

Topics in Streaming

Lecture 18 and 19

October 27 and 29, 2020

Topics in Streaming

- F_p estimation for $p \in (0, 2]$ via p -stable distributions and pseudorandom generators
- Priority Sampling
- Precision Sampling and Applications to ℓ_2 sampling in streams
- ℓ_0 Sampling

Part I

F_p Estimation

F_2 Estimation and JL

For F_2 estimation and JL and Euclidean LSH we used important “stability” property of the Normal distribution.

Lemma

Let Y_1, Y_2, \dots, Y_d be independent random variables with distribution $\mathcal{N}(0, 1)$. $Z = \sum_i x_i Y_i$ has distribution $\|x\|_2 \mathcal{N}(0, 1)$

Standard Gaussian is 2-stable.

$$(Y_1, Y_2, \dots, Y_n) \quad \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix}$$

F_p

$p = \underline{\underline{1.5}}$

$(0, \underline{\underline{2]}}$

$p \geq \underline{\underline{2}} \quad F_2$

p -stable distributions

Definition

A real-valued distribution \mathcal{D} is p -stable if $Z = \sum_{i=1}^n x_i Y_i$ has distribution $\|x\|_p \mathcal{D}$ when the Y_i are independent and each of them is distributed as \mathcal{D} .

$$\sum_{i=1}^n x_i Y_i \approx \|x\|_p Z \stackrel{\uparrow}{\approx} \mathcal{D}$$

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Question: Do p -stable distributions exist for $p \neq 2$?

p -stable distributions

Fact: p -stable distributions exist for all $p \in (0, 2]$ and do not exist for $p > 2$.

$p = 1$ is the Cauchy distribution which is the distribution of the ratio of two independent Gaussian random variables. Has a closed form density function $\frac{1}{\pi(1+x^2)}$. Mean and variance are *not* finite.

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For general p no closed form formula for density but can sample from the distribution.

Streaming, sketching, LSH ideas for ℓ_2 generalize to ℓ_p for $p \in (0, 2]$ via p -stable distributions and additional technical work.

Sampling from p -stable distribution

For $p \in (0, 2]$ let \mathcal{D}_p denote p -stable distribution. Sampling from \mathcal{D}_p via Chambers-Mallows-Stuck method

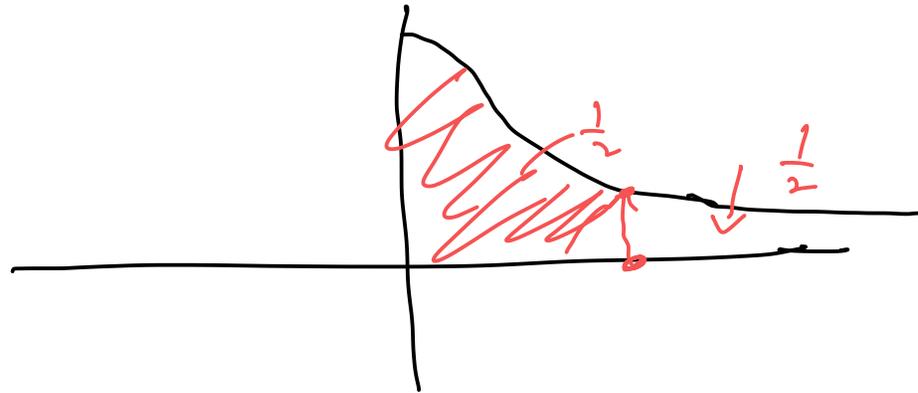
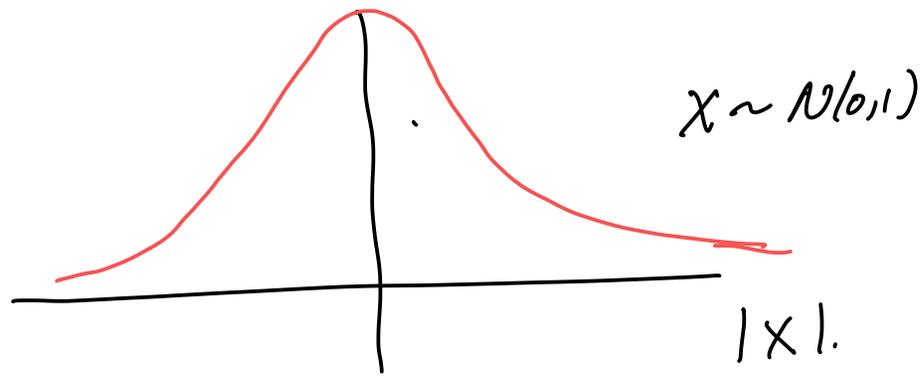
- Sample θ uniformly from $[-\pi/2, \pi/2]$.
- Sample r uniformly from $[0, 1]$.
- Output

