|s|)$,
 - $C(s, t) = \text{"yes"}$,
 - and C runs in polynomial time.

Example: Independent Set

- **Problem:** Does $G = (V, E)$ have an independent set of size $\geq k$?
 - **Certificate:** Set $S \subseteq V$.
 - **Certifier:** Check $|S| \geq k$ and no pair of vertices in S is connected by an edge.

Example: Vertex Cover

- **Problem:** Does G have a vertex cover of size $\leq k$?
 - **Certificate:** $S \subseteq V$.
 - **Certifier:** Check $|S| \leq k$ and that for every edge at least one endpoint is in S .

Example: SAT

- **Problem:** Does formula φ have a satisfying truth assignment?
 - **Certificate:** Assignment a of 0/1 values to each variable.
 - **Certifier:** Check each clause under a and say “yes” if all clauses are true.

Example: Composites

Composite

Instance: A number s .

Question: Is the number s a composite?

- **Problem:** Composite.

- **Certificate:** A factor $t \leq s$ such that $t \neq 1$ and $t \neq s$.
- **Certifier:** Check that t divides s .

Nondeterministic Polynomial Time

Definition

Nondeterministic Polynomial Time (denoted by **NP**) is the class of all problems that have efficient certifiers.

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Example

Independent Set, **Vertex Cover**, **Set Cover**, **SAT**, **3SAT**, and **Composite** are all examples of problems in **NP**.

Why is it called...

Nondeterministic Polynomial Time

- A certifier is an algorithm $C(I, c)$ with two inputs:
 - I : instance.
 - c : proof/certificate that the instance is indeed a YES instance of the given problem.
- Think about C as algorithm for original problem, if:
 - Given I , the algorithm guess (non-deterministically, and who knows how) the certificate c .
 - The algorithm now verifies the certificate c for the instance I .
- Usually **NP** is described using Turing machines (gag).

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Asymmetry in Definition of NP

- Only YES instances have a short proof/certificate. NO instances need not have a short certificate.
- For example...

Example

SAT formula φ . No easy way to prove that φ is NOT satisfiable!

- More on this and **co-NP** later on.

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P versus NP

Proposition

$$\mathbf{P} \subseteq \mathbf{NP}.$$

For a problem in \mathbf{P} no need for a certificate!

Proof.

Consider problem $X \in \mathbf{P}$ with algorithm **alg**. Need to demonstrate that X has an efficient certifier:

- Certifier C (input s, t):
runs **alg**(s) and returns its answer.
- C runs in polynomial time.
- If $s \in X$, then for every t , $C(s, t) = \text{"YES"}$.
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Exponential Time

Definition

Exponential Time (denoted **EXP**) is the collection of all problems that have an algorithm which on input s runs in exponential time, i.e., $O(2^{\text{poly}(|s|)})$.

Example: $O(2^n)$, $O(2^{n \log n})$, $O(2^{n^3})$, \dots

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Example: $O(2^n)$, $O(2^{n \log n})$, $O(2^{n^3})$, ...

NP versus EXP

Proposition

NP \subseteq **EXP**.

Proof.

Let $X \in \mathbf{NP}$ with certifier C . Need to design an exponential time algorithm for X .

- For every t , with $|t| \leq p(|s|)$ run $C(s, t)$; answer “yes” if any one of these calls returns “yes”.
- The above algorithm correctly solves X (exercise).
- Algorithm runs in $O(q(|s| + |p(s)|)2^{p(|s|)})$, where q is the running time of C . \square

Examples

- **SAT**: try all possible truth assignment to variables.
- **Independent Set**: try all possible subsets of vertices.
- **Vertex Cover**: try all possible subsets of vertices.

Is **NP** efficiently solvable?

We know **P** \subseteq **NP** \subseteq **EXP**.

Is **NP** efficiently solvable?

We know $\mathbf{P} \subseteq \mathbf{NP} \subseteq \mathbf{EXP}$.

Big Question

Is there are problem in **NP** that **does not** belong to **P**? Is $\mathbf{P} = \mathbf{NP}$?

If $P = NP$...

Or: If pigs could fly then life would be sweet.

- Many important optimization problems can be solved efficiently.
- The RSA cryptosystem can be broken.
- No security on the web.
- No e-commerce ...
- Creativity can be automated! Proofs for mathematical statement can be found by computers automatically (if short ones exist).

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P versus NP

Status

Relationship between **P** and **NP** remains one of the most important open problems in mathematics/computer science.

Consensus: Most people feel/believe **P** \neq **NP**.

Resolving **P** versus **NP** is a Clay Millennium Prize Problem. You can win a million dollars in addition to a Turing award and major fame!

