

## Applications of CountMin and Count Sketches

Lecture 10

September 24, 2020

# CountMin Sketch

**CountMin-Sketch( $w, d$ ):**

$h_1, h_2, \dots, h_d$  are pair-wise independent hash functions  
from  $[n] \rightarrow [w]$ .

While (stream is not empty) do

$e_t = (i_t, \Delta_t)$  is current item

    for  $\ell = 1$  to  $d$  do

$C[\ell, h_\ell(i_j)] \leftarrow C[\ell, h_\ell(i_j)] + \Delta_t$

    endWhile

For  $i \in [n]$  set  $\tilde{x}_i = \min_{\ell=1}^d C[\ell, h_\ell(i)]$ .

Counter  $C[\ell, j]$  simply counts the sum of all  $x_i$  such that  $h_\ell(i) = j$ .

That is,

$$C[\ell, j] = \sum_{i: h_\ell(i)=j} x_i.$$

# Summarizing

## Lemma

Let  $d = \Omega(\log \frac{1}{\delta})$  and  $w > \frac{2}{\epsilon}$ . Then for any fixed  $i \in [n]$ ,  $x_i \leq \tilde{x}_i$  and

$$\Pr[\tilde{x}_i \geq x_i + \epsilon \|x\|_1] \leq \delta.$$

## Corollary

With  $d = \Omega(\ln n)$  and  $w = 2/\epsilon$ , with probability  $(1 - \frac{1}{n})$  for all  $i \in [n]$ :

$$\tilde{x}_i \leq x_i + \epsilon \|x\|_1.$$

Total space:  $O(\frac{1}{\epsilon} \log n)$  counters and hence  $O(\frac{1}{\epsilon} \log n \log m)$  bits.

# Count Sketch

**Count-Sketch**( $w, d$ ):

$h_1, h_2, \dots, h_d$  are pair-wise independent hash functions  
from  $[n] \rightarrow [w]$ .

$g_1, g_2, \dots, g_d$  are pair-wise independent hash functions  
from  $[n] \rightarrow \{-1, 1\}$ .

While (stream is not empty) do

$e_t = (i_t, \Delta_t)$  is current item

    for  $\ell = 1$  to  $d$  do

$C[\ell, h_\ell(i_j)] \leftarrow C[\ell, h_\ell(i_j)] + g(i_t)\Delta_t$

    endWhile

For  $i \in [n]$

    set  $\tilde{x}_i = \text{median}\{g_1(i)C[1, h_1(i)], \dots, g_d(i)C[d, h_d(i)]\}$ .

# Summarizing

## Lemma

Let  $d \geq 4 \log \frac{1}{\delta}$  and  $w > \frac{3}{\epsilon^2}$ . Then for any fixed  $i \in [n]$ ,  $\mathbf{E}[\tilde{x}_i] = x_i$  and  $\Pr[|\tilde{x}_i - x_i| \geq \epsilon \|x\|_2] \leq \delta$ .

## Corollary

With  $d = \Omega(\ln n)$  and  $w = 3/\epsilon^2$ , with probability  $(1 - \frac{1}{n})$  for all  $i \in [n]$ :

$$|\tilde{x}_i - x_i| \leq \epsilon \|x\|_2.$$

Total space  $O(\frac{1}{\epsilon^2} \log n)$  counters and hence  $O(\frac{1}{\epsilon^2} \log n \log m)$  bits.

# Part I

## Applications

# Heavy Hitters: Point queries

**Heavy Hitters Problem:** Find all items  $i$  such that  $x_i > \alpha \|x\|_1$  for some fixed  $\alpha \in (0, 1]$ .

Approximate version: output any  $i$  such that  $x_i \geq (\alpha - \epsilon) \|x\|_1$

The sketches give us a data structure such that for any  $i \in [n]$  we get an estimate  $\tilde{x}_i$  of  $x_i$  with additive error.

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Go over each  $i$  and check if  $\tilde{x}_i > (\alpha - \epsilon) \|x\|_1$ .

