

# Program Verification: Lecture 23

José Meseguer

University of Illinois at Urbana-Champaign

## Decidability of Propositional LTL

It is well-known that, for any **computable** Kripke structure  $\mathcal{Q} = (Q, \rightarrow_{\mathcal{Q}}, \mathcal{Q})$  on state predicates  $\Pi$ , any state  $q \in Q$  such that the set of states **reachable** from  $q$  in  $\mathcal{Q}$  is **finite**, and any LTL formula  $\varphi \in LTL(\Pi)$  there is a **decision procedure** that can **effectively decide** the satisfaction relation

$$\mathcal{Q}, q \models_{LTL} \varphi.$$

# Decidability of Propositional LTL

It is well-known that, for any **computable** Kripke structure  $\mathcal{Q} = (Q, \rightarrow_{\mathcal{Q}}, \mathcal{Q})$  on state predicates  $\Pi$ , any state  $q \in Q$  such that the set of states **reachable** from  $q$  in  $\mathcal{Q}$  is **finite**, and any LTL formula  $\varphi \in LTL(\Pi)$  there is a **decision procedure** that can **effectively decide** the satisfaction relation

$$\mathcal{Q}, q \models_{LTL} \varphi.$$

Furthermore, if  $\mathcal{Q}, q \not\models_{LTL} \varphi$ , the decision procedure will exhibit a **counterexample**, that is, a path  $\pi \in Path(\mathcal{Q}^\bullet)_q$  violating  $\varphi$ .

## Decidability of Propositional LTL

It is well-known that, for any **computable** Kripke structure  $\mathcal{Q} = (Q, \rightarrow_{\mathcal{Q}}, \mathcal{Q})$  on state predicates  $\Pi$ , any state  $q \in Q$  such that the set of states **reachable** from  $q$  in  $\mathcal{Q}$  is **finite**, and any LTL formula  $\varphi \in LTL(\Pi)$  there is a **decision procedure** that can **effectively decide** the satisfaction relation

$$\mathcal{Q}, q \models_{LTL} \varphi.$$

Furthermore, if  $\mathcal{Q}, q \not\models_{LTL} \varphi$ , the decision procedure will exhibit a **counterexample**, that is, a path  $\pi \in Path(\mathcal{Q}^\bullet)_q$  violating  $\varphi$ .

Since in  $LTL(\Pi)^+$  we have  $\mathcal{Q}, q \not\models_{LTL} \varphi$  iff  $\mathcal{Q}, q \models_{LTL^+} \mathbf{E}\neg\varphi$ , the counterexample path is a **constructive proof** of  $\mathcal{Q}, q \models_{LTL^+} \mathbf{E}\neg\varphi$ .

## Decidability of Propositional LTL

It is well-known that, for any **computable** Kripke structure  $\mathcal{Q} = (Q, \rightarrow_{\mathcal{Q}}, \mathcal{Q})$  on state predicates  $\Pi$ , any state  $q \in Q$  such that the set of states **reachable** from  $q$  in  $\mathcal{Q}$  is **finite**, and any LTL formula  $\varphi \in LTL(\Pi)$  there is a **decision procedure** that can **effectively decide** the satisfaction relation

$$\mathcal{Q}, q \models_{LTL} \varphi.$$

Furthermore, if  $\mathcal{Q}, q \not\models_{LTL} \varphi$ , the decision procedure will exhibit a **counterexample**, that is, a path  $\pi \in Path(\mathcal{Q}^\bullet)_q$  violating  $\varphi$ .

Since in  $LTL(\Pi)^+$  we have  $\mathcal{Q}, q \not\models_{LTL} \varphi$  iff  $\mathcal{Q}, q \models_{LTL^+} \mathbf{E}\neg\varphi$ , the counterexample path is a **constructive proof** of  $\mathcal{Q}, q \models_{LTL^+} \mathbf{E}\neg\varphi$ .

Therefore, we can **prove** a **desired E-property**  $\mathcal{Q}, q \models_{LTL^+} \mathbf{E}\psi$  precisely by getting a counterexample **disproving**  $\mathcal{Q}, q \models_{LTL} \neg\psi$ .

## Decidability of Propositional LTL (II)

The procedure to decide whether  $\mathcal{Q}, q \models_{LTL} \varphi$  holds is called a **model checking algorithm**.

## Decidability of Propositional LTL (II)

The procedure to decide whether  $\mathcal{Q}, q \models_{LTL} \varphi$  holds is called a **model checking algorithm**. As explained in the Appendix, the problem can be reduced to a decidable **emptiness check** for regular languages, where a **trace**  $\tau \in [\mathbb{N} \rightarrow \mathcal{P}(\Pi)]$  is viewed as an **infinite word** in the alphabet  $\mathcal{P}(\Pi)$ .

## Decidability of Propositional LTL (II)

The procedure to decide whether  $\mathcal{Q}, q \models_{LTL} \varphi$  holds is called a **model checking algorithm**. As explained in the Appendix, the problem can be reduced to a decidable **emptiness check** for regular languages, where a **trace**  $\tau \in [\mathbb{N} \rightarrow \mathcal{P}(\Pi)]$  is viewed as an **infinite word** in the alphabet  $\mathcal{P}(\Pi)$ . Just as  $\mathcal{P}(\Pi)^*$  denotes a set of finite words,  $\mathcal{P}(\Pi)^\omega =_{def} [\mathbb{N} \rightarrow \mathcal{P}(\Pi)]$  denotes a set of infinite words.



## Decidability of Propositional LTL (II)

The procedure to decide whether  $\mathcal{Q}, q \models_{LTL} \varphi$  holds is called a **model checking algorithm**. As explained in the Appendix, the problem can be reduced to a decidable **emptiness check** for regular languages, where a **trace**  $\tau \in [\mathbb{N} \rightarrow \mathcal{P}(\Pi)]$  is viewed as an **infinite word** in the alphabet  $\mathcal{P}(\Pi)$ . Just as  $\mathcal{P}(\Pi)^*$  denotes a set of finite words,  $\mathcal{P}(\Pi)^\omega =_{def} [\mathbb{N} \rightarrow \mathcal{P}(\Pi)]$  denotes a set of infinite words. The regular languages we need are subsets  $L \subseteq \mathcal{P}(\Pi)^\omega$  called  **$\omega$ -regular** languages.