$$\frac{\sin(p\theta)}{(\cos \theta)^{1/p}} \left(\frac{\cos((1-p)\theta)}{\ln(1/r)} \right)^{(1-p)/p}.$$

p -stable distributions need not have finite mean/variance. Hence we need to work with *median* of distribution.

Definition

The median of a distribution \mathcal{D} is θ if for $Y \sim \mathcal{D}$, $\Pr[Y \leq \mu] = 1/2$. If $\phi(x)$ is the probability density function of \mathcal{D} then we have $\int_{-\infty}^{\mu} \phi(x) dx = 1/2$.



F_p estimation via p -stable distribution

For $p \in (0, 2]$ due to [Indyk]

F_p -Estimate:

$$k \leftarrow \Theta\left(\frac{1}{\epsilon^2} \log \frac{1}{\delta}\right)$$

Let M be a $k \times n$ matrix where each $M_{ij} \sim \mathcal{D}_p$

$$y \leftarrow Mx$$

$$\text{Output } Y \leftarrow \frac{\text{median}(|y_1|, |y_2|, \dots, |y_k|)}{\text{median}(|\mathcal{D}_p|)}$$

$(x_1, x_2, \dots, x_n) \sim \|\cdot\|_p \mathcal{D}_p, \epsilon, \Delta \epsilon$

$x_i \leftarrow x_i + \Delta \epsilon$

$\|x\|_p$

$$M = \begin{bmatrix} \downarrow & \downarrow & \downarrow & \downarrow \\ - & - & - & - \\ - & - & - & - \\ \pm 1 & & & \end{bmatrix} \begin{bmatrix} \\ \\ \\ \end{bmatrix} x = \begin{bmatrix} y_1 \\ y_2 \\ \dots \\ y_n \end{bmatrix}$$

$\downarrow \in [-1, 1]$

$$M \bar{x} = \bar{y}$$

$$\begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_k \end{bmatrix}$$

$$y_i \approx \|x\|_p \mathcal{D}_p$$

$$E[y_i] = 0$$

$$|y_i|^p$$

$$\frac{\text{median}(|y_1|, |y_2|, \dots, |y_k|)}{\text{median}(|\mathcal{D}_p|)}$$

$$\approx \|x\|_p.$$

F_p estimation via p -stable distribution

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$$\text{Output } Y \leftarrow \frac{\text{median}(|y_1|, |y_2|, \dots, |y_k|)}{\text{median}(|\mathcal{D}_p|)}$$

- Each y_j is distributed according to $\|x\|_p \mathcal{D}_p$
- Cannot take average of $|y_j|^p$ values since mean of distribution is not finite
- Take median of absolute values for k independent copies and normalize by median of distribution

Concentration Lemma

Lemma

Let $\epsilon > 0$ and let \mathcal{D} be a distribution with density function ϕ and a unique median $\mu > 0$. Suppose ϕ is absolutely continuous on $[(1 - \epsilon)\mu, (1 + \epsilon)\mu]$ and let

$\alpha = \min\{\phi(x) \mid x \in [(1 - \epsilon)\mu, (1 + \epsilon)\mu]\}$. Let

$Y = \text{median}(Y_1, Y_2, \dots, Y_k)$ where Y_1, \dots, Y_k are independent samples from the distribution \mathcal{D} . Then

$$\Pr[|Y - \mu| \geq \epsilon\mu] \leq 2e^{-\frac{2}{3}\epsilon^2\mu^2\alpha^2k}.$$

See notes for proof idea.