Part III

Not for lecture: Converting any
boolean formula into CNF

The dark art of formula conversion into CNF

Consider an arbitrary boolean formula ϕ defined over k variables. To keep the discussion concrete, consider the formula $\phi \equiv x_k = x_i \wedge x_j$. We would like to convert this formula into an equivalent CNF formula.

Formula conversion into CNF

Step 1

Build a truth table for the boolean formula.

| $x_k \quad x_i \quad x_j$ | | | value of $x_k = x_i \wedge x_j$ |
|---------------------------|---|---|------------------------------------|
| 0 | 0 | 0 | 1 |
| 0 | 0 | 1 | 1 |
| 0 | 1 | 0 | 1 |
| 0 | 1 | 1 | 0 |
| 1 | 0 | 0 | 0 |
| 1 | 0 | 1 | 0 |
| 1 | 1 | 0 | 0 |
| 1 | 1 | 1 | 1 |

Formula conversion into CNF

Step 1.5 - understand what a single CNF clause represents

Given an assignment, say, $x_k = 0$, $x_i = 0$ and $x_j = 1$, consider the CNF clause $x_k \vee x_i \vee \overline{x_j}$ (you negate a variable if it is assigned one). Its truth table is

| x_k | x_i | x_j | $x_k \vee x_i \vee \overline{x_j}$ | |
|-------|-------|-------|------------------------------------|---|
| 0 | 0 | 0 | 1 | Observe that a single clause assigns zero to one row, and one everywhere else. An conjunction of several such clauses, as such, would result in a formula that is 0 in all the rows that corresponds to these clauses, and one everywhere else. |
| 0 | 0 | 1 | 0 | |
| 0 | 1 | 0 | 1 | |
| 0 | 1 | 1 | 1 | |
| 1 | 0 | 0 | 1 | |
| 1 | 0 | 1 | 1 | |
| 1 | 1 | 0 | 1 | |
| 1 | 1 | 1 | 1 | |

Formula conversion into CNF

Step 2

Write down CNF clause for every row in the table that is zero.

| x_k | x_i | x_j | $x_k = x_i \wedge x_j$ | CNF clause |
|-------|-------|-------|------------------------|---|
| 0 | 0 | 0 | 1 | |
| 0 | 0 | 1 | 1 | |
| 0 | 1 | 0 | 1 | |
| 0 | 1 | 1 | 0 | $x_k \vee \overline{x_i} \vee \overline{x_j}$ |
| 1 | 0 | 0 | 0 | $\overline{x_k} \vee x_i \vee x_j$ |
| 1 | 0 | 1 | 0 | $\overline{x_k} \vee x_i \vee \overline{x_j}$ |
| 1 | 1 | 0 | 0 | $\overline{x_k} \vee \overline{x_i} \vee x_j$ |
| 1 | 1 | 1 | 1 | |

The conjunction (i.e., and) of all these clauses is clearly equivalent to the original formula. In this case

$$\psi \equiv (x_k \vee \overline{x_i} \vee \overline{x_j}) \wedge (\overline{x_k} \vee x_i \vee x_j) \wedge (\overline{x_k} \vee x_i \vee \overline{x_j}) \wedge (\overline{x_k} \vee \overline{x_i} \vee x_j)$$

Formula conversion into CNF

Step 3 - simplify if you want to

Using that $(x \vee y) \wedge (x \vee \overline{y}) = x$, we have that:

- $(\overline{x_k} \vee x_i \vee x_j) \wedge (\overline{x_k} \vee x_i \vee \overline{x_j})$ is equivalent to $(\overline{x_k} \vee x_i)$.
- $(\overline{x_k} \vee x_i \vee x_j) \wedge (\overline{x_k} \vee \overline{x_i} \vee x_j)$ is equivalent to $(\overline{x_k} \vee x_j)$.

Using the above two observation, we have that our formula

$$\psi \equiv (\overline{x_k} \vee \overline{x_i} \vee \overline{x_j}) \wedge (\overline{x_k} \vee x_i \vee x_j) \wedge (\overline{x_k} \vee x_i \vee \overline{x_j}) \wedge (\overline{x_k} \vee \overline{x_i} \vee x_j)$$

is equivalent to

$$\psi \equiv (\overline{x_k} \vee \overline{x_i} \vee \overline{x_j}) \wedge (\overline{x_k} \vee x_i) \wedge (\overline{x_k} \vee x_j).$$

We conclude:

Lemma

The formula $x_k = x_i \wedge x_j$ is equivalent to the CNF formula $\psi \equiv (\overline{x_k} \vee \overline{x_i} \vee \overline{x_j}) \wedge (\overline{x_k} \vee x_i) \wedge (\overline{x_k} \vee x_j)$.

Notes



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