

## CS477 Formal Software Development Methods

Elsa L Gunter  
2112 SC, UIUC  
egunter@illinois.edu  
<http://courses.engr.illinois.edu/cs477>

Slides based in part on previous lectures by Mahesh Vishwanathan, and by Gul Agha

February 21, 2014

## First Order Logic vs Propositional Logic

First Order Logic extends Propositional Logic with

- Non-boolean constants
- Variables
- Functions and relations (or predicates, more generally)
- Quantification of variables

Sample first order formula:

$$\forall x. \exists y. x < y \wedge y \leq x + 1$$

Reference: Peled, *Software Reliability Methods*, Chapter 3

## Signatures

Start with **signature**:

$$\mathcal{G} = (V, F, ar, R, ar)$$

- $V$  a countably infinite set of *variables*
- $F$  finite set of function symbols
- $af : F \rightarrow \mathbb{N}$  gives the *arity*, the number of arguments for each function Constant  $c$  is a function symbol of arity 0 ( $af(c) = 0$ )
- $R$  finite set of relation symbols
- $ar : R \rightarrow \mathbb{N}$ , the arity for each relation symbol
  - Assumes  $= \in R$  and  $ar(=) = 2$

## Terms over Signature

Terms  $t$  are expressions built over a signature  $(V, F, ar, R, ar)$

$$t ::= v \quad v \in V \\ | f(t_1, \dots, t_n) \quad f \in F \text{ and } n = af(f)$$

- **Example:**  $add(1, abs(x))$  where  $add, abs, 1 \in F$ ;  $x \in V$
- For constant  $c$  write  $c$  instead of  $c()$
- Will write  $s = t$  instead of  $=(s, t)$ 
  - Similarly for other common infixes (e.g.  $+$ ,  $-$ ,  $*$ ,  $<$ ,  $\leq$ , ...)

## Structures

Meaning of terms starts with a **structure**:

$$S = (\mathcal{D}, \mathcal{F}, \phi, \mathcal{R}, \rho)$$

where

- $\mathcal{G} = (V, F, ar, R, ar)$  a signature,
- $\mathcal{D}$  and *domain* on interpretation
- $\mathcal{F}$  set of functions over  $\mathcal{D}$ ;  $\mathcal{F} \subseteq \bigcup_{n \geq 0} \mathcal{D}^n \rightarrow \mathcal{D}$ 
  - **Note:**  $\mathcal{F}$  can contain elements of  $\mathcal{D}$  since  $\mathcal{D} = (\mathcal{D}^0 \rightarrow \mathcal{D})$
- $\phi : F \rightarrow \mathcal{F}$  where if  $\phi(f) \in (\mathcal{D}^n \rightarrow \mathcal{D})$  then  $n = af(f)$
- $\mathcal{R}$  set of relations over  $\mathcal{D}$ ;  $\mathcal{R} \subseteq \bigcup_{n \geq 1} \mathcal{P}(\mathcal{D}^n)$
- $\rho : R \rightarrow \mathcal{R}$  where if  $\rho(r) \subseteq \mathcal{D}^n$  then  $n = ar(r)$

## Assignments

$V$  set of variables,  $\mathcal{D}$  domain of interpretation

An **assignment** is a function  $a : V \rightarrow \mathcal{D}$

**Example:**

$$V = \{w, x, y, z\}$$

$$a = \{w \mapsto 3.14, x \mapsto -2.75, y \mapsto 13.9, z \mapsto -25.3\}$$

- Assignment is a fixed association of values to variables; not "update-able"

## Interpretation of Terms

Fix structure  $\mathcal{S} = (\mathcal{G}, \mathcal{D}, \mathcal{F}, \phi, \mathcal{R}, \rho)$  where  $\mathcal{G} = (V, F, af, R, ar)$

For given assignment  $a : V \rightarrow \mathcal{D}$ , the **interpretation**  $\mathcal{T}_a$  of a term  $t$  is defined by structural induction on terms:

- $\mathcal{T}_a(v) = a(v)$  for  $v \in V$
- $\mathcal{T}_a(f(t_1, \dots, t_n)) = \phi(f)(\mathcal{T}_a(t_1), \dots, \mathcal{T}_a(t_n))$

## Example of Interpretation

- $V = \{w, x, y, z\}$ ,  $\mathcal{D} = \mathbb{R}$
- $1, add, abs \in F$ , constant  $1$ , and functions (in  $\mathcal{F}$ ) for addition and absolute value respectively
- $a = \{w \mapsto 3.14, x \mapsto -2.75, y \mapsto 13.9, z \mapsto -25.3\}$

$$\begin{aligned} \mathcal{T}_a(add(1, abs(x))) &= (\mathcal{T}_a(1)) + (\mathcal{T}_a(abs(x))) \\ &= 1.0 + (\mathcal{T}_a(abs(x))) \\ &= 1.0 + |\mathcal{T}_a(x)| \\ &= 1.0 + |a(x)| \\ &= 1.0 + |-2.75| \\ &= 1.0 + 2.75 \\ &= 3.75 \end{aligned}$$