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Additional data structures to speed up above computation and reduce time/space to be proportional to  $O(\frac{1}{\alpha} \text{polylog}(n))$ . More tricky for Count Sketch. See notes and references

# Range Queries

**Range query:** given  $i, j \in [n]$  want to know  $\sum_{i \leq \ell \leq j} x[\ell]$

Examples:

- $[n]$  corresponds to IP address space in network routing and  $[i, j]$  corresponds to addresses in a range
- $[n]$  corresponds to some numerical attribute in a database and we want to know number of records within a range
- $[n]$  corresponds to the discretization of a signal value

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Want to create a sketch data structure that can answer range queries for any given range that is chosen *after* the sketch is done.  $\Omega(n^2)$  potential queries

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**Simple idea:** imagine a binary tree over  $[n]$  and any interval  $[i, j]$  can be broken up into  $O(\log n)$  disjoint "dyadic" intervals

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Create one sketch data structure per level of binary tree

Output estimate  $\tilde{x}[i, j]$  by adding estimates for  $O(\log n)$  dyadic intervals that  $[i, j]$  decomposes into

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Output estimate  $\tilde{x}[i, j]$  by adding estimates for  $O(\log n)$  dyadic intervals that  $[i, j]$  decomposes into

To manage error choose  $\epsilon' = \epsilon / \log n$ : total space is  $O(\alpha \log n / \epsilon)$  where  $\alpha$  is the space for single level sketch

## Part II

# Sparse Recovery

# Sparse Recovery

**Sparsity** is an important theme in optimization/algorithms/modeling

- Data is often *explicitly* sparse. Examples: graphs, matrices, vectors, documents (as word vectors)
- Data is often *implicitly* sparse — in a different representation the data is explicitly sparse. Examples: signals/images, topics, etc

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## Algorithmic goals

- Take advantage of sparsity to improve performance (speed, quality, memory etc)
- Find implicit sparse representation to reveal information about data. Example: topics in documents, frequencies in Fourier analysis

# Sparse Recovery

**Problem:** Given vector/signal  $x \in \mathbb{R}^n$  find a sparse vector  $z$  such that  $z$  approximates  $x$

**More concretely:** given  $x$  and integer  $k \geq 1$ , find  $z$  such that  $z$  has at most  $k$  non-zeroes ( $\|z\|_0 \leq k$ ) such that  $\|x - z\|_p$  is minimized for some  $p \geq 1$ .

**Optimum offline solution:**  $z$  picks the largest  $k$  coordinates of  $x$  (in absolute value)

Want to do it in streaming setting: turnstile streams and  $p = 2$  and want to use  $\tilde{O}(k)$  space proportional to output

# Sparse Recovery under $\ell_2$ norm

Formal objective function:

$$\text{err}_2^k(x) = \min_{z: \|z\|_0 \leq k} \|x - z\|_2$$

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$$\text{err}_2^k(\mathbf{x}) = \min_{z: \|z\|_0 \leq k} \|\mathbf{x} - z\|_2$$

$\text{err}_2^k(\mathbf{x})$  is interesting only when it is small compared to  $\|\mathbf{x}\|_2$

For instance when  $\mathbf{x}$  is uniform, say  $x_i = 1$  for all  $i$  then  $\|\mathbf{x}\|_2 = \sqrt{n}$  but  $\text{err}_2^k(\mathbf{x}) = \sqrt{n-k}$

$\text{err}_2^k(\mathbf{x}) = 0$  iff  $\|\mathbf{x}\|_0 \leq k$  and hence related to distinct element detection

# Sparse Recovery under $\ell_2$ norm

## Theorem

There is a linear sketch with size  $O(\frac{k}{\epsilon^2} \text{polylog}(n))$  that returns  $z$  such that  $\|z\|_0 \leq k$  and with high probability  $\|x - z\|_2 \leq (1 + \epsilon) \text{err}_2^k(x)$ .

Hence space is proportional to desired output. Assumption  $k$  is typically quite small compared to  $n$ , the dimension of  $x$ .

