

CS477 Formal Software Dev Methods

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Slides based in part on previous lectures
by Mahesh Vishwanathan, and by Gul Agha

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Standard Interpretation and Semantics

- Let $Contexts = \mathcal{P}(Env)$
 - $Contexts$ is a complete lattice
 - A context corresponds to a formula in predicate logic over the program variables (recall how we encoded Hoare Logic)
- If for all $e \in E$ we have $\theta(e) \subseteq \phi(e)$, then for all $e' \in E$ we have $Interp(\theta, e') \subseteq Interp(\phi, e')$
- **Result:** $(Contexts, Interp)$ is an abstract interpretation
- Recall: $Interp : ((E \rightarrow Contexts) \times E) \rightarrow Contexts$ so $\overline{Interp} : (E \rightarrow Contexts) \rightarrow (E \rightarrow Contexts)$
- $\overline{Interp}(\theta)(e) = Interp(\theta, e) = \overline{Interp}^1(\theta)(e)$
- $\overline{Interp}^{n+1}(\theta)(e) = \overline{Interp}(\overline{Interp}^n(\theta))(e)$
- $\mu \overline{Interp}(e) = \bigcup_{n \in \mathbb{N}} \overline{Interp}^n \{e' \mapsto \{\}\} (e)$
- $\mu \overline{Interp}$ tells us the best knowledge we can know about our program
- **Problem:** May take an unbounded amount of computation; as informative as transition semantics

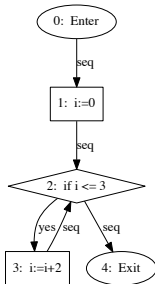
Example: *Interp*

Let θ map edges to sets of environments. *Interp* will tell us the set of environments `next_state` will associate with each edge assuming θ gives a set of (possibly) possible environments for each predecessor edge:

- Since $Var = \{i\}$,
 $Interp(\theta, (0, seq, 1)) = \{\text{next_state}((0, seq, 1), \{i \mapsto \perp\})\} = \{\{i \mapsto 0\}\}$
- Since $l(2) = \text{if } i \leq 3$ we have $Interp(\theta, (1, seq, 2)) = \theta((0, seq, 1))$
- $Interp(\theta, (2, yes, 3)) =$
 $\{\rho[i \mapsto \rho(i) + 2] \mid \rho \in (\theta(1, seq, 2) \cup \theta(3, seq, 2)) \wedge \rho(i) \leq 3\}$
- $Interp(\theta, (3, seq, 2)) = \theta(2, yes, 3)$
- $Interp(\theta, (2, no,)) = \{\rho \mid \rho \in (\theta(1, seq, 2) \cup \theta(3, seq, 2)) \wedge \rho(i) > 3\}$

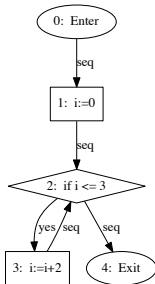
Example: $\mu \overline{\text{Interp}}$

- $\mu \overline{\text{Interp}} : E \rightarrow \text{Contexts} = \mathcal{P}(\text{Env})$
- Start with minimal θ_0 assigning no environments to any edge:
 $\theta_0(e) = \{ \}$
- $\mu \overline{\text{Interp}}(e) = \bigcup_{n \in \mathbb{N}} \overline{\text{Interp}}^n(e)$
- $\mu \overline{\text{Interp}}(0, \text{seq}, 1) = \{ \quad \quad \quad \}$
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- $\mu \overline{\text{Interp}}((2, \text{no}, 4)) = \{ \quad \quad \quad \}$