## First-Order Formulae

First-order formulae built from terms using relations, logical connectives, quantifiers:

```
form ::= true | false
      | r(t1, ..., tn)   r ∈ R, ti terms, n = ar(r)
      | (form) | ¬form
      | form ∧ form
      | form ∨ form
      | form ⇒ form
      | form ⇔ form
      | ∀v.form
      | ∃v.form
```

**Note:** Scope of quantifiers as far to right as possible

$\forall x.(x > y) \wedge (2 > x)$  same as  $\forall x.((x > y) \wedge (2 > x))$   
 not same as  $(\forall x.(x > y)) \wedge (2 > x)$

## Subformulae

- A **subformula** of formula  $\psi$  is a formula that occurs in  $\psi$ 
  - More rigorous definition by structural induction on formulae
  - $\psi$  subformula of  $\psi$
  - Use **proper subformula** to exclude  $\psi$
- Write  $\bigwedge_{i=1, \dots, n} \psi_i$  for  $\psi_1 \wedge \dots \wedge \psi_n$ 
  - $\psi_i$  called a **conjunct**
- Write  $\bigvee_{i=1, \dots, n} \psi_i$  for  $\psi_1 \vee \dots \vee \psi_n$ 
  - $\psi_i$  called a **disjunct**

## Free Variables: Terms

Informally: **free variables** of an expression are variables that have an occurrence in an expression that is not bound. Written  $fv(e)$  for expression  $e$

Free variables of terms defined by structural induction over terms; written

- $fv(x) = \{x\}$
- $fv(f(t_1, \dots, t_n)) = \bigcup_{i=1, \dots, n} fv(t_i)$

**Note:**

- Free variables of term just variables occurring in term; no bound variables
- No free variables in constants
- **Example:**  $fv(add(1, abs(x))) = \{x\}$

## Free Variables: Formulae

Defined by structural induction on formulae; uses  $fv$  on terms

- $fv(true) = fv(false) = \{ \}$
- $fv(r(t_1, \dots, t_n)) = \bigcup_{i=1, \dots, n} fv(t_i)$
- $fv(\psi_1 \wedge \psi_2) = fv(\psi_1 \vee \psi_2) = fv(\psi_1 \Rightarrow \psi_2) = fv(\psi_1 \Leftrightarrow \psi_2) = (fv(\psi_1) \cup fv(\psi_2))$
- $fv(\forall v. \psi) = fv(\exists v. \psi) = (fv(\psi) \setminus \{v\})$

Variable occurrence at quantifier are **binding occurrence**

Occurrence that is not free and not binding is a **bound occurrence**

**Example:**  $fv(x > 3 \wedge (\exists y. (\forall z. z \geq (y - x)) \vee (z \geq y))) = \{x, z\}$

## Interpretation of Formulae

Fix structure  $S = (\mathcal{G}, \mathcal{D}, \mathcal{F}, \phi, \mathcal{R}, \rho)$  where  $\mathcal{G} = (V, F, af, R, ar)$

For given assignment  $a : V \rightarrow \mathcal{D}$ , the **interpretation**  $\mathcal{M}_a$  of a formula  $\psi$  assigning a value in  $\{\mathbf{T}, \mathbf{F}\}$  is defined by structural induction on formulae:

## Interpretation of Formulae

Fix structure  $S = (\mathcal{G}, \mathcal{D}, \mathcal{F}, \phi, \mathcal{R}, \rho)$  where  $\mathcal{G} = (V, F, af, R, ar)$

For given assignment  $a : V \rightarrow \mathcal{D}$ , the **interpretation**  $\mathcal{M}_a$  of a formula  $\psi$  assigning a value in  $\{\mathbf{T}, \mathbf{F}\}$  is defined by structural induction on formulae:

- $\mathcal{M}_a(\text{true}) = \mathbf{T}$        $\mathcal{M}_a(\text{false}) = \mathbf{F}$

## Interpretation of Formulae

Fix structure  $S = (\mathcal{G}, \mathcal{D}, \mathcal{F}, \phi, \mathcal{R}, \rho)$  where  $\mathcal{G} = (V, F, af, R, ar)$

For given assignment  $a : V \rightarrow \mathcal{D}$ , the **interpretation**  $\mathcal{M}_a$  of a formula  $\psi$  assigning a value in  $\{\mathbf{T}, \mathbf{F}\}$  is defined by structural induction on formulae:

- $\mathcal{M}_a(\text{true}) = \mathbf{T}$        $\mathcal{M}_a(\text{false}) = \mathbf{F}$
- $\mathcal{M}_a(r(t_1, \dots, t_n)) = \rho(r)(\mathcal{T}_a(t_1), \dots, \mathcal{T}_a(t_n))$

## Interpretation of Formulae

Fix structure  $S = (\mathcal{G}, \mathcal{D}, \mathcal{F}, \phi, \mathcal{R}, \rho)$  where  $\mathcal{G} = (V, F, af, R, ar)$

