

CS477 Formal Software Development Methods

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Slides mostly a reproduction of Theo C. Ruys – SPIN Beginners'
Tutorial

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atomic

```
atomic { stat1; stat2; ... statn }
```

- can be used to group statements into an atomic sequence; all statements are executed in a single step (no interleaving with statements of other processes)
 - is executable if `stat1` is executable / no pure atomicity
 - if a `stati` (with `i>1`) is blocked, the “atomicity token” is (temporarily) lost and other processes may do a step
- (Hardware) solution to the mutual exclusion problem:

```
proctype P(bit i) {  
    atomic {flag != 1; flag = 1; }  
    mutex++;  
    mutex--;  
    flag = 0;  
}
```



d_step

```
d_step { stat1; stat2; ... statn }
```

- more **efficient** version of **atomic**: no intermediate states are generated and stored
- may only contain **deterministic** steps
- it is a **run-time error** if **stat_i** ($i > 1$) blocks.
- **d_step** is especially useful to perform intermediate computations in a **single transition**

```
:: Rout?i(v) -> d_step {  
    k++;  
    e[k].ind = i;  
    e[k].val = v;  
    i=0; v=0 ;  
}
```

- **atomic** and **d_step** can be used to **lower** the number of **states** of the model

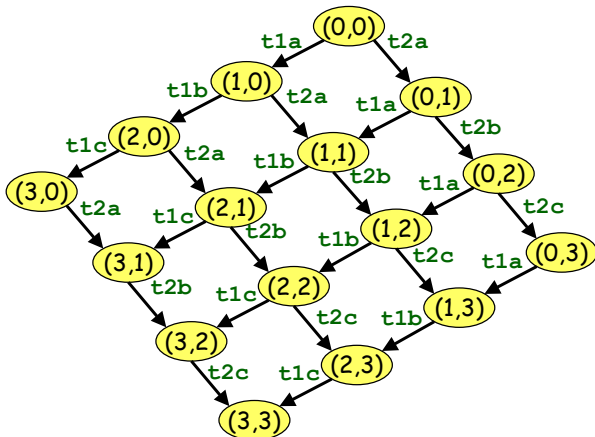
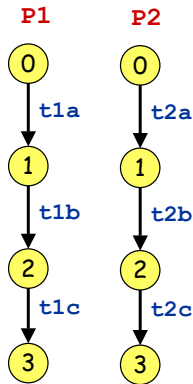


```

proctype P1() { t1a; t1b; t1c }
proctype P2() { t2a; t2b; t2c }
init { run P1(); run P2() }

```

No atomicity



Not completely correct as each process has an implicit end-transition...



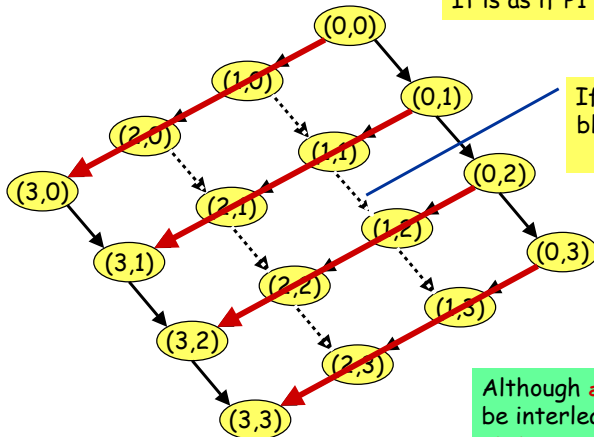
```

proctype P1() { atomic {t1a; t1b; t1c} }
proctype P2() { t2a; t2b; t2c }
init { run P1(); run P2() }

```

atomic

It is as if P1 has only one transition...



If one of P1's transitions blocks, these transitions may get executed

Although **atomic** clauses cannot be interleaved, the **intermediate states** are still constructed.