Note that if  $x$  is  $k$ -sparse vector is exactly reconstructed

Based on CountSketch

# Algorithm

- Use Count Sketch with  $w = 3k/\epsilon^2$  and  $d = \Omega(\log n)$ .
- Count Sketch gives estimates  $\tilde{x}_i$  for each  $i \in n$
- Output the  $k$  coordinates with the largest estimates

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## Intuition for analysis

- With  $w = ck/\epsilon^2$  the  $k$  biggest coordinates will be spread out in their own buckets
- rest of small coordinates will be spread out evenly
- refine the analysis of Count-Sketch to carefully analyze the two scenarios

# Analysis Outline

## Lemma

Count-Sketch with  $w = 3k/\epsilon^2$  and  $d = O(\log n)$  ensures that

$$\forall i \in [n], \quad |\tilde{x}_i - x_i| \leq \frac{\epsilon}{\sqrt{k}} \text{err}_2^k(x)$$

with high probability (at least  $(1 - 1/n)$ ).

## Lemma

Let  $x, y \in \mathbb{R}^n$  such that  $\|x - y\|_\infty \leq \frac{\epsilon}{\sqrt{k}} \text{err}_2^k(x)$ . Then,  $\|x - z\|_2 \leq (1 + 5\epsilon) \text{err}_2^k(x)$ , where  $z$  is the vector obtained as follows:  $z_i = y_i$  for  $i \in T$  where  $T$  is the set of  $k$  largest (in absolute value) indices of  $y$  and  $z_i = 0$  for  $i \notin T$ .

Lemmas combined prove the correctness of algorithm.

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    endWhile

For  $i \in [n]$

    set  $\tilde{x}_i = \text{median}\{g_1(i)C[1, h_1(i)], \dots, g_d(i)C[d, h_d(i)]\}$ .

# Recap of Analysis

Fix an  $i \in [n]$ . Let  $Z_\ell = g_\ell(i)C[\ell, h_\ell(i)]$ .

For  $i' \in [n]$  let  $Y_{i'}$  be the indicator random variable that is  $\mathbf{1}$  if  $h_\ell(i) = h_\ell(i')$ ; that is  $i$  and  $i'$  collide in  $h_\ell$ .

$E[Y_{i'}] = E[Y_{i'}^2] = 1/w$  from pairwise independence of  $h_\ell$ .

$$Z_\ell = g_\ell(i)C[\ell, h_\ell(i)] = g_\ell(i) \sum_{i'} g_\ell(i') x_{i'} Y_{i'}$$

Therefore,

$$E[Z_\ell] = x_i + \sum_{i' \neq i} E[g_\ell(i)g_\ell(i')Y_{i'}]x_{i'} = x_i,$$

because  $E[g_\ell(i)g_\ell(i')] = 0$  for  $i \neq i'$  from pairwise independence of  $g_\ell$  and  $Y_{i'}$  is independent of  $g_\ell(i)$  and  $g_\ell(i')$ .

# Recap of Analysis

$Z_\ell = g_\ell(i)C[\ell, h_\ell(i)]$ . And  $\mathbf{E}[Z_\ell] = x_i$ .

$$\begin{aligned}\text{Var}(Z_\ell) &= \mathbf{E}[(Z_\ell - x_i)^2] \\ &= \mathbf{E}\left[\left(\sum_{i' \neq i} g_\ell(i)g_\ell(i')Y_{i'}x_{i'}\right)^2\right] \\ &= \mathbf{E}\left[\sum_{i' \neq i} x_{i'}^2 Y_{i'}^2 + \sum_{i' \neq i''} x_{i'}x_{i''}g_\ell(i')g_\ell(i'')Y_{i'}Y_{i''}x_{i'}x_{i''}\right] \\ &= \sum_{i' \neq i} x_{i'}^2 \mathbf{E}[Y_{i'}^2] \\ &\leq \|\mathbf{x}\|_2^2/w.\end{aligned}$$