For given assignment  $a : V \rightarrow \mathcal{D}$ , the **interpretation**  $\mathcal{M}_a$  of a formula  $\psi$  assigning a value in  $\{\mathbf{T}, \mathbf{F}\}$  is defined by structural induction on formulae:

- $\mathcal{M}_a(\text{true}) = \mathbf{T}$        $\mathcal{M}_a(\text{false}) = \mathbf{F}$
- $\mathcal{M}_a(r(t_1, \dots, t_n)) = \rho(r)(\mathcal{T}_a(t_1), \dots, \mathcal{T}_a(t_n))$
- $\mathcal{M}_a((\psi)) = \mathcal{M}_a(\psi)$

## Interpretation of Formulae

Fix structure  $S = (\mathcal{G}, \mathcal{D}, \mathcal{F}, \phi, \mathcal{R}, \rho)$  where  $\mathcal{G} = (V, F, af, R, ar)$

For given assignment  $a : V \rightarrow \mathcal{D}$ , the **interpretation**  $\mathcal{M}_a$  of a formula  $\psi$  assigning a value in  $\{\mathbf{T}, \mathbf{F}\}$  is defined by structural induction on formulae:

- $\mathcal{M}_a(\text{true}) = \mathbf{T}$        $\mathcal{M}_a(\text{false}) = \mathbf{F}$
- $\mathcal{M}_a(r(t_1, \dots, t_n)) = \rho(r)(\mathcal{T}_a(t_1), \dots, \mathcal{T}_a(t_n))$
- $\mathcal{M}_a((\psi)) = \mathcal{M}_a(\psi)$
- $\mathcal{M}_a(\neg\psi) = \mathbf{T}$  if  $\mathcal{M}_a(\psi) = \mathbf{F}$  and  $\mathcal{M}_a(\neg\psi) = \mathbf{F}$  if  $\mathcal{M}_a(\psi) = \mathbf{T}$

## Interpretation of Formulae

Fix structure  $S = (\mathcal{G}, \mathcal{D}, \mathcal{F}, \phi, \mathcal{R}, \rho)$  where  $\mathcal{G} = (V, F, af, R, ar)$

For given assignment  $a : V \rightarrow \mathcal{D}$ , the **interpretation**  $\mathcal{M}_a$  of a formula  $\psi$  assigning a value in  $\{\mathbf{T}, \mathbf{F}\}$  is defined by structural induction on formulae:

- $\mathcal{M}_a(\text{true}) = \mathbf{T}$        $\mathcal{M}_a(\text{false}) = \mathbf{F}$
- $\mathcal{M}_a(r(t_1, \dots, t_n)) = \rho(r)(\mathcal{T}_a(t_1), \dots, \mathcal{T}_a(t_n))$
- $\mathcal{M}_a((\psi)) = \mathcal{M}_a(\psi)$
- $\mathcal{M}_a(\neg\psi) = \mathbf{T}$  if  $\mathcal{M}_a(\psi) = \mathbf{F}$  and  $\mathcal{M}_a(\neg\psi) = \mathbf{F}$  if  $\mathcal{M}_a(\psi) = \mathbf{T}$
- $\mathcal{M}_a(\psi_1 \wedge \psi_2) = \mathbf{T}$  if  $\mathcal{M}_a(\psi_1) = \mathbf{T}$  and  $\mathcal{M}_a(\psi_2) = \mathbf{T}$ , and  $\mathcal{M}_a(\psi_1 \wedge \psi_2) = \mathbf{F}$  otherwise

## Interpretation of Formulae

Fix structure  $S = (\mathcal{G}, \mathcal{D}, \mathcal{F}, \phi, \mathcal{R}, \rho)$  where  $\mathcal{G} = (V, F, af, R, ar)$

For given assignment  $a : V \rightarrow \mathcal{D}$ , the **interpretation**  $\mathcal{M}_a$  of a formula  $\psi$  assigning a value in  $\{\mathbf{T}, \mathbf{F}\}$  is defined by structural induction on formulae:

- $\mathcal{M}_a(\text{true}) = \mathbf{T}$        $\mathcal{M}_a(\text{false}) = \mathbf{F}$
- $\mathcal{M}_a(r(t_1, \dots, t_n)) = \rho(r)(\mathcal{T}_a(t_1), \dots, \mathcal{T}_a(t_n))$
- $\mathcal{M}_a((\psi)) = \mathcal{M}_a(\psi)$
- $\mathcal{M}_a(\neg\psi) = \mathbf{T}$  if  $\mathcal{M}_a(\psi) = \mathbf{F}$  and  $\mathcal{M}_a(\neg\psi) = \mathbf{F}$  if  $\mathcal{M}_a(\psi) = \mathbf{T}$
- $\mathcal{M}_a(\psi_1 \wedge \psi_2) = \mathbf{T}$  if  $\mathcal{M}_a(\psi_1) = \mathbf{T}$  and  $\mathcal{M}_a(\psi_2) = \mathbf{T}$ , and  $\mathcal{M}_a(\psi_1 \wedge \psi_2) = \mathbf{F}$  otherwise
- $\mathcal{M}_a(\psi_1 \vee \psi_2) = \mathbf{T}$  if  $\mathcal{M}_a(\psi_1) = \mathbf{T}$  or  $\mathcal{M}_a(\psi_2) = \mathbf{T}$ , and  $\mathcal{M}_a(\psi_1 \vee \psi_2) = \mathbf{F}$  otherwise