## Decidability of Propositional LTL (II)

The procedure to decide whether  $\mathcal{Q}, q \models_{LTL} \varphi$  holds is called a **model checking algorithm**. As explained in the Appendix, the problem can be reduced to a decidable **emptiness check** for regular languages, where a **trace**  $\tau \in [\mathbb{N} \rightarrow \mathcal{P}(\Pi)]$  is viewed as an **infinite word** in the alphabet  $\mathcal{P}(\Pi)$ . Just as  $\mathcal{P}(\Pi)^*$  denotes a set of finite words,  $\mathcal{P}(\Pi)^\omega =_{def} [\mathbb{N} \rightarrow \mathcal{P}(\Pi)]$  denotes a set of infinite words. The regular languages we need are subsets  $L \subseteq \mathcal{P}(\Pi)^\omega$  called  **$\omega$ -regular** languages. They are recognized by **finite automata**, called here **Büchi automata**, and are closed under all Boolean operations.

## Decidability of Propositional LTL (II)

The procedure to decide whether  $\mathcal{Q}, q \models_{LTL} \varphi$  holds is called a **model checking algorithm**. As explained in the Appendix, the problem can be reduced to a decidable **emptiness check** for regular languages, where a **trace**  $\tau \in [\mathbb{N} \rightarrow \mathcal{P}(\Pi)]$  is viewed as an **infinite word** in the alphabet  $\mathcal{P}(\Pi)$ . Just as  $\mathcal{P}(\Pi)^*$  denotes a set of finite words,  $\mathcal{P}(\Pi)^\omega =_{def} [\mathbb{N} \rightarrow \mathcal{P}(\Pi)]$  denotes a set of infinite words. The regular languages we need are subsets  $L \subseteq \mathcal{P}(\Pi)^\omega$  called  **$\omega$ -regular** languages. They are recognized by **finite automata**, called here **Büchi automata**, and are closed under all Boolean operations. Furthermore, it is **decidable** whether any such  $L \subseteq \mathcal{P}(\Pi)^\omega$  is empty.

## Decidability of Propositional LTL (II)

The procedure to decide whether  $\mathcal{Q}, q \models_{LTL} \varphi$  holds is called a **model checking algorithm**. As explained in the Appendix, the problem can be reduced to a decidable **emptiness check** for regular languages, where a **trace**  $\tau \in [\mathbb{N} \rightarrow \mathcal{P}(\Pi)]$  is viewed as an **infinite word** in the alphabet  $\mathcal{P}(\Pi)$ . Just as  $\mathcal{P}(\Pi)^*$  denotes a set of finite words,  $\mathcal{P}(\Pi)^\omega =_{def} [\mathbb{N} \rightarrow \mathcal{P}(\Pi)]$  denotes a set of infinite words. The regular languages we need are subsets  $L \subseteq \mathcal{P}(\Pi)^\omega$  called  **$\omega$ -regular** languages. They are recognized by **finite automata**, called here **Büchi automata**, and are closed under all Boolean operations. Furthermore, it is **decidable** whether any such  $L \subseteq \mathcal{P}(\Pi)^\omega$  is empty. The two key crucial facts are:

## Decidability of Propositional LTL (II)

The procedure to decide whether  $\mathcal{Q}, q \models_{LTL} \varphi$  holds is called a **model checking algorithm**. As explained in the Appendix, the problem can be reduced to a decidable **emptiness check** for regular languages, where a **trace**  $\tau \in [\mathbb{N} \rightarrow \mathcal{P}(\Pi)]$  is viewed as an **infinite word** in the alphabet  $\mathcal{P}(\Pi)$ . Just as  $\mathcal{P}(\Pi)^*$  denotes a set of finite words,  $\mathcal{P}(\Pi)^\omega =_{def} [\mathbb{N} \rightarrow \mathcal{P}(\Pi)]$  denotes a set of infinite words. The regular languages we need are subsets  $L \subseteq \mathcal{P}(\Pi)^\omega$  called  **$\omega$ -regular** languages. They are recognized by **finite automata**, called here **Büchi automata**, and are closed under all Boolean operations. Furthermore, it is **decidable** whether any such  $L \subseteq \mathcal{P}(\Pi)^\omega$  is empty. The two key crucial facts are: (1)  $\forall \varphi \in LTL(\Pi)$ , the language  $L_\varphi =_{def} \{\tau \in \mathcal{P}(\Pi)^\omega \mid \tau \models_{LTL} \varphi\}$  is  **$\omega$ -regular**, and

## Decidability of Propositional LTL (II)

The procedure to decide whether  $\mathcal{Q}, q \models_{LTL} \varphi$  holds is called a **model checking algorithm**. As explained in the Appendix, the problem can be reduced to a decidable **emptiness check** for regular languages, where a **trace**  $\tau \in [\mathbb{N} \rightarrow \mathcal{P}(\Pi)]$  is viewed as an **infinite word** in the alphabet  $\mathcal{P}(\Pi)$ . Just as  $\mathcal{P}(\Pi)^*$  denotes a set of finite words,  $\mathcal{P}(\Pi)^\omega =_{def} [\mathbb{N} \rightarrow \mathcal{P}(\Pi)]$  denotes a set of infinite words. The regular languages we need are subsets  $L \subseteq \mathcal{P}(\Pi)^\omega$  called  **$\omega$ -regular** languages. They are recognized by **finite automata**, called here **Büchi automata**, and are closed under all Boolean operations. Furthermore, it is **decidable** whether any such  $L \subseteq \mathcal{P}(\Pi)^\omega$  is empty. The two key crucial facts are: (1)  $\forall \varphi \in LTL(\Pi)$ , the language  $L_\varphi =_{def} \{\tau \in \mathcal{P}(\Pi)^\omega \mid \tau \models_{LTL} \varphi\}$  is  **$\omega$ -regular**, and (2)  $\mathcal{Q}, q \models_{LTL} \varphi$  iff  $Tr(\mathcal{Q}^\bullet)_q =_{def} \{\pi; preds \mid \pi \in Path(\mathcal{Q}^\bullet)_q\} \subseteq L_\varphi$ .