# Refining Analysis

$$\mathcal{T}_{\text{big}} = \{i' \mid i' \text{ is one of the } k \text{ biggest coordinates in } \mathbf{x}\}$$

$$\mathcal{T}_{\text{small}} = [n] \setminus \mathcal{T}$$

$$\sum_{i' \in \mathcal{T}_{\text{small}}} x_{i'}^2 = (\text{err}_2^k(\mathbf{x}))^2$$

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## Lemma

$$\Pr\left[|Z_\ell - x_i| \geq \frac{\epsilon}{\sqrt{k}} \text{err}_2^k(\mathbf{x})\right] \leq 2/5.$$

# Analysis

$$Z_\ell = g_\ell(i)C[\ell, h_\ell(i)].$$

Let  $A_\ell$  be event that  $h_\ell(i') = h_\ell(i)$  for some  $i' \in T_{\text{big}}, i' \neq i$

## Lemma

$\Pr[A_\ell] \leq \epsilon^2/3$ . In other words with  $1 - \epsilon^2/3$  probability no big coordinates collide with  $i$  under  $h_\ell$ .

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- $Y_{i'}$  indicator for  $i' \neq i$  colliding with  $i$ .  
 $\Pr[Y_{i'}] \leq 1/w \leq \epsilon^2/(3k)$ .
- Let  $Y = \sum_{i' \in T_{\text{big}}} Y_{i'}$ .  $\mathbf{E}[Y] \leq \epsilon^2/3$  by linearity of expectation.
- Hence  $\Pr[A_\ell] = \Pr[Y \geq 1] \leq \epsilon^2/3$  by Markov

# Analysis

$$\begin{aligned} Z_\ell &= g_\ell(i)C[\ell, h_\ell(i)] \\ &= x_i + \sum_{i' \in T_{\text{big}}} g_\ell(i)g_\ell(i')Y_{i'}x_{i'} + \sum_{i' \in T_{\text{small}}} g_\ell(i)g_\ell(i')Y_{i'}x_{i'} \end{aligned}$$

Let  $Z'_\ell = \sum_{i' \in T_{\text{small}}} g_\ell(i)g_\ell(i')Y_{i'}$

## Lemma

$$\Pr \left[ |Z'_\ell| \geq \frac{\epsilon}{\sqrt{k}} \text{err}_2^k(x) \right] \leq 1/3.$$

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## Lemma

$$\Pr \left[ |Z'_\ell| \geq \frac{\epsilon}{\sqrt{k}} \text{err}_2^k(x) \right] \leq 1/3.$$

- $\mathbf{E}[Z'_\ell] = 0$
- $\text{Var}(Z'_\ell) \leq \mathbf{E}[(Z'_\ell)^2] = \sum_{i' \in T_{\text{small}}} x_{i'}^2 / w \leq \frac{\epsilon^2}{3k} (\text{err}_2^k(x))^2$
- By Cheybshev  $\Pr \left[ |Z'_\ell| \geq \frac{\epsilon}{\sqrt{k}} \text{err}_2^k(x) \right] \leq 1/3.$

# Analysis: Proof of lemma

Want to show:

**Lemma**

$$\Pr \left[ |Z_\ell - x_i| \geq \frac{\epsilon}{\sqrt{k}} \text{err}_2^k(x) \right] \leq 2/5.$$

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We have  $Z_\ell = g_\ell(i) C[\ell, h_\ell(i)]$

$$= x_i + \sum_{i' \in T_{\text{big}}} g_\ell(i) g_\ell(i') Y_{i'} x_{i'} + \sum_{i' \in T_{\text{small}}} g_\ell(i) g_\ell(i') Y_{i'} x_{i'}$$

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We saw:

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$\Pr[A_\ell] \leq \epsilon^2/3$ . In other words with  $1 - \epsilon^2/3$  probability no big coordinates collide with  $i$  under  $h_\ell$ .