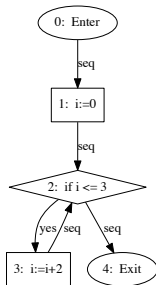
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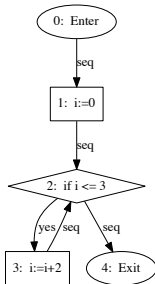
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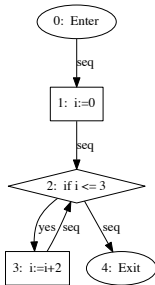
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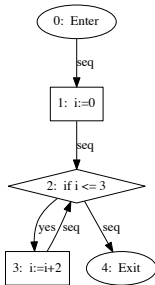
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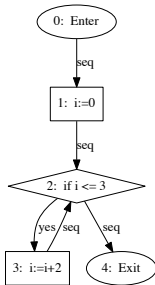
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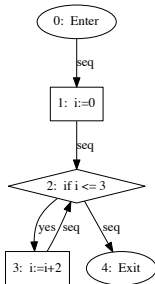
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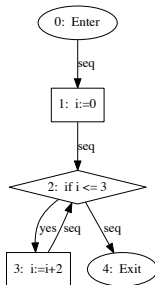
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Soundness of Abstract Semantics

Fact: An abstract interpretation (A, \mathcal{I}) is sound (or consistent) with respect to $(\text{Contexts}, \text{Interp})$ if and only if there exist α, β such that

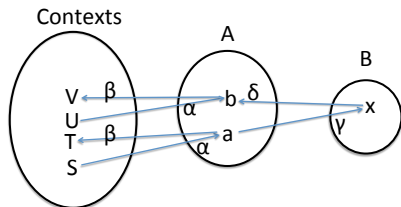
- $\alpha : \text{Contexts} \rightarrow A, \beta : A \rightarrow \text{Contexts}$
 - α, β order preserving
 - For all $a \in A$ have $\alpha(\beta(a)) = a$
 - For all $S \in \text{Contexts}$, have $S \subseteq \beta(\alpha(S))$
 - The abstract interpretation gives us more possibilities, is less precise
 - For all $e \in E, \alpha(\mu \overline{\text{Interp}}(e)) = \mu \overline{\mathcal{I}}(e)$
 - The pair (α, β) is called a *Galois Insertion*.
-
- Game: find useful A where we can compute $\mu \overline{\mathcal{I}}$, usually in time proportional to size of program

Composing Abstract Interpretations

- Observe: Can abstract an abstraction:
 - Given $\alpha : \text{Contexts} \rightarrow A$, $\beta : A \rightarrow \text{Contexts}$ such that for all $a \in A$ have $\alpha(\beta(a)) = a$ and for all $S \in \text{Contexts}$, have $S \subseteq \beta(\alpha(S))$
 - Given $\gamma : A \rightarrow B$, $\delta : B \rightarrow A$ such that for all $b \in B$ have $\gamma(\delta(b)) = b$ and for all $a \in A$, have $\delta(\gamma(a)) \leq a$
 - Then $(B, \gamma \circ \mu \bar{I})$ is another abstract interpretation.
 - If $A = \{a \mid \exists S \in \text{Contexts}. a = \alpha(S)\}$, then

$$\beta(a) = \bigcup \{S \in \text{Contexts} \mid \alpha(S) = a\}$$

- If our abstract domain is the image of *Contexts*, then we only need α , because we can compute β .



Some Abstract Interpretations

- Replace $Contexts = \mathcal{P}(Var \rightarrow Val)$ with $A = Var \rightarrow \mathcal{P}(Val)$.
Let $S \in Contexts$. Define

$$\alpha(S)(x) = \{v \mid \exists s \in S. s(x) = v\}$$

- Chain with $B = Var \rightarrow \{int, bool, \perp, \top\}$ and
 - $\gamma(a)(x) = int$ if $a(x)$ contains only integers (and \perp);
 - $\gamma(a)(x) = bool$ if $a(x)$ contains only booleans (and \perp);
 - $\gamma(a)(x) = \perp$ if $a(x) = \{\}$ or $a(x) = \{\perp\}$
 - $\gamma(a)(x) = \top$ otherwise
 - Can be used for type checking
- Chain with $B = Var \rightarrow \{\perp, \top\}$ and
 - $\gamma(a)(x) = \top$ if $a(x)$ contains something other than \perp ;
 - $\gamma(a)(x) = \perp$ if $a(x) = \{\perp\}$ or $a(x) = \{\}$
 - Can be used for checking variables are initialized before they are used.