Pseudorandom generator for F_p Estimation

For F_p estimation we need $M_{i,j}$ to be independent randomly distributed according to \mathcal{D}_p . Can use sampling from distribution even though it is not explicit.

How do we store M in small space?

Recall that for F_2 estimation and sketching we used matrix M where each row of M had 4-wise independent random variables. Needed separate proof to argue correctness.

Is there an equivalent limited independence hashing based algorithm for F_p estimation?

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Recall that for F_2 estimation and sketching we used matrix M where each row of M had 4-wise independent random variables. Needed separate proof to argue correctness.

Is there an equivalent limited independence hashing based algorithm for F_p estimation? No but can use a powerful pseudorandomness tool from TCS.

Pseudorandom generator

- P class of decision problems decided in poly time.
- RP class of decision problems decided in randomized poly time with one-sided error
- BPP class of decision problems decided in randomized poly time with two-sided error allowed

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Big Open Problem: Is $BPP = P$? Equivalently can every randomized polynomial time algorithm be derandomized with only polynomial-factor slow down?

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Big Open Problem: Is $BPP = P$? Equivalently can every randomized polynomial time algorithm be derandomized with only polynomial-factor slow down?

Equivalently: Is there a pseudo-random generator that fools every poly-sized algorithm?

Nisan's pseudorandom generator

Nisan constructed explicit pseudo-random generator that fools space-bounded algorithms.

Theorem

Let \mathcal{A} be an ^{algorithm} ~~algorithm~~ that uses space at most $S(n)$ on an input of length n . Then there is a pseudo-random generator G that fools \mathcal{A} and has seed length $\ell = O(S(n) \log n)$ and which is computable in $O(\ell)$ space and poly(ℓ) time.

Corollary

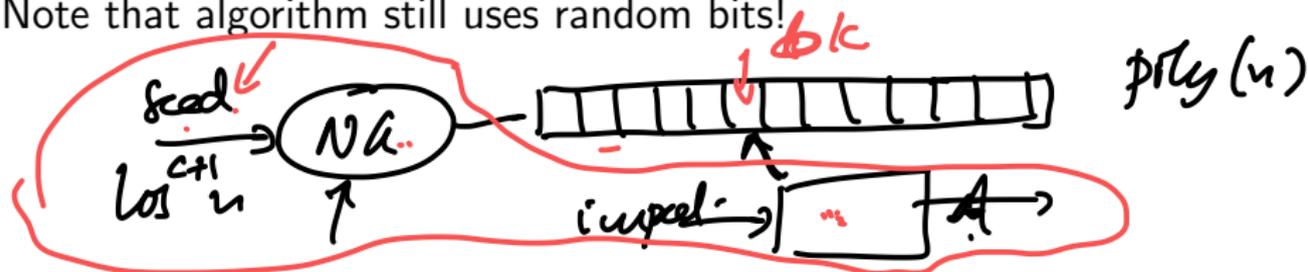
For $S(n) = O(\log^c n)$ the generator uses space $S(n) = O(\log^{c+1} n)$ and can generate any of the desired random pseudo-random bits for algorithm in poly($\log n$) time.

Applying Nisan's generator as a hammer

At a high-level if a streaming algorithm uses small space (polylogarithmic in input size) assuming access to *true* random bits then one can use Nisan's generator to reduce space.

- Nisan's generator requires small random seed. Store it.
- Generate required (pseudo)random bits "on the fly". Note that Nisan's generator itself runs in small space so total space is small.

Note that algorithm still uses random bits!