## Interpretation of Formulae

Fix structure  $S = (\mathcal{G}, \mathcal{D}, \mathcal{F}, \phi, \mathcal{R}, \rho)$  where  $\mathcal{G} = (V, F, af, R, ar)$

For given assignment  $a : V \rightarrow \mathcal{D}$ , the **interpretation**  $\mathcal{M}_a$  of a formula  $\psi$  assigning a value in  $\{\mathbf{T}, \mathbf{F}\}$  is defined by structural induction on formulae:

- $\mathcal{M}_a(\text{true}) = \mathbf{T}$        $\mathcal{M}_a(\text{false}) = \mathbf{F}$
- $\mathcal{M}_a(r(t_1, \dots, t_n)) = \rho(r)(\mathcal{T}_a(t_1), \dots, \mathcal{T}_a(t_n))$
- $\mathcal{M}_a((\psi)) = \mathcal{M}_a(\psi)$
- $\mathcal{M}_a(\neg\psi) = \mathbf{T}$  if  $\mathcal{M}_a(\psi) = \mathbf{F}$  and  $\mathcal{M}_a(\neg\psi) = \mathbf{F}$  if  $\mathcal{M}_a(\psi) = \mathbf{T}$
- $\mathcal{M}_a(\psi_1 \wedge \psi_2) = \mathbf{T}$  if  $\mathcal{M}_a(\psi_1) = \mathbf{T}$  and  $\mathcal{M}_a(\psi_2) = \mathbf{T}$ , and  $\mathcal{M}_a(\psi_1 \wedge \psi_2) = \mathbf{F}$  otherwise
- $\mathcal{M}_a(\psi_1 \vee \psi_2) = \mathbf{T}$  if  $\mathcal{M}_a(\psi_1) = \mathbf{T}$  or  $\mathcal{M}_a(\psi_2) = \mathbf{T}$ , and  $\mathcal{M}_a(\psi_1 \vee \psi_2) = \mathbf{F}$  otherwise
- $\mathcal{M}_a(\psi_1 \Rightarrow \psi_2) = \mathbf{T}$  if  $\mathcal{M}_a(\psi_1) = \mathbf{F}$  or  $\mathcal{M}_a(\psi_2) = \mathbf{T}$ , and  $\mathcal{M}_a(\psi_1 \Rightarrow \psi_2) = \mathbf{F}$  otherwise

## Interpretation of Formulae

Fix structure  $S = (\mathcal{G}, \mathcal{D}, \mathcal{F}, \phi, \mathcal{R}, \rho)$  where  $\mathcal{G} = (V, F, af, R, ar)$

Let

$$a + [v \mapsto d](w) = \begin{cases} d & \text{if } w = v \\ a(w) & \text{if } w \neq v \end{cases}$$

## Interpretation of Formulae

Fix structure  $S = (\mathcal{G}, \mathcal{D}, \mathcal{F}, \phi, \mathcal{R}, \rho)$  where  $\mathcal{G} = (V, F, af, R, ar)$

Let

$$(a + [v \mapsto d])(w) = \begin{cases} d & \text{if } w = v \\ a(w) & \text{if } w \neq v \end{cases}$$

## Interpretation of Formulae

Fix structure  $S = (\mathcal{G}, \mathcal{D}, \mathcal{F}, \phi, \mathcal{R}, \rho)$  where  $\mathcal{G} = (V, F, af, R, ar)$

Let

$$a + [v \mapsto d](w) = \begin{cases} d & \text{if } w = v \\ a(w) & \text{if } w \neq v \end{cases}$$

- $\mathcal{M}_a(\forall v. \psi) = \mathbf{T}$  if for every  $d \in \mathcal{D}$  we have  $\mathcal{M}_{a+[v \mapsto d]}(\psi) = \mathbf{T}$ , and  $\mathcal{M}_a(\forall v. \psi) = \mathbf{F}$  otherwise

## Interpretation of Formulae

Fix structure  $S = (\mathcal{G}, \mathcal{D}, \mathcal{F}, \phi, \mathcal{R}, \rho)$  where  $\mathcal{G} = (V, F, af, R, ar)$

Let

$$a + [v \mapsto d](w) = \begin{cases} d & \text{if } w = v \\ a(w) & \text{if } w \neq v \end{cases}$$