# The Maude Model Checker

Lecture 22 explained how, given an **admissible** system module  $M$  with rewrite theory  $\mathcal{R} = (\Sigma, E \cup B, R)$ , we can equationally define (possibly parametric) state predicates  $\Pi$  in an extended module  $M\text{-PREDS}$ , thus defining the Kripke structure  $\mathbb{C}_{\mathcal{R}}^{\Pi}$ .

# The Maude Model Checker

Lecture 22 explained how, given an **admissible** system module  $M$  with rewrite theory  $\mathcal{R} = (\Sigma, E \cup B, R)$ , we can equationally define (possibly parametric) state predicates  $\Pi$  in an extended module  $M\text{-PREDS}$ , thus defining the Kripke structure  $\mathbb{C}_{\mathcal{R}}^{\Pi}$ .

Given a **ground** LTL formula  $\varphi \in LTL(\Pi)$  and an initial state  $[u] \in \mathbb{C}_{\Sigma/E \cup B, State}$  having a **finite** set of reachable states, we can **decide** the satisfaction relation  $\mathbb{C}_{\mathcal{R}}^{\Pi}, [u] \models \varphi$  by applying the general LTL decidability result to the Kripke structure  $\mathbb{C}_{\mathcal{R}}^{\Pi}$ .



# The Maude Model Checker

Lecture 22 explained how, given an **admissible** system module  $M$  with rewrite theory  $\mathcal{R} = (\Sigma, E \cup B, R)$ , we can equationally define (possibly parametric) state predicates  $\Pi$  in an extended module  $M\text{-PREDS}$ , thus defining the Kripke structure  $\mathbb{C}_{\mathcal{R}}^{\Pi}$ .

Given a **ground** LTL formula  $\varphi \in LTL(\Pi)$  and an initial state  $[u] \in \mathbb{C}_{\Sigma/E \cup B, State}$  having a **finite** set of reachable states, we can **decide** the satisfaction relation  $\mathbb{C}_{\mathcal{R}}^{\Pi}, [u] \models \varphi$  by applying the general LTL decidability result to the Kripke structure  $\mathbb{C}_{\mathcal{R}}^{\Pi}$ .

Maude uses an on-the-fly LTL model checking procedure that performs the  $\omega$ -regular language operations (see page 3 above and further details in the Appendix).

# The Maude Model Checker

Lecture 22 explained how, given an **admissible** system module  $M$  with rewrite theory  $\mathcal{R} = (\Sigma, E \cup B, R)$ , we can equationally define (possibly parametric) state predicates  $\Pi$  in an extended module  $M\text{-PREDS}$ , thus defining the Kripke structure  $\mathbb{C}_{\mathcal{R}}^{\Pi}$ .

Given a **ground** LTL formula  $\varphi \in LTL(\Pi)$  and an initial state  $[u] \in \mathbb{C}_{\Sigma/E \cup B, State}$  having a **finite** set of reachable states, we can **decide** the satisfaction relation  $\mathbb{C}_{\mathcal{R}}^{\Pi}, [u] \models \varphi$  by applying the general LTL decidability result to the Kripke structure  $\mathbb{C}_{\mathcal{R}}^{\Pi}$ .

Maude uses an on-the-fly LTL model checking procedure that performs the  $\omega$ -regular language operations (see page 3 above and further details in the Appendix). Specifically, a procedure of the kind described in §9.5 of Clarke, Grumberg, and Peled's *Model Checking*, MIT Press, 2001, that I sketch in what follows.

## The Maude Model Checker (II)

The basis of this procedure (further explained in the Appendix) is the following. Each *LTL* formula  $\varphi$  has an associated Büchi automaton  $\mathbf{B}_\varphi$  whose acceptance  $\omega$ -language is exactly that the set of **traces** satisfying  $\varphi$ .

## The Maude Model Checker (II)

The basis of this procedure (further explained in the Appendix) is the following. Each *LTL* formula  $\varphi$  has an associated Büchi automaton  $\mathbf{B}_\varphi$  whose acceptance  $\omega$ -language is exactly that the set of **traces** satisfying  $\varphi$ . We can then reduce the satisfaction problem

$$\mathbb{C}_{\mathcal{R}}^\Pi, [u] \models \varphi$$

## The Maude Model Checker (II)

The basis of this procedure (further explained in the Appendix) is the following. Each *LTL* formula  $\varphi$  has an associated Büchi automaton  $\mathbf{B}_\varphi$  whose acceptance  $\omega$ -language is exactly that the set of **traces** satisfying  $\varphi$ . We can then reduce the satisfaction problem

$$\mathbb{C}_{\mathcal{R}}^\Pi, [u] \models \varphi$$

to the **emptiness problem** of the language accepted by the **synchronous product** of  $\mathbf{B}_{\neg\varphi}$  with (the Büchi automaton  $\mathbf{B}(\mathbb{C}_{\mathcal{R}}^{\Pi\bullet}, [u])$  associated to)  $\mathbb{C}_{\mathcal{R}}^\Pi, [u]$ .

## The Maude Model Checker (II)

The basis of this procedure (further explained in the Appendix) is the following. Each *LTL* formula  $\varphi$  has an associated Büchi automaton  $\mathbf{B}_\varphi$  whose acceptance  $\omega$ -language is exactly that the set of **traces** satisfying  $\varphi$ . We can then reduce the satisfaction problem

$$\mathbb{C}_{\mathcal{R}}^\Pi, [u] \models \varphi$$

to the **emptiness problem** of the language accepted by the **synchronous product** of  $\mathbf{B}_{\neg\varphi}$  with (the Büchi automaton  $\mathbf{B}(\mathbb{C}_{\mathcal{R}}^{\Pi\bullet}, [u])$  associated to)  $\mathbb{C}_{\mathcal{R}}^\Pi, [u]$ . The formula  $\varphi$  is satisfied iff such a language is **empty**.