Abstraction: $A = Var \rightarrow \mathcal{P}(Val)$

- Have $\alpha(S)(x) = \{v \mid \exists s \in S. s(x) = v\}$
 - Need to show
 - (onto A) $\forall x \in Var. \forall V \subseteq Val. \exists S \subseteq Env. V = \{v \mid \exists s \in S. s(x) = v\}$
- Pf:** Fix $x \in Var$ and $V \subseteq Val$. Let $S = \{s \in Env \mid s(x) \in V\}$. Because Env is all mappings of Var to Val , for any $v \in V$, there is a mapping s such that $s(x) = v$. Therefore, $V = \{v \mid \exists s \in S. s(x) = v\}$
- (order preserving) $\forall S, T \subseteq Env. S \subseteq T \Rightarrow (\forall x \in Var. \{v \in Val \mid \exists s \in S. s(x) = v\} \subseteq \{v \in Val \mid \exists s \in T. s(x) = v\})$
- Pf:** (sketch) If $s \in S$ then $s \in T$.
- This abstraction is the root of most abstraction
 - Still too informative; takes unbounded time to compute

Abstraction: $B = Var \rightarrow \{int, bool, \perp, \top\}$

- $\gamma : A \rightarrow B$ where
 - $\gamma(a)(x) = int$ if $a(x)$ contains only integers (and \perp);
 - $\gamma(a)(x) = bool$ if $a(x)$ contains only booleans (and \perp);
 - $\gamma(a)(x) = \perp$ if $a(x) = \{\}$ or $a(x) = \{\perp\}$
 - $\gamma(a)(x) = \top$ otherwise
- Still need onto and order-preserving
- Tells us for each variable if it is guaranteed to be used
- B has finite height this time
- Should be able to compute in bounded time
- But how?

New transfer (transition) functions from old

- Recall that $Interp : ((E \rightarrow \mathcal{P}(Env)) \times E) \rightarrow \mathcal{P}(Env)$ tells us how, for each edge, taking one step of computation updates the possible environments after that step of computation after that edge
- \overline{Interp} tells us how to update the environments at each edge after we let each edge do its endpoint computation, assuming each starting environment
- Given $\alpha : \mathcal{P}(Env) \rightarrow A$, order preserving and onto, construct $\alpha \circ \overline{Interp} : ((E \rightarrow A) \rightarrow (E \rightarrow A))$
- Calculating $\mu(\alpha \circ \overline{Interp}) : E \rightarrow A$ can be done in bounded time if calculating $\alpha \circ \overline{Interp}(\theta, e)$ can be for each $\theta \in (E \rightarrow A)$ and $e \in E$.

Worklist Algorithm

- Given transfer function $\mathcal{I} : ((E \rightarrow A) \times E) \rightarrow A$, want algorithm for finding $\mu \bar{\mathcal{I}}$
- Start with $\mathcal{I}_0 : E \rightarrow A$ by $\mathcal{I}_0(e) = \perp$ for all $e \in E$
- Let $Worklist = E$
- Assume we have computed \mathcal{I}_n
- while $not(Worklist = \{\})$ do
 - Pick $(n, k, m) \in Worklist$; let $Worklist = Worklist - \{(n, k, m)\}$
 - Let $in = lub\{a \mid \exists p, j. (p, j, n) \in E \wedge a = \mathcal{I}_n(p, j, n)\}$
 - Let $\mathcal{I}_{n+1}(n, k, m) = \mathcal{I}(\mathcal{I}_n, (n, k, m))$ and $\mathcal{I}_{n+1}(e) = \mathcal{I}_n(e)$ if $e \neq (n, k, m)$
 - If $\mathcal{I}_{n+1}(n, k, m) = \mathcal{I}_n(n, k, m)$ then
 $Worklist \neq Worklist \cup \{e \mid \exists j, p. e = (m, j, p)\}$
 - Repeat while
- $\mu \mathcal{I}(e) = \mathcal{I}_n(e)$ where n is the last value where a change was made