- $\mathcal{M}_a(\forall v. \psi) = \mathbf{T}$  if for every  $d \in \mathcal{D}$  we have  $\mathcal{M}_{a+[v \mapsto d]}(\psi) = \mathbf{T}$ , and  $\mathcal{M}_a(\forall v. \psi) = \mathbf{F}$  otherwise
- $\mathcal{M}_a(\exists v. \psi) = \mathbf{T}$  if there exists  $d \in \mathcal{D}$  such that  $\mathcal{M}_{a+[v \mapsto d]}(\psi) = \mathbf{T}$ , and  $\mathcal{M}_a(\exists v. \psi) = \mathbf{F}$  otherwise

## Modeling First-order Formulae

Given structure  $\mathcal{S} = (\mathcal{G}, \mathcal{D}, \mathcal{F}, \phi, \mathcal{R}, \rho)$  where  $\mathcal{G} = (V, F, af, R, ar)$

- $(\mathcal{S}, \mathcal{M})$  **model** for first-order language over signature  $\mathcal{G}$
- Truth of formulae in language over signature  $\mathcal{G}$  depends on structure  $\mathcal{S}$
- Assignment  $a$  **models**  $\psi$ , or  $a$  **satisfies**  $\psi$ , or  $a \models^{\mathcal{S}} \psi$  if  $\mathcal{M}_a(\psi) = \mathbf{T}$
- $\psi$  is **valid** for  $\mathcal{S}$  if  $a \models^{\mathcal{S}} \psi$  for some  $a$ .
- $\mathcal{S}$  is a **model** of  $\psi$ , written  $\models^{\mathcal{S}} \psi$  if every assignment for  $\mathcal{S}$  satisfies  $\psi$ .
- $\psi$  is **valid**, or a **tautology** if  $\psi$  valid for every mode. Write  $\models \psi$
- $\psi_1$  **logically equivalent** to  $\psi_2$  if for all structures  $\mathcal{S}$  and assignments  $a$ ,  $a \models^{\mathcal{S}} \psi_1$  iff  $a \models^{\mathcal{S}} \psi_2$

## Examples

- Assignment  $\{x \mapsto 0\}$  satisfies  $\exists y. x < y$  valid in interval  $[0, 1]$ ; assignment  $\{x \mapsto 1\}$  doesn't
- $\forall x. \exists y. x < y$  valid in  $\mathbb{N}$  and  $\mathbb{R}$ , but not interval  $[0, 1]$
- $(\exists x. \forall y. (y \leq x)) \Rightarrow (\forall y. \exists x. (y \leq x))$  tautology
  - Why?

## Sample Tautologies

All instances of propositional tautologies

## Sample Tautologies

All instances of propositional tautologies

$$\models (\exists x. \forall y. (y \leq x)) \Rightarrow (\forall y. \exists x. (y \leq x))$$

## Sample Tautologies

All instances of propositional tautologies

$$\models (\exists x. \forall y. (y \leq x)) \Rightarrow (\forall y. \exists x. (y \leq x))$$

$$\models ((\forall x. \forall y. \psi) \Leftrightarrow (\forall y. \forall x. \psi))$$

## Sample Tautologies

All instances of propositional tautologies

$$\models (\exists x. \forall y. (y \leq x)) \Rightarrow (\forall y. \exists x. (y \leq x))$$

$$\models ((\forall x. \forall y. \psi) \Leftrightarrow (\forall y. \forall x. \psi))$$

$$\models ((\forall x. \psi) \Rightarrow (\exists x. \psi))$$

## Sample Tautologies

All instances of propositional tautologies

$$\models (\exists x. \forall y. (y \leq x)) \Rightarrow (\forall y. \exists x. (y \leq x))$$

$$\models ((\forall x. \forall y. \psi) \Leftrightarrow (\forall y. \forall x. \psi))$$

$$\models ((\forall x. \psi) \Rightarrow (\exists x. \psi))$$

$$\models (\forall x. \psi_1 \wedge \psi_2) \Leftrightarrow ((\forall x. \psi_1) \wedge (\forall x. \psi_2))$$

## Sample Tautologies

All instances of propositional tautologies

$$\models (\exists x. \forall y. (y \leq x)) \Rightarrow (\forall y. \exists x. (y \leq x))$$

$$\models ((\forall x. \forall y. \psi) \Leftrightarrow (\forall y. \forall x. \psi))$$

$$\models ((\forall x. \psi) \Rightarrow (\exists x. \psi))$$

$$\models (\forall x. \psi_1 \wedge \psi_2) \Leftrightarrow ((\forall x. \psi_1) \wedge (\forall x. \psi_2))$$

$$(\exists x. \psi_1 \wedge \psi_2) \Rightarrow ((\exists x. \psi_1) \wedge (\exists x. \psi_2))$$

## Free Variables, Assignments and Interpretation

### Theorem

Assume given structure  $S = (\mathcal{G}, \mathcal{D}, \mathcal{F}, \phi, \mathcal{R}, \rho)$ , term  $t$  over  $\mathcal{G}$ , and  $a$  and  $b$  assignments. If for every  $x \in \text{fv}(t)$  we have  $a(x) = b(x)$  then  $T_a(t) = cT_b(a)$ .