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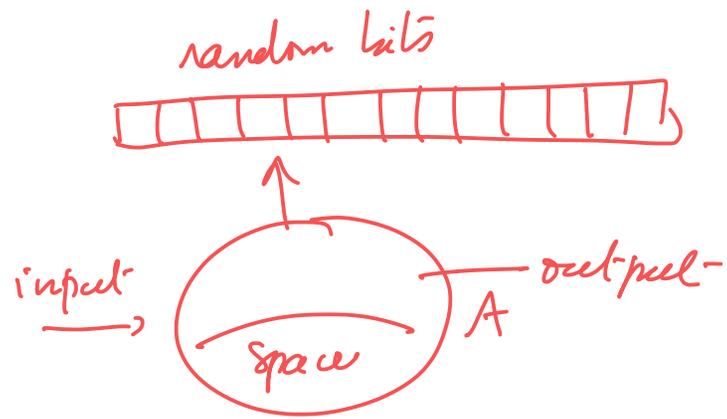
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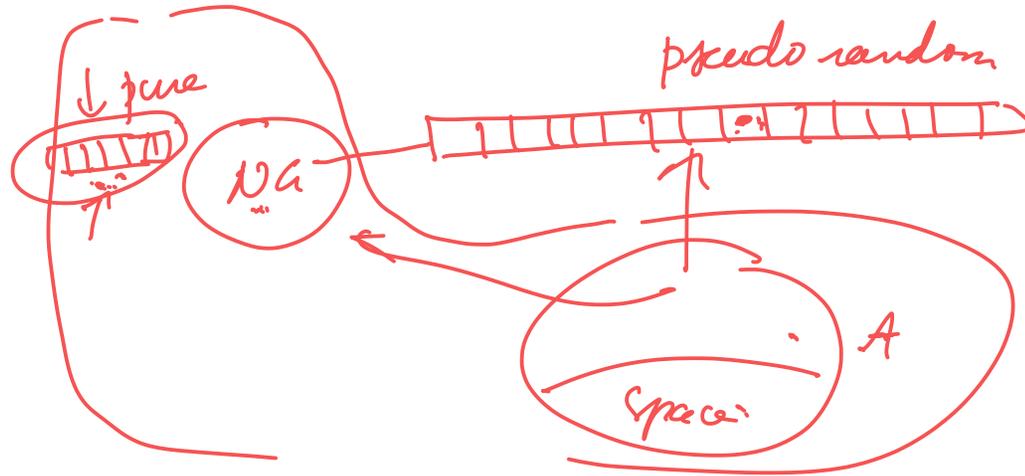
With additional discretization tricks one can convert Indyk's F_p estimation algorithm via Nisan's generator into a true small space algorithm.

[Kane-Nelson-Woodruff] show how to use limited independence hashing for F_p estimation instead of above hammer.