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$|Z_\ell - x_i| \geq \frac{\epsilon}{\sqrt{k}}\text{err}_2^k(x)$  implies

- $A_\ell$  happens (that is some big coordinate collides with  $i$  in  $h_\ell$  or
- $|Z'_\ell| \geq \frac{\epsilon}{\sqrt{k}}\text{err}_2^k(x)$

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Therefore, by union bound,

$$\Pr\left[|Z_\ell - x_i| \geq \frac{\epsilon}{\sqrt{k}} \text{err}_2^k(x)\right] \leq \epsilon^2/3 + 1/3 \leq 2/5$$

if  $\epsilon$  is sufficiently small.

# High probability estimate

## Lemma

$$\Pr \left[ |Z_\ell - x_i| \geq \frac{\epsilon}{\sqrt{k}} \text{err}_2^k(x) \right] \leq 2/5.$$

Recall  $\tilde{x}_i = \text{median}\{g_1(i)C[1, h_1(i)], \dots, g_d(i)C[d, h_d(i)]\}$ .

- Hence by Chernoff bounds with  $d = \Omega(\log n)$ ,

$$\Pr \left[ |\tilde{x}_i - x_i| \geq \frac{\epsilon}{\sqrt{k}} \text{err}_2^k(x) \right] \leq 1/n^2$$

- By union bound, with probability at least  $(1 - 1/n)$ ,  
 $|\tilde{x}_i - x_i| \leq \frac{\epsilon}{\sqrt{k}} \text{err}_2^k(x)$  for all  $i \in [n]$ .

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## Lemma

*Count-Sketch with  $w = 3k/\epsilon^2$  and  $d = O(\log n)$  ensures that  $\forall i \in [n]$ ,  $|\tilde{x}_i - x_i| \leq \frac{\epsilon}{\sqrt{k}} \text{err}_2^k(x)$  with high probability (at least  $(1 - 1/n)$ ).*

# Second lemma of outline

## Lemma

Let  $\mathbf{x}, \mathbf{y} \in \mathbb{R}^n$  such that  $\|\mathbf{x} - \mathbf{y}\|_\infty \leq \frac{\epsilon}{\sqrt{k}} \text{err}_2^k(\mathbf{x})$ . Then,  $\|\mathbf{x} - \mathbf{z}\|_2 \leq (1 + 5\epsilon) \text{err}_2^k(\mathbf{x})$ , where  $\mathbf{z}$  is the vector obtained as follows:  $z_i = y_i$  for  $i \in T$  where  $T$  is the set of  $k$  largest (in absolute value) indices of  $\mathbf{y}$  and  $z_i = 0$  for  $i \notin T$ .

What the lemma is saying:

- $\tilde{\mathbf{x}}$  the estimated vector of Count-Sketch approximates  $\mathbf{x}$  very closely in *each coordinate*
- Algorithm picks the top  $k$  coordinates of  $\tilde{\mathbf{x}}$  to create  $\mathbf{z}$
- Then  $\mathbf{z}$  approximates  $\mathbf{x}$  well

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What the lemma is saying:

- $\tilde{x}$  the estimated vector of Count-Sketch approximates  $x$  very closely in *each coordinate*
- Algorithm picks the top  $k$  coordinates of  $\tilde{x}$  to create  $z$
- Then  $z$  approximates  $x$  well

Proof is basically follows the intuition of triangle inequality

# Proof of lemma

$S$  (previously  $T_{\text{big}}$ ) is set of  $k$  biggest coordinates in  $x$

$T$  is the set of  $k$  biggest coordinates in  $y = \tilde{x}$

Let  $E = \frac{1}{\sqrt{k}} \text{err}_2^k(x)$  for ease of notation.

$$(\text{err}_2^k(x))^2 = kE^2 = \sum_{i \in [n] \setminus S} x_i^2 = \sum_{i \in T \setminus S} x_i^2 + \sum_{i \in [n] \setminus (S \cup T)} x_i^2.$$

Want to bound

$$\begin{aligned} \|x - z\|_2^2 &= \sum_{i \in T} |x_i - z_i|^2 + \sum_{i \in S \setminus T} |x_i - z_i|^2 + \sum_{i \in [n] \setminus (S \cup T)} x_i^2 \\ &= \sum_{i \in T} |x_i - y_i|^2 + \sum_{i \in S \setminus T} x_i^2 + \sum_{i \in [n] \setminus (S \cup T)} x_i^2. \end{aligned}$$