### Theorem

Assume given structure  $S = (\mathcal{G}, \mathcal{D}, \mathcal{F}, \phi, \mathcal{R}, \rho)$ , formula  $\psi$  over  $\mathcal{G}$ , and  $a$  and  $b$  assignments. If for every  $x \in \text{fv}(\psi)$  we have  $a(x) = b(x)$  then  $\mathcal{M}_a(\psi) = \mathcal{M}_b(\psi)$ .

## Syntactic Substitution versus Assignment Update

- When interpreting universal quantification  $(\forall x. \psi)$ , wanted to check interpretation of every instance of  $\psi$  where  $v$  was replaced by element of semantic domain  $\mathcal{D}$
- How: semantically - interpret  $\psi$  with assignment updated by  $v \mapsto d$  for every  $d \in \mathcal{D}$
- Syntactically?
- Answer: substitution

## Substitution in Terms

- Substitution of term  $t$  for variable  $x$  in term  $s$  (written  $s[t/x]$ ) gotten by replacing every instance of  $x$  in  $s$  by  $t$ 
  - $x$  called **redex**;  $t$  called **residue**
- Yields *instance* of  $s$

Formally defined by structural induction on terms:

- $x[t/x] = t$
- $y[t/x] = y$  for variable  $y$  where  $y \neq x$
- $f(t_1, \dots, t_n)[t/x] = f(t_1[t/x], \dots, t_n[t/x])$

**Example:**  $(\text{add}(1, \text{abs}(x)))[\text{add}(x, y)/x] = \text{add}(1, \text{abs}(\text{add}(x, y)))$

## Substitution in Formulae: Problems

- Want to define by structural induction, similar to terms
- Quantifiers must be handled with care
  - Substitution only replaces **free** occurrences of variable

**Example:**

$$(x > 3 \wedge (\exists y. (\forall z. z \geq (y - x) \vee (z \geq y))))[x + 2/z] = (x > 3 \wedge (\exists y. (\forall z. z \geq (y - x) \vee (x + 2 \geq y))))$$

- Need to avoid *free variable capture*

**Example Problem:**

$$(x > 3 \wedge (\exists y. (\forall z. z \geq (y - x) \vee (z \geq y))))[x + y/z] \neq (x > 3 \wedge (\exists y. (\forall z. z \geq (y - x) \vee (x + y \geq y))))$$

## Substitution in Formulae: Two Approaches

- When quantifier would capture free variable of redex, can't substitute in formula as is
- Solution 1: Make substitution partial function – undefined in this case
- Solution 2: Define equivalence relation based on renaming bound variables; define substitution on equivalence classes
- Will take Solution 1 here
- Still need definition of equivalence up to renaming bound variables

### Theorem

Assume given structure  $S = (\mathcal{G}, \mathcal{D}, \mathcal{F}, \phi, \mathcal{R}, \rho)$ , variable  $x$ , terms  $s$  and  $t$  over  $\mathcal{G}$ , and  $a$  assignment. Let  $b = a[x \mapsto T_a(t)]$ . Then  $T_a(s[t/x]) = T_b(s)$ .

## Substitution in Formulae

- Defined by structural induction; uses substitution in terms
- Read equations below as saying left is not defined if any expression on right not defined
- $\text{true}[t/x] = \text{true}$       $\text{false}[t/x] = \text{false}$
- $r(t_1, \dots, t_n)[t/x] = r((t_1[t/x], \dots, t_n[t/x]))$
- $(\psi)[t/x] = (\psi[t/x])$       $(\neg\psi)[t/x] = \neg(\psi[t/x])$
- $(\psi_1 \otimes \psi_2)[t/x] = (\psi_1[t/x]) \otimes (\psi_2[t/x])$  for  $\otimes \in \{\wedge, \vee, \Rightarrow, \Leftrightarrow\}$
- $(\mathcal{Q}x. \psi)[t/x] = \mathcal{Q}x. \psi$  for  $\mathcal{Q} \in \{\forall, \exists\}$
- $(\mathcal{Q}y. \psi)[t/x] = \mathcal{Q}y. (\psi[t/x])$  if  $x \neq y$  and  $y \notin \text{fv}(t)$  for  $\mathcal{Q} \in \{\forall, \exists\}$
- $(\mathcal{Q}y. \psi)[t/x]$  not defined if  $x \neq y$  and  $y \in \text{fv}(t)$  for  $\mathcal{Q} \in \{\forall, \exists\}$

## Substitution in Formulae

### Examples

$(x > 3 \wedge (\exists y. (\forall z. z \geq (y - x)) \vee (z \geq y)))[x + y/z]$  not defined

$$(x > 3 \wedge (\exists w. (\forall z. z \geq (w - x)) \vee (z \geq w)))[x + y/z] = (x > 3 \wedge (\exists w. (\forall z. z \geq (w - x)) \vee ((x + y) \geq y)))$$