## The Maude Model Checker (II)

The basis of this procedure (further explained in the Appendix) is the following. Each *LTL* formula  $\varphi$  has an associated Büchi automaton  $\mathbf{B}_\varphi$  whose acceptance  $\omega$ -language is exactly that the set of **traces** satisfying  $\varphi$ . We can then reduce the satisfaction problem

$$\mathbb{C}_{\mathcal{R}}^\Pi, [u] \models \varphi$$

to the **emptiness problem** of the language accepted by the **synchronous product** of  $\mathbf{B}_{\neg\varphi}$  with (the Büchi automaton  $\mathbf{B}(\mathbb{C}_{\mathcal{R}}^{\Pi\bullet}, [u])$  associated to)  $\mathbb{C}_{\mathcal{R}}^\Pi, [u]$ . The formula  $\varphi$  is satisfied iff such a language is **empty**. The model checking procedure checks emptiness by **searching for a counterexample**, that is, for an infinite path  $\pi$  in  $\mathbb{C}_{\mathcal{R}}^{\Pi\bullet}$  from  $[u]$  generating a trace  $\tau$  in the language recognized by the synchronous product  $\mathbf{B}(\mathbb{C}_{\mathcal{R}}^{\Pi\bullet}, [u]) \otimes \mathbf{B}_{\neg\varphi}$ , i.e., a trace of  $\mathbb{C}_{\mathcal{R}}^{\Pi\bullet}$  from  $[u]$  such that  $\tau \in L_{\neg\varphi}$ .

## The Maude Model Checker (III)

How do we then model check a given LTL formula  $\varphi$  in Maude for a given initial state  $[u]$  in an admissible system module  $M$  whose state predicates  $\Pi$  have been specified in  $M$ -PREDS?



## The Maude Model Checker (III)

How do we then model check a given LTL formula  $\varphi$  in Maude for a given initial state  $[u]$  in an admissible system module  $M$  whose state predicates  $\Pi$  have been specified in  $M$ -PREDS? We define a new module, say  $M$ -CHECK, according to the following pattern:

## The Maude Model Checker (III)

How do we then model check a given LTL formula  $\varphi$  in Maude for a given initial state  $[u]$  in an admissible system module  $M$  whose state predicates  $\Pi$  have been specified in  $M$ -PREDS? We define a new module, say  $M$ -CHECK, according to the following pattern:

```

mod M-CHECK is
  protecting M-PREDS .
  including MODEL-CHECKER .
  including LTL-SIMPLIFIER . *** optional
  op init : -> State .      *** optional
  eq init = u .             *** optional
endm

```

## The Maude Model Checker (III)

How do we then model check a given LTL formula  $\varphi$  in Maude for a given initial state  $[u]$  in an admissible system module  $M$  whose state predicates  $\Pi$  have been specified in  $M$ -PREDS? We define a new module, say  $M$ -CHECK, according to the following pattern:

```

mod M-CHECK is
  protecting M-PREDS .
  including MODEL-CHECKER .
  including LTL-SIMPLIFIER . *** optional
  op init : -> State .      *** optional
  eq init = u .             *** optional
endm

```

The declaration of `init` is not necessary: it is a matter of convenience, since the initial state  $u$  may be a large term.

## The Maude Model Checker (III)

How do we then model check a given LTL formula  $\varphi$  in Maude for a given initial state  $[u]$  in an admissible system module  $M$  whose state predicates  $\Pi$  have been specified in  $M$ -PREDS? We define a new module, say  $M$ -CHECK, according to the following pattern:

```
mod M-CHECK is
  protecting M-PREDS .
  including MODEL-CHECKER .
  including LTL-SIMPLIFIER . *** optional
  op init : -> State .      *** optional
  eq init = u .             *** optional
endm
```

The declaration of `init` is not necessary: it is a matter of convenience, since the initial state  $u$  may be a large term. Including the module `LTL-SIMPLIFIER` is also optional. Its purpose is to simplify the formula  $\neg\varphi$  to generate a **smaller** Büchi automaton  $\mathbf{B}_{\neg\varphi}$ , since  $|\mathbf{B}_{\neg\varphi}|$  is exponential in  $|\varphi|$ .

## The LTL Module

MODEL-CHECKER imports the following LTL functional module (in the file `model-checker.maude`) providing syntax for LTL formulas:

# The LTL Module

MODEL-CHECKER imports the following LTL functional module (in the file `model-checker.maude`) providing syntax for LTL formulas:

```

mod LTL is
  protecting BOOL .
  sort Formula .

  *** primitive LTL operators
  ops True False : -> Formula [ctor format (g o)] .
  op ~_ : Formula -> Formula [ctor prec 53 format (r o d)] .
  op _/\_ : Formula Formula -> Formula [comm ctor gather (E e)
                                         prec 55 format (d r o d)] .
  op _\/_ : Formula Formula -> Formula [comm ctor gather (E e)
                                         prec 59 format (d r o d)] .
  op O_ : Formula -> Formula [ctor prec 53 format (r o d)] .
  op _U_ : Formula Formula -> Formula [ctor prec 63 format (d r o d)] .
  op _R_ : Formula Formula -> Formula [ctor prec 63 format (d r o d)] .

```

# The LTL Module (II)

\*\*\* defined LTL operators

op  $\_ \rightarrow \_$  : Formula Formula  $\rightarrow$  Formula [gather (e E) prec 65  
format (d r o d)] .

op  $\_ \leftrightarrow \_$  : Formula Formula  $\rightarrow$  Formula [prec 65 format (d r o d)] .

op  $\langle \rangle \_$  : Formula  $\rightarrow$  Formula [prec 53 format (r o d)] .

op  $\square \_$  : Formula  $\rightarrow$  Formula [prec 53 format (r d o d)] .

op  $\_ W \_$  : Formula Formula  $\rightarrow$  Formula [prec 63 format (d r o d)] .

op  $\_ | \rightarrow \_$  : Formula Formula  $\rightarrow$  Formula [prec 63 format (d r o d)] .  
\*\*\* leads-to

op  $\_ \Rightarrow \_$  : Formula Formula  $\rightarrow$  Formula [gather (e E) prec 65 format (d r o d)] .

op  $\_ \Leftrightarrow \_$  : Formula Formula  $\rightarrow$  Formula [prec 65 format (d r o d)] .

vars f g : Formula .

eq  $f \rightarrow g = \sim f \vee g$  .

eq  $f \leftrightarrow g = (f \rightarrow g) \wedge (g \rightarrow f)$  .

eq  $\langle \rangle f = \text{True } U f$  .

eq  $\square f = \text{False } R f$  .

eq  $f W g = (f U g) \vee \square f$  .

eq  $f | \rightarrow g = \square (f \rightarrow (\langle \rangle g))$  .

eq  $f \Rightarrow g = \square (f \rightarrow g)$  .

eq  $f \Leftrightarrow g = \square (f \leftrightarrow g)$  .