# Analysis continued

Want to bound

$$\begin{aligned}\|x - z\|_2^2 &= \sum_{i \in T} |x_i - z_i|^2 + \sum_{i \in S \setminus T} |x_i - z_i|^2 + \sum_{i \in [n] \setminus (S \cup T)} x_i^2 \\ &= \sum_{i \in T} |x_i - y_i|^2 + \sum_{i \in S \setminus T} x_i^2 + \sum_{i \in [n] \setminus (S \cup T)} x_i^2.\end{aligned}$$

First term:  $\sum_{i \in T} |x_i - \tilde{x}_i|^2 \leq k\epsilon^2 E^2 \leq \epsilon^2 (\text{err}_2^k(x))^2$

# Analysis continued

Want to bound

$$\begin{aligned}\|x - z\|_2^2 &= \sum_{i \in T} |x_i - z_i|^2 + \sum_{i \in S \setminus T} |x_i - z_i|^2 + \sum_{i \in [n] \setminus (S \cup T)} x_i^2 \\ &= \sum_{i \in T} |x_i - y_i|^2 + \sum_{i \in S \setminus T} x_i^2 + \sum_{i \in [n] \setminus (S \cup T)} x_i^2.\end{aligned}$$

First term:  $\sum_{i \in T} |x_i - \tilde{x}_i|^2 \leq k\epsilon^2 E^2 \leq \epsilon^2 (\text{err}_2^k(x))^2$

Third term: common to expression for  $(\text{err}_2^k(x))^2$

# Analysis continued

Want to bound

$$\begin{aligned}\|x - z\|_2^2 &= \sum_{i \in T} |x_i - z_i|^2 + \sum_{i \in S \setminus T} |x_i - z_i|^2 + \sum_{i \in [n] \setminus (S \cup T)} x_i^2 \\ &= \sum_{i \in T} |x_i - y_i|^2 + \sum_{i \in S \setminus T} x_i^2 + \sum_{i \in [n] \setminus (S \cup T)} x_i^2.\end{aligned}$$

First term:  $\sum_{i \in T} |x_i - \tilde{x}_i|^2 \leq k\epsilon^2 E^2 \leq \epsilon^2 (\text{err}_2^k(x))^2$

Third term: common to expression for  $(\text{err}_2^k(x))^2$

Second term: needs more care

# Analysis contd

Want to bound  $\sum_{i \in S \setminus T} x_i^2$

Let  $\ell = |S \setminus T| \leq k$ . Since  $|S| = |T| = k$ ,  $|T \setminus S| = \ell$

Coordinates in  $S \setminus T$  and  $T \setminus S$  must be close: within  $\frac{\epsilon}{\sqrt{k}} \text{err}_2^k(x)$

# Analysis contd

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Coordinates in  $S \setminus T$  and  $T \setminus S$  must be close: within  $\frac{\epsilon}{\sqrt{k}} \text{err}_2^k(x)$

**Claim:** Let  $a = \max_{i \in S \setminus T} |x_i|$  and  $b = \min_{i \in T \setminus S} |x_i|$ . Then  $a \leq b + 2 \frac{\epsilon}{\sqrt{k}} \text{err}_2^k(x)$ .

# Analysis contd

Want to bound  $\sum_{i \in S \setminus T} x_i^2$

Let  $\ell = |S \setminus T| \leq k$ . Since  $|S| = |T| = k$ ,  $|T \setminus S| = \ell$

Coordinates in  $S \setminus T$  and  $T \setminus S$  must be close: within  $\frac{\epsilon}{\sqrt{k}} \text{err}_2^k(x)$

**Claim:** Let  $a = \max_{i \in S \setminus T} |x_i|$  and  $b = \min_{i \in T \setminus S} |x_i|$ . Then  $a \leq b + 2 \frac{\epsilon}{\sqrt{k}} \text{err}_2^k(x)$ .