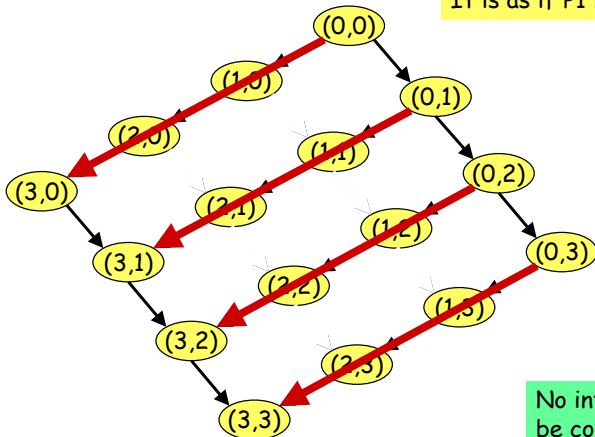
```

proctype P1() { d_step {t1a; t1b; t1c} }
proctype P2() { t2a; t2b; t2c }
init { run P1(); run P2() }

```

d_step

It is as if P1 has only one transition...



No intermediate states will be constructed.



timeout (1)

- Promela does **not** have **real-time** features.
 - In Promela we can only specify **functional behaviour**.
 - Most protocols, however, use **timers** or a **timeout** mechanism to **resend** messages or acknowledgements.
- **timeout**
 - SPIN's **timeout** becomes **executable** if there is **no other process** in the system which is executable
 - so, **timeout** models a **global timeout**
 - **timeout** provides an **escape** from **deadlock states**
 - **beware of statements** that are always executable...



goto

goto label

- transfers execution to **label**
- each Promela statement might be labelled
- quite useful in modelling **communication protocols**

```
wait_ack:
  if
  :: B?ACK -> ab=1-ab ; goto success
  :: ChunkTimeout?SHAKE ->
     if
     :: (rc < MAX) -> rc++; F!(i==1), (i==n), ab, d[i];
                    goto wait_ack
     :: (rc >= MAX) -> goto error
     fi
  fi ;
```

Timeout modelled by a channel.

Part of model of BRP



unless

```
{ <stats> } unless { guard; <stats> }
```

- Statements in *<stats>* are executed **until** the first statement (*guard*) in the escape sequence becomes executable.
- resembles **exception handling** in languages like Java
- *Example:*

```
proctype MicroProcessor() {  
  {  
    ...  
    /* execute normal instructions */  
  }  
  unless { port ? INTERRUPT; ... }  
}
```



Communication

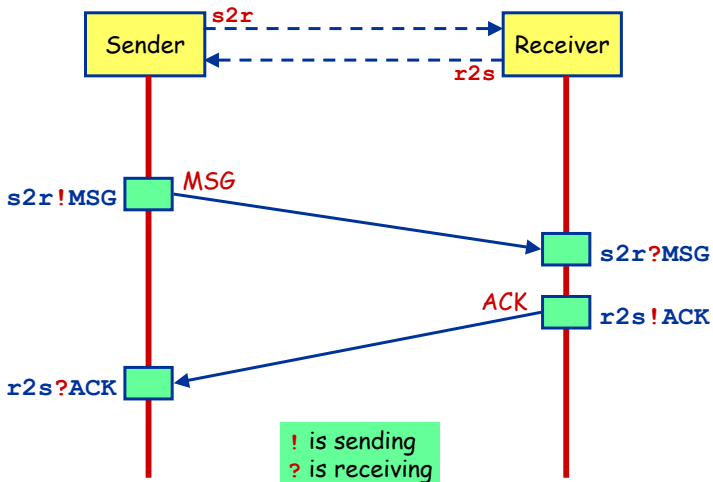
Major models of communication

- 1 **Shared variables**
 - one writes, many read later
- 2 **Point-to-Point synchronous** message passing
 - one **sends**, one other **receives at the same time**
 - **send blocks** until receive can happen
- 3 **Point-to-Point asynchronous** message passing
 - one **sends**, one other **receives some time later**
 - **send never blocks**
- 4 **Point-to-Point buffered** message passing
 - When buffer **not full** behaves like **asynchronous**
 - When buffer **full**, two variations: **block** or **drop message** *
 - **send never blocks**
- 5 **Synchronous broadcast**
 - one **sends**, many **receive synchronously**
 - First variation: **send never blocks** process may receive if ready to ready
 - Second variation: **send blocks** until all possible recipients ready to receive