# The LTL Module (III)

```
*** negative normal form
eq ~ True = False .
eq ~ False = True .
eq ~ ~ f = f .
eq ~ (f \\/ g) = ~ f /\ ~ g .
eq ~ (f /\ g) = ~ f \\/ ~ g .
eq ~ 0 f = 0 ~ f .
eq ~(f U g) = (~ f) R (~ g) .
eq ~(f R g) = (~ f) U (~ g) .
endfm
```



## The LTL Module (III)

```

*** negative normal form
eq ~ True = False .
eq ~ False = True .
eq ~ ~ f = f .
eq ~ (f \\/ g) = ~ f /\ ~ g .
eq ~ (f /\ g) = ~ f \\/ ~ g .
eq ~ 0 f = 0 ~ f .
eq ~(f U g) = (~ f) R (~ g) .
eq ~(f R g) = (~ f) U (~ g) .
endfm

```

The set  $\Pi$  of state predicates is not specified. This happens in MODEL-CHECKER through declaration: `subsort Prop < Formula` and the importation of M-PREDS, where  $\Pi$  is equationally specified.

## The LTL Module (III)

```

*** negative normal form
eq ~ True = False .
eq ~ False = True .
eq ~ ~ f = f .
eq ~ (f \\/ g) = ~ f /\ ~ g .
eq ~ (f /\ g) = ~ f \\/ ~ g .
eq ~ 0 f = 0 ~ f .
eq ~(f U g) = (~ f) R (~ g) .
eq ~(f R g) = (~ f) U (~ g) .
endfm

```

The set  $\Pi$  of state predicates is not specified. This happens in MODEL-CHECKER through declaration: `subsort Prop < Formula` and the importation of M-PREDS, where  $\Pi$  is equationally specified.

Since, for model checking, LTL formulas are put in **negative normal form**, we also need as constructors the **duals** of the basic constructor connectives  $\top$ ,  $\bigcirc$ ,  $\mathcal{U}$ , and  $\vee$ , i.e., the dual connectives:  $\perp$ ,  $\mathcal{R}$ , and  $\wedge$  ( $\bigcirc$  is self-dual).

## The Maude Model Checker (IV)

The module MODEL-CHECKER is as follows.

# The Maude Model Checker (IV)

The module MODEL-CHECKER is as follows.

```
fmod MODEL-CHECKER is protecting QID . including SATISFACTION .
including LTL .
subsort Prop < Formula .

*** transitions and results
sorts RuleName Transition TransitionList ModelCheckResult .
subsort Qid < RuleName .
subsort Transition < TransitionList .
subsort Bool < ModelCheckResult .
ops unlabeled deadlock : -> RuleName .
op {_,_} : State RuleName -> Transition [ctor] .
op nil : -> TransitionList [ctor] .
op __ : TransitionList TransitionList -> TransitionList [ctor assoc id: nil] .
op counterexample : TransitionList TransitionList -> ModelCheckResult [ctor] .
op modelCheck : State Formula ~> ModelCheckResult [special ( ... )] .
endfm
```

## A MUTEX Example

Its key operator is `modelCheck` (whose `special` attribute has been omitted here), which takes an initial state and an LTL formula and returns either the Boolean `true` if the formula is satisfied, or a counterexample when it is not satisfied.

## A MUTEX Example

Its key operator is `modelCheck` (whose `special` attribute has been omitted here), which takes an initial state and an LTL formula and returns either the Boolean `true` if the formula is satisfied, or a counterexample when it is not satisfied.

Let us illustrate the use of `MODEL-CHECKER` with a very simple `MUTEX` mutual exclusion protocol with two processes `a` and `b`.

## A MUTEX Example

Its key operator is `modelCheck` (whose `special` attribute has been omitted here), which takes an initial state and an LTL formula and returns either the Boolean `true` if the formula is satisfied, or a counterexample when it is not satisfied.

Let us illustrate the use of `MODEL-CHECKER` with a very simple MUTEX mutual exclusion protocol with two processes `a` and `b`.

```

mod MUTEX is
  sorts Name Mode Proc Token Conf .
  subsorts Token Proc < Conf .
  op none : -> Conf .
  op __ : Conf Conf -> Conf [assoc comm id: none] .
  ops a b : -> Name .
  ops wait critical : -> Mode .
  op [_,_] : Name Mode -> Proc .
  ops * $ : -> Token .
  rl [a-enter] : $ [a,wait] => [a,critical] .
  rl [b-enter] : * [b,wait] => [b,critical] .
  rl [a-exit] : [a,critical] => [a,wait] * .
  rl [b-exit] : [b,critical] => [b,wait] $ .
endm

```

# A MUTEX Example (II)

```

mod MUTEX-PREDS is protecting MUTEX . including SATISFACTION .
  subsort Conf < State .
  ops crit wait : Name -> Prop .
  var N : Name .
  var C : Conf .
  eq [N,critical] C |= crit(N) = true .
  eq C |= crit(N) = false [owise] .
  eq [N,wait] C |= wait(N) = true .
  eq C |= wait(N) = false [owise] .
endm

```

```

mod MUTEX-CHECK is
  protecting MUTEX-PREDS .
  including MODEL-CHECKER .
  including LTL-SIMPLIFIER .
  ops initial1 initial2 : -> Conf .
  eq initial1 = $ [a,wait] [b,wait] .
  eq initial2 = * [a,wait] [b,wait] .
endm

```



## A MUTEX Example (III)

We are now ready to model check different LTL properties of MUTEX. The first obvious property to check is **mutual exclusion**:

## A MUTEX Example (III)

We are now ready to model check different LTL properties of MUTEX. The first obvious property to check is **mutual exclusion**:

```
Maude> red modelCheck(initial1, [] ~(crit(a) /\ crit(b))) .
```

```
result Bool: true
```

```
Maude> red modelCheck(initial2, [] ~(crit(a) /\ crit(b))) .
```

```
result Bool: true
```