Therefore

$$\begin{aligned} \sum_{i \in S \setminus T} x_i^2 &\leq \ell a^2 \leq \ell \left( b + 2 \frac{\epsilon}{\sqrt{k}} \text{err}_2^k(x) \right)^2 \\ &\leq \ell b^2 + 4k \frac{\epsilon^2}{k} (\text{err}_2^k(x))^2 + 4kb \frac{\epsilon}{\sqrt{k}} \text{err}_2^k(x). \end{aligned}$$

# Analysis contd

$$\begin{aligned}\sum_{i \in S \setminus T} x_i^2 &\leq la^2 \leq l(b + 2\frac{\epsilon}{\sqrt{k}}\text{err}_2^k(x))^2 \\ &\leq lb^2 + 4k\frac{\epsilon^2}{k}(\text{err}_2^k(x))^2 + 4kb\frac{\epsilon}{\sqrt{k}}\text{err}_2^k(x) \\ &\leq lb^2 + 4\epsilon^2(\text{err}_2^k(x))^2 + 4\epsilon(\sqrt{k}b)\text{err}_2^k(x) \\ &\leq lb^2 + 8\epsilon(\text{err}_2^k(x))^2 \\ &\leq \sum_{i \in T \setminus S} x_i^2 + 8\epsilon(\text{err}_2^k(x))^2.\end{aligned}$$

**Exercise:** Why is  $\sqrt{k}b \leq \text{err}_2^k(x)$ ? (We used it above.)

# Analysis contd

$$\begin{aligned}\|x - z\|_2^2 &= \sum_{i \in T} |x_i - z_i|^2 + \sum_{i \in S \setminus T} |x_i - z_i|^2 + \sum_{i \in [n] \setminus (S \cup T)} x_i^2 \\ &= \sum_{i \in T} |x_i - y_i|^2 + \sum_{i \in S \setminus T} x_i^2 + \sum_{i \in [n] \setminus (S \cup T)} x_i^2.\end{aligned}$$

First term:  $\sum_{i \in T} |x_i - \tilde{x}_i|^2 \leq k\epsilon^2 E^2 \leq \epsilon^2 (\text{err}_2^k(x))^2$

Third term: common to expression for  $(\text{err}_2^k(x))^2$

Second term: at most  $\sum_{i \in T \setminus S} x_i^2 + 8\epsilon (\text{err}_2^k(x))^2$

Hence

$$\|x - z\|_2^2 \leq (1 + 9\epsilon) (\text{err}_2^k(x))^2$$

Implies

$$\|x - z\|_2 \leq (\sqrt{1 + 9\epsilon}) \text{err}_2^k(x) \leq (1 + 5\epsilon) \text{err}_2^k(x)$$

# Application to signal processing

Given signal  $x$  approximate it via small number of basis signals

- Fourier analysis and Wavelets
- Useful in compression of various kinds

# Application to signal processing

Given signal  $x$  approximate it via small number of basis signals

- Fourier analysis and Wavelets
- Useful in compression of various kinds

Transform  $x$  into  $y = Bx$  where  $B$  is a transform and then approximate  $y$  by  $k$ -sparse vector  $z$

To (approximately) reconstruct  $x$ , output  $x' = B^{-1}z$

If  $Bx$  can be computed in streaming fashion from stream for  $x$ , we can apply preceding algorithm to obtain  $z$

# Compressed Sensing

We saw that *given*  $x$  in streaming fashion we can construct sketch that allows us to find  $k$ -sparse  $z$  that approximates  $x$  with high probability

**Compressed sensing:** we want to create projection matrix  $\Pi$  such that for *any*  $x$  we can create from  $\Pi x$  a good  $k$ -sparse approximation to  $x$

Doable! With  $\Pi$  that has  $O(k \log(n/k))$  rows. Creating  $\Pi$  requires randomization but once found it can be used. Called RIP matrices. First due to Candes, Romberg, Tao and Donoho. Lot of work in signal processing and algorithms.