Communication in SPIN

- With more or less complexity each can implement the others
- Spin supports 1 and 4 (blocks send when buffer full), but with bounded buffers
- Buffer size = 0 \implies **synchronous** communication
- Large buffer size approximates **asynchronous** communication

Communication (1)



Communication (2)

- Communication between processes is via **channels**:
 - **message passing**
 - **rendez-vous** synchronisation (**handshake**)
- Both are defined as **channels**:

also called:
queue or **buffer**

```
chan <name> = [<dim>] of {<t1>, <t2>, ... <tn>};
```

name of
the channel

type of the elements that will be
transmitted over the channel

number of elements in the channel
dim==0 is special case: **rendez-vous**

```
chan c      = [1] of {bit};  
chan toR   = [2] of {mtype, bit};  
chan line[2] = [1] of {mtype, Record};
```

array of
channels



Communication (3)

- channel = **FIFO**-buffer (for **dim>0**)

! Sending - putting a message into a channel

```
ch ! <expr1>, <expr2>, ... <exprn>;
```

- The values of **<expr_i>** should correspond with the types of the channel declaration.
- A **send**-statement is **executable** if the channel is **not full**.

? Receiving - getting a message out of a channel

<var> +
<const>
can be
mixed

```
ch ? <var1>, <var2>, ... <varn>;
```

message passing

- If the channel is **not empty**, the message is fetched from the channel and the individual parts of the message are stored into the **<var_i>**s.

```
ch ? <const1>, <const2>, ... <constn>;
```

message testing

- If the channel is **not empty** and the message at the front of the channel evaluates to the individual **<const_i>**, the statement is executable and the message is removed from the channel.



Communication (4)

- **Rendez-vous** communication

`<dim> == 0`

The number of elements in the channel is now **zero**.

- If **send ch!** is enabled and if there is a **corresponding receive ch?** that can be executed **simultaneously** and the constants match, then both statements are enabled.
- Both statements will “**handshake**” and **together** take the transition.
- **Example:**
 - `chan ch = [0] of {bit, byte};`
 - P wants to do `ch ! 1, 3+7`
 - Q wants to do `ch ? 1, x`
 - Then after the communication, `x` will have the value **10**.



Alternating Bit Protocol (1)

- **Alternating Bit Protocol**
 - To every message, the **sender** adds a **bit**.
 - The **receiver** **acknowledges** each message by sending the **received bit** back.
 - To **receiver** only **excepts** messages with a bit that it **excepted** to receive.
 - If the **sender** is sure that the **receiver** has **correctly** **received** the previous message, it sends a **new** **message** and it **alternates** the **accompanying bit**.



Alternating Bit Protocol (2)

```

mtype {MSG, ACK};

chan toS = ([2] of {mtype, bit});
chan toR = ([2] of {mtype, bit});

proctype Sender(chan in, out)
{
  bit sendbit, rcvbit;
  do
  :: out ! MSG, sendbit ->
    in ? ACK, rcvbit;
    if
    :: rcvbit == sendbit ->
      sendbit = 1-sendbit
    :: else
    fi
  od
}

```

channel
length of 2

```

proctype Receiver(chan in, out)
{
  bit rcvbit;
  do
  :: in ? MSG(rcvbit) ->
    out ! ACK(rcvbit);
  od
}

init
{
  run Sender(toS, toR);
  run Receiver(toR, toS);
}

```

Alternative notation:
 ch ! MSG(par1, ...)
 ch ? MSG(par1, ...)



```
bit flag; /* signal entering/leaving the section */
byte mutex; /* # procs in the critical section. */
proctype P(bit i) {
    flag != 1;
    flag = 1;
    mutex++;
    printf("MSC: P(%d) has entered section.\n", i); mutex--;
    flag = 0;
}
proctype monitor() {
    assert(mutex != 2);
}
init {
    atomic { run P(0); run P(1); run monitor(); }
}
```

SPIN as Simulator

```
bash-3.2$ spin mutexwrong1.pml
      MSC: P(0) has entered section.
          MSC: P(1) has entered section.
4 processes created
bash-3.2$ !s
spin mutexwrong1.pml
      MSC: P(1) has entered section.
          MSC: P(0) has entered section.
4 processes created
```