Original



New/Modify



Part II

Priority Sampling

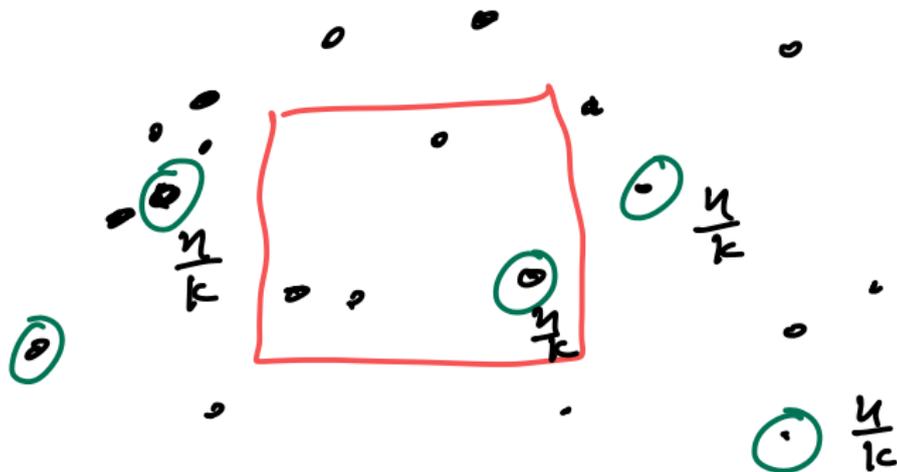
Sampling for data reduction

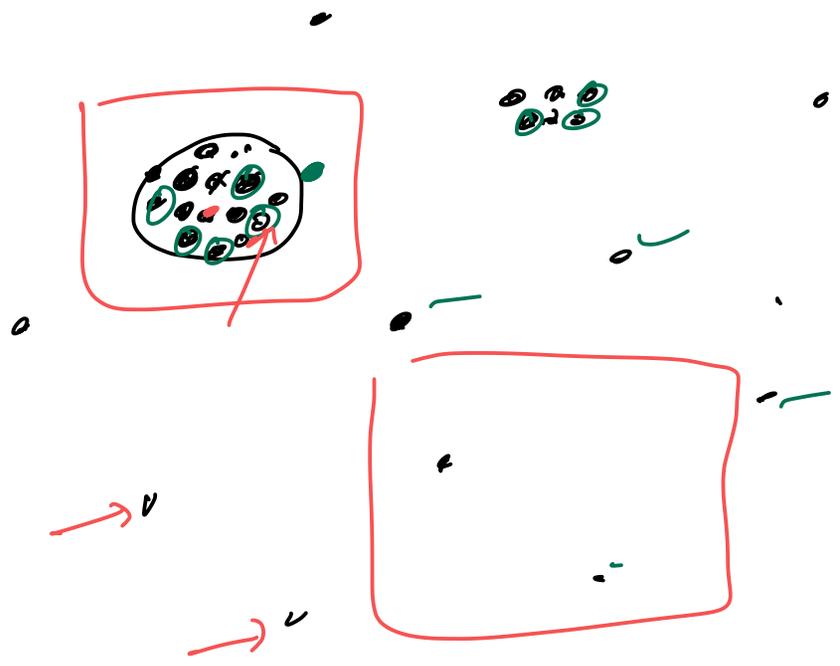
- X set of n points in the plane a_1, a_2, \dots, a_n .
- Want to answer queries of the form: given some shape C (say circles), how many points inside C ?
- standard data structures or brute force linear search say

n

picked k
from n .

$$\frac{n}{k} \times$$





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Question: Suppose n is too large and we can only store k points for some $k < n$.

Sampling approach:

- S sample of size k (with replacement). Store only S
- Given query C , compute $|C \cap S|$. What should we report as an estimate for $|C \cap X|$?

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Sampling approach:

- S sample of size k (with replacement). Store only S
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Weighted case

- X set of n points in the plane a_1, a_2, \dots, a_n . Each point a_i has a non-negative weight w_i
- Want to answer queries of the form: given some shape C (say circles), what is weight of point inside C ?

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Sampling approach?

- Easy to see that uniform sampling is not ideal
- Sample in proportion to weight? Say a_i sampled with $p_i = w_i / W$ where $W = \sum_i w_i$.
- What do we set the weight of the sampled points to? Can we control sample size? What is the variance?

Importance Sampling

- Decide sampling probabilities $\underline{p_1}, \underline{p_2}, \dots, \underline{p_n}$
- Choose $\underline{a_i}$ independently with probability $\underline{p_i}$ and if \underline{i} is chosen set $\underline{\hat{w}_i} = \underline{w_i/p_i}$. If \underline{i} is not chosen we implicitly set $\underline{\hat{w}_i} = \underline{0}$.

$$E[\hat{w}_i] = p_i \cdot \frac{w_i}{p_i} = w_i$$



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- For any i , $\mathbf{E}[\hat{w}_i] = w_i$.

A handwritten red box containing the equation $\sum_{i=1}^n p_i = 1$. An arrow points from the left towards the box.

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Question: How should we choose p_i 's?

- Choose to reduce variance for queries of interest (depends on queries)
- Expected number of chosen points is $\sum_i p_i$ and hence choose p_i 's to roughly meet the memory bound. If we have memory of size k then can scale p_i values (sampling rate) to achieve this.

Importance Sampling in Streaming Setting

Setting:

- points a_1, \dots, a_n with weights arriving in stream
- have a memory size of k
- want to maintain a k -sample (to utilize memory as well as possible) such that we can estimate $w(C \cap X)$ accurately
- Stream length unknown! How can we adjust sampling rate?

w_1, w_2, \dots, w_n
 a_1, a_2, \dots, a_n

Memory k .