### Theorem

Assume given structure  $S = (\mathcal{G}, \mathcal{D}, \mathcal{F}, \phi, \mathcal{R}, \rho)$ , formula  $\psi$  over  $\mathcal{G}$ , and  $a$  assignment. If  $\psi[t/x]$  defined, then  $a \models^S \psi[t/x]$  if and only if  $a[x \mapsto T_a(t)] \models^S \psi$

## Renaming by Swapping: Terms

Define the **swapping** of two variables in a term  $t[x \leftrightarrow y]$  by structural induction on terms:

- $x[x \leftrightarrow y] = y$  and  $y[x \leftrightarrow y] = x$
- $z[x \leftrightarrow y] = z$  for  $z$  a variable,  $z \neq x$ ,  $z \neq y$
- $f(t_1, \dots, t_n)[x \leftrightarrow y] = f(t_1[x \leftrightarrow y], \dots, t_n[x \leftrightarrow y])$

### Examples:

$$\begin{aligned} \text{add}(1, \text{abs}(\text{add}(x, y)))[x \leftrightarrow y] &= \text{add}(1, \text{abs}(\text{add}(y, x))) \\ \text{add}(1, \text{abs}(\text{add}(x, y)))[x \leftrightarrow z] &= \text{add}(1, \text{abs}(\text{add}(z, y))) \end{aligned}$$

## Renaming by Swapping: Terms

### Theorem

Assume given structure  $S = (\mathcal{G}, \mathcal{D}, \mathcal{F}, \phi, \mathcal{R}, \rho)$ , variables  $x$  and  $y$ , term  $t$  over  $\mathcal{G}$ , and  $a$  assignment. Let  $b = a[x \mapsto a(y)][y \mapsto a(x)]$ . Then  $T_a(t[x \leftrightarrow y]) = T_b(t)$

## Renaming by Swapping: Terms

### Proof.

By structural induction on terms, suffices to show theorem for the case where  $t$  variable, and case  $t = f(t_1, \dots, t_n)$ , assuming result for  $t_1, \dots, t_n$

- Case:  $t$  variable
  - Subcase:  $t = x$ . Then  $\mathcal{T}_a(x[x \leftrightarrow y]) = \mathcal{T}_a(y) = a(y)$  and  $\mathcal{T}_b(x) = b(x) = a[x \mapsto a(y)][y \mapsto a(x)](x) = a[x \mapsto \mathcal{T}_a(y)](x) = a(y)$  so  $\mathcal{T}_a(t[x \leftrightarrow y]) = \mathcal{T}_b(t)$
  - Subcase:  $t = y$ . Then  $\mathcal{T}_a(y[x \leftrightarrow y]) = \mathcal{T}_a(x) = a(x)$  and  $\mathcal{T}_b(y) = b(y) = a[x \mapsto a(y)][y \mapsto a(x)](x) = a(x)$  so  $\mathcal{T}_a(t[x \leftrightarrow y]) = \mathcal{T}_b(t)$
  - Subcase:  $t = z$  variable,  $z \neq x$  and  $z \neq y$ . Then  $\mathcal{T}_a(z[x \leftrightarrow y]) = \mathcal{T}_a(z) = a(z)$  and  $\mathcal{T}_b(z) = b(z) = a[x \mapsto a(y)][y \mapsto a(x)](z) = a[x \mapsto \mathcal{T}_a(y)](z) = a(z)$  so  $\mathcal{T}_a(t[x \leftrightarrow y]) = \mathcal{T}_b(t)$

## Renaming by Swapping: Terms

### Proof.

- Case:  $t = f(t_1, \dots, t_n)$ . Assume  $\mathcal{T}_a(t_i[x \leftrightarrow y]) = \mathcal{T}_b(t_i)$  for  $i = 1, \dots, n$ . Then

$$\begin{aligned} \mathcal{T}_a(t[x \leftrightarrow y]) &= \mathcal{T}_a(f(t_1, \dots, t_n)[x \leftrightarrow y]) \\ &= \mathcal{T}_a(f(t_1[x \leftrightarrow y], \dots, t_n[x \leftrightarrow y])) \\ &= \phi(f)(\mathcal{T}_a(t_1[x \leftrightarrow y]), \dots, \mathcal{T}_a(t_n[x \leftrightarrow y])) \\ &= \phi(f)(\mathcal{T}_b(t_1), \dots, \mathcal{T}_b(t_n)) \\ &\quad \text{since } \mathcal{T}_a(t_i[x \leftrightarrow y]) = \mathcal{T}_b(t_i) \text{ for } i = 1, \dots, n \\ &= \mathcal{T}_b(f(t_1, \dots, t_n)) \\ &= \mathcal{T}_b(t) \quad \square \end{aligned}$$

## Renaming by Swapping: Formulae

Define the **swapping** of two variables in a formula  $\psi[x \leftrightarrow y]$  by structural induction, using swapping on terms:

- $\text{true}[x \leftrightarrow y] = \text{true}$      $\text{false}[x \leftrightarrow y] = \text{false}$
- $r(t_1, \dots, t_n)[x \leftrightarrow y] = r((t_1[x \leftrightarrow y], \dots, t_n[x \leftrightarrow y]))$
- $(\psi)[x \leftrightarrow y] = (\psi[x \leftrightarrow y])$      $(\neg\psi)[x \leftrightarrow y] = \neg(\psi[x \leftrightarrow y])$
- $(\psi_1 \otimes \psi_2)[x \leftrightarrow y] = (\psi_1[x \leftrightarrow y]) \otimes (\psi_2[x \leftrightarrow y])$  for  $\otimes \in \{\wedge, \vee, \Rightarrow, \Leftrightarrow\}$
- $(Qx. \psi)[x \leftrightarrow y] = Qy. (\psi[x \leftrightarrow y])$  for  $Q \in \{\forall, \exists\}$
- $(Qy. \psi)[x \leftrightarrow y] = Qy. (\psi[x \leftrightarrow y])$  for  $Q \in \{\forall, \exists\}$
- $(Qz. \psi)[x \leftrightarrow y] = Qz. (\psi[x \leftrightarrow y])$  for  $z$  a variable with  $z \neq x$ ,  $z \neq y$ , and  $Q \in \{\forall, \exists\}$

## Renaming by Swapping: Formulae

### Examples

$$\begin{aligned} (x > 3 \wedge (\exists y. (\forall z. z \geq (y - x)) \vee (z \geq y)))[x \leftrightarrow y] \\ &= (y > 3 \wedge (\exists x. (\forall z. z \geq (x - y)) \vee (z \geq x))) \\ (x > 3 \wedge (\exists y. (\forall z. z \geq (y - x)) \vee (z \geq y)))[y \leftrightarrow z] \\ &= (x > 3 \wedge (\exists y. (\forall z. z \geq (y - x)) \vee (z \geq y)))[y \leftrightarrow w] \end{aligned}$$

### Theorem

Assume given structure  $\mathcal{S} = (\mathcal{G}, \mathcal{D}, \mathcal{F}, \phi, \mathcal{R}, \rho)$ , variables  $x$  and  $y$ , formula  $\psi$  over  $\mathcal{G}$ , and  $a$  assignment. If  $x \notin \text{fv}(t)$  and  $y \notin \text{fv}(t)$  then  $\psi[x \leftrightarrow y] \equiv \psi$

## $\alpha$ -equivalence

- $\psi \stackrel{\alpha}{\equiv} \psi$
- If  $\psi_1 \stackrel{\alpha}{\equiv} \psi_2$  then  $\psi_2 \stackrel{\alpha}{\equiv} \psi_1$ .
- If  $\psi_1 \stackrel{\alpha}{\equiv} \psi_2$  and  $\psi_2 \stackrel{\alpha}{\equiv} \psi_3$  then  $\psi_1 \stackrel{\alpha}{\equiv} \psi_3$
- If  $x \notin \text{fv}(\psi)$  and  $y \notin \text{fv}(\psi)$  then  $\psi \stackrel{\alpha}{\equiv} \psi[x \leftrightarrow y]$ .
- If  $\psi_i \stackrel{\alpha}{\equiv} \psi'_i$  for  $i = 1, 2$  then
  - $(\psi_1) \stackrel{\alpha}{\equiv} (\psi'_1)$      $\neg\psi_1 \stackrel{\alpha}{\equiv} \neg\psi'_1$
  - $\psi_1 \otimes \psi_2 \stackrel{\alpha}{\equiv} \psi'_1 \otimes \psi'_2$  for  $\otimes \in \{\wedge, \vee, \Rightarrow, \Leftrightarrow\}$
  - $Qz. \psi_1 \stackrel{\alpha}{\equiv} Qz. \psi'_1$  for  $Q \in \{\forall, \exists\}$

## $\alpha$ -equivalence: Example

$$\begin{aligned} (x > 3 \wedge (\exists y. (\forall z. z \geq (y - x)) \vee (z \geq y))) \\ &\stackrel{\alpha}{\equiv} (x > 3 \wedge (\exists w. (\forall z. z \geq (w - x)) \vee (z \geq w))) \end{aligned}$$

$$\begin{aligned} (x > 3 \wedge (\exists y. (\forall z. z \geq (y - x)) \vee (z \geq y))) \\ &\stackrel{\alpha}{\equiv} (x > 3 \wedge (\exists w. (\forall y. y \geq (w - x)) \vee (z \geq w))) \end{aligned}$$



## Proof Rules

Natural Deduction rules:

All rules from Propositional Logic included

$$\frac{\Gamma \vdash \psi[t/x]}{\Gamma \vdash \exists x.\psi} \text{ } ExI \qquad \frac{}{\Gamma \vdash \exists x.\psi} \text{ } ExI$$
$$\frac{\Gamma \vdash \psi[y/x] \quad y \notin (fv(\psi) \setminus \{x\}) \cup \bigcup \psi' \in \Gamma fv(\psi')}{\Gamma \vdash \forall x.\psi} \text{ } AllI$$