SPIN as Model Checker

```
bash-3.2$ spin -a mutexwrong1.pml
```

```
bash-3.2$ ls -ltr
```

```
total 3520
```

```
-rw-r--r-- 1 elsa staff    335 Apr 11 23:27 mutexwrong1.pml
-rw-r--r-- 1 elsa staff  18801 Apr 11 23:28 pan.t
-rw-r--r-- 1 elsa staff  54243 Apr 11 23:28 pan.p
-rw-r--r-- 1 elsa staff   3450 Apr 11 23:28 pan.m
-rw-r--r-- 1 elsa staff  16489 Apr 11 23:28 pan.h
-rw-r--r-- 1 elsa staff 309382 Apr 11 23:28 pan.c
-rw-r--r-- 1 elsa staff   919 Apr 11 23:28 pan.b
```

SPIN as Model Checker

```
bash-3.2$ cc -o pan pan.c
```

```
bash-3.2$ ./pan
```

```
hint: this search is more efficient if pan.c is  
      compiled -DSAFETY
```

```
pan:1: assertion violated (mutex!=2) (at depth 11)
```

```
pan: wrote mutexwrong1.pml.trail
```

```
(Spin Version 6.2.4 -- 8 March 2013)
```

```
Warning: Search not completed
```

```
+ Partial Order Reduction
```

```
Full statespace search for:
```

```
never claim          - (none specified)
```

```
assertion violations +
```

```
acceptance cycles - (not selected)
```

```
invalid end states +
```

SPIN as Model Checker

```
State-vector 44 byte, depth reached 20, errors: 1
  121 states, stored
  47 states, matched
  168 transitions (= stored+matched)
  2 atomic steps
hash conflicts:          0 (resolved)
```

```
Stats on memory usage (in Megabytes):
  0.008 equivalent memory usage for states
      (stored*(State-vector + overhead))
  0.291 actual memory usage for states
128.000 memory used for hash table (-w24)
  0.534 memory used for DFS stack (-m10000)
128.730 total actual memory usage
```

mutextwrong1.pml Error Trace

```
bash-3.2$ spin -t -p mutextwrong1.pml
using statement merging
Starting P with pid 1
  1: proc 0 (:init:) mutextwrong1.pml:14 (state 1) [(run P(0))]
Starting P with pid 2
  2: proc 0 (:init:) mutextwrong1.pml:14 (state 2) [(run P(1))]
Starting monitor with pid 3
  3: proc 0 (:init:) mutextwrong1.pml:14 (state 3) [(run monit
  4: proc 2 (P) mutextwrong1.pml:4 (state 1) [((flag!=1))]
  5: proc 1 (P) mutextwrong1.pml:4 (state 1) [((flag!=1))]
  6: proc 2 (P) mutextwrong1.pml:5 (state 2) [flag = 1]
  7: proc 2 (P) mutextwrong1.pml:6 (state 3) [mutex = (mutex+1)
      MSC: P(1) has entered section.
  8: proc 2 (P) mutextwrong1.pml:7 (state 4)
[printf('MSC: P(%d) has entered section.\n',i)]
  9: proc 1 (P) mutextwrong1.pml:5 (state 2) [flag = 1]
```

mutexwrong1.pml Error Trace

```
10: proc 1 (P) mutexwrong1.pml:6 (state 3) [mutex = (mutex+1)
    MSC: P(0) has entered section.
11: proc 1 (P) mutexwrong1.pml:7 (state 4)
[printf('MSC: P(%d) has entered section.\n',i)]
spin: mutexwrong1.pml:11, Error: assertion violated
spin: text of failed assertion: assert((mutex!=2))
12: proc 3 (monitor) mutexwrong1.pml:11 (state 1)
[assert((mutex!=2))]
spin: trail ends after 12 steps
```


mutexwrong1.pml Error Trace

```
#processes: 4
flag = 1
mutex = 2
 12: proc  3 (monitor) mutexwrong1.pml:12 (state 2) <valid end
 12: proc  2 (P) mutexwrong1.pml:7 (state 5)
 12: proc  1 (P) mutexwrong1.pml:7 (state 5)
 12: proc  0 (:init:) mutexwrong1.pml:15 (state 5) <valid end
4 processes created
bash-3.2$
```