## A MUTEX Example (IV)

We can also model check the **strong fairness** property (a kind of liveness property) that if a process waits infinitely often, then it is in its critical section infinitely often:

## A MUTEX Example (IV)

We can also model check the **strong fairness** property (a kind of liveness property) that if a process waits infinitely often, then it is in its critical section infinitely often:

```
Maude> red modelCheck(initial1, ([] <> wait(a)) -> ([] <> crit(a))) .
```

```
result Bool: true
```

```
Maude> red modelCheck(initial1, ([] <> wait(b)) -> ([] <> crit(b))) .
```

```
result Bool: true
```

```
Maude> red modelCheck(initial2, ([] <> wait(a)) -> ([] <> crit(a))) .
```

```
result Bool: true
```

```
Maude> red modelCheck(initial2, ([] <> wait(b)) -> ([] <> crit(b))) .
```

```
result Bool: true
```

## A MUTEX Example (V)

Of course, not all properties are true. Therefore, instead of a success we can get a **counterexample** showing why a property fails. Suppose that we want to check whether, beginning in the state `initial1`, process `b` will always be waiting. We then get the counterexample:

## A MUTEX Example (V)

Of course, not all properties are true. Therefore, instead of a success we can get a **counterexample** showing why a property fails. Suppose that we want to check whether, beginning in the state `initial1`, process `b` will always be waiting. We then get the counterexample:

```
Maude> red modelCheck(initial1, [] wait(b)) .
```

```
result ModelCheckResult:
```

```
  counterexample({$ [a,wait] [b,wait], 'a-enter}
                 {[a,critical] [b,wait], 'a-exit}
                 {* [a,wait] [b,wait], 'b-enter},
                 {[a,wait] [b,critical], 'b-exit}
                 {$ [a,wait] [b,wait], 'a-enter}
                 {[a,critical] [b,wait], 'a-exit}
                 {* [a,wait] [b,wait], 'b-enter})
```

# The Maude Model Checker (V)

The main counterexample term constructors are:

```
op {_,_} : State RuleName -> Transition .
op nil : -> TransitionList [ctor] .
op __ : TransitionList TransitionList -> TransitionList [ctor assoc id: nil] .
op counterexample : TransitionList TransitionList -> ModelCheckResult [ctor] .
```

# The Maude Model Checker (V)

The main counterexample term constructors are:

```

op {_,_} : State RuleName -> Transition .
op nil : -> TransitionList [ctor] .
op __ : TransitionList TransitionList -> TransitionList [ctor assoc id: nil] .
op counterexample : TransitionList TransitionList -> ModelCheckResult [ctor] .

```

A **counterexample** is a pair consisting of two lists of transitions: the first is a finite path beginning in the initial state, and the second describes a loop.



# The Maude Model Checker (V)

The main counterexample term constructors are:

```

op {_,_} : State RuleName -> Transition .
op nil : -> TransitionList [ctor] .
op __ : TransitionList TransitionList -> TransitionList [ctor assoc id: nil] .
op counterexample : TransitionList TransitionList -> ModelCheckResult [ctor] .

```

A **counterexample** is a pair consisting of two lists of transitions: the first is a finite path beginning in the initial state, and the second describes a loop. This is because, if an LTL formula  $\varphi$  is **not** satisfied by a finite-state Kripke structure, it is always possible to find a counterexample for  $\varphi$  having the form of a path of transitions followed by a cycle.

# The Maude Model Checker (V)

The main counterexample term constructors are:

```

op {_,_} : State RuleName -> Transition .
op nil : -> TransitionList [ctor] .
op __ : TransitionList TransitionList -> TransitionList [ctor assoc id: nil] .
op counterexample : TransitionList TransitionList -> ModelCheckResult [ctor] .

```

A **counterexample** is a pair consisting of two lists of transitions: the first is a finite path beginning in the initial state, and the second describes a loop. This is because, if an LTL formula  $\varphi$  is **not** satisfied by a finite-state Kripke structure, it is always possible to find a counterexample for  $\varphi$  having the form of a path of transitions followed by a cycle. Note that each transition is represented as a **pair**, consisting of a state and the label of the rule applied to reach the next state.

## COMM Revisited

In Lecture 22 we defined equationally the state predicates used in formalizing the requirements for **successful communication** between a sender A and a receiver B as a **parametric formula**.

## COMM Revisited

In Lecture 22 we defined equationally the state predicates used in formalizing the requirements for **successful communication** between a sender A and a receiver B as a **parametric formula**. Now we can verify it for any initial state with a list of data to be sent:

## COMM Revisited

In Lecture 22 we defined equationally the state predicates used in formalizing the requirements for **successful communication** between a sender A and a receiver B as a **parametric formula**. Now we can verify it for any initial state with a list of data to be sent:

```
omod COMM-CHECK is
  protecting COMM-PREDS .
  inc MODEL-CHECKER .

  vars A B : Oid .  var L : List .

  op success-comm : Oid Oid List -> Formula .

  eq success-comm(A,B,L) =
    <> ((~ enabled) /\ no-msgs /\ holds(B,L) /\ holds(A,nil) /\
      (~ waits-ack(A)) /\ cnt(A,| L |) /\ cnt(B,| L |)) .
endom

red modelCheck(init('a','b,1 ; 2 ; 3),success-comm('a','b,1 ; 2 ; 3)) .

result Bool: true
```

## COMM Revisited (II)

Usually, by a **deadlock** we mean an **unwanted** terminating state.

## COMM Revisited (II)

Usually, by a **deadlock** we mean an **unwanted** terminating state. For example, the final state guaranteed by the `success-comm` formula is a **wanted** terminating state and therefore **not** a deadlock in this sense.