Given query C . reclaim

want to estimate $w(C \cap X)$

Priority Sampling

[Duffield,Lund,Thorup]

- Queries are arbitrary subset sums so no structure there to exploit
- Focus on streaming aspect and using memory

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Scheme:

$$\rightarrow q_i = \frac{w_i}{u_i} \quad u_i \in_r (0,1)$$

- 1 For each $i \in [n]$ set priority $q_i = w_i / u_i$ where u_i is chosen uniformly (and independently from other items) at random from $[0, 1]$.
- 2 S is the set of items with the k highest priorities.
- 3 τ is the $(k + 1)$ 'st highest priority. If $k \geq n$ we set $\tau = 0$.
- 4 If $i \in S$, set $\hat{w}_i = \max\{w_i, \tau\}$, else set $\hat{w}_i = 0$.

$$\begin{array}{cccc}
 a_1 & a_2 & a_{10} & a_n \\
 | & | & | & | \\
 u_1 & u_2 & \dots & u_n \\
 0.1 & 0.5 & 0.4 & 0.6 \\
 a_i = \frac{1}{0.1} & \frac{1}{0.5} & \frac{1}{0.4} & \frac{1}{0.6} \quad k=2
 \end{array}$$

indep
 $u_i \in (0,1)$

$$S = \{a_1, a_{10}\} \quad \tau = \frac{1}{0.5}$$

$$\hat{\omega}_1 = \max \{ \omega_1, \tau \}$$

$$\{1, \tau\}$$

(1)

$$\frac{1}{k+2}$$

(k+2)

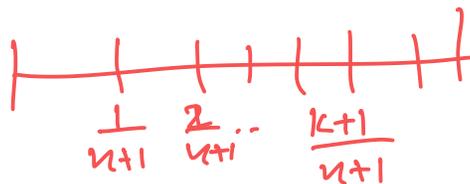
$\tau \approx ?$

throwing n random #

n (0,1) random #s.

want $k+1$ st smallest value?

$$\frac{k+2}{n} \quad \tau = \frac{n}{k+2}$$



$$\frac{n+1}{k+1}$$

Priority Sampling

[Duffield,Lund,Thorup]

- Queries are arbitrary subset sums so no structure there to exploit
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Claim: Can maintain S, τ in streaming setting

	a_1	a_2	\dots	a_n	
w	10	5	3	2	11
u	0.3	0.2	0.5		0.6

$$q_i = \frac{w_i}{u_i}$$

Sort and take k
highest
elements

$\tau = k+1$ highest
priority

$$\hat{w}_i = \max\{w_i, \tau\}$$

Priority Sampling

Intuition: from uniform weight case

- Suppose $w_i = 1$ for all i . Then sampling k without repetition can be done via adaptation of reservoir sampling.
- A different approach: pick a uniformly random $r_i \in [0, 1]$ for each i . And pick top k in terms of r_i values (simulates random permutation) but can be done in streaming fashion. Many other distributions would work too and picking top k according to $1/r_i$ works too.
- Why $1/r_i$? What is the expected value of τ ?

Priority Sampling: Properties

Lemma

$$E[\hat{w}_i] = w_i. \quad \checkmark$$

Priority Sampling: Properties

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Lemma

$$\underline{\underline{Var[\hat{w}_i]}} = E[\hat{v}_i] \text{ where } \hat{v}_i = \begin{cases} \tau \max\{0, \tau - w_i\} & \text{if } i \in S \\ 0 & \text{if } i \notin S \end{cases}$$

Useful: storing τ and w_i gives $Var[\hat{w}_i]$.

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Lemma

If $k \geq 2$ for any $i \neq j$, $E[\hat{w}_i \hat{w}_j] = \underline{w_i w_j}$.

Lemma

Fix any set $C \subset [n]$. $\underline{E[\prod_{i \in C} \hat{w}_i]} = \underline{\prod_{i \in C} w_i}$ if $|C| \leq k$ and is 0 if $|C| > k$.

