1. Write down a 3x3 filter that returns a positive value if the average value of the 4-adjacent neighbors is less than the center and a negative value otherwise

2. Write down a filter that will compute the gradient in the x-direction:

```
gradx(y,x) = im(y,x+1)-im(y,x) for each x, y
```

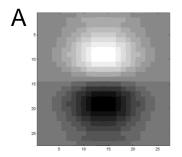
**Filtering Operator** 

#### 3. Fill in the blanks:

a) 
$$_{-}$$
 = D \* B

$$C) F = D *$$

$$d) = D * D$$





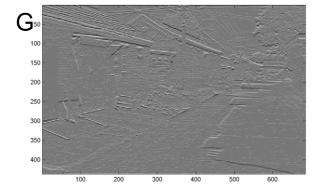


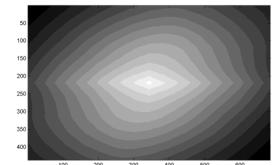
F

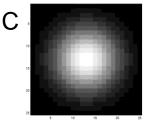
Н





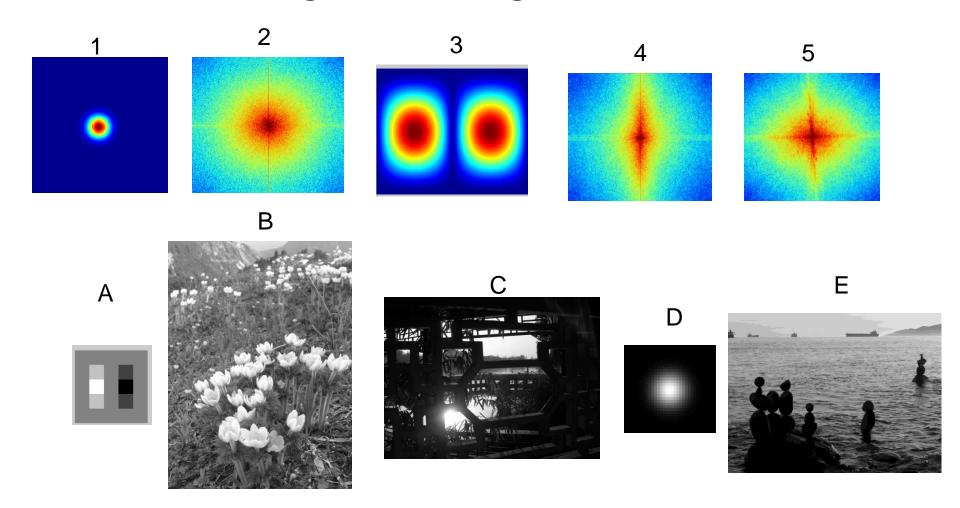


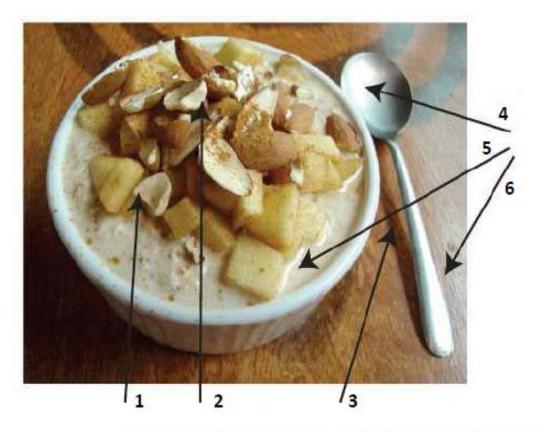






1. Match the spatial domain image to the Fourier magnitude image





A. For each of the arrows in the above image, name the reasons the pixel near the end of the arrow has its brightness value and explain very briefly. The arrow pointing to milk is pointing to the thin bright line at the edge of the piece of apple; the arrow pointing to the spoon handle is pointing to the bright area on the handle.

Possible factors: albedo, shadows, texture, specularities, curvature, lighting direction

1. What would be the result in "Intelligent Scissors" if all of the edge costs were set to 1?

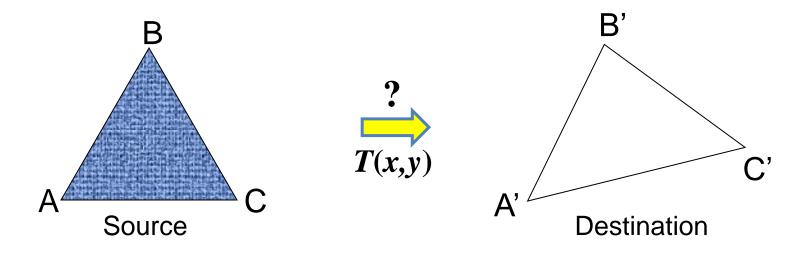
2. Typically, "GrabCut" will not work well on objects with thin structures. How could you change the boundary costs to better segment such objects?

- 1) I am trying to blend this bear into this pool. What problems will I have if I use:
  - a) Alpha compositing with feathering
  - b) Laplacian pyramid blending
  - c) Poisson editing?

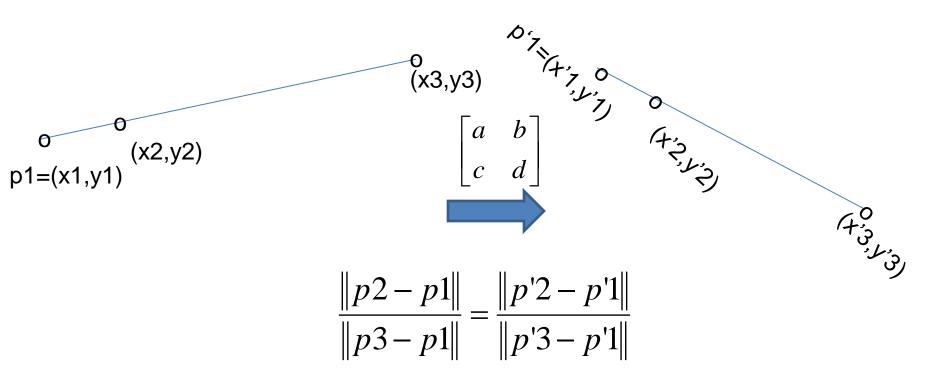


2) How would you make a sharpening filter using gradient domain processing? What are the constraints on the gradients and the intensities?

1) Suppose we have two triangles: ABC and A'B'C'. What transformation will map A to A', B to B', and C to C'? How can we get the parameters?



2) Show that distance ratios along a line are preserved under 2d linear transformations.



Hint: Write down x2 in terms of x1 and x3, given that the three points are co-linear

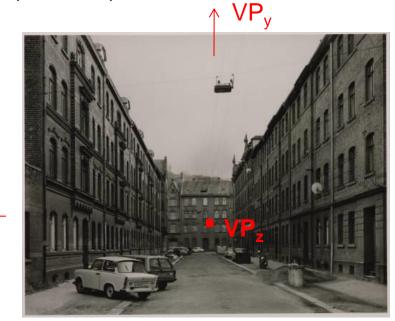
Suppose we have two 3D cubes on the ground facing the viewer, one near, one far.

- 1. What would they look like in perspective?
- 2. What would they look like in weak perspective?



Suppose you have estimated three vanishing points corresponding to orthogonal directions. How can you recover the rotation matrix that is aligned with the 3D axes defined by these points?

- Assume that intrinsic matrix K has three parameters
- Remember, in homogeneous coordinates, we can write a 3d point at infinity as (X, Y, Z, 0)



Assume that the camera height is 5 ft.

- What is the height of the man?
- What is the height of the building?