## COMM Revisited (II)

Usually, by a **deadlock** we mean an **unwanted** terminating state. For example, the final state guaranteed by the `success-comm` formula is a **wanted** terminating state and therefore **not** a deadlock in this sense. So we can also ask: Are there any deadlocks in COMM? The LTL formula asserting that there are **none** is remarkably simple:



## COMM Revisited (II)

Usually, by a **deadlock** we mean an **unwanted** terminating state. For example, the final state guaranteed by the `success-comm` formula is a **wanted** terminating state and therefore **not** a deadlock in this sense. So we can also ask: Are there any deadlocks in COMM? The LTL formula asserting that there are **none** is remarkably simple:

```
red modelCheck(init('a','b,nil),((~ enabled) => success-comm('a','b,nil))) .
```

```
result Bool: true
```

```
red modelCheck(init('a','b,1 ; 2 ; 3),((~ enabled) =>
                                     success-comm('a','b,1 ; 2 ; 3))) .
```

```
result Bool: true
```

```
red modelCheck(init('a','b,1 ; 2 ; 3 ; 4 ; 5),((~ enabled) =>
                                               success-comm('a','b,1 ; 2 ; 3 ; 4 ; 5))) .
```

```
result Bool: true
```

## COMM Revisited (III)

We can try to ask an answer a stronger question about COMM.

## COMM Revisited (III)

We can try to ask an answer a stronger question about COMM. Given a parametric initial state  $\text{init}(A,B,L)$  the  $\text{success-comm}(A,B,L)$  property ensures that  $L$  is received correctly. But is the order of  $L$  **preserved** in all **intermediate states** of the computation?

## COMM Revisited (III)

We can try to ask an answer a stronger question about COMM. Given a parametric initial state  $\text{init}(A,B,L)$  the  $\text{success-comm}(A,B,L)$  property ensures that  $L$  is received correctly. But is the order of  $L$  **preserved** in all **intermediate states** of the computation?

This question is interesting because it requires us to:

## COMM Revisited (III)

We can try to ask an answer a stronger question about COMM. Given a parametric initial state  $\text{init}(A,B,L)$  the  $\text{success-comm}(A,B,L)$  property ensures that  $L$  is received correctly. But is the order of  $L$  **preserved** in all **intermediate states** of the computation?

This question is interesting because it requires us to:

- 1 Think carefully about COMM to see how we can specify those intermediate states as a disjunction of **constrained constructor patterns**, and therefore as a (parametric) **state predicate**.

## COMM Revisited (III)

We can try to ask an answer a stronger question about COMM. Given a parametric initial state  $\text{init}(A,B,L)$  the  $\text{success-comm}(A,B,L)$  property ensures that  $L$  is received correctly. But is the order of  $L$  **preserved** in all **intermediate states** of the computation?

This question is interesting because it requires us to:

- 1 Think carefully about COMM to see how we can specify those intermediate states as a disjunction of **constrained constructor patterns**, and therefore as a (parametric) **state predicate**.
- 2 Once we have done so, verify that this conjectured set of intermediate states is an **invariant** from  $\text{init}(A,B,L)$ .

## COMM Revisited (III)

We can try to ask an answer a stronger question about COMM. Given a parametric initial state  $\text{init}(A,B,L)$  the  $\text{success-comm}(A,B,L)$  property ensures that  $L$  is received correctly. But is the order of  $L$  **preserved** in all **intermediate states** of the computation?

This question is interesting because it requires us to:

- ① Think carefully about COMM to see how we can specify those intermediate states as a disjunction of **constrained constructor patterns**, and therefore as a (parametric) **state predicate**.
- ② Once we have done so, verify that this conjectured set of intermediate states is an **invariant** from  $\text{init}(A,B,L)$ .

Part (1) of the question can be answered by adding to COMM-PREDS the following parametric state predicate and its defining equations:

# COMM Revisited (IV)

```
*** parametric predicate: in-order-comm
```

```
op in-order-comm : Oid Oid List -> Prop [ctor] .
```

```
ceq < A : Sender | buff : L2, rec : B, cnt : M, ack-w : false >
  < B : Receiver | buff : L1, snd : A, cnt : M >
  |= in-order-comm(A,B,L) = true if L = L1 ; L2 /\ M = | L1 | .
```

```
ceq < A : Sender | buff : L2, rec : B, cnt : M, ack-w : true >
  (to B from A val N cnt M)
  < B : Receiver | buff : L1, snd : A, cnt : M >
  |= in-order-comm(A,B,L) = true if L = L1 ; N ; L2 /\ | L1 | = M .
```

```
ceq < A : Sender | buff : L2, rec : B, cnt : M, ack-w : true >
  (to A from B ack M)
  < B : Receiver | buff : (L1 ; N), snd : A, cnt : s(M) >
  |= in-order-comm(A,B,L) = true if L = L1 ; N ; L2 /\ | L1 | = M .
```



# COMM Revisited (IV)

\*\*\* parametric predicate: in-order-comm

```
op in-order-comm : Oid Oid List -> Prop [ctor] .
```

```
ceq < A : Sender | buff : L2, rec : B, cnt : M, ack-w : false >
  < B : Receiver | buff : L1, snd : A, cnt : M >
  |= in-order-comm(A,B,L) = true if L = L1 ; L2 /\ M = | L1 | .
```

```
ceq < A : Sender | buff : L2, rec : B, cnt : M, ack-w : true >
  (to B from A val N cnt M)
  < B : Receiver | buff : L1, snd : A, cnt : M >
  |= in-order-comm(A,B,L) = true if L = L1 ; N ; L2 /\ | L1 | = M .
```

```
ceq < A : Sender | buff : L2, rec : B, cnt : M, ack-w : true >
  (to A from B ack M)
  < B : Receiver | buff : (L1 ; N), snd : A, cnt : s(M) >
  |= in-order-comm(A,B,L) = true if L = L1 ; N ; L2 /\ | L1 | = M .
```

Note that, as explained in Lecture 22, each conditional equation uses each of the **constrained constructor patterns** in the disjunction to define the `in-order-comm` state predicate.

## COMM Revisited (V)

We can now answer Part (2) of the question by giving, for various instances of the parametric initial state `init(A,B,L)`, the model checking commands:

## COMM Revisited (V)

We can now answer Part (2) of the question by giving, for various instances of the parametric initial state  $\text{init}(A,B,L)$ , the model checking commands:

```
red modelCheck(init('a,'b,nil), [] in-order-comm('a,'b,nil)) .
```

```
result Bool: true
```

```
red modelCheck(init('a,'b,1 ; 2 ; 3), [] in-order-comm('a,'b,1 ; 2 ; 3)) .
```

```
result Bool: true
```

```
red modelCheck(init('a,'b,1 ; 2 ; 3 ; 4 ; 5),
                [] in-order-comm('a,'b,1 ; 2 ; 3 ; 4 ; 5)) .
```

```
result Bool: true
```

## COMM Revisited (VI)

As a last example, we can use COMM to illustrate how we can verify  $LTL(\Pi)^+$  formulas  $\mathbf{E} \varphi$  by model checking  $\neg \varphi$  and getting a counterexample as a **proof** of  $\mathbf{E} \varphi$ .