Variance of subset sum

Lemma

If $k \geq 2$ for any $i \neq j$, $\mathbf{E}[\hat{w}_i \hat{w}_j] = w_i w_j$.

Consequence:

- Fix C . Unbiased estimator of $w(C \cap X)$ is $\hat{w}(C \cap S)$.
- Can we know the variance of the estimate to know if we are doing ok?
- $\text{Var}[\hat{w}(C \cap S)] = \sum_{i \in C \cap S} \text{Var}[\hat{w}_i] = \sum_{i \in C \cap S} \mathbf{E}[\hat{v}_i]$. Hence, storing τ and \hat{w}_i values suffices to estimate the variance of the estimate.

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Fix i . Let $A(\tau')$ be the event that the k 'th highest priority among items $j \neq i$ is τ' .

Note that u_i is independent of τ' . Hence $i \in S$ if $q_i = w_i/u_i \geq \tau'$ and if $i \in S$ then $\hat{w}_i = \max\{w_i, \tau'\}$, otherwise $\hat{w}_i = 0$. To evaluate $\Pr[i \in S \mid A(\tau')]$ we consider two cases.

Case 1: $w_i \geq \tau'$. Here we have $\Pr[i \in S \mid A(\tau')] = 1$ and $\hat{w}_i = w_i$.

Case 2: $w_i < \tau'$. Then $\Pr[i \in S \mid A(\tau')] = \frac{w_i}{\tau'}$ and $\hat{w}_i = \tau'$.

In both cases we see that $E[\hat{w}_i] = w_i$.

Variance

Lemma

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Fix i . We define $A(\tau')$ to be the event that τ' is the k 'th highest priority among elements $j \neq i$.

Show that

$$E[\hat{v}_i \mid A(\tau')] = E[\hat{w}_i^2 \mid A(\tau')] - w_i^2.$$

Since u_i is independent of τ' we can remove conditioning

Variance

$$E[\hat{v}_i | A(\tau')] = E[\hat{w}_i^2 | A(\tau')] - w_i^2.$$

$$\begin{aligned} E[\hat{v}_i | A(\tau')] &= \Pr[i \in S | A(\tau')] \times E[\hat{v}_i | i \in S \wedge A(\tau')] \\ &= \min\{1, w_i/\tau'\} \times \tau' \max\{0, \tau' - w_i\} \\ &= \max\{0, w_i\tau' - w_i^2\}. \end{aligned}$$

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Requires a proof by induction. See notes

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More generally

Lemma

Fix any set $C \subset [n]$. $\mathbf{E}[\prod_{i \in C} \hat{w}_i] = \prod_{i \in C} w_i$ if $|C| \leq k$ and is 0 if $|C| > k$.

Requires a proof by induction. See notes

Why is this interesting/non-obvious? In vanilla importance sampling the variables \hat{w}_i are independent. However, here the variables are correlated because we choose exactly k . Nevertheless, they exhibit properties similar to independence.

Application of ℓ_2 sampling to F_p estimation

For $p > 2$ AMS-Sampling gives algorithm to estimate F_p using $\tilde{O}(n^{1-1/p})$ space. Optimal space is $\tilde{O}(n^{1-2/p})$.

- Use ℓ_2 sampling algorithm to generate $(i, |\tilde{x}_i|)$
- Estimate $\|x\|_2^2$
- Output $T = \|x\|_2^2 |\tilde{x}_i|^{p-2}$ as estimate

To simplify analysis/notation assume sampling is exact.

$$\mathbf{E}[T] = \|x\|_2^2 \sum_i \frac{x_i^2}{\|x\|_2^2} |x_i|^{p-2} = \sum_i |x_i|^p$$

$$\mathbf{Var}[T] \leq \|x\|_2^4 \sum_i \frac{x_i^2}{\|x\|_2^2} x_i^{2(p-2)} \leq \|x\|_2^2 \sum_i x_i^{2p-2} \leq n^{1-2/p} (\sum_i |x_i|^p)^2.$$

Now do average plus median.