## COMM Revisited (VI)

As a last example, we can use COMM to illustrate how we can verify  $LTL(\Pi)^+$  formulas  $\mathbf{E} \varphi$  by model checking  $\neg \varphi$  and getting a counterexample as a **proof** of  $\mathbf{E} \varphi$ .

The point is that  $LTL(\Pi)^+$  allows us to ask useful questions regarding **possible** relations between reachable states not expressible in  $LTL(\Pi)$ . For example, we can ask:

## COMM Revisited (VI)

As a last example, we can use COMM to illustrate how we can verify  $LTL(\Pi)^+$  formulas  $\mathbf{E} \varphi$  by model checking  $\neg \varphi$  and getting a counterexample as a **proof** of  $\mathbf{E} \varphi$ .

The point is that  $LTL(\Pi)^+$  allows us to ask useful questions regarding **possible** relations between reachable states not expressible in  $LTL(\Pi)$ . For example, we can ask:

*Are there states reachable from  $init(A, B, L)$  such that the counters of  $A$  and  $B$  hold different values?*

## COMM Revisited (VI)

As a last example, we can use COMM to illustrate how we can verify  $LTL(\Pi)^+$  formulas  $\mathbf{E} \varphi$  by model checking  $\neg \varphi$  and getting a counterexample as a **proof** of  $\mathbf{E} \varphi$ .

The point is that  $LTL(\Pi)^+$  allows us to ask useful questions regarding **possible** relations between reachable states not expressible in  $LTL(\Pi)$ . For example, we can ask:

*Are there states reachable from  $init(A, B, L)$  such that the counters of  $A$  and  $B$  hold different values?*

We can express the negation  $\neg \varphi$  of this property by adding to CHECK-PREDS the following **parametric** predicate definition:

# COMM Revisited (VII)

```
op same-cnts : Oid Oid -> Prop .
```

```
eq < A : Sender | buff : L2, rec : B, cnt : N, ack-w : TV >  
  < B : Receiver | buff : L1, snd : A, cnt : N > C |= same-cnts(A,B) = true .
```



# COMM Revisited (VII)

```
op same-cnts : Oid Oid -> Prop .
```

```
eq < A : Sender | buff : L2, rec : B, cnt : N, ack-w : TV >
  < B : Receiver | buff : L1, snd : A, cnt : N > C |= same-cnts(A,B) = true .
```

Now we can ask and answer the original question  $\mathbf{E} \varphi(A, B)$ , i.e.,

# COMM Revisited (VII)

```
op same-cnts : Oid Oid -> Prop .
```

```
eq < A : Sender | buff : L2, rec : B, cnt : N, ack-w : TV >
  < B : Receiver | buff : L1, snd : A, cnt : N > C |= same-cnts(A,B) = true .
```

Now we can ask and answer the original question  $\mathbf{E} \varphi(A, B)$ , i.e.,

$\mathbf{E} \langle \rangle \sim \text{same-cnts}(A, B)$

# COMM Revisited (VII)

```
op same-cnts : Oid Oid -> Prop .
```

```
eq < A : Sender | buff : L2, rec : B, cnt : N, ack-w : TV >  
  < B : Receiver | buff : L1, snd : A, cnt : N > C |= same-cnts(A,B) = true .
```

Now we can ask and answer the original question  $\mathbf{E} \varphi(A, B)$ , i.e.,

$\mathbf{E} \langle \rangle \sim \text{same-cnts}(A, B)$

by model checking  $\neg \varphi(A, B)$ , that is, by model checking

# COMM Revisited (VII)

```
op same-cnts : Oid Oid -> Prop .
```

```
eq < A : Sender | buff : L2, rec : B, cnt : N, ack-w : TV >  
  < B : Receiver | buff : L1, snd : A, cnt : N > C |= same-cnts(A,B) = true .
```

Now we can ask and answer the original question  $\mathbf{E} \varphi(A, B)$ , i.e.,

$\mathbf{E} \langle \rangle \sim \text{same-cnts}(A, B)$

by model checking  $\neg \varphi(A, B)$ , that is, by model checking

$\square \text{ same-cnts}(A, B)$

# COMM Revisited (VII)

```
op same-cnts : Oid Oid -> Prop .
```

```
eq < A : Sender | buff : L2, rec : B, cnt : N, ack-w : TV >
  < B : Receiver | buff : L1, snd : A, cnt : N > C |= same-cnts(A,B) = true .
```

Now we can ask and answer the original question  $\mathbf{E} \varphi(A, B)$ , i.e.,

$\mathbf{E} \langle \rangle \sim \text{same-cnts}(A, B)$

by model checking  $\neg \varphi(A, B)$ , that is, by model checking

$\square \text{ same-cnts}(A, B)$

and getting as a **proof** the counterexample:

# COMM Revisited (VIII)

```
red modelCheck(init('a,'b,1),[] same-cnts('a,'b)) .
```

```
result ModelCheckResult: counterexample(
{< 'a : Sender | buff : 1, rec : 'b, cnt : 0, ack-w : false >
  < 'b : Receiver | buff : nil, cnt : 0, snd : 'a >,'snd}
{< 'a : Sender | buff : nil, rec : 'b, cnt : 0, ack-w : true >
  < 'b : Receiver | buff : nil, cnt : 0, snd : 'a >
  to 'b from 'a val 1 cnt 0,'rec}
{< 'a : Sender | buff : nil, rec : 'b, cnt : 0, ack-w : true >
  < 'b : Receiver | buff : 1, cnt : 1, snd : 'a >
  to 'a from 'b ack 0,'ack-rec},
{< 'a : Sender | buff : nil, rec : 'b, cnt : 1, ack-w : false >
  < 'b : Receiver | buff : 1, cnt : 1, snd : 'a >,'deadlock})
```